The SAC Story: From Functional Programming with Curly Brackets to High Performance Computing

**Clemens Grelck** 

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MSc Course Parallel Functional Programming Chalmers University of Technology Göteborg, Sweden May 26, 2015



SAC: Functional Array Programming with Curly Brackets

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SAC: High Productivity meets High Performance

### Functional Programming with Curly Brackets ?

- Design Rationale of SAC
- Data-Parallel Functional Array Programming in SAC
- Abstraction and Composition
- Case Study: Generic Convolution
- **Compilation Challenge**
- Does it Work ? Some Experimental Evaluation
- Summary and Conclusion



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What the heck....



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What the heck....

Imagine...

(you want to design a new functional language)



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- (you want to design a new functional language)
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- you want to exploit functional semantics for compiler optimisation and parallelisation



### What the heck....

### Imagine...

- (you want to design a new functional language)
- you want to seduce "curly bracket" programmers
- you want people on non-functional programming conferences to "understand" your code
- you want to exploit functional semantics for compiler optimisation and parallelisation
- you are pragmatic



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#### ...then your Factorial function could look like this:

```
int fac( int n)
{
    if (n <= 1) f = 1;
    else f = n * fac(n-1);
    return f;
}</pre>
```



### ...then your Factorial function could look like this:

```
int fac( int n)
{
    if (n <= 1) f = 1;
    else f = n * fac(n-1);
    return f;
}</pre>
```

#### ...or like this:

```
int fac( int n)
{
    f = 1;
    while (n > 1) {
        f = f * n;
        n = n - 1;
    }
    return f;
}
```



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What is Functional Programming ?

#### **Execution Model:**

#### Imperative programming:

Sequence of instructions that step-wise manipulate the program state



#### **Functional programming:**

Context-free substitution of expressions until fixed point is reached



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```
{
    ...
    a = 5;
    b = 7;
    a = a + b;
    return a;
}
```

```
let a = 5
in let b = 7
in let a = a + b
in a
```



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```
ł
  . . .
  a = 5;
  b = 7;
  a = a + b;
  return a;
}
```

```
. . .
let a = 5
and b = 7
in let a = a + b
in a
```



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```
-
```

### Functional pseudo code:

```
int fac( int n)
{
    if (n>1) {
        r = fac( n-1);
        f = n * r;
    }
    else {
        f = 1;
    }
    return f;
}
```

```
fun fac n =
    if n>1
    then let r = fac (n-1)
        in let f = n * r
        in f
    else let val f = 1
        in f
```



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```
SAC:
int fac( int n)
ł
  f = 1;
  while (n>1) {
    f = f * n;
    n = n - 1;
  }
  return f;
}
```

### Functional pseudo code:

```
fun fac n =
  let f = 1 in
  let rec fac_while f n =
    if n>1
    then let f = f * n
        in let n = n - 1
        in fac_while f n
    else f
  in
  let f = fac_while f n
  in f
```

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### **Execution model:**

- NOT: Step-wise modification of state
- BUT: Context-free substitution of expressions



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### Role of variables:

- NOT: Names of a memory locations
- BUT: Placeholders for values



### Execution model:

- NOT: Step-wise modification of state
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### Role of variables:

- NOT: Names of a memory locations
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### **Role of functions:**

- NOT: Subroutines with side-effects
- BUT: Mappings of argument values to result values



Interesting but ....



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Interesting but ....

- ... why should I use SAC ?
- ... is there anything SAC can do better ?



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#### Hardware in the many-core era is a zoo:

- Diverse low-level programming models
- Each requires expert knowledge
- Heterogeneous combinations of the above ?



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Program what to compute, not exactly how



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### SAC: Genericity through abstraction

- Program what to compute, not exactly how
- Leave execution organisation to compiler and runtime system



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- Leave execution organisation to compiler and runtime system
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- Let programs remain architecture-agnostic



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- Compile one source to diverse target hardware



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- Let programs remain architecture-agnostic
- Compile one source to diverse target hardware
- Pursue data-parallel approach



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## What Does Data Parallel Really Mean ?

## **Factorial recursive:**

```
int fac( int n)
{
    if (n <= 1) f = 1;
    else f = n * fac(n-1);
    return f;
}</pre>
```

### **Factorial iterative:**

```
int fac( int n)
{
    f = 1;
    while (n > 1) {
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    }
    return f;
}
```



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```

#### Factorial data parallel:

```
int fac( int n)
{
    return prod( 1 + iota( n));
}
```

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### **Factorial iterative:**

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    }
    return f;
}
```


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prod( 1+iota(n))



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$$\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$$
 dim: 2  
shape: [3,3]  
data: [1,2,3,4,5,6,7,8,9]



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$$\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix} \qquad \begin{array}{c} \text{dim:} & 2 \\ \text{shape:} & [3,3] \\ \text{data:} & [1,2,3,4,5,6,7,8,9] \\ \\ \hline \\ \hline \\ 2 & 3 \\ \hline \\ 3 \\ \hline \\ 4 & -1 \\ \hline \\ 1 & -1 \\ \hline 1 & -1 \\ \hline \\ 1 & -1 \\ \hline 1 & -1 \\ \hline \\ 1 & -1 \\ \hline 1 &$$



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$$\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix} \quad \begin{array}{l} \dim: & 2 \\ \text{shape:} & [3,3] \\ \text{data:} & [1,2,3,4,5,6,7,8,9] \\ \\ \hline \\ 1 & 2 & 3 \\ \hline \\ 4 & 5 & 6 \\ \hline \\ 4 & 5 & 6 \\ \hline \\ 4 & 5 & 6 \\ \hline \\ 1 & 2 & 3 \\ \hline \\ 4 & 5 & 6 \\ \hline \\ 1 & 2 & 3 \\ \hline \\ 4 & 5 & 6 \\ \hline \\ 1 & 2 & 3 \\ \hline \\ 4 & 5 & 6 \\ \hline \\ 1 & 2 & 3 \\ \hline \\ 3 & \text{shape:} & [2,2,3] \\ \text{data:} & [1,2,3,4,5,6,7,8,9,10,11,12] \\ \hline \\ 1 & 1 \\ \text{shape:} & [6] \\ \text{data:} & [1,2,3,4,5,6] \\ \hline \\ \end{array}$$



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Defining a vector:

vec = [1, 2, 3, 4, 5, 6];



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Defining a vector:

vec = [1,2,3,4,5,6];

• Defining a higher-dimensional array:

```
mat = [vec,vec];
mat = reshape( [3,2], vec);
```



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- Querying for the rank of an array:

rank = dim( mat);  $\rightarrow 2$ 



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Defining a vector:

vec = [1,2,3,4,5,6];

Defining a higher-dimensional array:

mat = [vec,vec]; mat = reshape( [3,2], vec);

Querying for the shape of an array:

 $shp = shape(mat); \rightarrow [3,2]$ 

Querying for the rank of an array:

rank = dim( mat);  $\rightarrow$  2

Selecting elements:

$$x = sel([4], vec); \rightarrow 5$$
  

$$y = sel([2,1], mat); \rightarrow 6$$
  

$$x = vec[[4]]; \rightarrow 5$$
  

$$y = mat[[2,1]]; \rightarrow 6$$



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With-Loops: Versatile Array Comprehensions

- Multidimensional array comprehensions
- Mapping from index domain into value domain

[0,0]	[0,1]	[0,2]	[0,3]
[1,0]	[1,1]	[1,2]	[1,3]
[2,0]	[2,1]	[2,2]	[2,3]
[3,0]	[3,1]	[3,2]	[3,3]
[4,0]	[4,1]	[4,2]	[4,3]

def	def	def	def
def	e([1,1])	e([1,2])	e([1,3])
def	e([2,1])	e([2,2])	e([2,3])
def	e([3,1])	e([3,2])	e([3,3])
def	def	def	def

index domain

value domain



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With-Loops: Modarray Variant

$$A = with \{ ([1,1] \le iv \le [3,4]) : e(iv); \}: modarray(B); \}$$
  
$$A = \begin{pmatrix} B[[0,0]] & B[[0,1]] & B[[0,2]] & B[[0,3]] & B[[0,4]] \\ B[[1,0]] & e([1,1]) & e([1,2]) & e([1,3]) & B[[1,4]] \\ B[[2,0]] & e([2,1]) & e([2,2]) & e([2,3]) & B[[2,4]] \\ B[[3,0]] & B[[3,1]] & B[[3,2]] & B[[3,3]] & B[[3,4]] \end{pmatrix}$$

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With-Loops: Fold Variant

 $\begin{array}{rcl} \mathsf{A} & = & \textit{neutr} & \oplus & e([1,1]) & \oplus & e([1,2]) & \oplus & e([1,3]) \\ & \oplus & e([2,1]) & \oplus & e([2,2]) & \oplus & e([2,3]) \end{array}$ 

(  $\oplus$  denotes associative, commutative binary function. )



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## Principle of Abstraction

#### Element-wise subtraction of arrays:

```
int[20,20] (-) (int[20,20] A, int[20,20] B)
{
  res = with {
        ([0,0] <= iv < [20,20]) : A[iv] - B[iv];
        }: genarray( [20,20], 0);
  return( res);
}</pre>
```



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## Principle of Abstraction

```
int [20,20] (-) (int [20,20] A, int [20,20] B)
Ł
  res = with {
          ([0,0] <= iv < [20,20]) : A[iv] - B[iv];
        }: genarray( [20,20], 0);
  return( res);
}
               Shape-generic code
int[.,.] (-) (int[.,.] A, int[.,.] B)
ł
  shp = min( shape(A), shape(B));
  res = with {
          ([0,0] \le iv \le shp) : A[iv] - B[iv];
        }: genarray( shp, 0);
  return( res);
}
```

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## Principle of Abstraction

```
int[.,.] (-) (int[.,.] A, int[.,.] B)
ſ
 shp = min( shape(A), shape(B));
 res = with {
          ([0,0] <= iv < shp) : A[iv] - B[iv];
       }: genarray( shp, 0);
 return( res);
}
               Rank-generic code
int[*] (-) (int[*] A. int[*] B)
ł
 shp = min( shape(A), shape(B));
 res = with {
          (0*shp \le iv \le shp) : A[iv] - B[iv];
       }: genarray( shp, 0);
 return( res);
}
                                       (日本)
```

# Shapely Array Type Hierarchy With Subtyping



- AUD : Array of Unknown Dimension
- AKD : Array of Known Dimension
- AKS : Array of Known Shape



## Function Overloading Example:

int[20,20]	(-)	(int[20,20] A,	int[20,20] B) {}
int[.,.]	(-)	(int[.,.] A,	<pre>int[.,.] B) {}</pre>
int[*]	(-)	(int[*] A,	int[*] B) {}

#### Features:

- Multiple function definitions with same name, but
  - different numbers of arguments
  - different base types
  - different shapely types
- No restriction on function semantics
- Argument subtyping must be monotonous
- Function dispatch:
  - as static as possible
  - as dynamic as needed



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# Principle of Composition

#### **Characteristics:**

- Step-wise composition of functions
- from previously defined functions
- or basic building blocks (with-loop defined)

### Example: convergence test

```
bool
is_convergent (double[*] new, double[*] old, double eps)
{
  return( all( abs( new - old) < eps));
}</pre>
```



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# Principle of Composition

#### Example: convergence test

```
bool
is_convergent (double[*] new, double[*] old, double eps)
{
   return( all( abs( new - old) < eps));
}</pre>
```

#### **Advantages:**

- Rapid prototyping
- High confidence in correctness
- Good readability of code



**Convergence Test:** 

is\_convergent( [1,2,3,8], [3,2,1,4], 3 )



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### **Convergence Test:**



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### **Convergence Test:**

is\_convergent( [1,2,3,8], [3,2,1,4], 3 )
all( abs( [1,2,3,8] - [3,2,1,4]) < 3 )
all( abs( [-2,0,2,4]) < 3 )</pre>



### **Convergence Test:**

is\_convergent( [1,2,3,8], [3,2,1,4], 3 )
all( abs( [1,2,3,8] - [3,2,1,4]) < 3 )
all( abs( [-2,0,2,4]) < 3 )
all( abs( [-2,0,2,4]) < 3 )
all( [2,0,2,4] < 3 )</pre>



### **Convergence Test:**

is\_convergent( [1,2,3,8], [3,2,1,4], 3) all( abs( [1,2,3,8] - [3,2,1,4]) < 3 ) all( abs( [-2,0,2,4]) < 3 ) all([2,0,2,4] < 3)all( [true, true, true, false])



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### **Convergence Test:**





# Shape-Generic Programming

2-dimensional convergence test:

is\_convergent(
$$\begin{pmatrix} 1 & 2 \\ 3 & 8 \end{pmatrix}$$
,  $\begin{pmatrix} 3 & 2 \\ 1 & 7 \end{pmatrix}$ , 3)



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# Shape-Generic Programming

2-dimensional convergence test:

is\_convergent(
$$\begin{pmatrix} 1 & 2 \\ 3 & 8 \end{pmatrix}$$
,  $\begin{pmatrix} 3 & 2 \\ 1 & 7 \end{pmatrix}$ , 3)

#### **3-dimensional convergence test:**

$$is\_convergent(\begin{pmatrix} \begin{pmatrix} 1 & 2 \\ 3 & 8 \\ & 6 & 7 \\ 2 & 8 \end{pmatrix}), \begin{pmatrix} \begin{pmatrix} 2 & 1 \\ 0 & 8 \\ & 1 & 1 \\ & 3 & 7 \end{pmatrix}), 3)$$



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- NO large collection of built-in operations
  - Simplified compiler design



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- ► INSTEAD: library of array operations
  - Improved maintainability
  - Improved extensibility



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- INSTEAD: library of array operations
  - Improved maintainability
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- Composition of building blocks
  - Rapid prototyping
  - High confidence in correctness
  - Good readability of code
- General intermediate representation for array operations
  - Basis for code optimization
  - Basis for implicit parallelization



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# Case Study: Convolution

### **Algorithmic principle:**

Compute weighted sums of neighbouring elements



Periodic boundary conditions (1-dimensional):





Convolution Step in SAC

### **1-dimensional:**

```
double[.] convolution_step (double[.] A)
ſ
  R = with {
         . . .
      }
  return R;
}
```



A B + A B +

Sac

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# Convolution Step in SAC

### **1-dimensional:**

```
double[.] convolution_step (double[.] A)
{
    R = A + rotate( 1, A) + rotate( -1, A);
    return R / 3.0;
}
```



A B M A B M

# Convolution Step in SAC

### 1-dimensional:

```
double[.] convolution_step (double[.] A)
{
    R = A + rotate( 1, A) + rotate( -1, A);
    return R / 3.0;
}
```

#### **N-dimensional:**

```
double[*] convolution_step (double[*] A)
{
    R = A;
    for (i=0; i<dim(A); i++) {
        R = R + rotate( i, 1, A) + rotate( i, -1, A);
    }
    return R / tod( 2 * dim(A) + 1);
}</pre>
```



SAC: Functional Array Programming with Curly Brackets

#### Fixed number of iterations:

```
double[*] convolution (double[*] A, int iter)
{
  for (i=0; i<iter; i++) {
    A = convolution_step( A);
  }
  return A;
}</pre>
```



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# Convolution in SAC

#### Variable number of iterations with convergence check:

```
double[*] convolution (double[*] A, double eps)
{
    do {
        A_old = A;
        A = convolution_step( A_old);
    }
    while (!is_convergent( A, A_old, eps));
    return A;
}
```



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# Convolution in SAC

### Variable number of iterations with convergence check:

```
double[*] convolution (double[*] A, double eps)
{
    do {
        A_old = A;
        A = convolution_step( A_old);
    }
    while (!is_convergent( A, A_old, eps));
    return A;
}
```

#### **Convergence check:**

# Summary: Power of Abstraction

## Functional array programming in SAC:

- ► High productivity software engineering and maintenance
- High confidence in correctness of code
- Programming by abstraction
- Programming by composition of abstractions
- High readability of code
- Entirely architecture- and resource-agnostic



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# Summary: Power of Abstraction

## Functional array programming in SAC:

- ► High productivity software engineering and maintenance
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- Entirely architecture- and resource-agnostic

### Opportunities for compiler and runtime system:

- Aggressive machine-independent optimisation exploiting compositional, side-effect-free semantics
- Machine-specific customisation and adaptation
- Automatic granularity control: Customised adaptation to concrete computing architecture
- Automatic resource management:

memory, cores, nodes, energy, ...

SAC: High Productivity meets High Performance

Functional Programming with Curly Brackets ?

- Design Rationale of SAC
- Data-Parallel Functional Array Programming in SAC
- Abstraction and Composition
- Case Study: Generic Convolution
- Compilation Challenge

Does it Work ? Some Experimental Evaluation

Summary and Conclusion



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SAC: Functional Array Programming with Curly Brackets

# **Compilation Challenge**



And achieve reasonably high performance....



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## **Compilation Challenge**





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### **Compiler fact sheet:**

- Around 300,000 lines of code
- Around 1000 files:
  - + standard prelude
  - + standard library
- Around 250 compiler passes
- Complete compiler construction toolkit as side product:
  - re-used in other compiler research projects
  - re-used in teaching compiler courses (Bachelor/Master)



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### **Compiler fact sheet:**

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  - re-used in other compiler research projects
  - re-used in teaching compiler courses (Bachelor/Master)

### Where's the trick ?

- Purely functional semantics benefits large-scale program transformation
- Stringent language-compiler co-design with one goal: high performance in parallel execution of array programs



# The SAC Project

#### International partners:

- University of Kiel, Germany (1994–2005)
- University of Toronto, Canada (since 2000)
- University of Lübeck, Germany (2001–2008)
- University of Hertfordshire, England (2003–2012)
- University of Amsterdam, Netherlands (since 2008)
- Heriot-Watt University, Scotland (since 2011)



SAC: High Productivity meets High Performance

Functional Programming with Curly Brackets ?

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SAC: Functional Array Programming with Curly Brackets

## Experiment: SAC on x86 Multi-Core Multi-Processor

### Machine:

- 4 AMD Opteron 8356 processors
- 4 fully-fledged cores each

### **Unsteady Shock Wave Simulation:**





# Experiment: SAC on Graphics Accelerator

### Machine:

NVidia Tesla GPU

### Lattice-Boltzmann:





# Experiment: SAC on Multiple Graphics Accelerators

### Machine:

8 NVidia GeForce GTX 580

### **Convolution kernel:**

- 8000×8000 matrix, 10000 iterations
- requires data exchange between GPGPUs after each iteration





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# Experiment: SAC on Heterogeneous System

### Machine:

- 2 quad-core Intel Xeon processors
- 2 NVidia GTX480 GPUs

### **Convolution kernel:**





# Experiment: SAC on Ultra Sparc T3-4 Server

### Machine:

- 4 Oracle Ultra Sparc T3 processors
- ▶ 4 × 16 = 64 cores
- $4 \times 16 \times 8 = 512$  hardware threads

### Matrix multiplication:



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SAC: High Productivity meets High Performance

Functional Programming with Curly Brackets ?

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SAC: Functional Array Programming with Curly Brackets

# Summary

## Language design:

- Functional state-less semantics with C-like syntax
- Data parallel array programming
- Abstraction and composition
- Shape-generic programming
- Index-free programming



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# Summary

## Language design:

- Functional state-less semantics with C-like syntax
- Data parallel array programming
- Abstraction and composition
- Shape-generic programming
- Index-free programming

### Language implementation:

- Fully-fledged compiler
- Automatic parallelisation
- Automatic memory management
- High-level program transformation
- Large-scale machine-independent optimisation



Performance competitive with the "real" curly brackets!!

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The End

# **Questions** ?

## Check out www.sac-home.org !!



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Bonus Slides: Input and Output

#### **Example:**

```
import StdIO: all;
import ArrayIO: all;
int main()
Ł
  a = 42;
  b = [1, 2, 3, 4, 5];
  errcode, outfile = fopen( "filename", "w");
  fprintf( outfile, "a = %d\n", a);
  fprint( outfile, b);
  fclose( outfile);
  return 0;
}
```



SAC: Functional Array Programming with Curly Brackets

# Digression: Input and Output

### Example functionalised by compiler:

```
FileSystem, int main( FileSystem theFileSystem)
ſ
 a = 42:
  b = [1, 2, 3, 4, 5];
  theFileSystem, errcode, outfile
    = fopen( theFileSystem, "filename", "w");
  outfile = fprintf( outfile, "a = %d\n", a);
  outfile = fprint( outfile, b);
  theFileSystem = fclose( theFileSystem, outfile);
  return( theFileSystem, 0);
}
```

### FileSystem and File are uniqueness types.



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