Parallel Functional Programming Lecture 3

Mary Sheeran

(with thanks to Simon Marlow and Koen Claessen for use of slides)

http://www.cse.chalmers.se/edu/course/pfp

Simon Marlow's landscape for parallel Haskell



Using par

You must

pass an unevaluated computation to par

ensure that its value will not be required by the enclosing computation for a while

ensure that the result is shared by the rest of the program

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tion for a while

Demands an operational understanding of program execution

Eval monad plus Strategies

Eval monad enables expressing ordering between instances of par and pseq

Strategies separate algorithm from parallelisation Provide useful higher level abstractions But still demand an understanding of laziness

A monad for deterministic parallelism

Simon Marlow Microsoft Research, Cambridge, U.K. simonmar@microsoft.com

Ry an Newton Intel, Hudson, MA, U.S.A ryan.r.newton@intel.com Simon Peyton Jones Microsoft Research, Cambridge, U.K. simonpj@microsoft.com

Abstract

We present a new programming model for deterministic parallel computation in a pure functional language. The model is monadic and has explicit granularity, but allows dynamic construction of dataflow networks that are scheduled at runtime, while remaining deterministic and pure. The implementation is based on monadic concurrency, which has until now only been used to simulate concurrency in functional languages, rather than to provide parallelism. We present the API with its semantics, and argue that parallel execution is deterministic. Furthermore, we present a complete workstealing scheduler implemented as a Haskell library, and we show that it performs at least as well as the existing parallel programming models in Haskell.

pure interface, while allowing a parallel implementation. We give a formal operational semantics for the new interface.

Our programming model is closely related to a number of othens; a detailed comparison can be found in Section 8. Probably the closest relative is pH (Nikhil 2001), a variant of Haskell that also has I-structures; the principal difference with our model is that the monad allows us to retain referential transparency, which was lost in pH with the introduction of I-structures. The target domain of our programming model is large-grained irregular parallelism, rather than tine-grained regular data parallelism (for the latter Data Parallel Haskell (Chakravarty et al. 2007) is more appropriate).

Our implementation is based on monadic concurrency (Scholz. 1995), a technique that has previously been used to good effect to simulate concurrency in a sequential functional language (Claessen

Builds on this idea

FUNCTIONAL PEARLS

A Poor Man's Concurrency Monad

Koen Claessen

Chalmers University of Technology email: koen@cs.chalmers.se

Abstract

Without adding any primitives to the language, we define a concurrency monad transformer in Haskell. This allows us to add a limited form of concurrency to any existing monad. The atomic actions of the new monad are lifted actions of the underlying monad. Some extra operations, such as fork, to initiate new processes, are provided. We discuss the implementation, and use some examples to illustrate the usefulness of this construction.

A Poor Man's Con currency Monad

Koen Claessen

without adding primitives,
we construct a way to lift
any monad into a limited,
but useful concurrent
setting.

Monads

· abstraction from computation

class Monad m where $(>>=):: ma \rightarrow (a \rightarrow mb) \rightarrow mb$ return:: $a \rightarrow ma$

· we use special notation

do a \leftarrow expr. \Rightarrow = $a \Rightarrow$ expr. \Rightarrow expr. \Rightarrow expr.

Writer Monad

- · can produce some output during computation
 - class Monad m => Writer m where write :: String -> m ()
- · An implementation could be:
- type Wa = (a, String)
- instance Monad W where $m \gg = k = let (a, s) = m$ (b, s') = kain (b, s++s')return a = (a, "")
- instance Writer W where write s = (1), s
- output :: Wa → String output (a, s) = s

Monad Transformer

· adds a feature to an existing monad

class Monad T t where

lift :: Monad m \Rightarrow m a \rightarrow (t m) a

- · examples:
 - . state
 - exception
 - · non determinism
- · "compose your own monad"- LEGO

Concurrency

- * interleaving actions
- * atomic actions are actions in some monad.
- * round robin scheduler
- * process has to consist of initial action + future.

Actions

```
We build actions from three different constructions:
atomic actions, forked actions and no-action.

data Action m

= Atom (m (Action m))

I Fork (Action m)

(Action m)
```

1 Stop

We use constructors:

- general & simple
- expressive See also Scholz [2].

Continuation

specifies what to do with result.

type C a =

(a -> Action) -> Action

parametrize over a monad:

type C m $\alpha =$ $(a \rightarrow Action m) \rightarrow Action m$

for some type Action that stands for a process.

It is a monad:

instance Monod (C m) where $m \gg = k = |cont \rightarrow m|$ $(|a \rightarrow k| a cont)$ return $a = |cont \rightarrow cont| a$

Useful Operations

some functions that make life easier.

· Turn a C ma into an Action:

action :: $C m a \rightarrow Action m$ action $c = c (la \rightarrow Stop)$

· Turn an ma into an (atomic) Cma:

atom :: $m a \rightarrow C m a$ atom $m = \setminus cont \rightarrow$ Atom (do $a \leftarrow m$ return (cont a))

· End a process (the empty process):

stop :: C m a stop = \cont → Stop

Fork

Some operations on fork:

· 'Imperative' fork:

fork :: $C m a \rightarrow C m ()$ fork $c = | cont \rightarrow Fork$ (action c) (cont ())

· 'Alegebraic' or symmetrical fork:

par:: $Cma \rightarrow Cma \rightarrow Cma$ par c1 c2 = 1 cont \rightarrow Fork (c1 cont) (c2 cont)

Running a C

Ideally, we would like a function

run:: Cma -> ma
this is "not" possible, due
to typing problems.
We will define a function

This means we'll only get the side-effects of the computation.

Round Robin

simple scheduler.

```
round :: [Action m] -> m ()
round [] = return ()
round (p:ps) =
  case p of
  -Atom ma ->
      do p' + ma
          round (ps++ [p'])
  -fork p1 p2 ->
      round (ps++[p1,p2])
 - Stop →
     round ps
```

Using C

· We can use the scheduler to define:

run :: C m a -> m ()
run c = round [action c]

· We can construct C's with atom, fork, stop, and can run them using run.

C is a Monad Transformer

C can be made an instance of Monad Trans.

instance Monod Trans C where lift = atom

All lifted actions become atomic actions in the new setting.

Example 1: Writer

We lift every uniter monad:

instance Writer m =>

Writer (C m) where

write s = lift (write s)

Every unite action is now atomic.

example :: CW()

example = do urite "hej!"

fork (loop "apa")

fork (loop "hund")

where

loop s = do write s loop s

will result in:

hej! apa.hund apa.hund apa....

Example 2: Another lifting

We can lift writers in a.

different way:

instance Writer m =>

Writer (c m) where

write "" = return ()

write (c:s) = do lift (write [c])

write s

a write action is now split up in atomic actions for each character.

hej! ahpuanad phaupn

the Par Monad

Our goal with this work is to find a parallel programming model that is expressive enough to subsume Strategies, robust enough to reliably express parallelism, and accessible enough that non-expert programmers can achieve parallelism with little effort.

The Par Monad

```
Par is a monad for
                                     parallel computation
data Par
instance Monad Par
                                        Parallel computations
                                        are pure (and hence
runPar :: Par a -> a
                                           deterministic)
fork :: Par () -> Par ()
                                          forking is explicit
data IVar
                                     results are communicated
new :: Par (IVar a)
                                         through IVars
get :: IVar a -> Par a
put :: NFData a \Rightarrow IVar a \Rightarrow a \Rightarrow Par
```

IVar

a write-once mutable reference cell

supports two operations: put and get

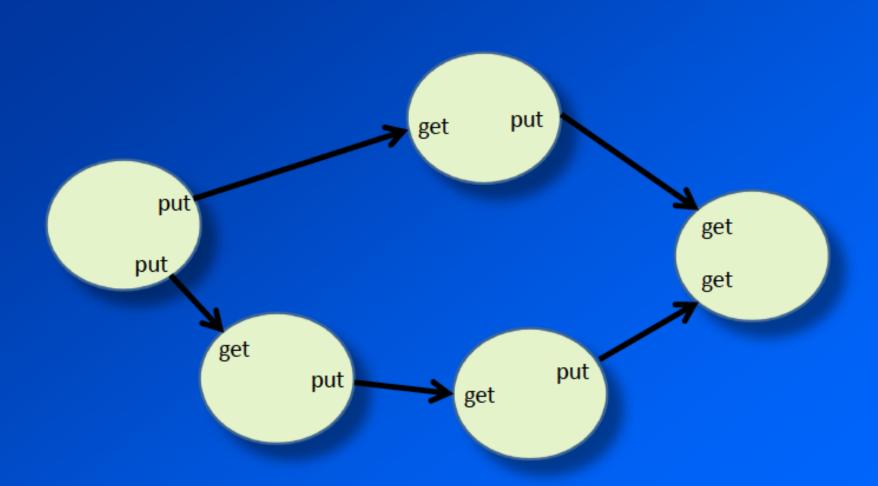
put assigns a value to the IVar, and may only be executed once per Ivar Subsequent puts are an error

get waits until the IVar has been assigned a value, and then returns the value

the Par Monad

```
Implemented as a Haskell library
     surprisingly little code!
     includes a work stealing scheduler
     You get to roll your own schedulers!
Programmer has more control than with Strategies
     => less error prone?
Good performance (comparable to Strategies)
     particularly if granularity is not too small
```

Par expresses dynamic dataflow



```
spawn :: NFData a => Par a -> Par (IVar a)
spawn p = do
   i <- new
   fork (do x <- p; put i x)
   return i</pre>
```

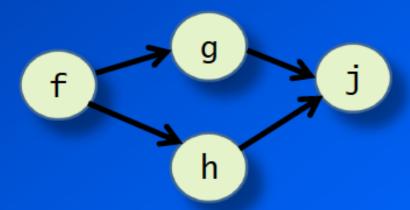
```
parMapM :: NFData b => (a -> Par b) -> [a] -> Par [b]
parMapM f as = do
   ibs <- mapM (spawn . f) as
   mapM get ibs</pre>
```

Dataflow

Consider typechecking a set of (non-recursive)
 bindings: f _

```
f = ...
g = ... f ...
h = ... f ...
j = ... g ... h ...
```

treat this as a dataflow graph:



```
parInfer :: [(Var,Expr)] -> [(Var,Type)]

parInfer bindings = runPar $ do
  let binders = map fst bindings
  ivars <- replicateM (length binders) new
  let env = Map.fromList (zip binders ivars)
  mapM_ (fork . infer env) bindings
  types <- mapM_ get ivars
  return (zip binders types)</pre>
```

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```

Create nodes and edges and let the scheduler do the work

No dependency analysis required!

Maximum parallelism for little programmer effort

Dynamic parallelism

Very nice ©

Divide and Conquer skeleton

```
divCong :: NFData sol => (prob -> Bool) -- indivisible?
        -> (prob -> [prob]) -- split into subproblems
        -> ([sol] -> sol) -- join solutions
        -> (prob -> sol) -- solve a subproblem
        -> (prob -> sol)
divConq indiv split join f prob
   = runPar $ go prob
      where
        go prob
             indiv prob = return (f prob)
            otherwise = do
               sols <- parMapM go (split prob)</pre>
               return (join sols)
```

Another D&C skeleton

```
divCong :: NFData sol
            => (prob -> Bool) -- indivisible?
            -> (prob -> (prob,prob)) -- split into subproblems
            -> (sol -> sol -> sol) -- join solutions
            -> (prob -> sol) -- solve a subproblem
            -> (prob -> sol)
divConq indiv split join f prob
 = runPar $ go prob
     where
       go prob
          | indiv prob = return (f prob)
          | otherwise = do
             let (a,b) = split prob
             i <- spawn $ qo a
             j <- spawn $ go b
             a <- get i
             b <- get i
             return (join a b)
```

parallel sort

```
parsort :: Int -> [Int] -> [Int]
parsort thresh xs
  = divConq indiv divide merge (List.sort . snd) (thresh,xs)
    where
    indiv (n,xs) = n == 0

    divide (n,xs) = ((n-1, as), (n-1, bs))
        where (as,bs) = halve xs

halve xs = splitAt n2 xs
    where
    n2 = div (length xs)
```

Implementation

- Starting point: A Poor Man's Concurrency Monad (Claessen JFP'99)
- PMC was used to simulate concurrency in a sequential Haskell implementation. We are using it as a way to implement very lightweight nonpreemptive threads, with a parallel scheduler.
- Following PMC, the implementation is divided into two:
 - Par computations produce a lazy Trace
 - A scheduler consumes the Traces, and switches between multiple threads

Traces

A "thread" produces a lazy stream of operations:

The Par monad

Par is a CPS monad:

```
newtype Par a = Par {
    runCont :: (a -> Trace) -> Trace
}
instance Monad Par where
    return a = Par $ \c -> c a
    m >>= k = Par $ \c -> runCont m $
    \a -> runCont (k a) c
```

Operations

```
fork :: Par () -> Par ()
fork p = Par  \c ->
        Fork (runCont p (\backslash -> Done)) (c ())
new :: Par (IVar a)
new = Par \c -> New c
get :: IVar a -> Par a
get v = Par  c -> Get v c
put :: NFData a => IVar a -> a -> Par ()
```

e.g.

This code:

```
do
x <- new
fork (put x 3)
r <- get x
return (r+1)
```

will produce a trace like this:

```
New (\x ->
Fork (Put x 3 $ Done)
(Get x (\r ->
c (r + 1))))
```

The scheduler

First, a sequential scheduler.

The currently running thread

```
sched :: SchedState -> Trace -> IO ()
```

type SchedState = [Trace]

The work pool, "runnable threads" Why IO?
Because we're going
to extend it to be a
parallel scheduler in a
moment.

Slide by Simon Marlow

Representation of IVar

```
newtype IVar a = IVar (IORef (IVarContents a))
data IVarContents a = Full a | Blocked [a -> Trace]
```

set of threads blocked in **get**

Fork and Done

sched state Done = reschedule state

```
reschedule :: SchedState -> IO ()
reschedule [] = return ()
reschedule (t:ts) = sched ts t
```

```
sched state (Fork child parent) =
  sched (child:state) parent
```

New and Get

```
sched state (New f) = do
r <- newIORef (Blocked [])
sched state (f (IVar r))</pre>
```

```
sched state (Get (IVar v) c) = do
  e <- readIORef v
  case e of
  Full a -> sched state (c a)
  Blocked cs -> do
    writeIORef v (Blocked (c:cs))
  reschedule state
```

Put

```
sched state (Put (IVar v) a t) = do
  cs <- modifyIORef v $ \e -> case e of
        case e of
        Full _ -> error "multiple put"
        Blocked cs -> (Full a, cs)
  let state' = map ($ a) cs ++ state
  sched state' t
```

Wake up all the blocked threads, add them to the work pool

modifyIORef :: IORef a -> (a -> (a,b)) -> IO b

Finally... runPar

```
rref is an IVar to hold
                                                 the return value
runPar :: Par a -> a
runPar x = unsafePerformIO $ do
   rref <- newIORef (Blocked [])</pre>
                                                    the "main thread"
                                                  stores the result in rref
   sched [] $
       runCont (x >>= put_ (IVar rref))
                 (const Done)
                                             if the result is empty,
   r <- readIORef rref
                                             the main thread must
   case r of——
                                               have deadlocked
      Full a -> return a
              -> error "no result"
```

that's the complete sequential scheduler

A real parallel scheduler

- We will create one scheduler thread per core
- Each scheduler has a local work pool
 - when a scheduler runs out of work, it tries to steal from the other work pools
- The new state:

New/Get/Put

- New is the same
- Mechanical changes to Get/Put:
 - use atomicModifyIORef to operate on IVars
 - use atomicModifyIORef to modify the work pool (now an IORef [Trace], was previously [Trace]).

reschedule

Here's where we go stealing

stealing

```
steal :: SchedState -> IO ()
steal state@SchedState{ scheds, no=me } = go scheds
 where
   go (x:xs)
      \mid no x == me = go xs
      otherwise = do
         r <- atomicModifyIORef (workpool x) $ \ ts ->
                 case ts of
                    [] -> ([], Nothing)
                    (x:xs) \rightarrow (xs, Just x)
         case r of
           Just t -> sched state t
           Nothing -> go xs
    go [] = do
      -- failed to steal anything; add ourself to the
      -- idle queue and wait to be woken up
```

runPar

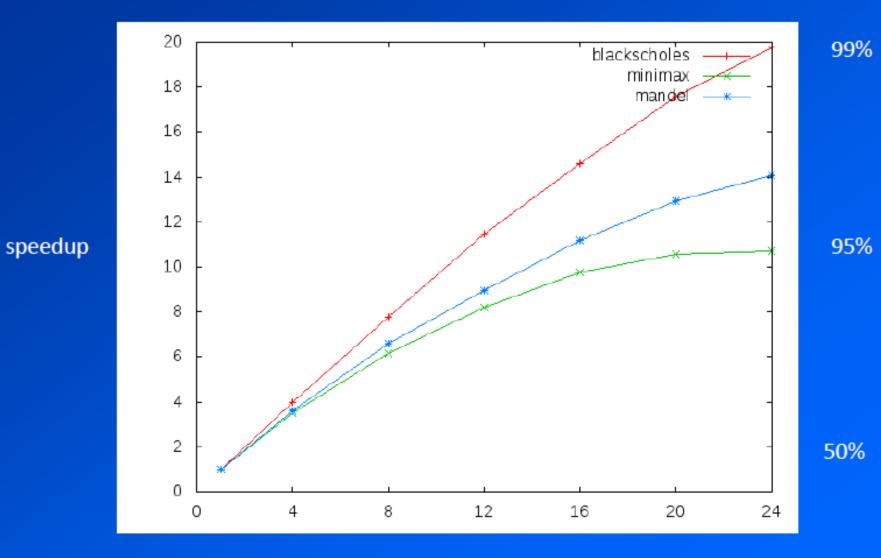
```
runPar :: Par a -> a
runPar x = unsafePerformIO \$ do
   let states = ...
   main_cpu <- getCurrentCPU
   m <- newEmptyMVar</pre>
   forM_ (zip [0..] states) $ (cpu, state) ->
     forkOnIO cpu $
                                                 The "main thread"
       if (cpu /= main_cpu) -
                                                 runs on the current.
          then reschedule state
                                                 CPU, all other CPUs
          else do
                                                   run workers
                rref <- newIORef Empty</pre>
                sched state $
                    runCont (x >>= put_ (IVar rref))
                             (const Done)
                readIORef rref >>= putMVar m
                                                        An MVar
   r <- takeMVar m
                                                    communicates the
   case r of Full a -> return a
```

_ -> error "no result"

Slide by Simon Marlow

result back to the caller of runPar

Results



cores

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Modularity

Key property of Strategies is modularity

```
parMap f xs = map f xs `using` parList rwhnf
```

- Relies on lazy evaluation
 - fragile
 - not always convenient to build a lazy data structure
- Par takes a different approach to modularity:
 - the Par monad is for coordination only
 - the application code is written separately as pure Haskell functions
 - The "parallelism guru" writes the coordination code
 - Par performance is not critical, as long as the grain size is not too small

Par monad compared to Strategies

Separation of function and parallelisation done differently

Eval monad and Strategies are advisory

Par monad does not support speculative parallelism as Stategies do

Par monad supports stream processing pipelines well

Note: Par monad and Strategies can be combined...

Par Monad easier to use than par?

fork creates one parallel task

Dependencies between tasks represented by Ivars

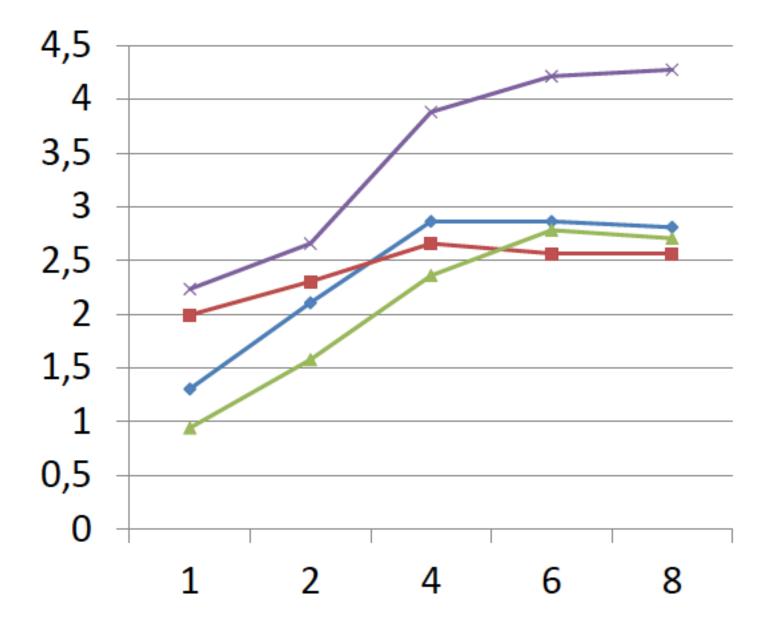
No need to reason about laziness

put is hyperstrict by default

Final suggestion in Par Monad paper is that maybe par is suitable for automatic parallelisation

Sorting speedups

For those curious about the Sort Challenge (from 2012), the results are presented in this gzipped file, including slides



In the meantime

Do exercise 1 (not graded)

Read papers and PCPH

Continue working on Lab A (due midnight April 6)

Note Nick's office hours

(room 5461, wed 13-14 and fri 13-14)

Extra office hours today from 15.00

Use him! He is your best resource.