

An heuristic for verifying safety properties of infinite-state systems

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Motivation

- How to build **correct** complex systems?



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- Synthesis (from the specification)



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- Build them and then
 - Test
 - Simulate



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- How to build **correct** complex systems?
- Synthesis (from the specification)
- Build them and then
 - Test
 - Simulate
- Alternative: **Formal verification**



What is Verification?

- Instance:
 - P : Program (Hw circuit, communication protocol, distributed system, C program, Real-time system, etc)
 - ϕ : Specification
- Question:
 - Does P satisfies ϕ ?



Formal Verification

- It is a very active field for theoretical research and practical development
- Deductive vs Algorithmic approach



Formal Verification

- Model Checking (Algorithmic)
 - By now, a quite well-established theory (80's)
 - Exhaustive exploration of the state-space
 - Fully automatic
 - Practical applications:
 - Hardware controllers
 - Circuit design
 - Many communication protocols



Formal Verification

- Limitations of Model Checking:
 - Finite-state systems
 - State explosion problem



Formal Verification

- Limitations of Model Checking:
 - Finite-state systems
 - State explosion problem
- Infinite-state systems: More general but more difficult to analyse!



Verification of Infinite-State Systems

- Key aspects to take into account
 - Non-bounded variables and/or data structures (e.g. counters, clocks, queues)
 - Parameterised systems (e.g. nets of unbounded number of id. processes)
 - Mobility
 - Security



Verification of Infinite-State Systems

- Examples of infinite-state systems
 - Timed and hybrid automata
 - Process rewrite systems
 - Push-down automata
 - Communicating FSA (e.g. Lossy channel systems)
 - Petri nets
 - Parameterised systems (mutual exclusion protocols, broadcast protocols, etc)



Verification of Infinite-State Systems

- Techniques:
 - Abstraction
 - Symbolic analysis
 - Well-quasi-ordering (WQO)



The Problem

- Our Dream: Verify the π -calculus!



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- Not yet there! We start with something simpler: CCS-like Calculus



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- Which kind of properties?
 - Safety properties (Reachability)



The Problem

- Our Dream: Verify the π -calculus!
- Not yet there! We start with something simpler: CCS-like Calculus
- Which kind of properties?
 - Safety properties (Reachability)
- Problems?
 - Verifying safety properties is undecidable in CCS
 - Termination



Our Solution

Algorithm:

- Give a Petri net semantics to CCS-like Agents
Agent: A , Petri net: N_A
- Obtain an over-approximation Petri net $W(N_A)$
- Prove that $W(N_A)$ is a Well-Structured System
- Reachability is decidable in $W(N_A)$

Our Solution

- Our algorithm is partial:
 - If it says (NO) YES: the property is (not) satisfied
 - Sometimes it says UNKNOWN



Agenda

- Preliminaries
 - Well-Structured Systems
 - An Agent Language (CCS-like)
 - Petri Nets
- Petri Nets Semantics of the Agent Lang.
- Safety Properties Verification
- Concluding Remarks

Well-Structured Systems: Preliminaries

Let $\langle S, \rightarrow \rangle$ (where $S = Q \times D$ is a set of *states*)
be a **labelled transition system (LTS)** and \preceq a
preorder (reflexive and transitive)



Well-Structured Systems: Preliminaries

Let $\langle S, \rightarrow \rangle$ (where $S = Q \times D$ is a set of *states*) be a labelled transition system (LTS) and \preceq a preorder (reflexive and transitive)

- \preceq is a **WQO** if there is no infinite sequence a_0, a_1, \dots , so that $a_i \not\preceq a_j$ for any $i \leq j$



Well-Structured Systems: Preliminaries

Let $\langle S, \rightarrow \rangle$ (where $S = Q \times D$ is a set of *states*) be a labelled transition system (LTS) and \preceq a preorder (reflexive and transitive)

- Let D be a set. A subset $U \subseteq D$ is **upward closed** if whenever $a \in U, b \in D$ and $a \preceq b$, then $b \in U$. The *upward closure* of a set

$A \subseteq D$ is

$$\mathcal{C}(A) := \{b \in D \mid \exists a \in A. a \preceq b\}$$



Well-Structured Systems: Preliminaries

Let $\langle S, \rightarrow \rangle$ (where $S = Q \times D$ is a set of *states*) be a labelled transition system (LTS) and \preceq a preorder (reflexive and transitive)

- A LTS $\langle S, \rightarrow \rangle$ is **monotonic** if, whenever $s \preceq t$ and $s \xrightarrow{\alpha} s'$, then $t \xrightarrow{\alpha} t'$ for some t' so that $s' \preceq t'$



Well-Structured Systems: Definition

A trans. system $\mathcal{L} = \langle S, \rightarrow \rangle$ (with \preceq on data values) is **well-structured** if

- \preceq is a well-quasi-ordering, and
- $\langle S, \rightarrow \rangle$ is monotonic with respect to \preceq , and
- for all $s \in S$ and $\alpha \in L$, the set $\min(\text{pre}_\alpha(\mathcal{C}(\{s\})))$ is computable



WSS: Some Nice Properties

Theorem:

- Let $\langle S, \rightarrow \rangle$ be a WSS, $\langle q, d \rangle$ a state and U an upward-closed subset of the set of data values
- Then it is decidable whether it is possible to reach, from $\langle q, d \rangle$, any state $\langle q', d' \rangle$ with $d' \in U$



An Agent Language (CCS-like)

- Given:
 - A set of *names*, \mathcal{N} ($a, b, x, y \dots$)
 - A set of *co-names*, $\overline{\mathcal{N}} = \{\overline{a} \mid a \in \mathcal{N}\}$. The set of *visible actions*: $Act = \mathcal{N} \cup \overline{\mathcal{N}}$
 - We denote by $Act_\tau = \mathcal{N} \cup \overline{\mathcal{N}} \cup \{\tau\}$ (α)



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 - We denote by $Act_\tau = \mathcal{N} \cup \overline{\mathcal{N}} \cup \{\tau\}$ (α)
- The syntax is given by:

$$P ::= \mathbf{0} \mid \alpha.P \mid P + Q \mid P \setminus c \mid P \parallel P \mid A$$

Where $A \stackrel{\text{def}}{=} P$



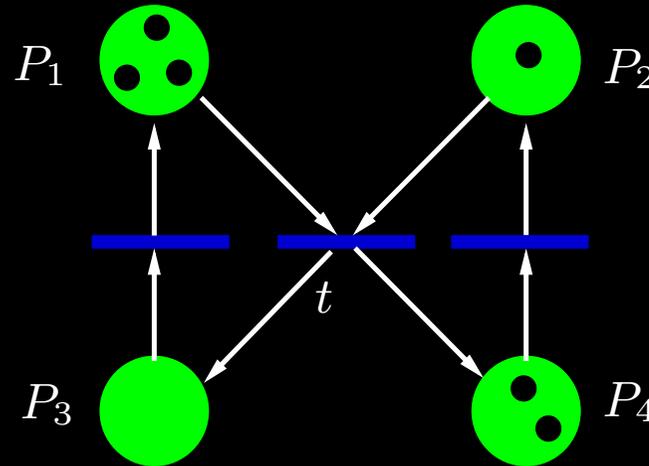
Petri Nets

- A Petri net is a tuple $N = (P, A, T, M_0)$:
 - P is a finite set of *places*
 - A is a finite set of *actions* (or *labels*)
 - $T \subseteq \mathcal{M}(P) \times A \times \mathcal{M}(P)$ is a finite set of *transitions*
 - M_0 is the *initial marking*

where $\mathcal{M}(P)$ is a collection of multisets (bags) over P



Petri Nets: Graphical representation



Marking

M : is a mapping from places to the set of natural numbers

$$M(P_1) = 3 \quad M(P_2) = 1$$

$$M(P_3) = 0 \quad M(P_4) = 2$$



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- Safety Properties Verification
- Concluding Remarks

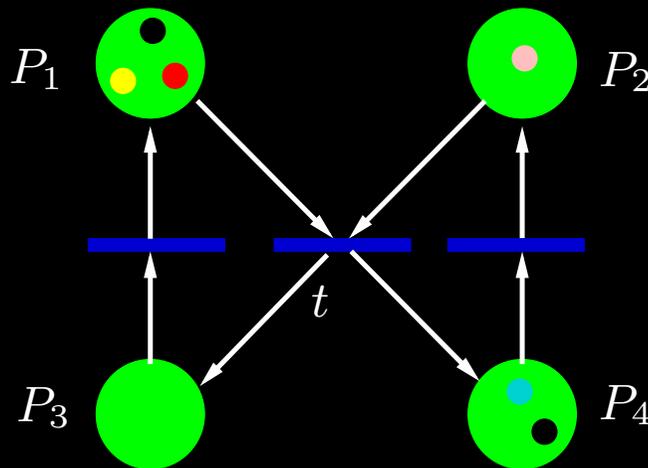
Petri Nets Semantics of the Agent Lang.

- We will use Coloured Petri Nets



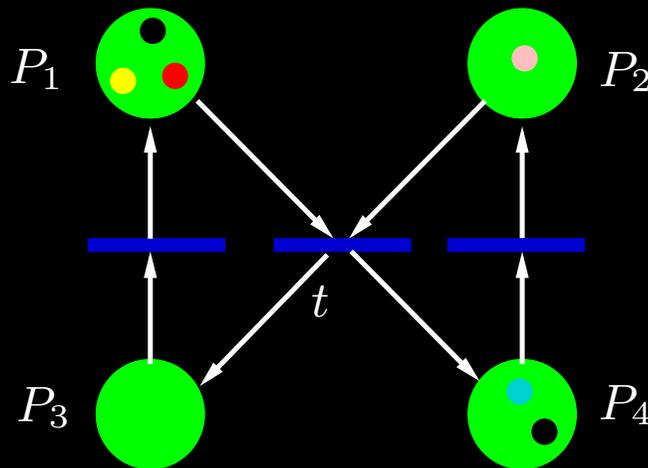
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Petri Nets Semantics of the Agent Lang.

- We will use **Coloured Petri Nets**



- In particular, we will use *strings* as colours

Petri Nets Semantics of the Agent Lang.: Formal Definition

- Places : all agent constants together with all agents and sub-agents that occur on the right-hand side of any defining equation within the environment



Petri Nets Semantics of the Agent Lang.: Formal Definition

- Places
- Transitions :

$$\text{Trans}(\alpha.P) = \left\{ \left\langle \{\alpha.P\}, \{P\} \right\rangle \mapsto \alpha \right\}$$

$$\text{Trans}(P + Q) = \left\{ \left\langle \{P + Q\}, \{P\} \right\rangle, \left\langle \{P + Q\}, \{Q\} \right\rangle \right\}$$

$$\text{Trans}(P|Q) = \left\{ \left\langle \{P|Q\}, \{P \mapsto l, Q \mapsto r\} \right\rangle \right\}$$

$$\text{Trans}(P \setminus c) = \left\{ \left\langle \{P \setminus c\}, \{P\} \right\rangle \mapsto \setminus c \right\}$$

$$\text{Trans}(A) = \left\{ \left\langle \{A\}, \{P\} \right\rangle \right\}, \text{ given that } A \triangleq P$$

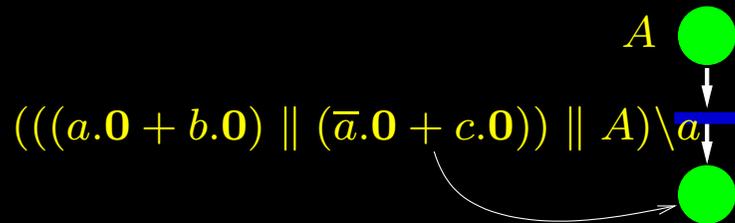


Petri Nets Semantics of the Agent Lang.: Example

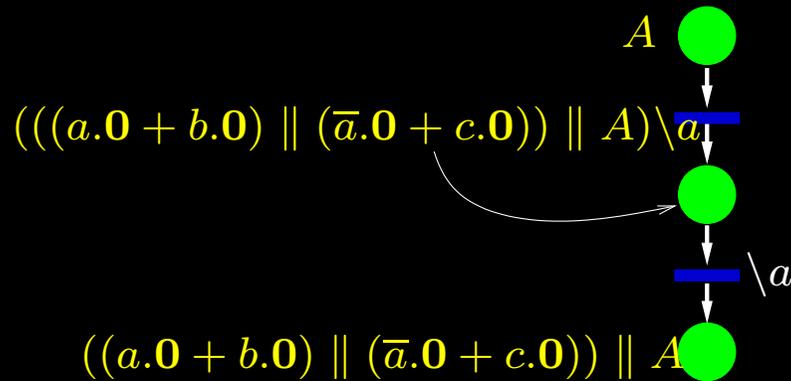
$$A \stackrel{\text{def}}{=} (((a.\mathbf{0} + b.\mathbf{0}) \parallel (\bar{a}.\mathbf{0} + c.\mathbf{0})) \parallel A) \setminus a$$



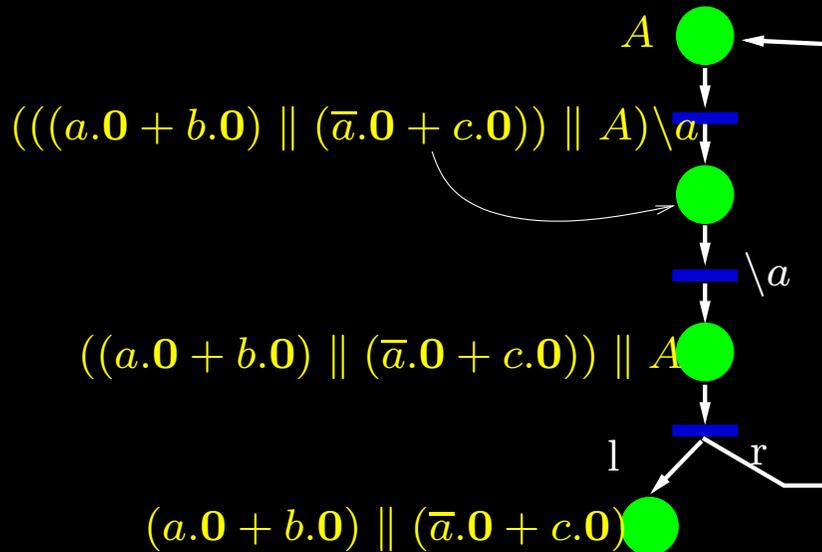
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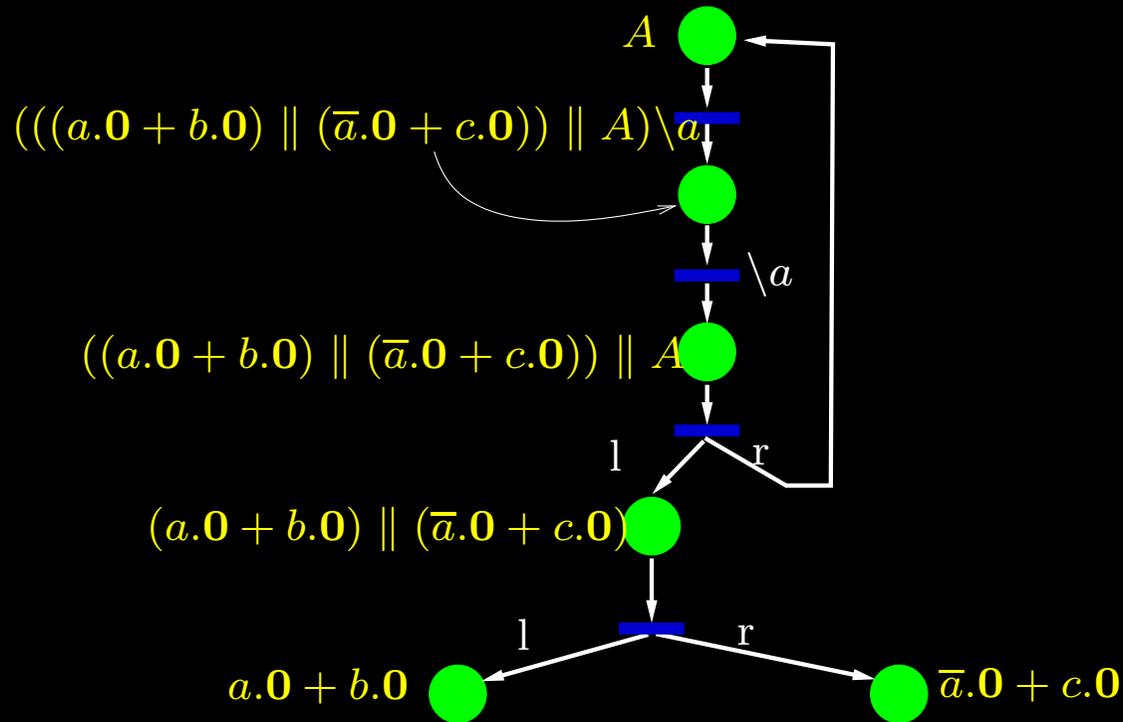
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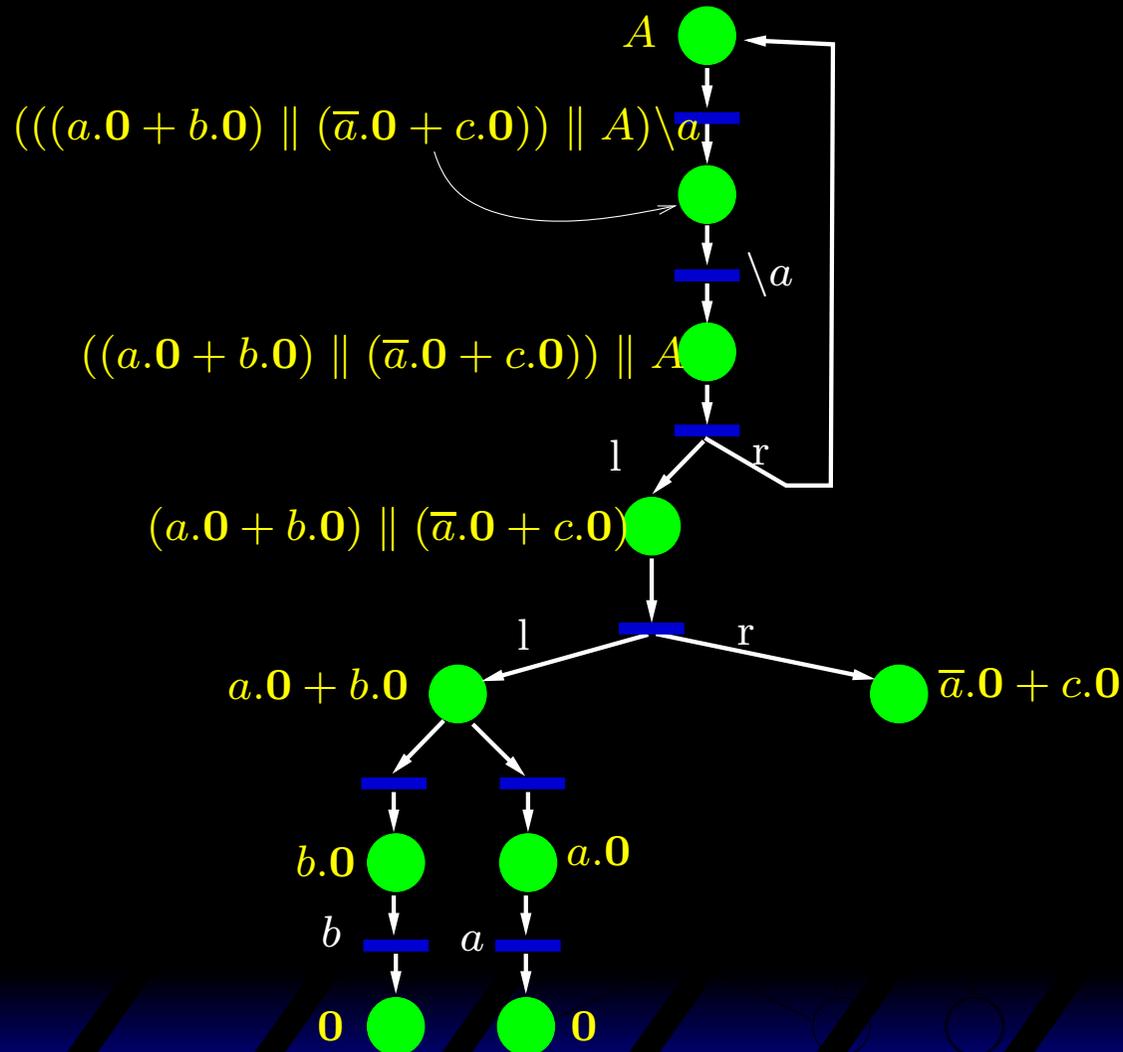
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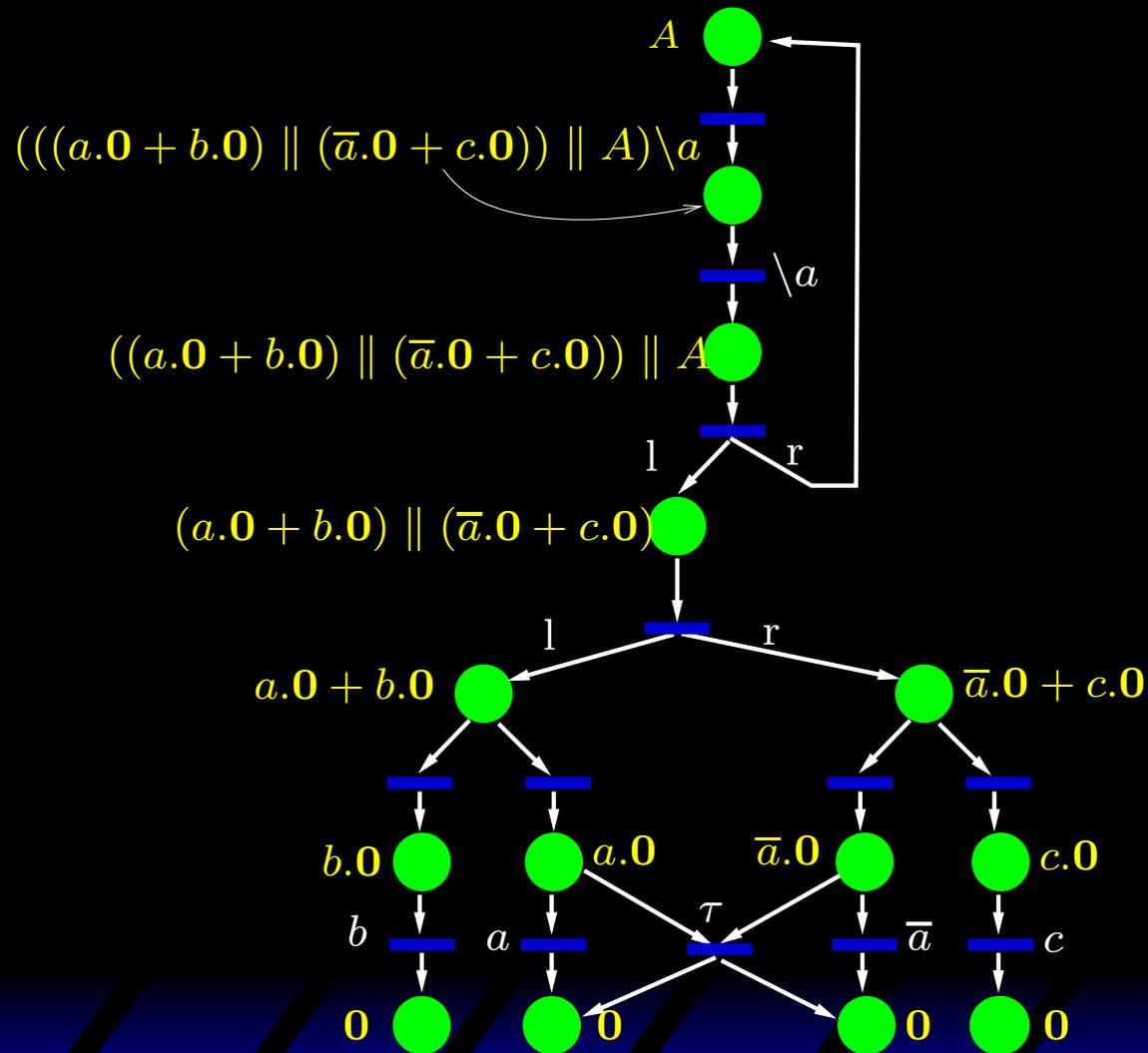
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Petri Nets Semantics of the Agent Lang.: Example



Petri Nets Semantics of the Agent Lang.: Formal Definition

- Tokens : $(Act \cup \{l, r\})^*$; Empty token: ϵ .
They carry history information about:
 - Concurrent threads, and
 - In which scope w.r.t. restriction they are

Petri Nets Semantics of the Agent Lang.: Formal Definition

- Tokens
- Firing (Enabling of Transitions):
 - For transition t with one input place and a token θ , t is enabled if *some* of the following hold
 - t is **not** labelled with a visible action
 - t is labelled with a visible action a and θ doesn't contain a

Petri Nets Semantics of the Agent Lang.: Formal Definition

- Tokens
- Firing (Enabling of Transitions):
 - For transition t with two input places p_1 and p_2 and tokens θ_1 and θ_2 , t is enabled if *both* of the following hold
 - $\text{pc}(pre_i(t)) \setminus Act \neq \epsilon$, $i = 1, 2$, while $\text{pc}(pre_1(t)) \setminus Act \neq \text{pc}(pre_2(t)) \setminus Act$
 - $\text{maxpref}_a(\text{pc}(pre_1(t))) = \text{maxpref}_a(\text{pc}(pre_2(t)))$

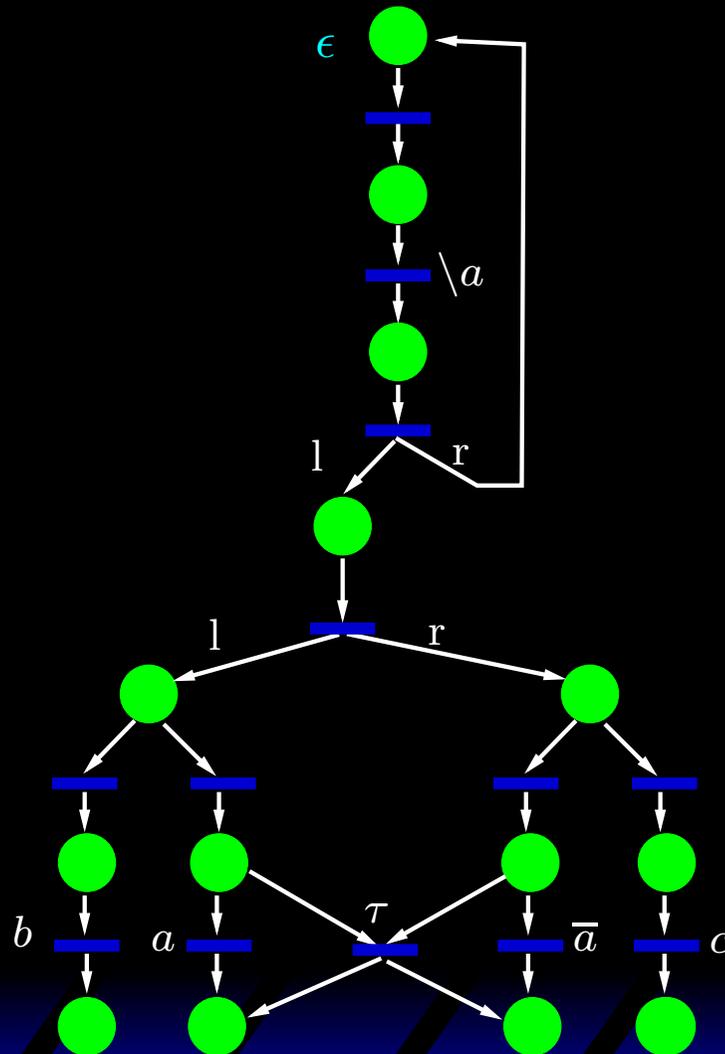


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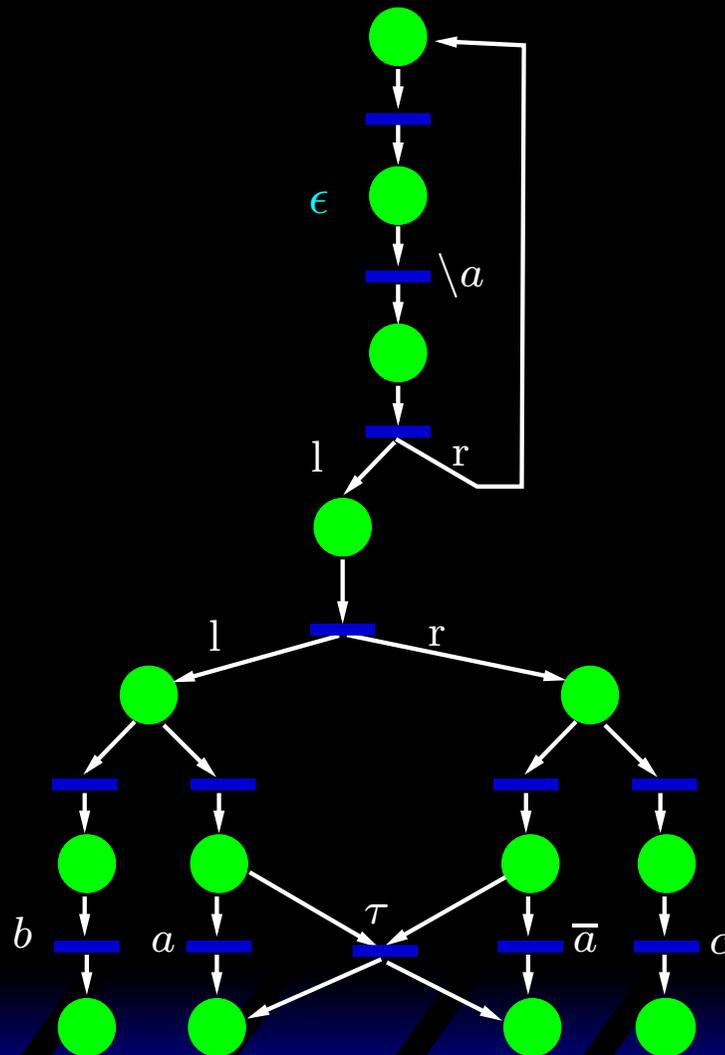
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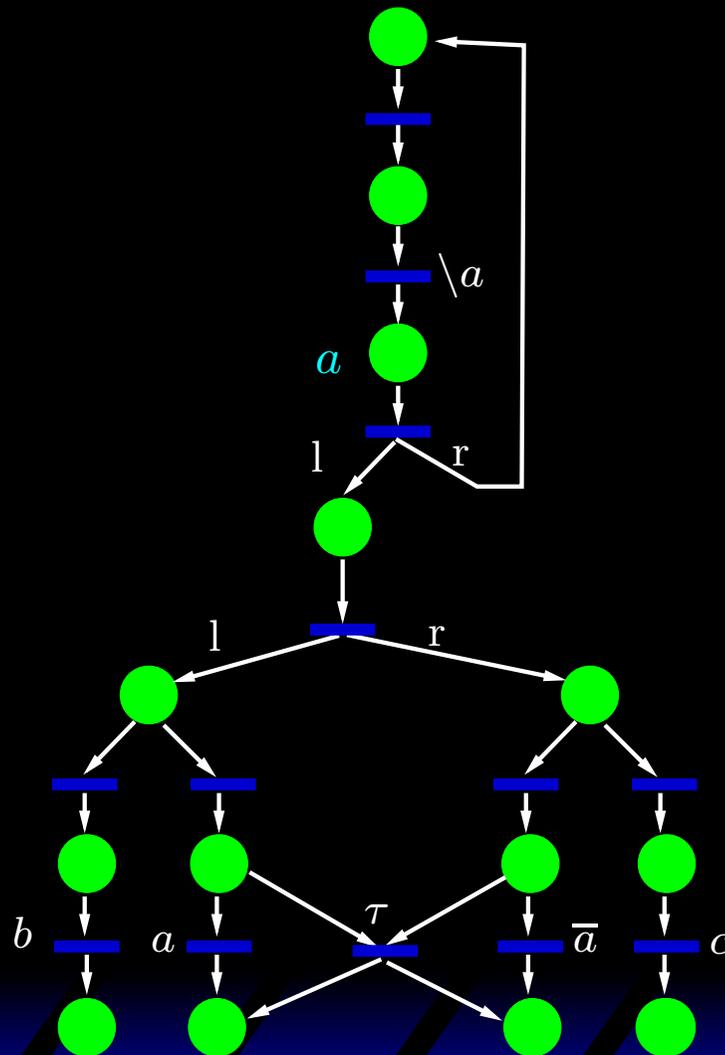
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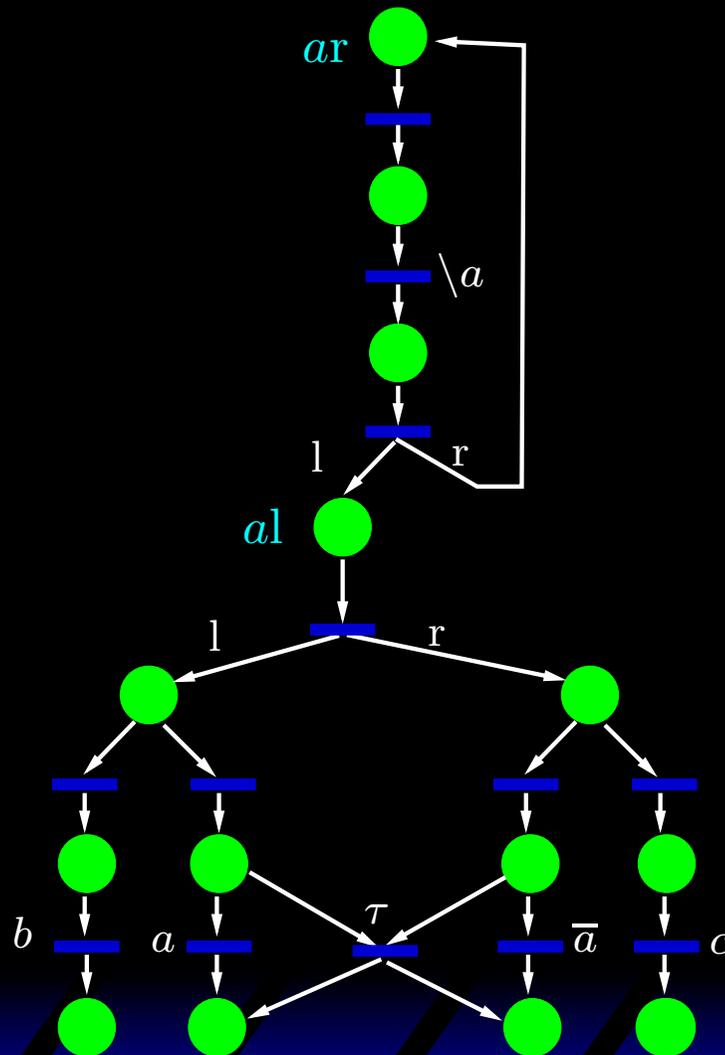
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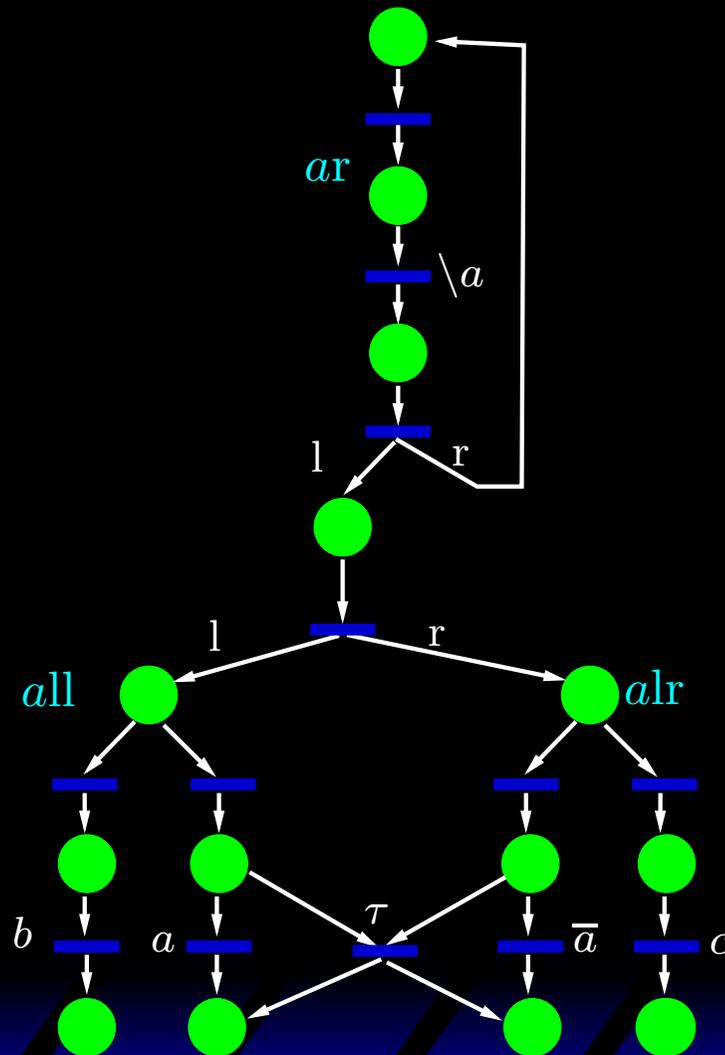
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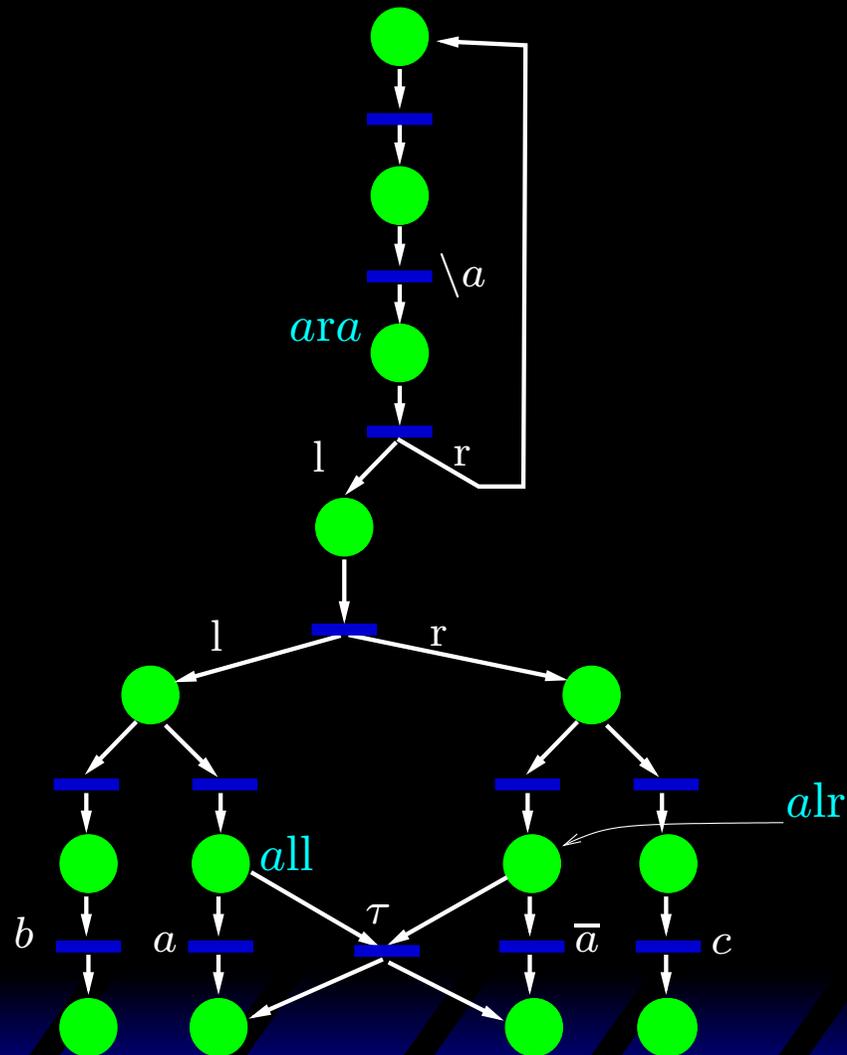
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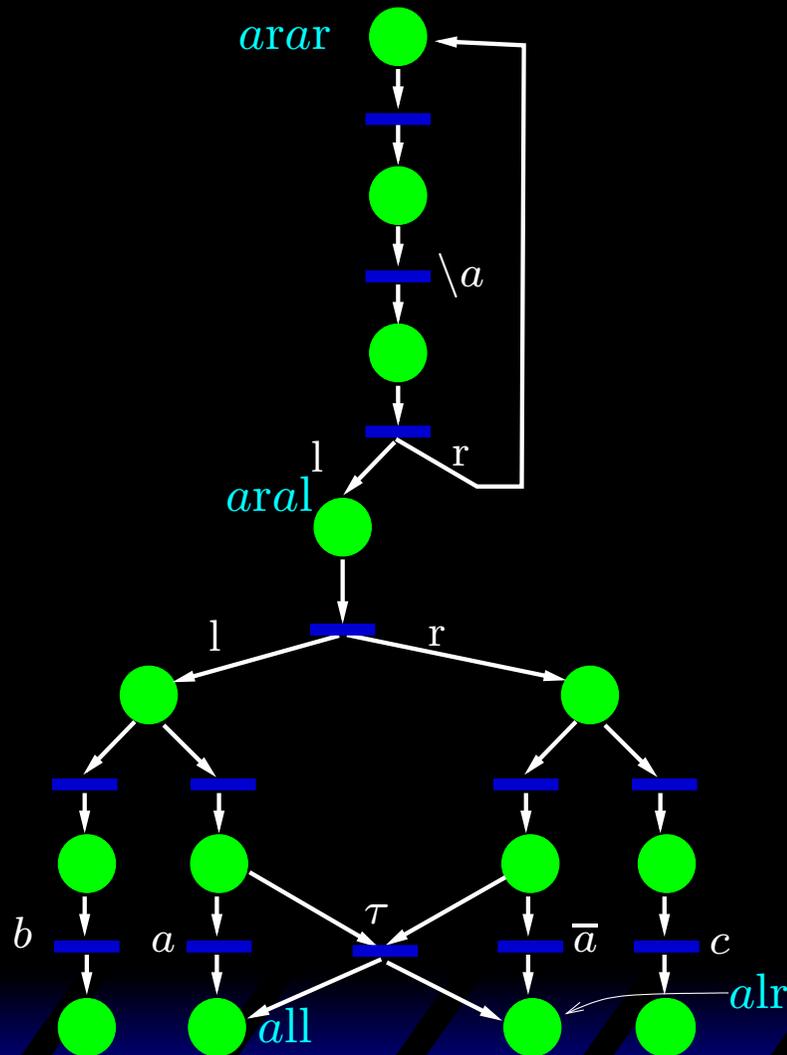
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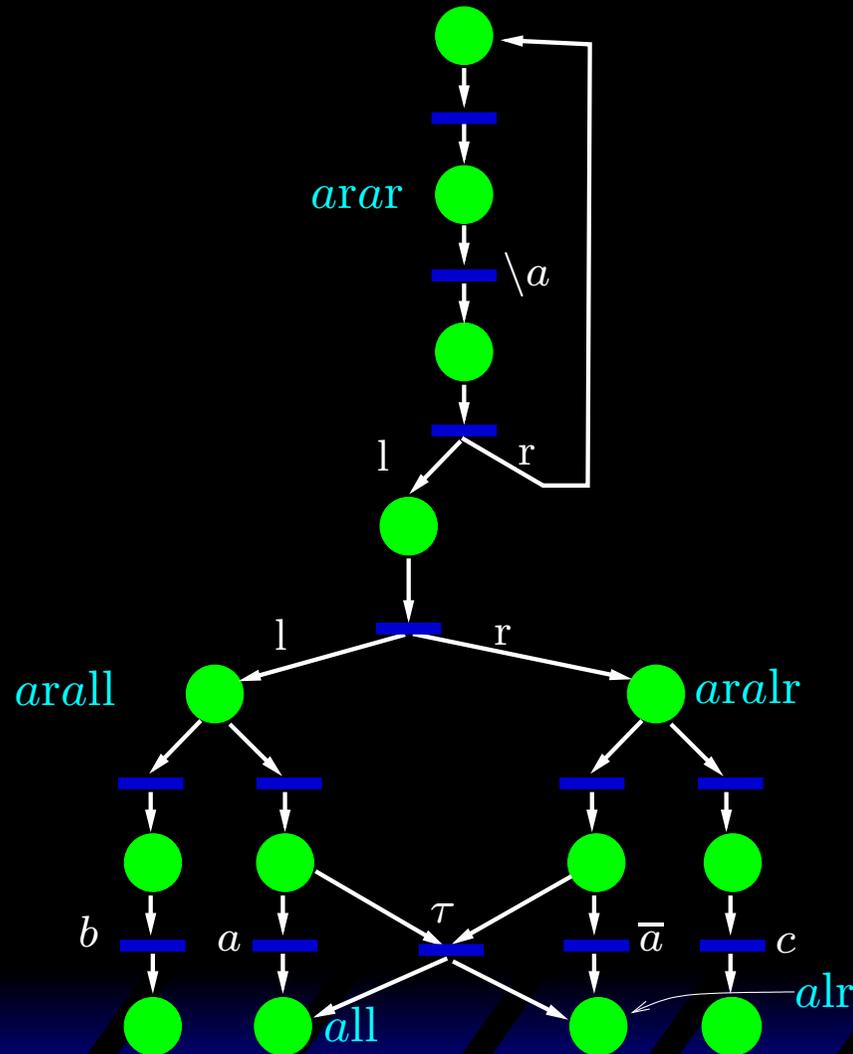
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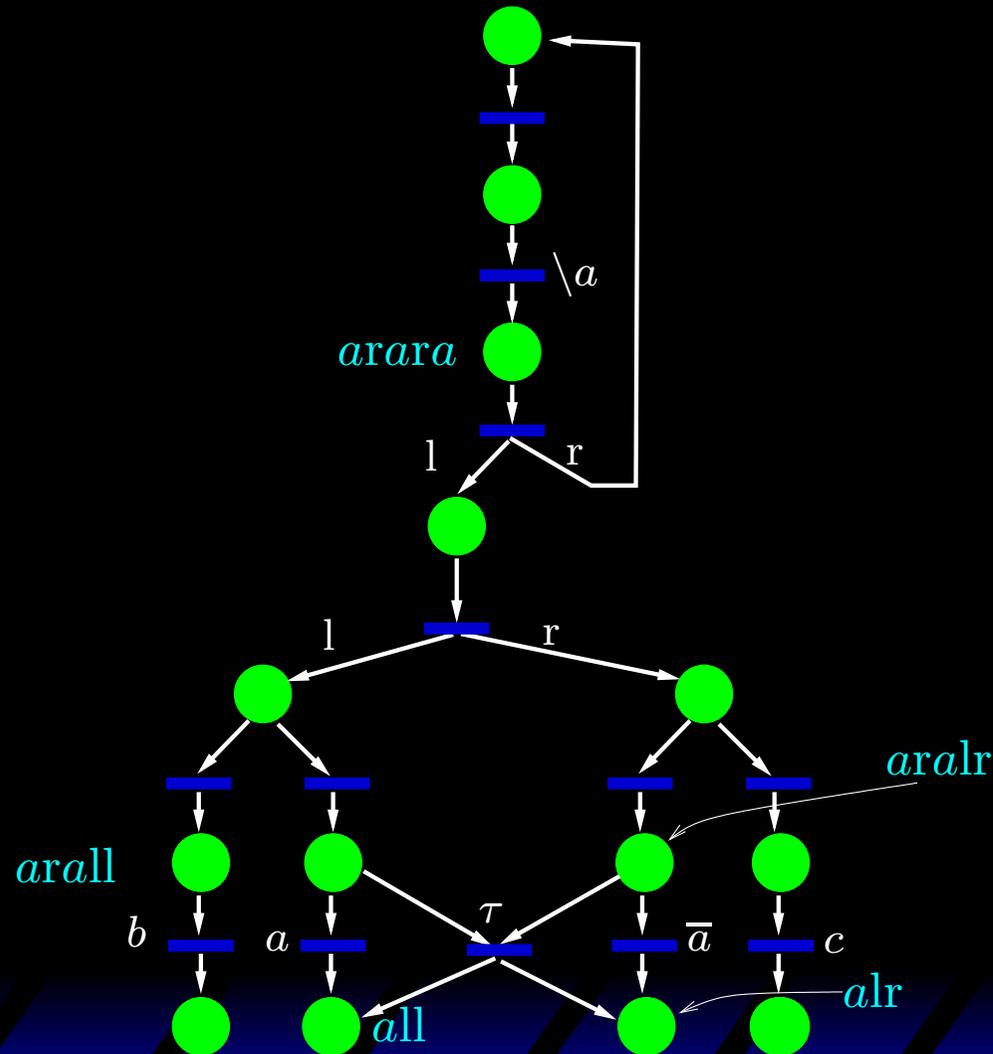
Petri Nets Semantics of the Agent Lang.: Example



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Petri Nets Semantics of the Agent Lang.: Example



Petri Nets Semantics of the Agent Lang.: Extra Structure

- We define a preorder between tokens:

$\eta \preceq \theta$ if η is a (not necessarily contiguous) substring of θ

Example:

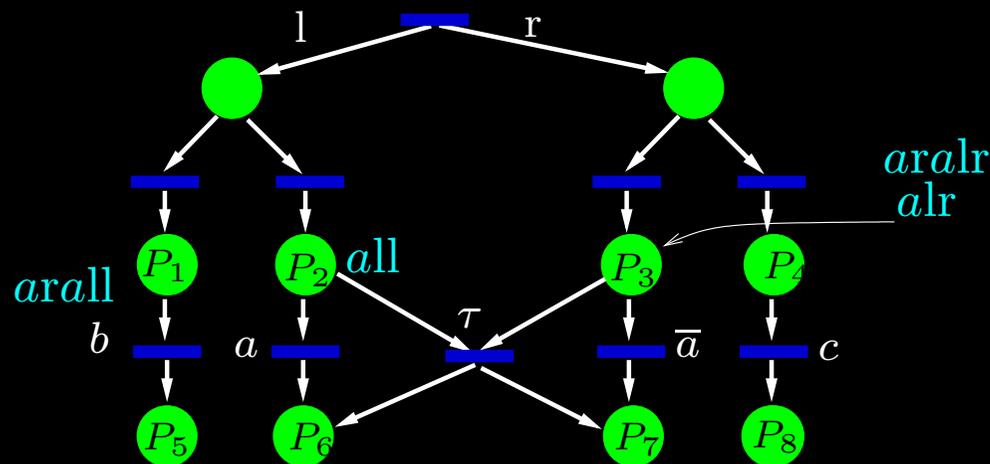
$all \preceq ararall$

Petri Nets Semantics of the Agent Lang.: Extra Structure

- We define an ordering between markings:

$$m_1 \sqsubseteq m_2$$

Example: m_1



Petri Nets Semantics of the Agent Lang.: Extra Structure

- We define an ordering between markings:

$$m_1 \sqsubseteq m_2$$

Example:

$$m_1 = \{\dots, (P_1, \{arall\}), (P_2, \{all\}), (P_3, \{alr, aralr\}), \\ (P_4, \{\}), (P_5, \{\}), (P_6, \{\}), (P_7, \{\}), (P_8, \{\})\}$$

$$m_2 = \{\dots, (P_1, \{arall\}), (P_2, \{ararall\}), (P_3, \{alr, aralr\}), \\ (P_4, \{araralr\}), (P_5, \{all\}), (P_6, \{\}), (P_7, \{\}), (P_8, \{\})\}$$



Petri Nets Semantics of the Agent Lang.: Extra Structure

- We define an ordering between markings:

$$m_1 \sqsubseteq m_2$$

Intuition: $m \sqsubseteq m'$ if m' represents a (not necessarily strictly) longer firing history than m

Petri Nets Semantics of the Agent Lang.: Extra Structure

- We define an ordering between markings:

$$m_1 \sqsubseteq m_2$$

- Markings represent upward closed sets

Example:

$$m_1 = \{ \dots, (P_1, \{arall\}), (P_2, \{all\}), (P_3, \{alr, aralr\}), \\ (P_4, \{\}), (P_5, \{\}), (P_6, \{\}), (P_7, \{\}), (P_8, \{\}) \}$$



Our Petri Nets are not WSS

Very nice, but...



Our Petri Nets are not WSS

Very nice, but...

- Our Petri nets are not monotonic!



Our Petri Nets are not WSS

- Counter-example: Let

$$m_1 = \{\dots, (P_1, \{arall\}), (P_2, \{all\}), (P_3, \{alr, aralr\}), (P_4, \{\}), (P_5, \{\}), (P_6, \{\}), (P_7, \{\}), (P_8, \{\})\}$$

$$m_2 = \{\dots, (P_1, \{arall\}), (P_2, \{ararall\}), (P_3, \{alr, aralr\}), (P_4, \{araralr\}), (P_5, \{all\}), (P_6, \{\}), (P_7, \{\}), (P_8, \{\})\}$$

- Notice that $m_1 \sqsubseteq m_2$



Our Petri Nets are not WSS

- Counter-example: Let

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- Moreover, $m_1 \rightarrow m'_1$, where

$$m'_1 = \{\dots, (P_1, \{arall\}), (P_2, \{\}), (P_3, \{aralr\}), (P_4, \{\}), (P_5, \{\}), (P_6, \{all\}), (P_7, \{alr\}), (P_8, \{\})\}$$



Our Petri Nets are not WSS

- Counter-example: Let

$$m_1 = \{\dots, (P_1, \{arall\}), (P_2, \{all\}), (P_3, \{alr, aralr\}), \\ (P_4, \{\}), (P_5, \{\}), (P_6, \{\}), (P_7, \{\}), (P_8, \{\})\}$$

But, there is **no** m'_2 such that $m'_1 \sqsubseteq m'_2$ and
 $m_2 \rightarrow m'_2$

\Rightarrow It is not monotonic!



Petri Nets as WSS

We make an over-approximation of the Petri net

- We change the synchronisation policy: A transition may be fired even if the tokens don't synchronise (**Weak Firings**)



Petri Nets as WSS

We make an over-approximation of the Petri net

- We change the synchronisation policy: A transition may be fired even if the tokens don't synchronise (**Weak Firings**)

Lemma: P-nets with *weak firings* are well-structured systems



Petri Nets as WSS

We make an over-approximation of the Petri net

- We change the synchronisation policy: A transition may be fired even if the tokens don't synchronise (**Weak Firings**)

Lemma: P-nets with *weak firings* are well-structured systems

Corollary: The control state reachability problem is decidable for p-nets with weak firings



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Verification of Safety Properties: The Problem

Instance: An agent A with initial state ini and an atomic action a

Question: Can agent A ever execute action a ?



Verification of Safety Properties: The Algorithm

Preparatory phase:

[1] Build the p-net N associated with A

[2] For every transition t labelled with a there is a minimal marking m_t that enables t . It is given by an ϵ -token on all places in $pre(t)$. Then $M^a = \{m_t \mid t \text{ labelled by } a\}$.



Verification of Safety Properties: The Algorithm

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[2] For every transition t labelled with a there is a minimal marking m_t that enables t . It is given by an ϵ -token on all places in $pre(t)$. Then $M^a = \{m_t \mid t \text{ labelled by } a\}$.

Remark: m_t is an upward closed set: “At least one token in $pre(t)$ ”



Verification of Safety Properties: The Algorithm

Algorithm:

```
function Reachability( $N, M^a, ini$ ) :  
  ( $OB, s$ ) := Search_backward( $M^a, ini$ )  
  if  $ini \notin OB$   
  then  $\leftarrow$  NO  
  else  $\leftarrow$  Search_forward( $ini, M^a, OB, b(s)$ )
```



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Concluding Remarks

- We have given a (finite-control) Petri net semantics to a CCS-like calculus
- We have presented a general technique for reachability analysis of non-WSS
 - It combines backward and forward reachability analysis
 - It produces answers: YES, NO, UNKNOWN (YES and NO always correct)
- We have applied it to partially decide the reachability problem for a CCS-like calculus



Future Work (Research Topics)

- Use this methodology for verifying safety properties of
 - π -calculus
 - Concurrent Constraint Programming
 - Others?
- Implementation of the Algorithm

MUITO OBRIGADO!

