## Sorting

## Weiss chapter 8.1 – 8.3, 8.6



Very many different sorting algorithms (bubblesort, insertion sort, selection sort, quicksort, heapsort, mergesort, shell sort, counting sort, radix sort, ...)

## Application of sorting

Are two words anagrams of each other? Sort both words, check if they come out the same!



Check for *adjacent elements* that are in the wrong order, and swap them Starting from one end of the array and working towards the other

## Compare a[0] and a[1]:



## Compare a[1] and a[2]:



## Compare a[2] and a[3]:



## Compare a[3] and a[4]:



## Back to the beginning!



## Compare a[1] and a[2]:



## Compare a[2] and a[3]:



## Compare a[3] and a[4]:



## Back to the beginning!



## What order to do the swaps in?

- Start at the beginning of the array, loop upwards until you reach the top
- Then go round again
- How do we know when to stop?
  - When the array is sorted
  - When the last loop didn't swap any elements

```
Bubblesort
                                This for-loop is O(n)
void sort(int[] array) {
  boolean swapped;
  do {
    swapped = false;
    for (int i = 0; i < array.length-1; i++)
      if (a[i] > a[i+1]) {
        // Swap a[i] and a[i+1]
        int x = a[i];
        a[i] = a[i+1];
                                 But how many
        a[i] = x;
        swapped = true;
                                  times does the
      }
                                do-loop execute?
  } while(swapped);
}
```

## Performance of bubblesort

After one loop, the biggest element in the array has "bubbled up" to the top (hence the name bubblesort)

Look at what happens to 9 in our example
So the do-loop executes n times
Total complexity O(n<sup>2</sup>)
(we assume that comparisons and swaps take O(1) time)

## Bubble sort is *bad*!

What if the array is in reverse order?

After one loop, only the 9 is in the right place: 8 5 3 2 9

It is very inefficient.

## Insertion sort

Imagine someone deals you cards. You pick up each one in turn and put it into the right place in your hand:



This is the idea of *insertion sort*.

## Start by "picking up" the 5:

5

## Then insert the 3 into the right place:





### Then the 9:



#### Then the 2:

2	3	5	9

## Insertion sortSorting53928:

### Finally the 8:

|--|

## Complexity of insertion sort

- Insertion sort does n insertions for an array of size n
- Does this mean it is O(n)? *No!* An insertion is not constant time.
- To insert into a sorted array, you must move all the elements up one, which is O(n).
- Thus total is  $O(n^2)$ .

## Insertion sort in Haskell

sort [] = []
sort (x:xs) = insert x (sort xs)

A sorting algorithm is *in-place* if it does not need to create any temporary arrays Let's make an in-place insertion sort! Basic idea: loop through the array, and insert each element into the part which is already sorted

## The first element of the array is sorted:



### Insert the 3 into the correct place:

## Insert the 9 into the correct place:

## Insert the 2 into the correct place:

2 3 5 9 8	)
-----------	---

## Insert the 8 into the correct place:

2 3 5 8 9
-----------

## In-place insertion

To insert an item, make space by moving everything greater than it upwards





## In-place insertion

This notation means 0, 1, ..., n-1

```
// Assuming that a[0..n) is sorted,
// inserting a[n] into the right place
// so that a[0..n] is sorted
void insert(int[] a, int n) {
  int x = a[n];
  int i = n;
  while(i > 0 && a[i-1] > x) {
    a[i] = a[i-1];
    1--;
  }
  a[i] = x;
```

```
void sort(int[] array) {
   for (int i = 1; i < n; i++)
      insert(array, i);
}</pre>
```

An aside: we have the *invariant* that array[0..i) is sorted

- An invariant is something that holds whenever the loop starts
- Initially, i = 1 and array[0..1) is sorted
- When array[0..i) is sorted, the loop body makes array[0..i+1) sorted, establishing the invariant for the next iteration
- When the loop finishes, i = n, so array[0..n) is sorted the whole array!

## A negative result

Bubblesort and insertion sort are both based on *swapping adjacent elements* No sorting algorithm that works like this can be better than  $O(n^2)$ ! See section 8.3 for details.

## Selection sort

- Find the smallest element of the array, and delete it
- Find the smallest remaining element, and delete it
- And so on

Finding the smallest element is O(n), so total complexity is  $O(n^2)$ 

### The smallest element is 2:

## 2

## We also delete 2 from the input array.

#### Now the smallest element is 3:

2 3

#### We delete 3 from the input array.

## Selection sort

## Now the smallest element is 5:

We delete 5 from the input array. (...and so on)

Instead of deleting the smallest element, *swap it* with the first element!

The next time round, ignore the first element of the array: we know it's the smallest one.

Instead, find the smallest element of the *rest* of the array, and swap it with the second element.

## The smallest element is 2:



## The smallest element in the rest of the array is 3:

## The smallest element in the rest of the array is 5:



## The smallest element in the rest of the array is 8:



## Divide and conquer algorithms and quicksort

## Divide and conquer

Very general name for a type of recursive algorithm

## You have a problem to solve.

- *Split* that problem into smaller subproblems
- *Recursively* solve those subproblems
- *Combine* the solutions for the subproblems to solve the whole problem

#### To solve this...









1. *Split* the problem into subproblems

2. *Recursively* solve the subproblems

3. *Combine* the solutions



## Quicksort

Pick an element from the array, called the *pivot* 

*Partition* the array:

• First come all the elements smaller than the pivot, then the pivot, then all the elements greater than the pivot

Recursively quicksort the two partitions

## Quicksort

Say the pivot is 5.

Partition the array into: all elements less than 5, then 5, then all elements greater than 5

## Quicksort

## Now recursively quicksort the two partitions!

3	3	2	2	1	4	5	9	8	7
Quicksort Quicksort									
1	2	2	3	3	4	5	7	8	9

## Pseudocode

```
// call as sort(a, 0, a.length-1);
void sort(int[] a, int low, int high) {
    if (low >= high) return;
    int pivot = partition(a, low, high);
        // assume that partition returns the
        // index where the pivot now is
        sort(a, low, pivot-1);
        sort(a, pivot+1, high);
}
```

Usual optimisation: switch to insertion sort when the input array is small

## Haskell code

## sort [] = [] sort (x:xs) = sort (filter (< x) xs) ++</pre> $\begin{bmatrix} X \end{bmatrix} ++$ sort (filter (>= x) xs) *Split*: filter *Combine*: ++

## Complexity of quicksort

## In the best case, partitioning splits an array of size n into two halves of size n/2:



## Complexity of quicksort

## The recursive calls will split these arrays into four arrays of size n/4:





**O(n)** time per level

## Complexity of quicksort

But that's the best case!

In the worst case, everything is greater than the pivot (say)

- The recursive call has size n-1
- Which in turn recurses with size n-2, etc.
- Amount of time spent in partitioning:  $n + (n-1) + (n-2) + ... + 1 = O(n^2)$

### Worst cases

Sorted array Reverse-sorted array Try these out!

## Complexity of quicksort

Quicksort works well when the pivot splits the array into roughly equal parts

- Median-of-three: pick first, middle and last element of the array and pick the median of those three
- Pick pivot at random: gives O(n log n) *expected* (probabilistic) complexity

Introsort: detect when we get into the  $O(n^2)$  case and switch to a different algorithm (e.g. heapsort)

## Summary of quicksort

- Divide-and-conquer algorithm: choose pivot, partition array into two, recursively sort both partitions
- O(n log n) if both partitions have about equal size, O(n<sup>2</sup>) if one is much bigger than the other
  - One solution: choose pivot at random (others in book)
- Very fast in practice

## Next lecture

How to perform partitioning More sorting algorithms Is O(n log n) the limit of sorting? How to find the complexity of recursive programs