Monitoring Information Flow

Dynamic tracking of the information flows at execution time

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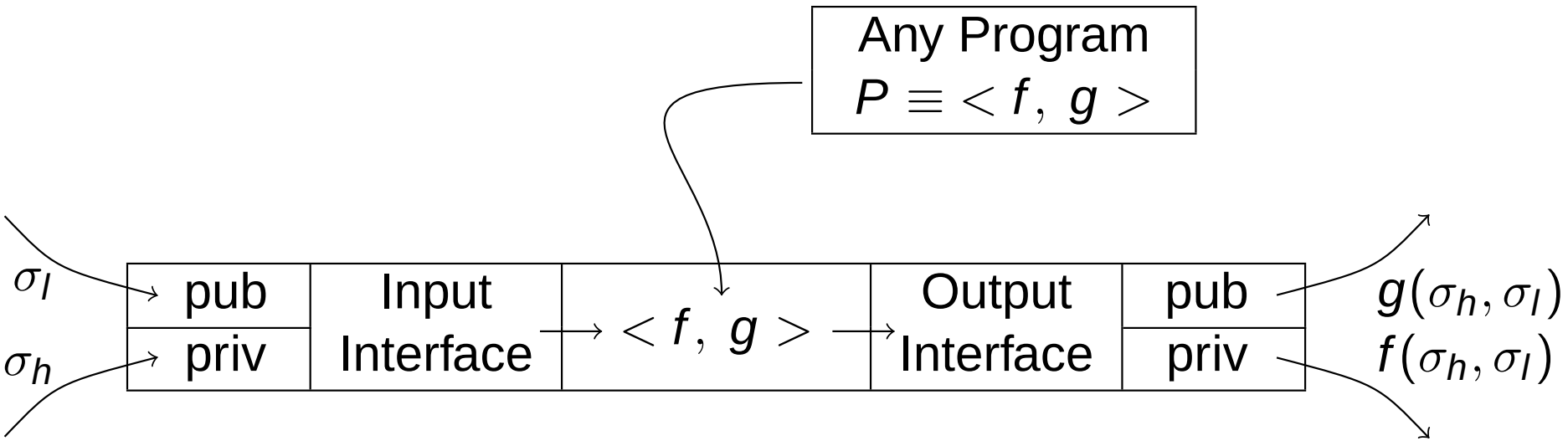
Outline

Goal

$P : \Sigma_{H_i} \times \Sigma_{L_i} \rightarrow \Sigma_{H_o} \times \Sigma_{L_o}$

$f : \Sigma_{H_i} \times \Sigma_{L_i} \rightarrow \Sigma_{H_o} = P\downarrow_1$ (private output slice)

$g : \Sigma_{H_i} \times \Sigma_{L_i} \rightarrow \Sigma_{L_o} = P\downarrow_2$ (public output slice)



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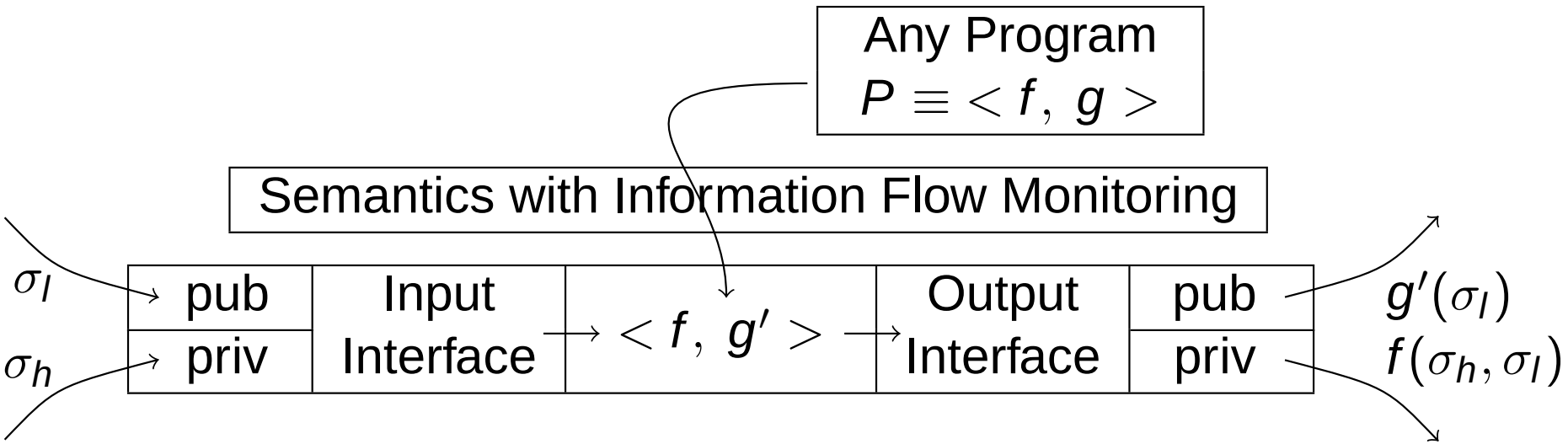


- $\forall o \in \mathrm{dom}(\Sigma_{L_o}),\ \sigma_h \in \Sigma_{H_i},\ \sigma_l \in \Sigma_{L_i}$:
  $g'(\sigma_l)(o) = g(\sigma_h, \sigma_l)(o) \quad \vee \quad g'(\sigma_l)(o) = \delta$

Why not use static analyses ?

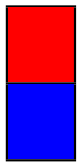
- monitoring can be more precise
  - benefit from more contextual information
- allow usage of programs which can not be proved to respect the confidentiality of secret data
  - allow executions proved to respect secrets' confidentiality
  - alter others

Non-Interference

Presentation of the concept of non-interference

- Cohen (77), Goguen and Meseguer (82)
- Property of a program respecting secrets' confidentiality

input stores $\begin{array}{|c|}\hline h \\ \hline l \\ \hline \end{array}$:



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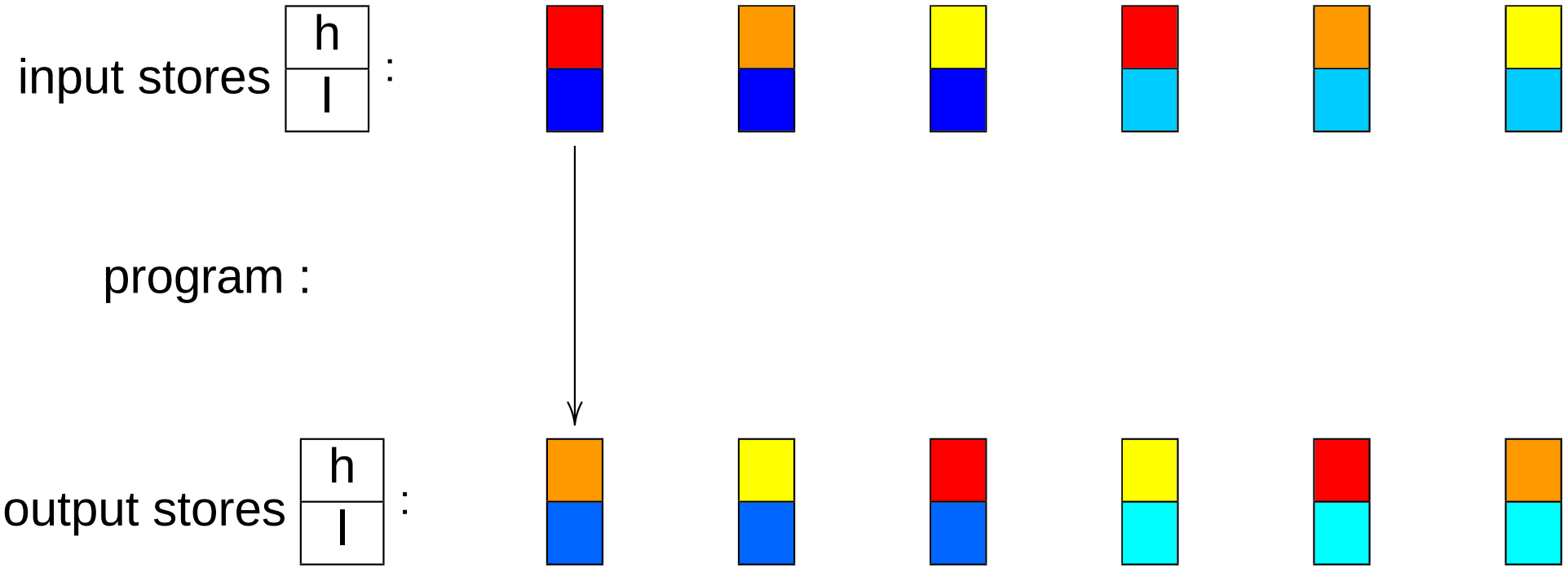

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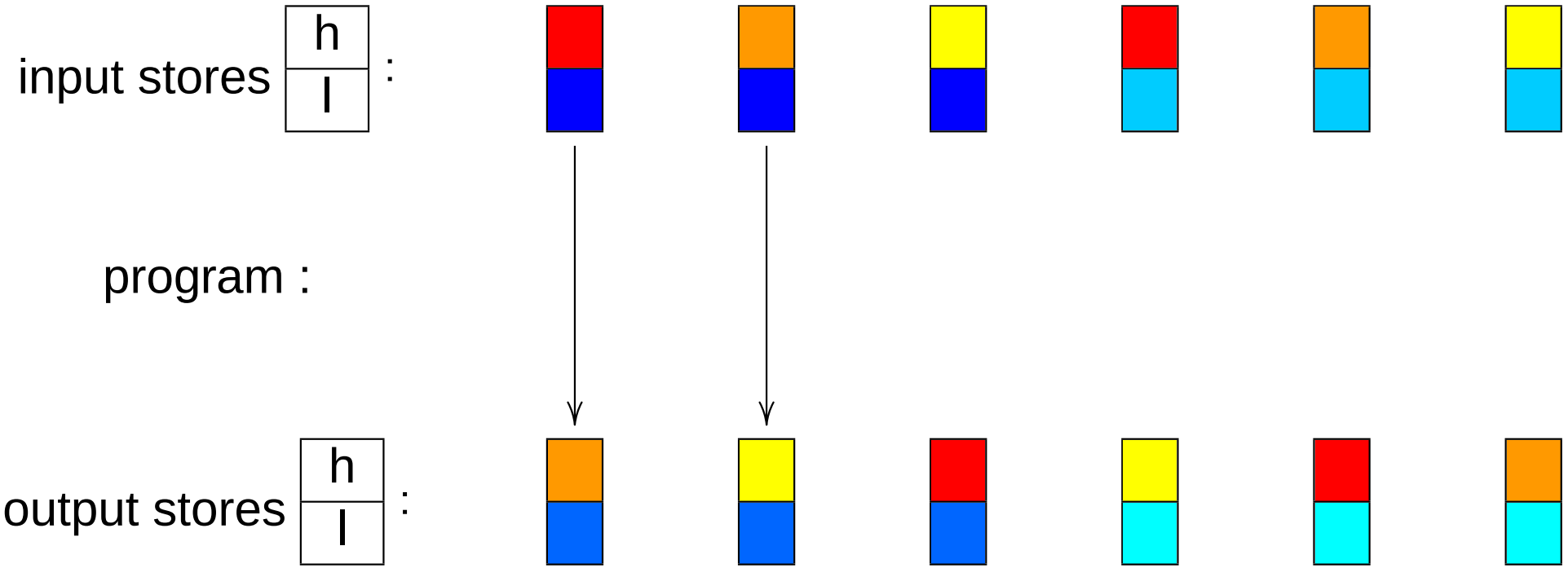

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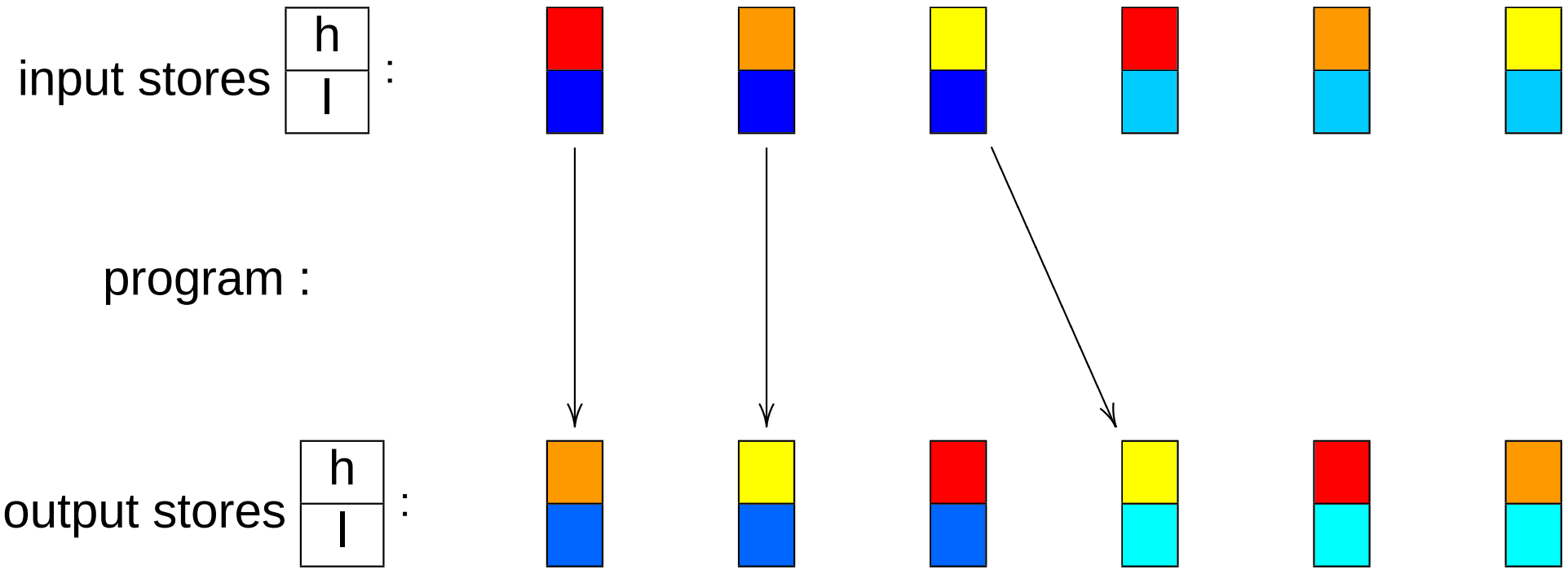

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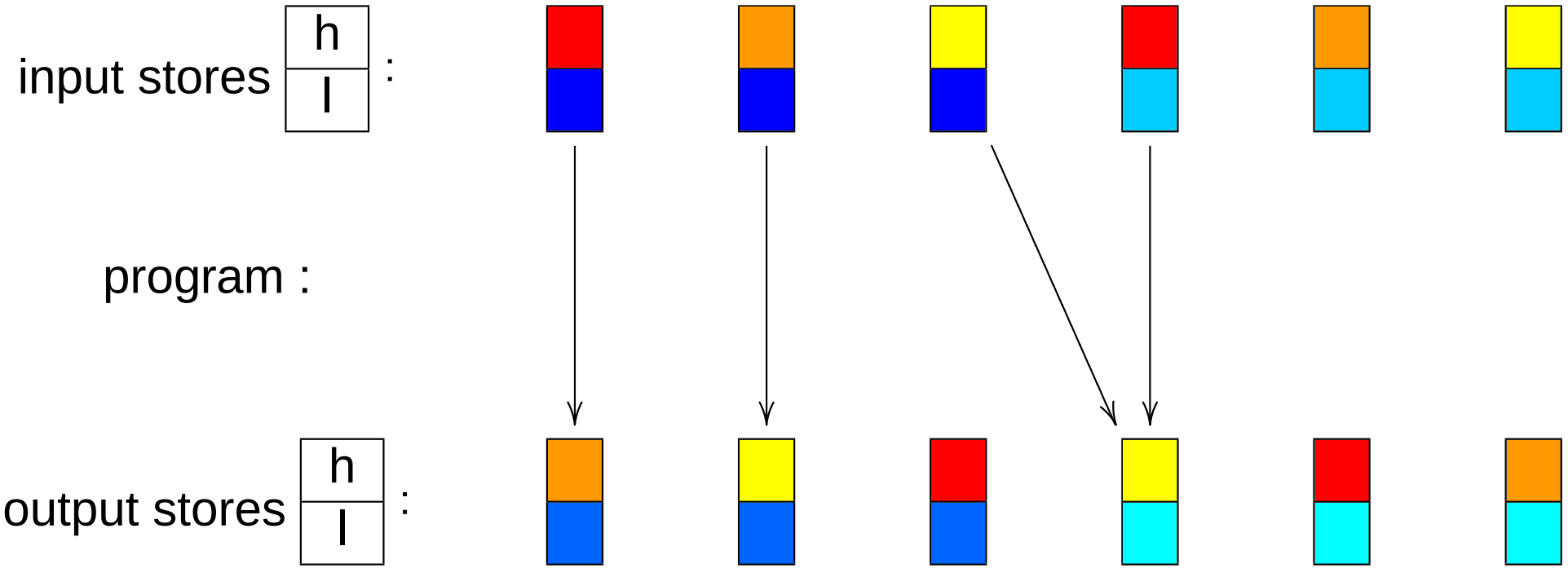

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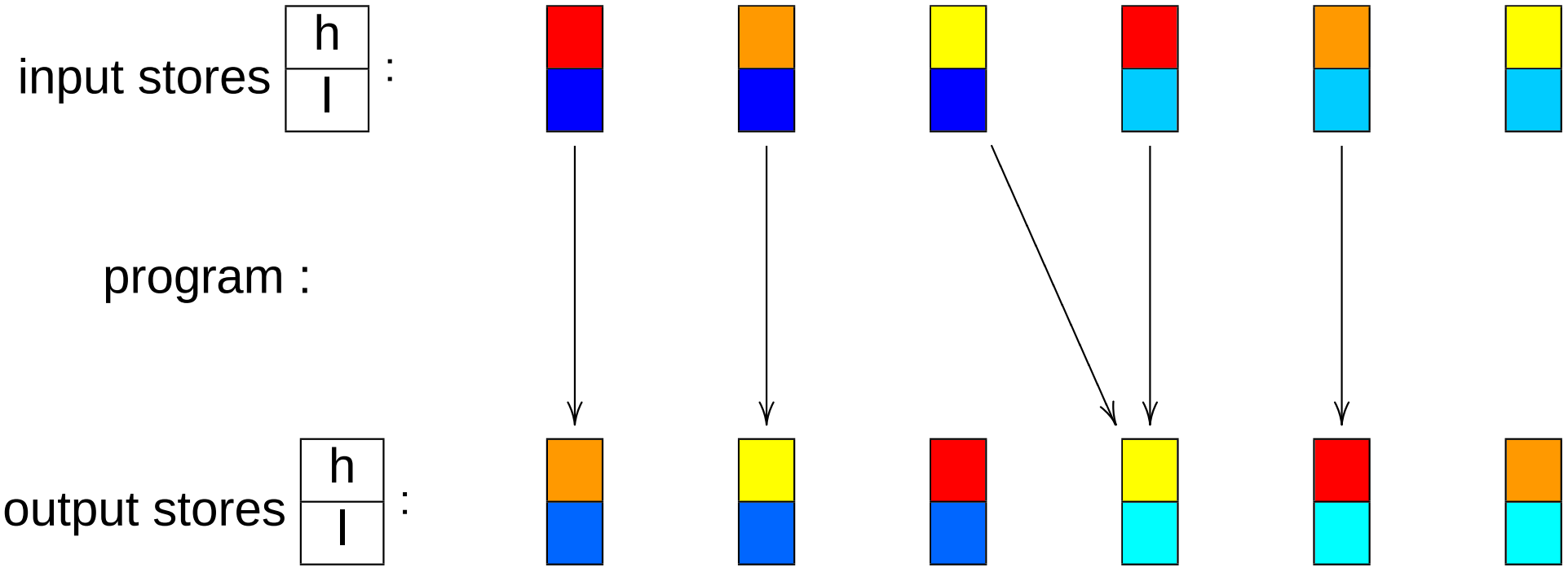

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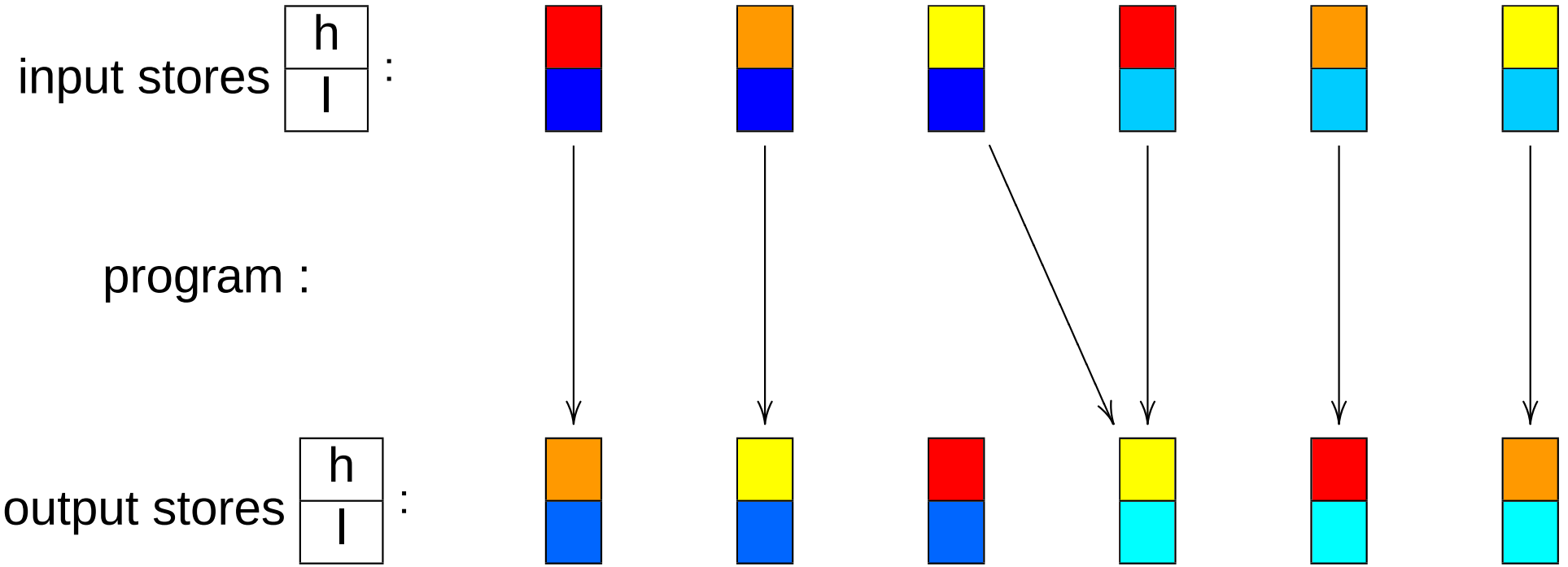

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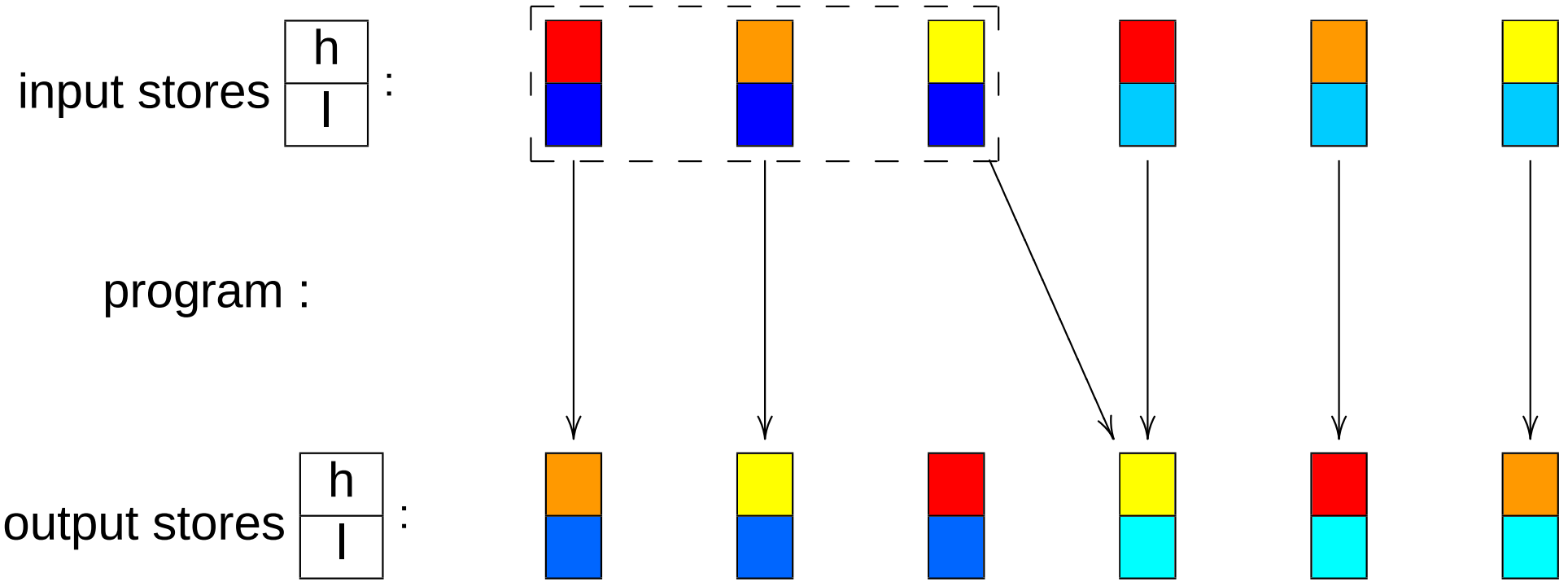

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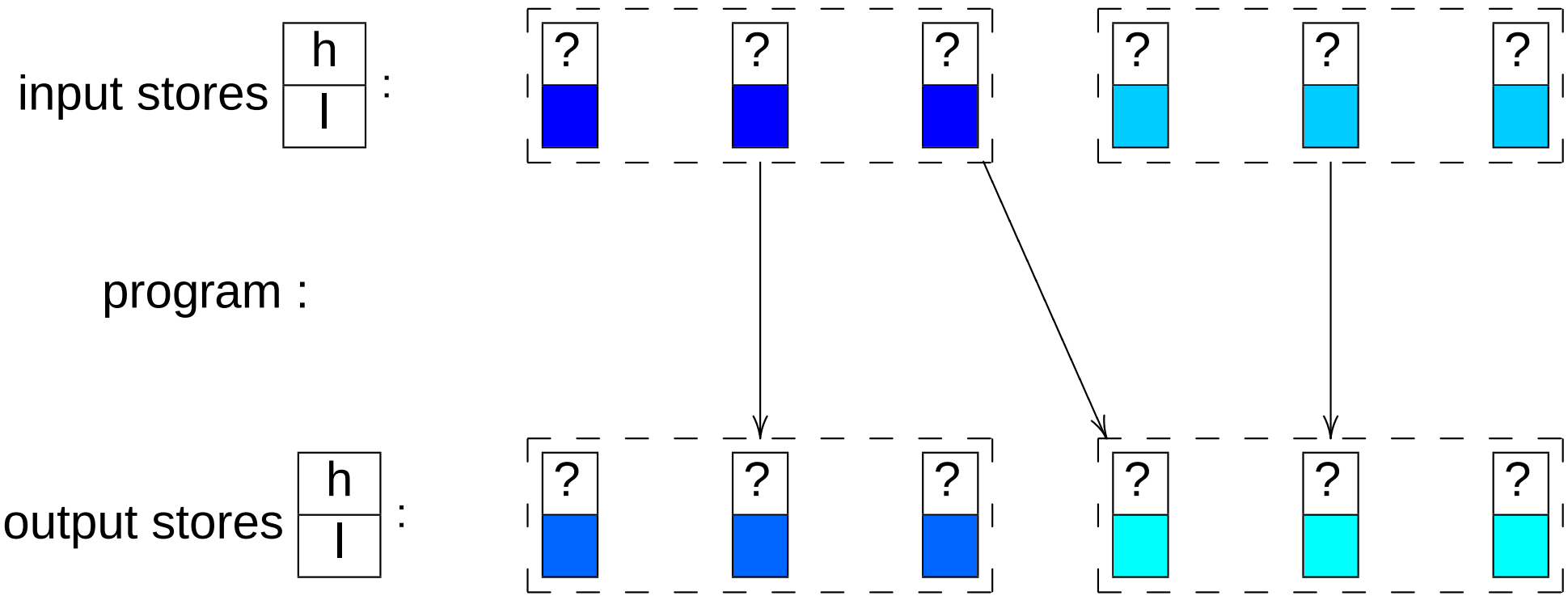

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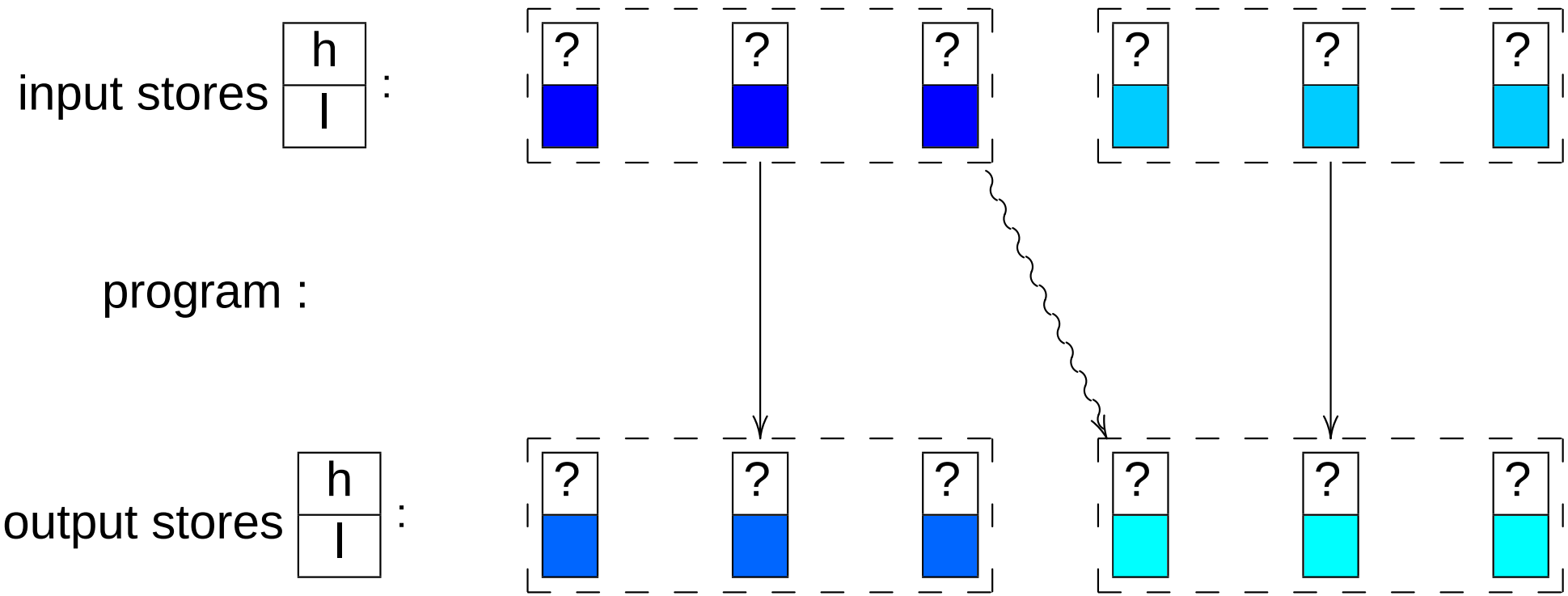

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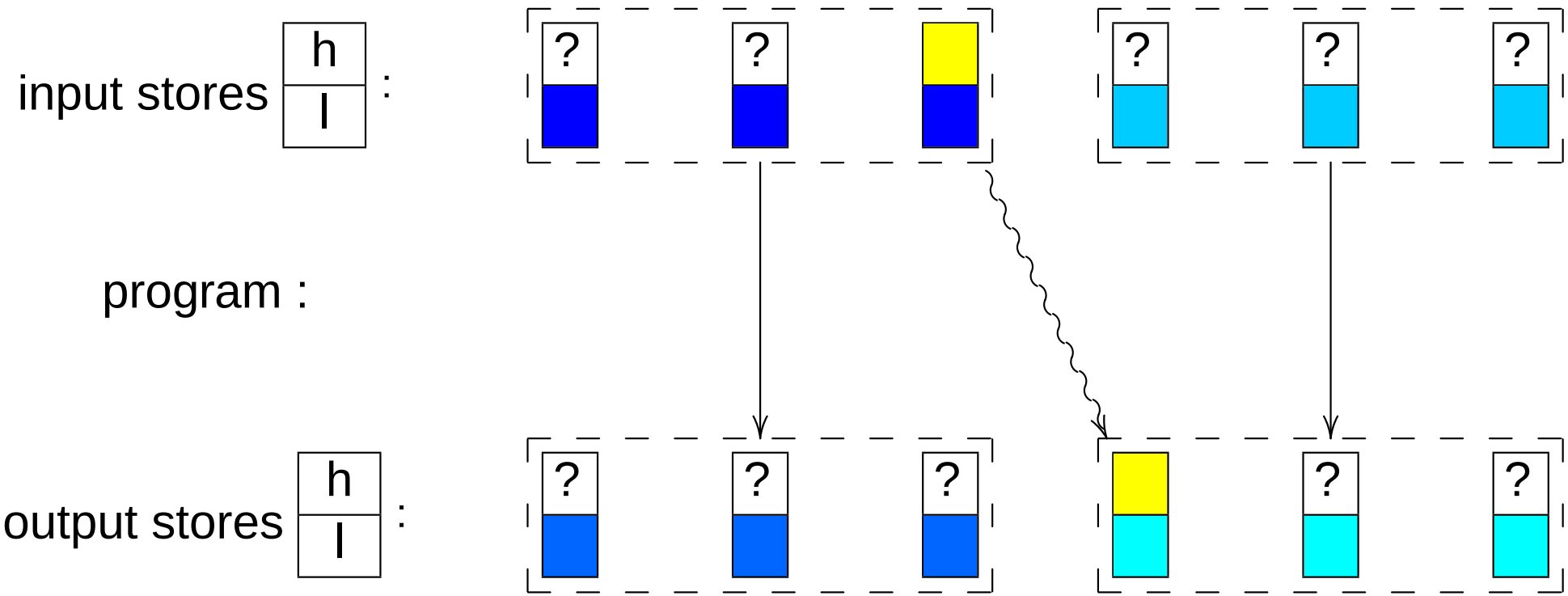

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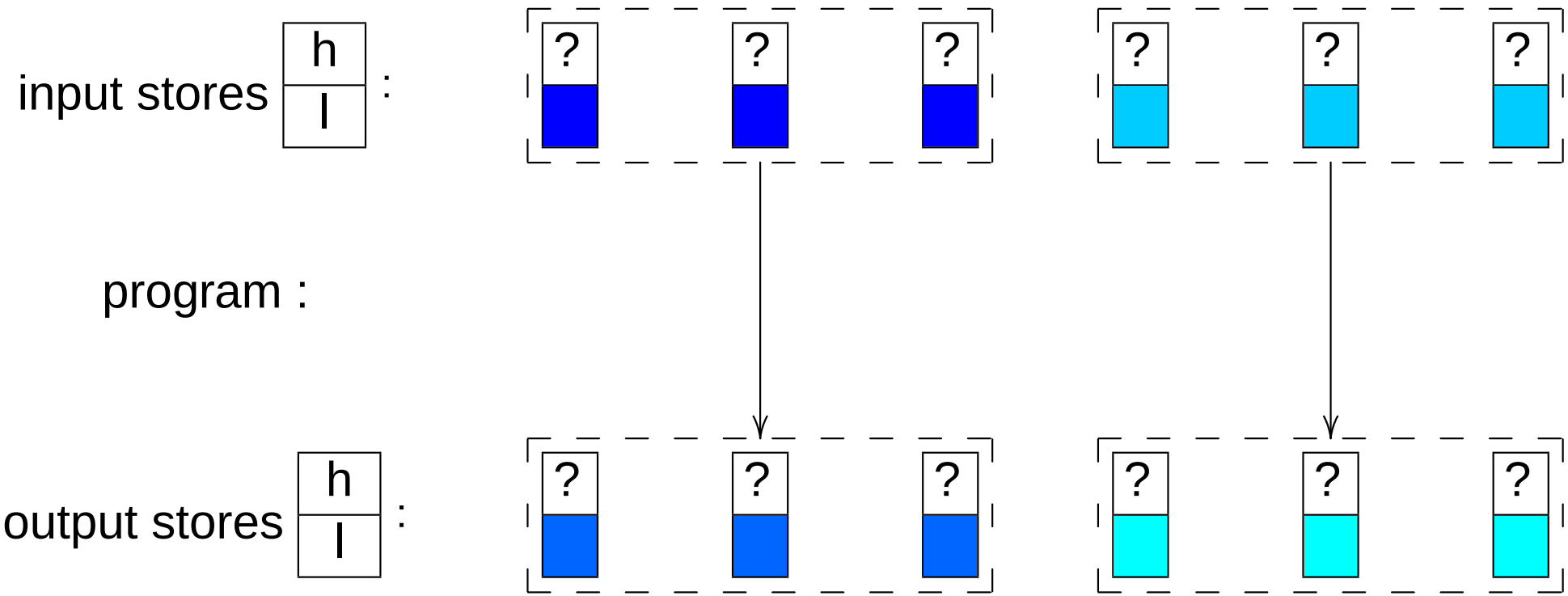

Non-Interference

Formalization of non-interference

Definition 1 (Non-Interference)

$$\forall s_1, s_2 \in S.\ s_1 =_{L_i} s_2 \Rightarrow [\![C]\!]s_1 =_{L_o} [\![C]\!]s_2$$

- Weaknesses for our purpose :
  - not fitted for monitoring (scope too large)
  - statically difficult to verify precisely

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Example 2 (Is it possible to deduce the value of h from the one of x ?)

```
x := 0 ; tmp := l ;
if test1( l ) then tmp := h else skip end ;
if test2( l ) then x := tmp else skip end ;
tmp := 0 ; print x ;
```

h : private input
l : public input
x : public output

Non-interfering execution

Main Goal : being able to detect executions respecting the confidentiality of secret data independently from other executions

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Definition 3 (Non-interfering execution)

let $s_1 \in S$, $\mathrm{NIExec}(C, s_1) \equiv \forall s_2.\ s_1 =_{L_i} s_2 \Rightarrow [\![C]\!]s_1 =_{L_o} [\![C]\!]s_2$

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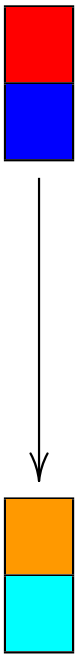

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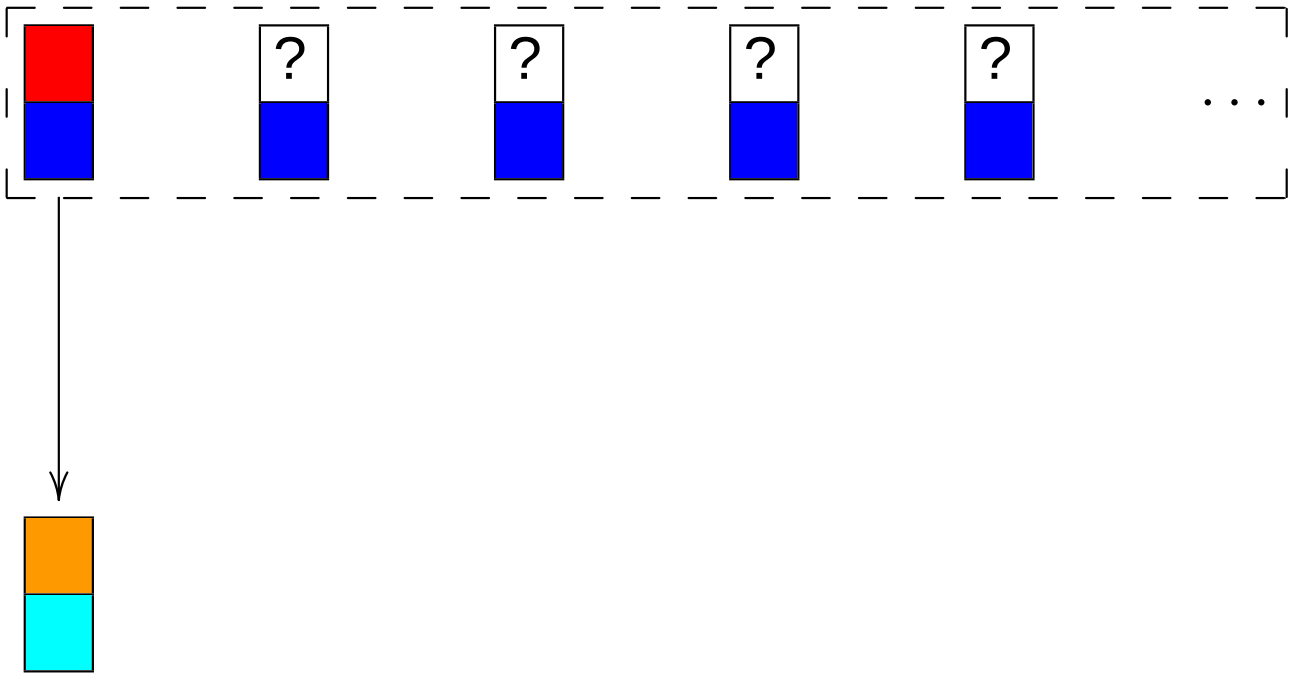

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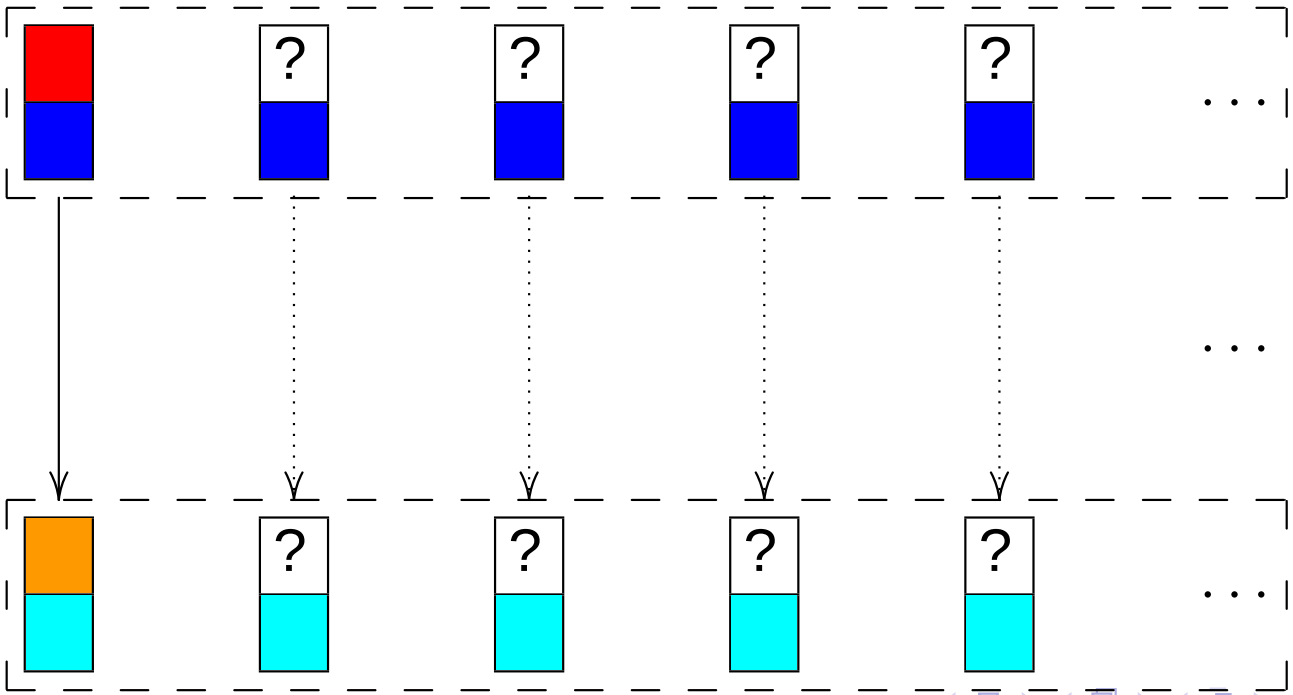

The approach

- instrumented semantics ($[\![C]\!] : \Sigma_{H_i} \times \Sigma_{L_i} \rightarrow \Sigma^{\mathbb{V}} \times \Sigma^{\mathbb{T}}$
  - value store : $\Sigma^{\mathbb{V}} = \Sigma_{H_o} \times \Sigma_{L_o}$
  - tag store : $\Sigma^{\mathbb{T}}$
- predicate ($\mathrm{Safe}() : \Sigma^{\mathbb{T}} \rightarrow \mathbb{B}$

Assumption 4 (Predicate Safe)

$$\forall s_1 \in S.\ \mathrm{Safe}([\![C]\!]^{\mathbb{T}} s_1) \Rightarrow \mathrm{NIExec}(C, s_1)$$

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Benefit : one execution may be sufficient to deduce a property of infinitely many executions

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- general idea :
  - data are tagged ($\bot \sqsubseteq \top$)
    - $\bot \Rightarrow$ data is constant for all σ_L-equivalent executions
    - $\top \Rightarrow$ value may be different

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if true$^{\bot}$
    then skip
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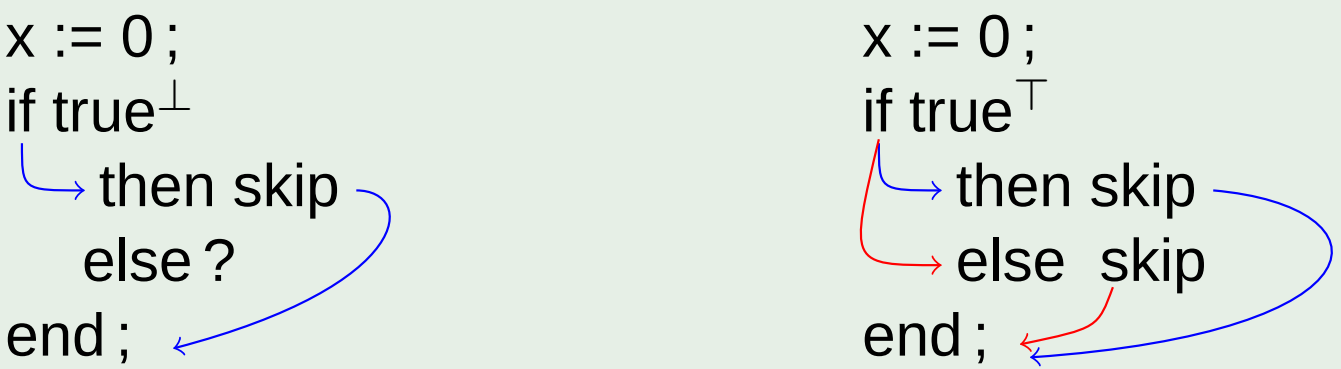

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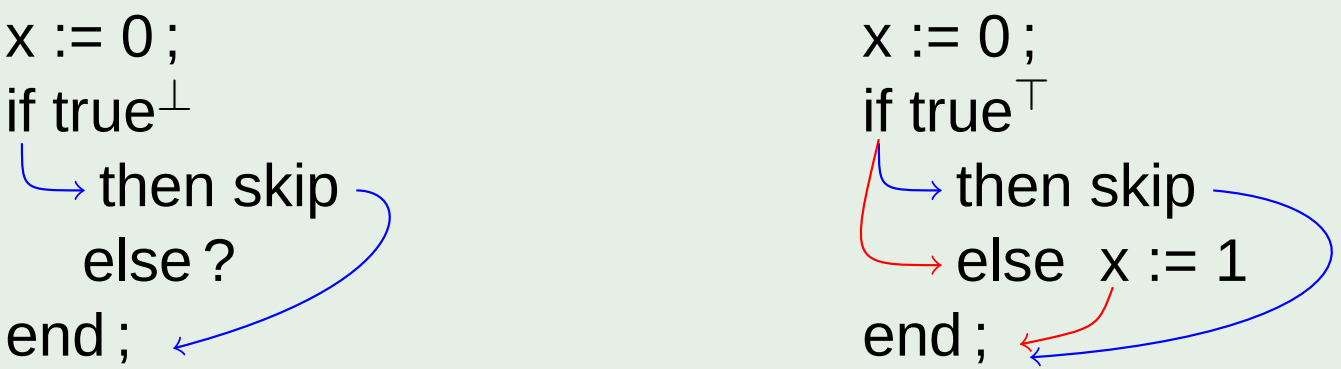

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  - $\mathrm{Safe}([\![C]\!]s_1)$ **iff** public outputs are tagged with $\bot$
- when branching on a condition which is :
  - $\bot$: execute the designated branch
  - $\top$: merge the result of the execution of the designated branch with an analysis that approximates all the other σ_L-equivalent executions that take the other branch

Example 6

x := 0 ;
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else ?

x := 0 ;
if true$^{\top}$
↳ then skip
↳ else x := 1

Properties of the semantics

Definition 7 (Predicate Safe)

For all tag store $\rho \in \Sigma^{\mathbb{T}} (= Var \rightarrow \{\bot, \top\})$, $\text{Safe}(\rho)$ iff :

$$\forall o \in \text{dom}(\Sigma_{L_o}),\ \rho(o) = \bot$$

Theorem 8

For any command C and $\sigma_1, \sigma_2 \in \Sigma_{H_i} \times \Sigma_{L_i}$, *such that :*

1. $[\![C]\!]^{\mathbb{V}}_{\sigma_2} \neq \bot$
2. $\text{Safe}([\![C]\!]^{\mathbb{T}}_{\sigma_1})$

if $\sigma_1 =_{L_i} \sigma_2$ *then* $[\![C]\!]^{\mathbb{V}}_{\sigma_1} =_{L_o} [\![C]\!]^{\mathbb{V}}_{\sigma_2}$

Example

Example 9

```
x := 0 ;
if l then
    if h then x := 1 else skip end
else skip end
```

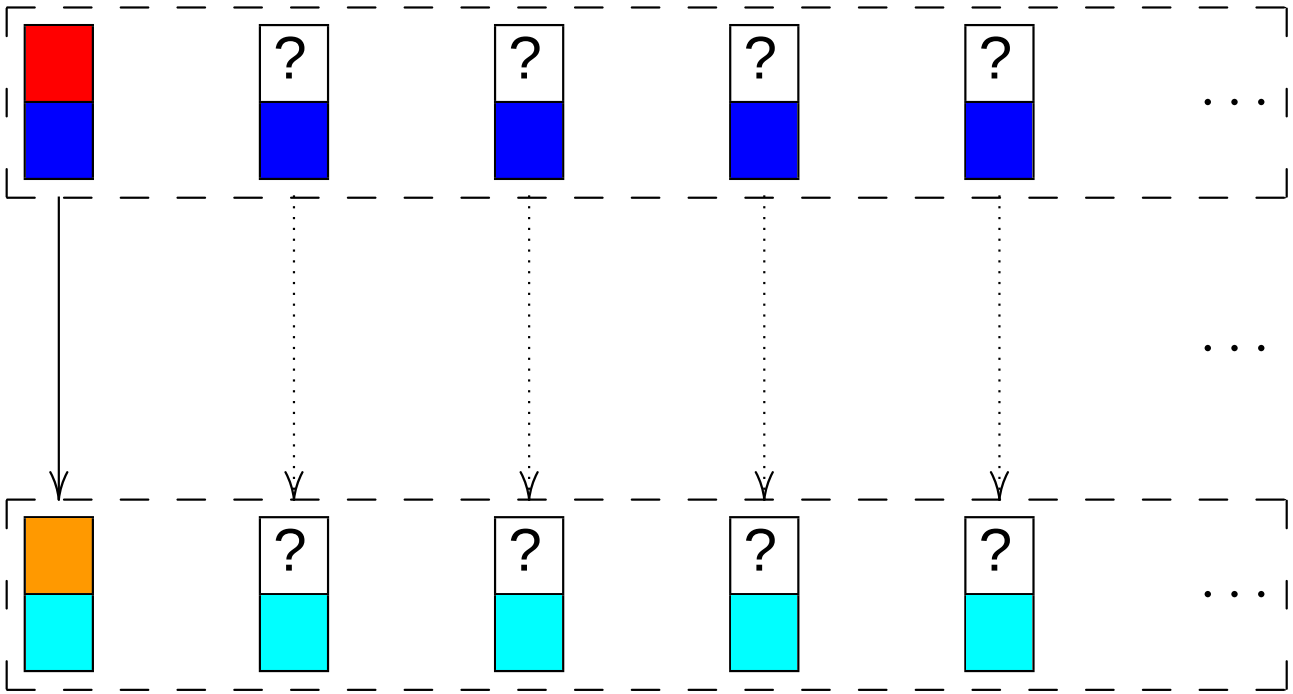
Final value of x

σ_h(h) \ σ_l(l)	True	False
True	1	0
False	0	0

Final tag of x

σ_h(h) \ σ_l(l)	True	False
True	$\top$	$\bot$
False	$\top$	$\bot$

Correcting Information Flows : Main Idea



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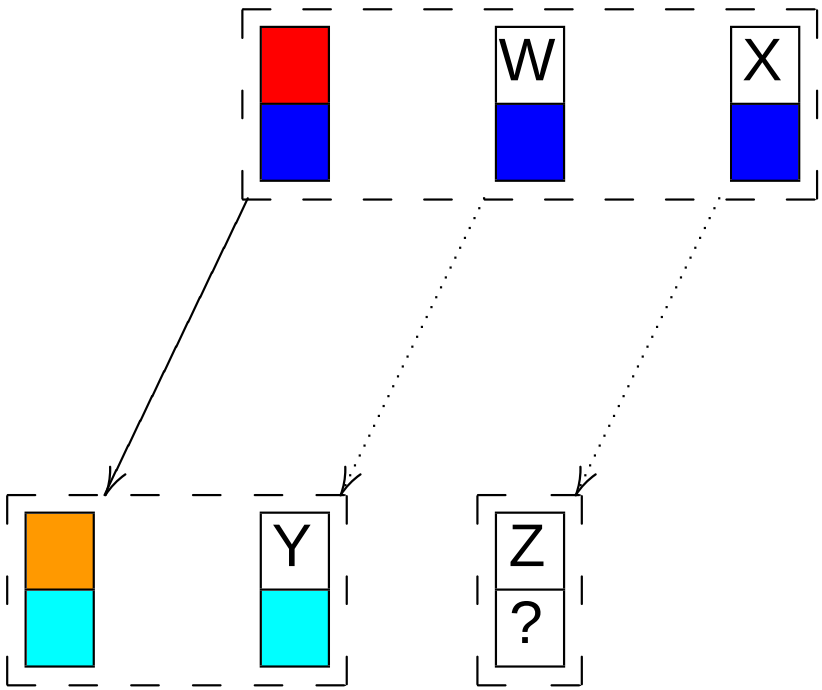

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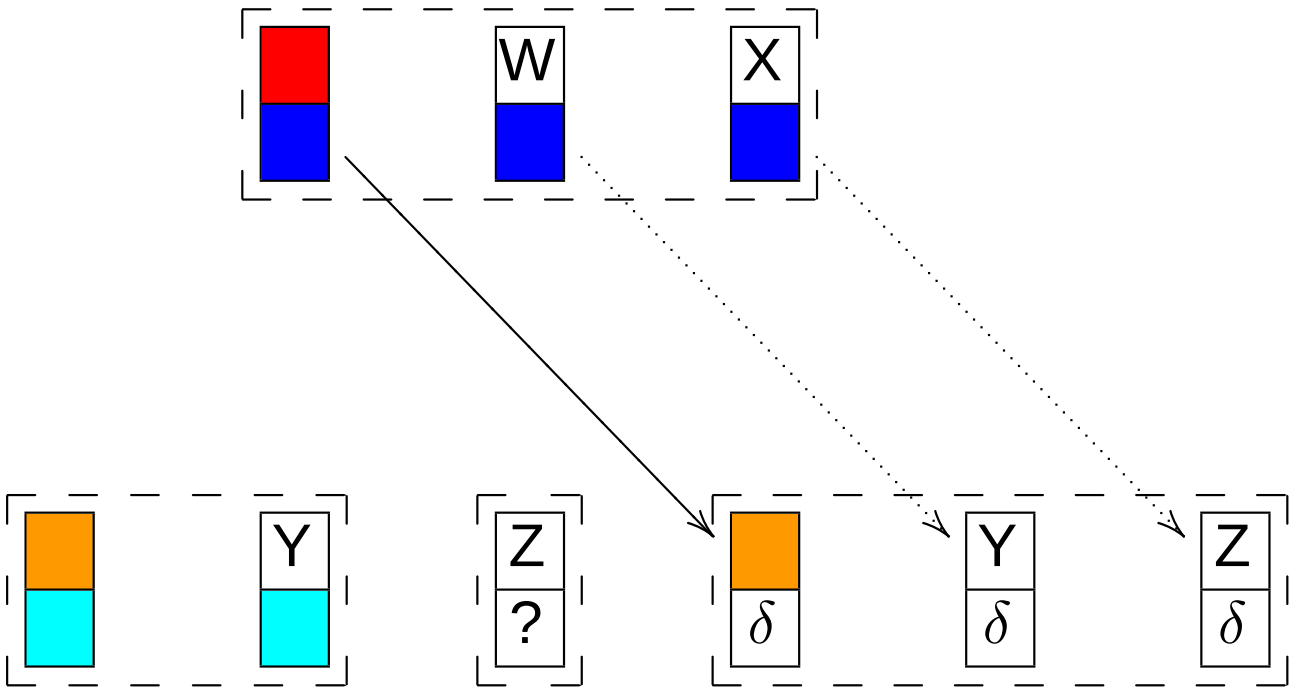

- set a default value (δ) for *unsafe* public outputs
- keep the value of private outputs and *safe* public outputs

Problem : correction may cause information leakage

Fact 10

$$\forall s_1, s_2 \in S.\ s_1 =_{L_i} s_2 \not\Rightarrow (\text{Safe}([\![C]\!]^{\mathbb{T}} s_1) \Leftrightarrow \text{Safe}([\![C]\!]^{\mathbb{T}} s_2))$$

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Example 11

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x := 0 ;
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else skip end
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Final value of x

σ_h(h) \ σ_l(l)	True	False
True	1	0
False	0	0

Final tag of x

σ_h(h) \ σ_l(l)	True	False
True	$\top$	$\bot$
False	$\top$	$\top$

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Final value of x

σ_h(h) \ σ_l(l)	True	False
True	δ	0
False	δ	δ

Final tag of x

σ_h(h) \ σ_l(l)	True	False
True	$\top$	$\bot$
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Work in progress

Theorem 12 (proof in progress)

For any command C and $\sigma_1, \sigma_2 \in \Sigma_{H_i} \times \Sigma_{L_i}$*, such that :*

1. $[\![C]\!]^{\mathbb{V}}_{\sigma_1} \neq \perp$ *and* $[\![C]\!]^{\mathbb{V}}_{\sigma_2} \neq \perp$

   if $\sigma_1 =_{L_i} \sigma_2$ *then* $[\![C]\!]^{\mathbb{T}}_{\sigma_1} =_{L_o} [\![C]\!]^{\mathbb{T}}_{\sigma_2}$

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   if $\sigma_1 =_{L_i} \sigma_2$ *then* $[\![C]\!]^{\mathbb{T}}_{\sigma_1} =_{L_o} [\![C]\!]^{\mathbb{T}}_{\sigma_2}$

Hypothesis 13 (proof in progress)

"$[\![\sigma; \rho \vdash C]\!]^{\sharp_{\mathcal{G}}}$ *and* $[\![C]\!]^{\mathbb{T}}_{\sigma}$ *compute the same tags"*

Related work

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Final word

- A non-interference definition with a reduced scope :
  - non-interfering execution
- A “smart” semantics
- A predicate for detecting non-interfering executions
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$\Rightarrow$ Possible to detect the “safe” behavior of a set of executions from only one of those executions ; and correct it if that is not the case.

Monitoring Information Flow

Dynamic tracking of the information flows at execution time

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