











### Parallelism vs. Concurrency

- Primary distinguishing feature of Concurrent Haskell: threads of control
  - Concurrent programming is done in the IO monad
     because threads have *effects*
    - effects from multiple threads are interleaved
    - nondeterministically at runtime.
  - Concurrent programming allows programs that interact with multiple external agents to be modular
    - the interaction with each agent is programmed separately
    - Allows programs to be structured as a collection of interacting agents (actors)
       Slide: S. Marlow











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- Compile sudoku2

   (add -threaded -rtsopts)
   run with sudoku17.1000.txt +RTS -N2
- · Take note of the Elapsed Time



# Why not 2?

- two reasons for lack of parallel speedup:
   less than 100% utilisation (some processors idle for part of the time)
  - extra overhead in the parallel version
- · Each of these has many possible causes...



- less than 100% utilisation
  - parallelism was not created, or was discarded
  - algorithm not fully parallelised residual sequential computation
  - uneven work loads
  - poor scheduling
  - communication latency
- · extra overhead in the parallel version
  - overheads from rpar, work-stealing, deep,  $\ldots$
  - lack of locality, cache effects...
  - larger memory requirements leads to GC overhead
     GC synchronisation
  - duplicating work

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## So we need tools

- to tell us why the program isn't performing as well as it could be
- · For Parallel Haskell we have ThreadScope

\$ ghc -02 sudoku2.hs -threaded -rtsopts -eventlog
\$ ./sudoku2 +RTS -N2 -ls
\$ threadscope sudoku2.eventlog

-eventlog has very little effect on runtime

 important for profiling parallelism



### Uneven workloads...

 So one of the tasks took longer than the other, leading to less than 100% utilisation

let (as,bs) = splitAt (length grids `div` 2) grids

- One of these lists contains more work than the other, even though they have the same length
  - sudoku solving is not a constant-time task: it is a searching problem, so depends on how quickly the search finds the solution



- static partitioning is simple, but can lead to
- under-utilisation if the tasks can vary in size static partitioning does not adapt to varying
- availability of processors our solution here can use only 2 processors

# **Dynamic Partitioning**

- GHC's runtime system provides spark pools to track dynamic work units, and a work-stealing scheduler to assign them to processors
- So all we need to do is use smaller tasks and more pars, and we get dynamic partitioning



	Result (2 cores)										
0.1s	0.28 0.3	ls 0.4s	0.58 0.68	0.78 0.1	85 0.95	15 1.15	1.28 1.3	8 1.48 1.58			
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- Compositional larger Eval sequences can be built by composing smaller ones using monad combinators
   Internal workings of Eval are very simple (see Haskell)
- Internal workings of Eval are very simple (see Haskell Symposium 2010 paper)





### Some Basic Strategies

- r0 no evaluation
- rpar create a parallel spark
- rdeepseq deep evaluation

















### Summary

- Strategies, in theory: – Algorithm + Strategy = Parallelism
- Strategies, in practice (sometimes):
   Algorithm + Strategy = No Parallelism
- laziness is the magic ingredient that bestows modularity, but laziness can be tricky to deal with.

### Where to look next

- Other alternatives are emerging, see e.g. – The Par monad: abandon modularity via
  - laziness for more explicit concurrency
  - Data-parallel Haskell operations on bulk data (think GPU's – thousands of cores)



- Many slides here adapted from Simon Marlow's CEFP summer school slides
- http://research.microsoft.com/en-us/ people/simonmar
  - /par-tutorial.pdf
  - /papers/strategies.pdf
- haskell.org/haskellwiki/ThreadScope