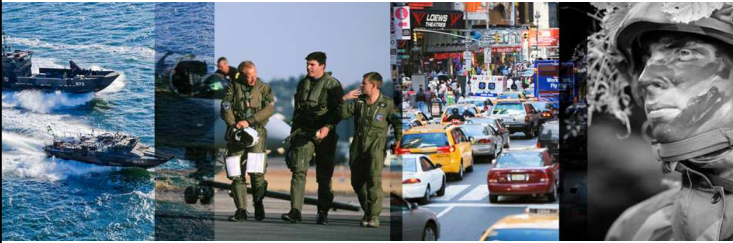


**SAAB**

# SAAB AEROSYSTEMS

## Dependable Aircraft Systems



Lars Holmlund  
October 12, 2009  
Chalmers University

## 70 years of experience

 1940 (322)	 1942 (245)	 1944 (229)	 1947 (60)
 1948 (18)	 1948 (664)	 1945 (323)	 1952 (447)
 1955 (644)	 1963 (150)	 1967 (329)	
 1983 (459)	 1988 (234)	 1992 (63)	

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## Gripen in South Africa



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## Gripen Next Generation



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## ERIEYE™ Airborne Early Warning & Control Improved Surveillance Capability



Originally designed for the Swedish Air Force and now also in operation in; Brazil, Greece, Mexico, Pakistan



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## Unmanned Aerial Vehicles Ongoing projects



SKELDAR



NEURON

([www.youtube.com/saabgroup](http://www.youtube.com/saabgroup))

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## Dependable Products



Gripen accident outside Karlskrona



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## The Gripen Flight Control System



A fault tolerant computer system

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# Scope

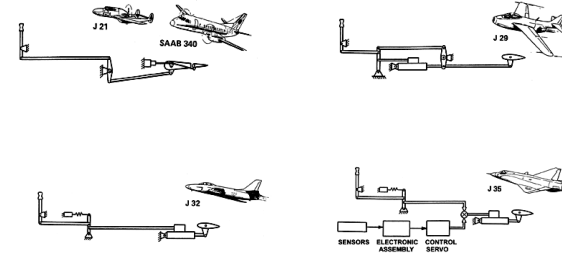
A retrospective of flight control system evolution

## The Gripen Flight Control System

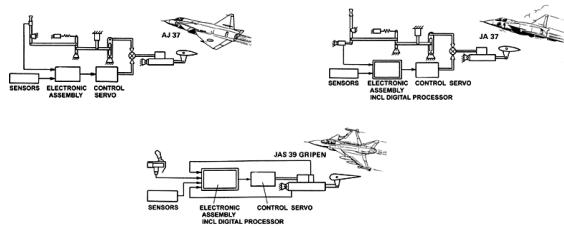
- Requirements
- Design decisions
- Principle of operation
- The philosophy behind redundancy - monitoring – fault accommodation
- System- and computer architecture



# The Evolution of FCS 1945-1990



# The Evolution of FCS 1945-1990



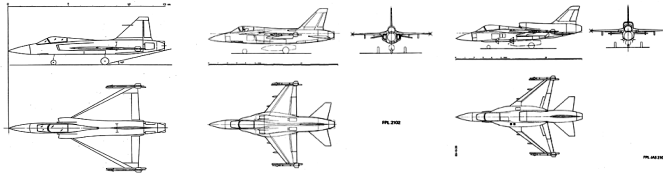
# Design Drivers

- Performance  
E.g.: range, speed, altitude, acceleration, turn ratio
- Function  
operative, pilot relief functions
- Safety/Availability  
Prob. for loss of a/c , pilot survivability, “graceful degradation”
- Weight/ Volume
- Environmental  
Temp., mech., electrical (EME, EMI,) EMP
- Maintenance and Testability



## Design Decision

- Different a/c configurations were suggested



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## Design Decision

Decision to choose an a/c with :

Relaxed stability in pitch, 7 primary control surfaces

- turn ratio, better weight/volume ratio

Electric control system

- eliminates mechanical linkage and equipment
- simplified installation and maintenance, less vulnerable

Computerized flight control system

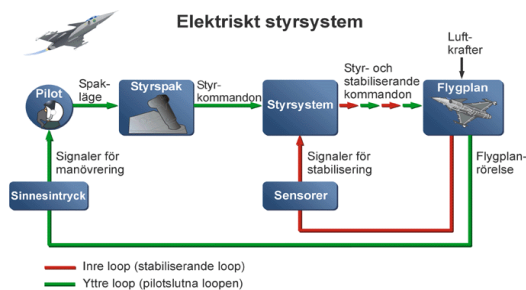
- flexibility during development and design, good growth potential (40 years)

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## The Gripen flight control system's control loops



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## Design Decisions

Pros :

- Light and "small" system
- Advanced control law calculations
  - Automatic stability in pitch
  - Optimized control and stability characteristics
  - Gust alleviation
  - Maneuvering load limits
  - Outer loop functions
- Simplified and improved maintenance and test

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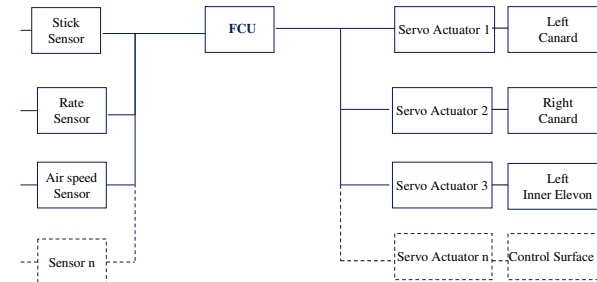
## Design Decisions

Cons:

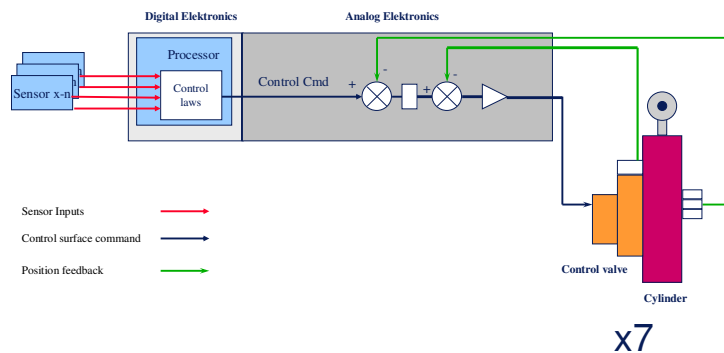
- Requires a reliable power supply
- Needs precautions when handling:
  - EME and EMI
  - Cosmic and nuclear radiation
- Extensive qualification/verification

## Fault Tolerance

A simplex system will meet functional and performance requirements



## Concept of redundancy, simplex system



## Fault Tolerance

Other requirements affect the design of the system, e.g. safety req. :

- No single failures may cause loss of a/c
- Maximum allowed probability for loss of a/c
- Maximum allowed A/C transients as a result of a fault in the system

Probability for mission success

## Fault Tolerance

Fault tolerance in the Gripen FCS is built up by:

- **Redundancies**
- Voting planes
- Monitoring
- Redundancy Management
- Asynchronous operating FCU
- Pre flight test



## The Philosophy Behind The Redundancy Concept

- Good flying qualities with 6 out of 7 primary control surfaces operating
- Maneuverable with 5 out of 7 primary control surfaces operating
- Able to cope with all single faults and most double faults
- QUAD vs TRIPLEX
  - Economical system – slim as far as resources are concerned
  - Brain power instead of muscles
- Safety critical function must be tripled
- Important functions are doubled, “tie break”



## Redundancies within the system

- Example of tripled functions (lack fail-safe position)
  - Three channel FCU
    - Independent BU-mode (HW/SW)
  - Control stick sensors
  - Rate gyro
  - Electrical power supply



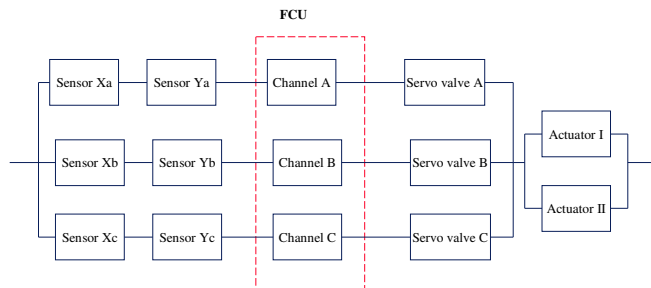
## Redundancies within the system

- Example of doubled functions (have a “fail-safe” position\*)
  - Accelerometers
  - Angle of attack sensors
  - Air data (speed and altitude)
  - Hydraulic power supply

\* as long as we can detect a fault



## General simplified architecture

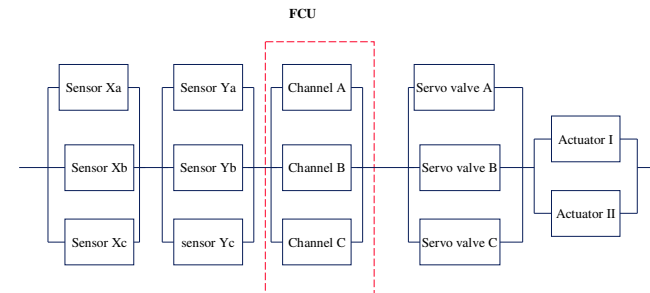


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## General simplified architecture II



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## Fault Tolerance

Fault tolerance is built up by:

- Redundancies
- **Voting planes**
- Monitoring
- Redundancy Management
- Asynchronous operating FCU
- Pre flight test

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## Voting planes

MLV – Mid Level Voting

Input signal voting (S/W)

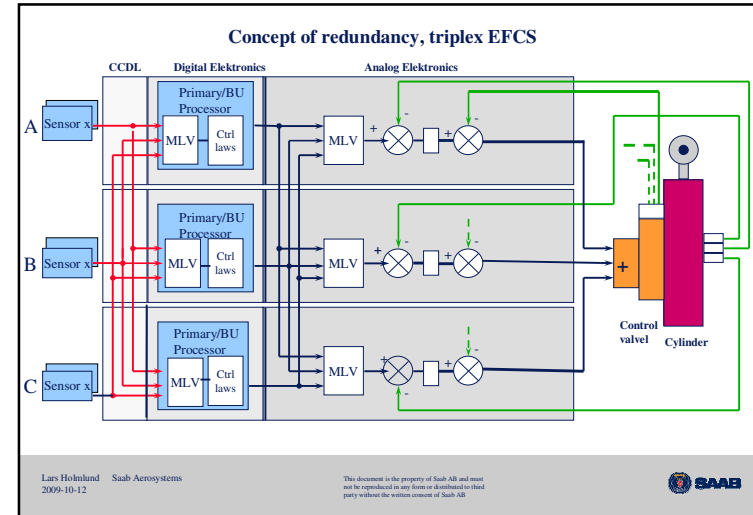
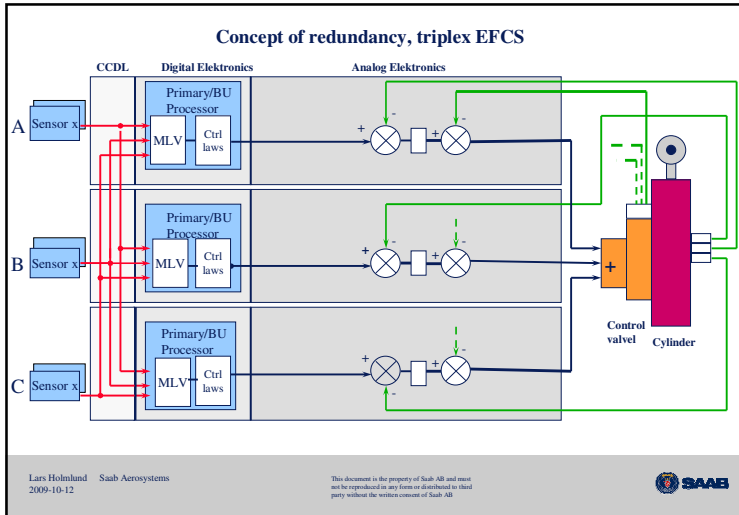
Voting of computed control signals (H/W)

”Flux summing” (H/W)

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## Fault Tolerance

Fault tolerance is built up by:

- Redundancies
- Voting planes
- **Monitoring**
- **Redundancy Management**
- Asynchronous operating FCU
- Pre flight test

## Functional Monitoring and Redundancy Management

- Extensive functional monitoring and redundancy management compensates for lack of redundancy
- Functional monitoring detects the fault and informs the A/C system and pilot about the fault.
- Redundancy management allows for reconfigurations, graceful degradation and high survivability



## Functional Monitoring

- Methodology
  - Cross channel monitoring
  - In line monitoring
  - Direct monitoring
  - Reasonableness monitoring
- Self healing
  - Minimizes the effect of nuisance trips
  - Creates resilience within the system

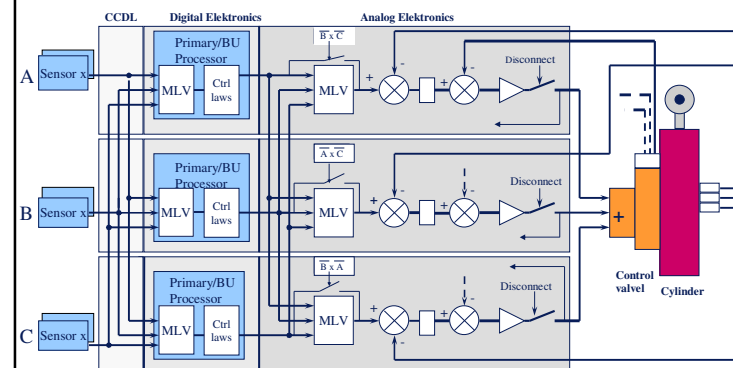
## Redundancy Management

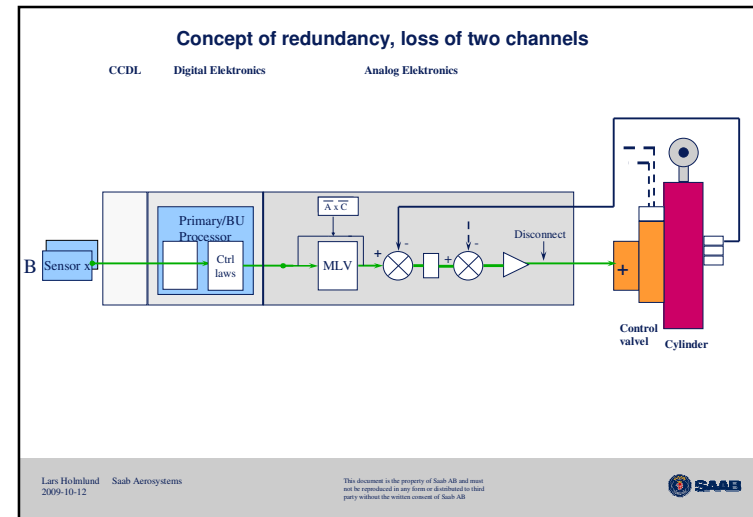
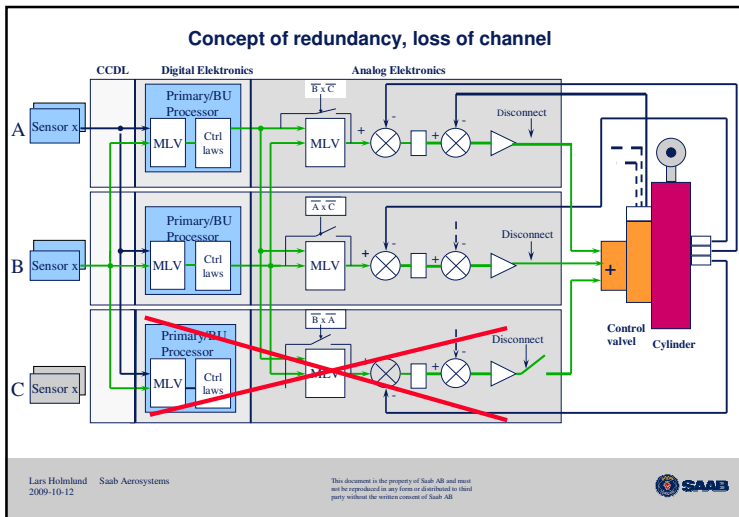
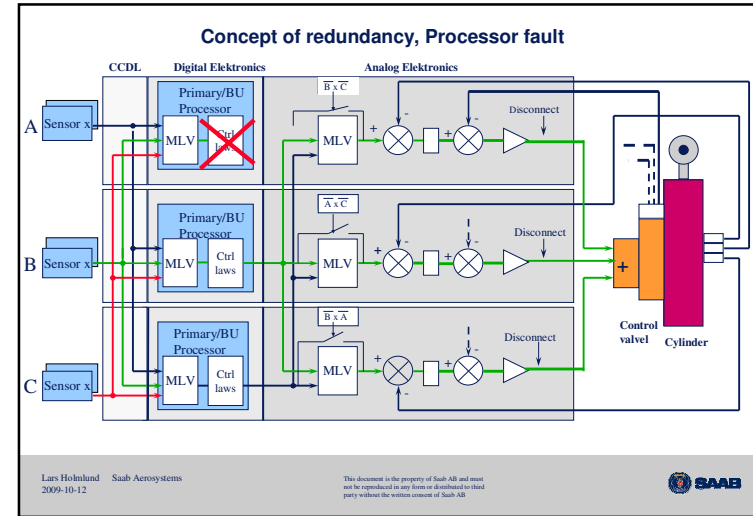
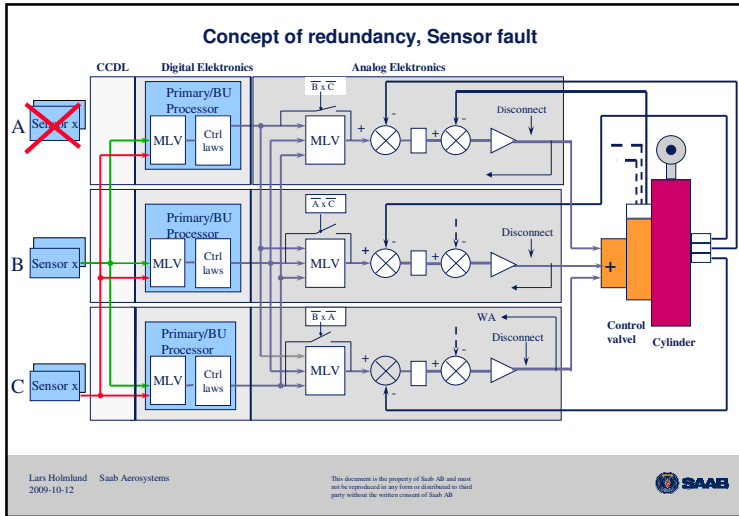
- Reconfiguration helps minimizing the possible effect of a fault
  - Selects and removes the faulty signal. Continues operation with the remaining ones or substitutes the faulty signal with another similar signal
- Reconfiguration can also compensate for lack of resources
  - Control surfaces, fail-safe values, model based signals

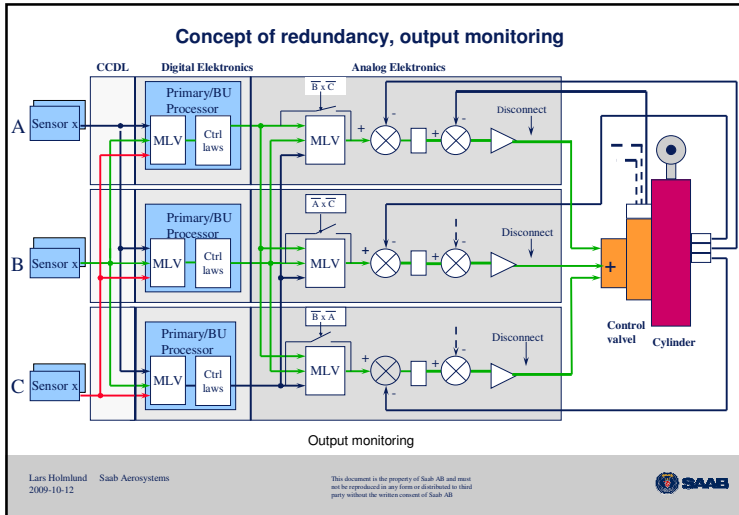
## Redundancy Management

- Example of reconfigurations:
  - Sensor faults, i.e:
    - oRate gyro
    - oAngle of attack
    - oAngle of side slip
    - oAccelerometer
  - Data bus faults
  - Servo actuator faults
  - Computer faults

### Concept of redundancy, triplex EFCS







## Fault Tolerance

Fault tolerance is built up by:

- Redundancies
- Voting planes
- Monitoring
- Redundancy Management
- **Asynchronous operating FCU**
- Pre flight test

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## Fault Tolerance

Fault tolerance is built up by:

- Redundancies
- Voting planes
- Monitoring
- Redundancy Management
- Asynchronous operating FCU
- **Pre flight test**

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## Fault Tolerance

- Extensive pre-flight test guarantees safe function of flight critical functions, redundancies and monitoring circuits

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## Summary: The Gripen FCS - A Hybrid System

### Static Redundancy

- Basically a triplex system – but not a fully TMR system
- MLV- used to isolate faults
- Asynchronous System

### Dynamic Redundancy

- Fault Detection – Application specific due to an asynchronous system
- Reconfiguration (Graceful Degradation)
- S/W redundancy – but not a real N-version programming
- Warm standby system for processor and S/W faults

### Byzantine faults

- The system is not sensitive to single Byzantine faults– due to three independent asynchronous channels + MLV

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## System Safety Work

Processes – Methodology  
Random and Systematic Faults  
Fault Injection

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## System Safety Work

# MIL-STD-882C

[http://stinet.dtic.mil/str/dodiss4\\_fields.html](http://stinet.dtic.mil/str/dodiss4_fields.html), search for the above

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- **Random failure.** Failures that result from a variety of degradation (wear out) mechanisms in hardware. System failure rates arising from random hardware failures can be quantified with reasonable accuracy based on past experience (*e.g. previous in service failure rate =  $10^{-6}$  / flight hour*)



**Systematic failure.** Failures resulting from faults in the specification, design, construction, operation or maintenance of the system or its components. A systematic failure will always occur under a particular combination of inputs, or under some particular environmental conditions.

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# RTCA/DO-178B

“Software Considerations in Airborne Systems and Equipment”

[www.rtca.org](http://www.rtca.org)

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