# Software Engineering using Formal Methods Reasoning about Programs with Loops and Method Calls

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#### Calculus realises symbolic interpreter:

works on first active statement

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- decomposition of complex statements into simpler ones

$$\Gamma \Rightarrow \langle \mathbf{t=j;j=j+1;i=t;if} (isValid) \{ok=true;\}... \rangle \phi$$

$$\Gamma \Rightarrow \langle i=j++;if(isValid) \{ok=true;\}... \rangle \phi$$

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- simple assignments to updates

```
\Gamma \Rightarrow \{\mathbf{t} := \mathbf{j}\} \langle \mathbf{j} = \mathbf{j} + 1; \mathbf{i} = \mathbf{t}; \mathbf{i} \mathbf{f} (\mathbf{i} \mathbf{s} \mathbf{Valid}) \{\mathbf{o} \mathbf{k} = \mathbf{t} \mathbf{r} \mathbf{u} \mathbf{e}; \} \dots \rangle \phi
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- accumulated update captures changed program state

```
\Gamma \Rightarrow \{\mathbf{t} := \mathbf{j} || \mathbf{j} := \mathbf{j} + \mathbf{1} || \mathbf{i} := \mathbf{j} \} \langle \mathbf{if}(\mathbf{isValid}) \{ \mathbf{ok=true}; \} \dots \rangle \phi
\vdots
\Gamma \Rightarrow \{\mathbf{t} := \mathbf{j} \} \langle \mathbf{j} = \mathbf{j} + \mathbf{1}; \mathbf{i=t}; \mathbf{if}(\mathbf{isValid}) \{ \mathbf{ok=true}; \} \dots \rangle \phi
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\Gamma \Rightarrow \langle \mathbf{i} = \mathbf{j} + \mathbf{j}; \mathbf{if}(\mathbf{isValid}) \{ \mathbf{ok=true}; \} \dots \rangle \phi
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- works on first active statement
- decomposition of complex statements into simpler ones
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- lacktriangle accumulated update captures changed program state (abbr. w.  $\mathcal{U}$ )

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- works on first active statement
- decomposition of complex statements into simpler ones
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- control flow branching induces proof splitting

```
'branch1' \Gamma, {\mathcal{U}}(isValid \doteq TRUE) \Longrightarrow {\mathcal{U}}\langle {ok=true;}...\rangle\phi
'branch2' \Gamma, {\mathcal{U}}(isValid \doteq FALSE) \Longrightarrow {\mathcal{U}}\langle...\rangle\phi
\Gamma \Longrightarrow {\mathcal{U}}\langle if (isValid) {ok=true;}...\rangle\phi
...
\Gamma \Longrightarrow {\mathsf{t} := \mathsf{j}}\langle j=j+1; i=t; if (isValid) {ok=true;}...\rangle\phi
\Gamma \Longrightarrow \langle t=j; j=j+1; i=t; if (isValid) {ok=true;}...\rangle\phi
\Gamma \Longrightarrow \langle i=j++; if (isValid) {ok=true;}...\rangle\phi
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- works on first active statement
- decomposition of complex statements into simpler ones
- simple assignments to updates
- accumulated update captures changed program state
- control flow branching induces proof splitting
- ightharpoonup application of update computes weakest precondition of  $\mathcal{U}'$  wrt.  $\phi$

$$\Gamma' \Rightarrow \{\mathcal{U}'\}\phi$$
 ...

```
'branch1' \Gamma, {\mathcal{U}}(isValid \doteq TRUE) \Longrightarrow {\mathcal{U}}\langle{ok=true;}...\rangle \phi 'branch2' \Gamma, {\mathcal{U}}(isValid \doteq FALSE) \Longrightarrow {\mathcal{U}}\langle...\rangle \phi \Gamma \Longrightarrow {\mathcal{U}}\langleif(isValid){ok=true;}...\rangle \phi
```

$$\Gamma \Rightarrow \{t := j\} \langle j = j+1; i = t; if(isValid) \{ok = true; \} \dots \rangle \phi$$

$$\Gamma \Rightarrow \langle t = j; j = j+1; i = t; if(isValid) \{ok = true; \} \dots \rangle \phi$$

$$\Gamma \Rightarrow \langle i = j++; if(isValid) \{ok = true; \} \dots \rangle \phi$$

How to express using updates that a formula  $\phi$  is evaluated in a state where

program variable i has been set to 5?

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- ▶ all components of an array arr of length 2 have value 0?
  - $\{arr[0] := 0 \parallel arr[1] := 0\}\phi$
- all components of an array arr of length n have value 0?

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- ▶ all components of an array arr of length n have value 0?

For example to deal with things like

$$\langle \mathtt{int[]} \ \mathtt{a = new int[n];} \rangle$$
  
 $\forall \mathtt{int } x; \ (0 \le x < \mathtt{a.length} \rightarrow \mathtt{a[x]} \doteq 0)$ 

# **Quantified Updates**

### **Definition (Quantified Update)**

For T well-ordered type (no  $\infty$  descending chains): quantified update:

$$\{ \forall x \in T \ x; \forall \phi(x); l(x) := r(x) \}$$

- For all objects d in T such that  $\phi(d)$  perform the updates  $\{I(d) := r(d)\}$  in parallel
- ▶ If there are several / with conflicting d then choose T-minimal one
- The conditional expression is optional
- ▶ Typically, x occurs in  $\phi$ , I, and r (but doesn't need to)
- ► There is a normal form for updates computed efficiently by KeY

### **Quantified Updates Cont'd**

Example (Initialization of field a for all objects in class C)

$$\{ \texttt{\for} \ \texttt{C} \ o; o.\texttt{a} := 0 \}$$

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Example (Initialization of components of array a )

$$\{ \text{\for int } i; a[i] := 0 \}$$

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Example (Initialization of components of array a )

$$\{ \text{\for int } i; a[i] := 0 \}$$

Example (Integer types are well-ordered in KeY)

$$\{\text{\ for int } i; a[0] := i\}(a[0] \doteq 0)$$

- ightharpoonup Non-standard order for  $\mathbb{Z}$  (with 0 smallest and preserving < for arguments of same sign)
- Proven automatically by update simplifier

### Symbolic execution of loops: unwind

(We omitted  ${\cal U}$  last lecture, for simplicity.)

### Symbolic execution of loops: unwind

unwindLoop 
$$\frac{\Gamma \Longrightarrow \mathcal{U}[\pi \ \mathbf{if} \ (\mathbf{b}) \ \{\mathbf{p}; \ \mathbf{while} \ (\mathbf{b}) \ \mathbf{p}\} \ \omega]\phi, \Delta}{\Gamma \Longrightarrow \mathcal{U}[\pi \ \mathbf{while} \ (\mathbf{b}) \ \mathbf{p} \ \omega]\phi, \Delta}$$

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How to handle a loop with...

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How to handle a loop with...

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### Symbolic execution of loops: unwind

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- 0 iterations? Unwind 1×
- ▶ 10 iterations?

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- ▶ 0 iterations? Unwind 1×
- ▶ 10 iterations? Unwind 11×

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- an unknown number of iterations?

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How to handle a loop with...

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We need an invariant rule (or some other form of induction)

#### Idea behind loop invariants

- ► A formula *Inv* whose validity is preserved by loop guard and body
- ► Consequence: if *Inv* was valid at start of the loop, then it still holds after arbitrarily many loop iterations
- ▶ If the loop terminates at all, then *Inv* holds afterwards
- Construct Inv such that it implies postcondition of loop

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#### **Basic Invariant Rule**

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$$\Gamma \Longrightarrow \mathcal{U}[\pi \text{ while (b) p } \omega]\phi, \Delta$$

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$$\Gamma \Longrightarrow \mathcal{U}$$
Inv,  $\Delta$ 

(valid when entering loop)

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- ▶ Context  $\Gamma$ ,  $\Delta$ ,  $\mathcal{U}$  must be omitted in 2nd and 3rd premise:
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  - $\blacktriangleright$  keeping  $\Gamma,\,\Delta$  without  ${\cal U}$  meant executing p in prestate of program
- ▶ But: context contains important preconditions and class invariants
- ▶ Needed context information must be added to *Inv* ②

# **Example**

```
int i = 0;
while(i < a.length) {
    a[i] = 1;
    i++;
}</pre>
```

```
(Implicit) Class Invariant: a \neq null
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(Implicit) Class Invariant: a ≠ null
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Postcondition:  $\forall int x$ ;  $(0 \le x < a.length \rightarrow a[x] = 1)$ 

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Loop invariant:  $0 \le i \& i \le a.length$ 

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Analogous situation: \forall-Right quantifier rule \Rightarrow \forall x; \phi Replace x with a fresh constant
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To change value of program location use update, not substitution

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► How to erase all values of assignable locations in formula Γ?
Analogous situation: ∀-Right quantifier rule ⇒ ∀x; φ
Replace x with a fresh constant

To change value of program location use update, not substitution

ightharpoonup Anonymising updates  ${\cal V}$  erase information about modified locations

```
V = \{i := c \mid | \mathbf{for} x; \ a[x] := f_a(x) \}
(c, f_a fresh constant resp. function symbol)
```

$$\Gamma \Longrightarrow \mathcal{U}[\pi \text{ while (b) p } \omega]\phi, \Delta$$

### Improved Invariant Rule

$$\Gamma \Longrightarrow \mathcal{U} Inv, \Delta$$

(valid when entering loop)

$$\Gamma \Longrightarrow \mathcal{U}[\pi \, \mathtt{while} \, (\mathtt{b}) \, \, \mathtt{p} \, \, \omega] \phi, \Delta$$

$$\Gamma \Longrightarrow \mathcal{U} \textit{Inv}, \Delta \qquad \text{(valid when entering loop)}$$
 
$$\Gamma \Longrightarrow \mathcal{U} \mathcal{V} (\textit{Inv} \& b \doteq \texttt{TRUE} \rightarrow [\texttt{p}] \textit{Inv}), \Delta \qquad \text{(preserved by p)}$$
 
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```

- Context is kept as far as possible
- Invariant does not need to include unmodified locations
- For assignable \everything (the default):
  - $\mathcal{V} = \{* := *\}$  wipes out **all** information
  - Equivalent to basic invariant rule
  - Avoid this! Always give a specific assignable clause

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(Implicit) Class Invariant: a # null

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Loop invariant: 0 \le i & i \le a.length & \forall int x; (0 \le x < i \rightarrow a[x] = 1)
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(Implicit) Class Invariant:  $a \neq null not needed for invariant$ 

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Loop invariant: 
$$0 \le i$$
 &  $i \le a.length$  &  $\forall int x$ ;  $(0 \le x < i \rightarrow a[x] = 1)$ 

# Example in JML/Java - Loop.java

```
public int[] a;
    /*@ public normal_behavior
                                                                 ensures (\forall int x; 0 \le x \& x \le 1 = 1);
                                   0 diverges true;
                                 0*/
public void m() {
                                 int i = 0:
                                   /*@ loop_invariant
                                                                 0 (0 <= i && i <= a.length &&
                                                                                                                                    (\int x \cdot \int x
                                                                 @ assignable i, a[*];
                                                                 0*/
                               while(i < a.length) {</pre>
                                                                 a[i] = 1;
                                                                   i++:
```

```
∀ int x;

(x \doteq n \land x >= 0 \rightarrow [i = 0; r = 0;

while (i<n) { i = i + 1; r = r + i;}

r=r+r-n;

|r \div ?)
```

How can we prove that the above formula is valid (i.e. satisfied in all states)?

```
\forall int x;

(x \(\displie\) n \(\lambda\) x >= 0 \(\righta\)

[ i = 0; r = 0;

while (i < n) { i = i + 1; r = r + i;}

r=r+r-n;

]r \(\displie\) x * x)
```

How can we prove that the above formula is valid (i.e. satisfied in all states)?

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\forall int x;

(x \(\displie\) n \(\lambda\) x >= 0 \(\righta\)

[ i = 0; r = 0;

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#### Solution:

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File: Loop2.java

### Hints

### Proving assignable

- ► The invariant rule assumes that assignable is correct E.g., with assignable \nothing; one can prove nonsense
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### Setting in the KeY Prover when proving loops

- ► Loop treatment: Invariant
- Quantifier treatment: No Splits with Progs
- ▶ If program contains \*, /: Arithmetic treatment: DefOps
- ▶ Is search limit high enough (time out, rule apps.)?
- ▶ When proving partial correctness, add diverges true;

### Find a decreasing integer term v (called variant)

Add the following premisses to the invariant rule:

- $v \ge 0$  is initially valid
- $v \ge 0$  is preserved by the loop body
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### Example (The array loop)

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#### Files:

- ► LoopT.java
- ► Loop2T.java

## Method Calls - Repetition

### Method Call with actual parameters $arg_0, \ldots, arg_n$

$$\{arg_0 := t_0 \mid\mid \ldots \mid\mid arg_n := t_n \mid\mid c := t_c\} \langle c.m(arg_0, \ldots, arg_n); \rangle \phi$$

where m declared as **void**  $m(T_0 p_0, ..., T_n p_n)$ 

#### Actions of rule methodCall

For each formal parameter p<sub>i</sub> of m: declare and initialize new local variable T<sub>i</sub> p#i = arg;

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- ► create method invocation c.m(p#0,...,p#n)@C

#### Method Body Expand

- 1. Execute code that binds actual to formal parameters  $T_i p \# i = arg_i$ ;
- 2. Call rule methodBodyExpand

$$\Gamma \Longrightarrow \langle \pi \text{ method-frame(source=C, this=c)} \{ \text{ body } \} \; \omega \rangle \phi, \Delta$$

$$\Gamma \Longrightarrow \langle \pi \text{ c.m(p\#0,...,p\#n)@C; } \omega \rangle \phi, \Delta$$

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File: inlineDynamicDispatch.key

### Formal specification of JAVA API and other called methods

How to perform symbolic execution when JAVA API method is called?

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- Method has reference implementation in JAVA Inline method body and execute symbolically
  - Problems Reference implementation not always available
    Too expensive
    - Impossible to deal with recursion
- 2. Use method contract instead of method implementation

## Method Contract Rule - Normal Behavior Case

```
/*@ public normal_behavior
  @ requires preNormal;
  @ ensures normalPost;
  @ assignable mod;
  @*/
```

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Warning: Simplified version

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- $\triangleright$   $\mathcal{F}(\cdot)$ : translation to Java DL (see last lecture)
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                                            \rightarrow \langle \pi \, \text{throw exc}; \, \omega \rangle \phi \rangle, \Delta \quad \text{(exceptional)}
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# **Understanding Proof Situations**

#### Reasons why a proof may not close

- bug or incomplete specification
- bug in program
- ▶ maximal number of steps reached: restart or increase # of steps
- automatic proof search fails and manual rule applications necessary

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### Understanding open proof goals

- ▶ follow the taken control-flow from the root to the open goal
- branch labels may give useful hints
- identify (part of) the post-condition or invariant that cannot be proven
- ▶ sequent remains always in "pre-state".
  I.e., constraints like i ≥ 0 refer to the value of i before executing the program (exception: formula is behind update or modality)
- ▶ remember:  $\Gamma \Longrightarrow o \stackrel{.}{=} null$ ,  $\Delta$  is equivalent to  $\Gamma$ ,  $o \not= null \Longrightarrow \Delta$

# **Summary**

- Most Java features covered in KeY
- ► Several of remaining features available in experimental version
  - Simplified multi-threaded JMM
  - Floats
- Degree of automation for loop-free programs is high
- Proving loops requires user to provide invariant
  - Automatic invariant generation sometimes possible
- Symbolic execution paradigm lets you use KeY w/o understanding details of logic

### Literature for this Lecture

#### Essential

- **KeY Book** Verification of Object-Oriented Software (see course web page), Chapter 10: Using KeY
- **KeY Book** Verification of Object-Oriented Software (see course web page), Chapter 3: Dynamic Logic, Sections 3.1, 3.2, 3.4, 3.5, 3.6.1, 3.6.2, 3.6.3, 3.6.4, 3.6.5, 3.6.7, 3.7