

More on Semaphores, on to Monitors

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Questions?

- Anything you did not get
- Was I too fast/slow?
- Found a lab partner?
- Haven't yet got email for one course rep

Natural Example

1. Clocks occur in nature
 1. Repressilator – human-made, incorporated in E-coli

Primitives and Machines

- We see this repeatedly in Computer Science
 - Whether for primitives or whole machines
- Recognise pattern in nature or in use
- Specify primitive or machine
- Figure out range of use and problems
- Figure out (efficient) implementation

Many Concurrency models

1. What world are we living in, or choose to?
 - a. Synchronous or asynchronous?
 - b. Real-time?
 - c. Distributed?
2. We choose any abstraction that
 - a. Mimics enough of the real world to be useful
 - b. Has nice properties (can build useful and good programs)
 - c. Can be implemented correctly, preferably easily

Concurrency Primitives in History

- 1950's onwards
 - Read-compute-print records *in parallel*
 - Needs *timing*
- 1960's onward
 - slow i/o devices in parallel with fast and expensive CPU
 - *Interrupts, synchronisation, shared memory*
- *Processes and context switching*
 - Late 1960's : timesharing expensive CPU between users
 - Modern laptop: background computation from which the foreground process steals time

Terminology

- A “process” is a sequential component that may interact or communicate with other processes.
- A (concurrent) “program” is built out of component processes
- The components can potentially run in parallel, or may be interleaved on a single processor. Multiple processors may allow actual parallelism.

How to structure processes?

- What are they?
 - How do you answer that?
- Start with examples from real life
 - Each I/O device can be a process
 - Then what about the CPU?
 - Each device at least has a “virtual process” in the CPU
 - Context switching
 - move next process data into CPU
 - When? On time signal or “interrupt”
 - How? CPU checks before each instruction
- What does a process look like to others?
 - What does each process need to know?
 - What does the system need to know about each process?

These ideas became standard in Operating Systems (60's thru 70's)

- Divided into kernel and other services
 - Other services run as processes
- The kernel
 - Handles the actual hardware
 - Implements abstractions
 - Processes, with priorities and communication
 - Schedules the processes
 - using time-slicing or other interrupts
- A 90's terminology footnote
 - When a single OS process structures itself as several processes, these are called "threads"

The counting example

- See algorithm 2.9 on slide 2.24
 - What are the min and max possible values of n?
- How to say it in C-BACI, Ada and Java
 - 2.27 to 2.32

The Critical Section Problem

- Attempts to solve them
 - without special hardware instructions
 - Assuming load and store are atomic
 - Designing suitable hardware instructions
 - Or software instructions

Recap: Requirements & Assumptions

- Correctness
 - Both p and q cannot be in their CS at once (mutex)
 - If p and q both wish to enter their CS, one must succeed eventually (no deadlock)
 - If p tries to enter its CS, it will succeed eventually (no starvation)
- Assumptions
 - A process in its CS will leave eventually (progress)
 - Progress in non-CS optional

Recap: CS protocols

- Pre- and post-protocols
 - These don't share local or global vars with the rest of the program
- The CS models access to data shared between p and q

Rethink

- P checks wantq
 - Finds it false, enters CS,
 - but q enters before p can set wantp
- Could we prevent that?
 - When I find the book free, I take it
 - Before anyone else even sees it free
- Test-and-set(common, local) =
`atomic{local:=common; common:=1}`
 - Now see Ben-Ari p76, slide 3.22, alg 3.11
 - See Wikipedia article, also Herlihy 1991

Exchange and other atomics

- Slides 3.22 and 3.23
- Other atomic instructions
 - Compare and swap
 - Fetch-and-add
- All use busy waits
 - OK in multiprocessors
 - Particularly if low contention

Critical Section with semaphore

- See alg 6.1 and 6.2 (slides 6.2 through 6.4)
- Semaphore is like alg 3.6
 - The second attempt at CS without special ops
 - There, the problem was
 - P checks wantq
 - Finds it false, enters CS,
 - but q enters before p can set wantp
- We can prevent that by compare-and-swap
- Semaphores are high level versions of this

Correct?

- Look at state diagram (p 112, s 6.4)
 - Mutex, because we don't have a state (p2, q2, ..)
 - No deadlock
 - Of a set of waiting (or blocked) procs, one gets in
 - Simpler definition of deadlock now
 - Both blocked, no hope of release
 - No starvation, with fair scheduler
 - A wait will be executed
 - A blocked process will be released

Invariants

- Do you know what they are?
 - Help to prove loops correct
 - Game example
- Semaphore invariants
 - $k \geq 0$
 - $k = k.\text{init} + \#\text{signals} - \#\text{waits}$
 - Proof by induction
 - Initially true
 - The only changes are by signals and waits

CS correctness via sem invariant

- Let #CS be the number of procs in their CS's.
 - Then $\#CS + k = 1$
 - True at start
 - Wait decrements k and increments #CS; only one wait possible before a signal intervenes
 - Signal
 - Either decrements #CS and increments k
 - Or leaves both unchanged
 - Since $k \geq 0$, $\#CS \leq 1$. So mutex.
 - If a proc is waiting, $k=0$. Then $\#CS=1$, so no deadlock.
 - No starvation – see book, page 113

Why two proofs?

- The state diagram proof
 - Looks at each state
 - Will not extend to large systems
 - Except with machine aid (model checker)
- The invariant proof
 - In effect deals with sets of states
 - E.g., all states with one proc is CS satisfy #CS=1
 - Better for human proofs of larger systems
 - Foretaste of the logical proofs we will see (Ch. 4)

Producer - consumer

- Yet another meaning of "synchronous"
 - Buffer of 0 size
- Buffers can only even out transient delays
 - Average speed must be same for both
- Infinite buffer first. Means
 - Producer never waits
 - Only one semaphore needed
 - Need partial state diagram
 - Like mergesort, but signal in a loop
- See algs 6.6 and 6.7

Infinite buffer is correct

- Invariant
 - $\#sem = \#buffer$
 - 0 initially
 - Incremented by append-signal
 - Need more detail if this is not atomic
 - Decrement by wait-take
- So cons cannot take from empty buffer
- Only cons waits – so no deadlock or starvation, since prod will always signal

Bounded buffer

- See alg 6.8 (p 119, s 6.12)
 - Two semaphores
 - Cons waits if buffer empty
 - Prod waits if buffer full
 - Each proc needs the other to release "its" sem
 - Different from CS problem
 - "Split semaphores"
 - Invariant
 - $\text{notEmpty} + \text{notFull} = \text{initially empty places}$

Different kinds of semaphores

- “Strong semaphores”
 - use queue instead of set of blocked procs
 - No starvation
- Busy wait semaphores
 - No blocked processes, simply keep checking
 - See book re problems about starvation
 - Simpler.
 - Useful in multiprocessors where each proc has own CPU
 - The CPU can’t be used for anything else anyway
 - Or if there is very little contention

Dining Philosophers

- Obvious solution deadlocks (alg 6.10)
- Break by limiting 4 phils at table (6.11)
- Or by asymmetry (6.12)

Semaphore recap

- Designed for CS problem or atomic actions
 - (even with n-proc)
 - Avoid busy waiting
- But for the producer-consumer problem
 - The correctness of each proc
 - Depends on the correctness of the other
 - Not modular
- Monitors modularise synchronisation
 - for shared memory