

## Why standards for functional safety ? – An introduction to the international standard IEC 61508

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### Our Core Areas



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## Process of innovation

- 9000 customers
- Wide technical range
- Experimental resources
- Strong research environments
- High scientific quality



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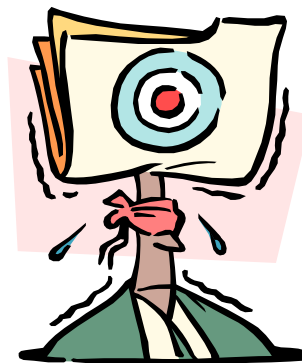
## Contents

- What is risk?
- What is “functional safety” and “safety function”?
- Is there “high” and “low” safety?
- What is the IEC 61508 standard?
- ISO 26262 for the automotive industry
- Failure rate
- An example of calculation of probability of failure
- Experiences regarding dependable systems
- More to read



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## What is risk?



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## Elements of risk

Risk

Severity

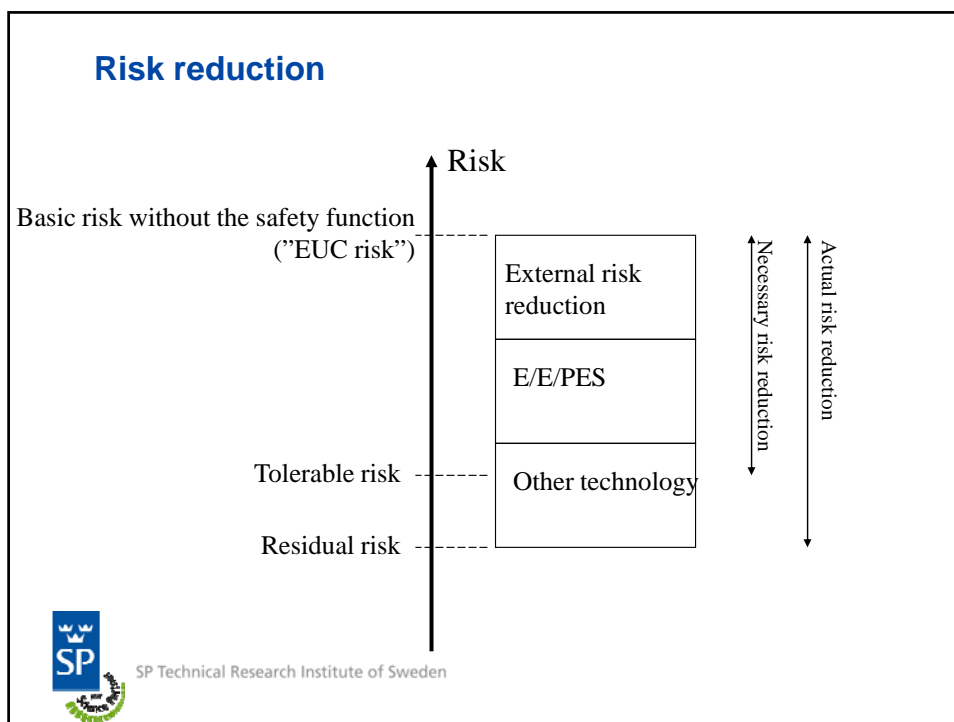
Probability of occurrence

- frequency and duration
- probability of occurrence of hazardous event
- possibility to avoid or limit the harm

Risk is a function of severity and probability.



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### Risk reduction

- Risks will be reduced by
  - proper safety functions (correctly implemented)
  - expected system behaviour at fault
  - expected probability for faults
  - suitable development methods
  - suitable safety principles
  - ....

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## Failures of the systems

Dangerous failures may arise from:

- incorrect specifications of the system, hardware or software;
- omissions in the safety requirements specification (e.g. failure to develop all relevant safety functions during different modes of operation);
- random failures of hardware;
- systematic failures of hardware and software;
- common cause failures;
- human error;
- environmental influences (e.g. electromagnetic, temperature, mechanical phenomena);
- supply system voltage disturbances (e.g. loss of supply, reduced voltages, re-connection of supply).



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www.autoliv.se

## Example: Hydraulically operated guillotine

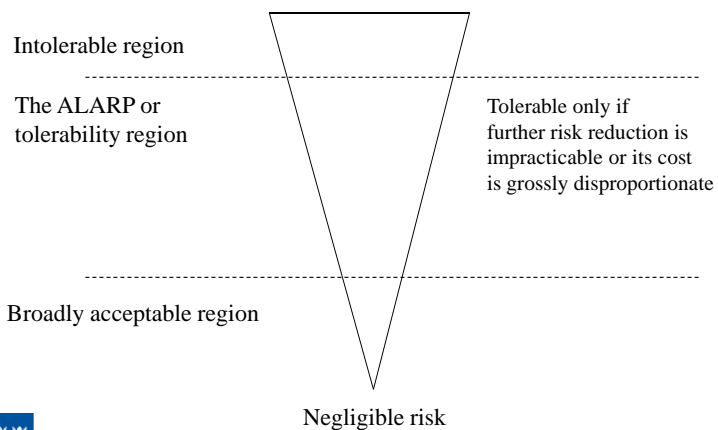


- 'hold-to-run'
- light curtain
- amputating his hand
- recently reconditioned
- replacing a hydraulic valve
- connections of 'up' and 'down' solenoids transposed
- HSE 'Out of Control'



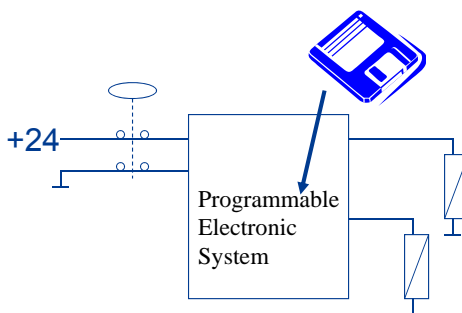
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## ALARP (As Low As Reasonably Practicable)



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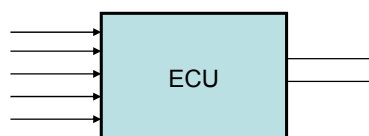
**What is "functional safety" and "safety function"?**



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## Functional safety

- Functional safety is part of the overall safety that depends on a system or equipment operating correctly in response to its inputs.
- Functionality  $\neq$  Functional safety
- Focus on development of functions must not reduce efforts for functional safety.
- It will be expensive to try to “add functional safety” late in the development process.



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## Safety function

- *“Function to be implemented by an E/E/PE safety-related system, other technology safety related system or external risk reduction facilities, which is intended to achieve or maintain a safe state for the EUC, in respect of a specific hazardous event”*
- Defined in standard IEC 61508



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## Safety requirements specification

- Overall safety requirements specification :  
safety functions AND safety integrity levels
- Example:  
safety function: pressure monitoring (alarm at high pressure)  
safety integrity: 1 fault/10 years



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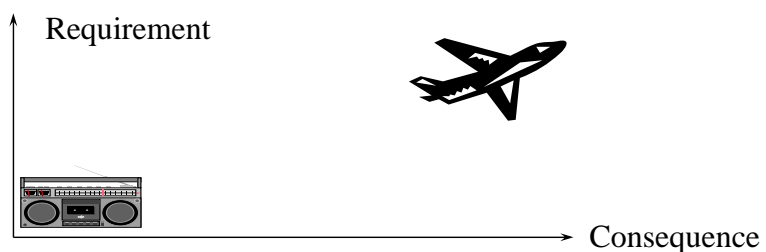
Is there "high" and "low" safety?



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## Different safety requirements



- Serious consequences – high requirements
- Moderate consequences – moderate requirements

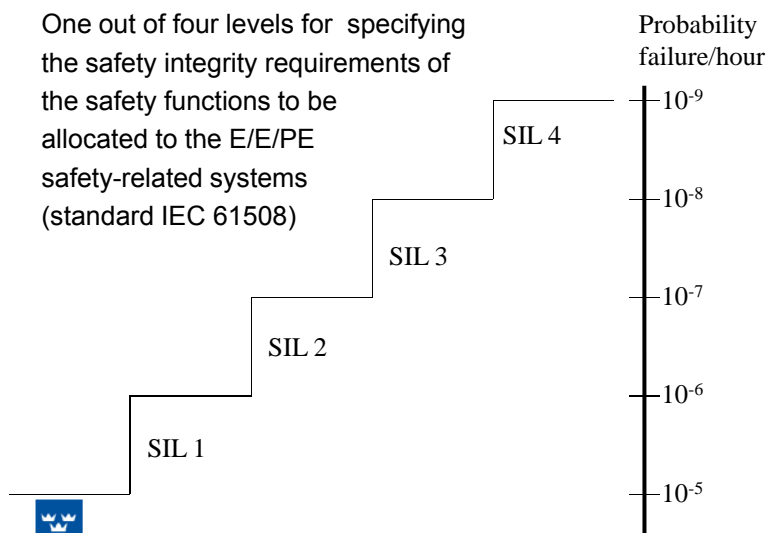
... but the safety integrity level depends on other parameters also.



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## Safety Integrity Level (SIL)

One out of four levels for specifying the safety integrity requirements of the safety functions to be allocated to the E/E/PE safety-related systems (standard IEC 61508)



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## Qualitative assessment of SIL

- Consequence
  - C1 minor injury
  - C2 serious permanent injury to one or more persons. Death to one person
  - C3 death to several people
  - C4 very many people killed
- Possibility of avoiding
  - P1 Possible under certain conditions
  - P2 Almost impossible
- Frequence & exposure
  - F1 rare to more often
  - F2 frequent to permanent
- Probability of the unwanted occurrence
  - W1 very slight probability
  - W2 slight probability
  - W3 relatively high probability



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## Risk graph

**Basic risk:** Serious injury to person depending on uncontrolled start of remote controlled machine.

**Safety function:** Emergency stop. Estimated parameters are C2, F1, P1, W3.

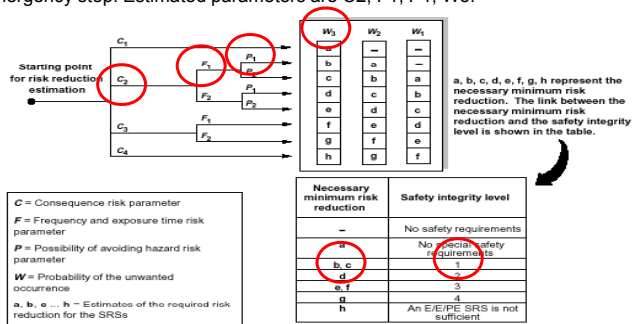


Figure D.2 – Risk graph: example (illustrates general principles only)



## What is the IEC 61508 standard?



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## IEC 61508

Functional safety of  
electrical/electronic/programmable electronic (E/E/PE)  
safety related systems

- Part 1: General requirements
- Part 2: Requirements for E/E/PE safety-related systems
- Part 3: Software requirements
- Part 4: Definitions and abbreviation
- Part 5: Examples of methods for the determination of safety integrity levels
- Part 6: Guidelines on the application of IEC 61508-2 and IEC 61508-3
- Part 7: Overview of techniques and measures



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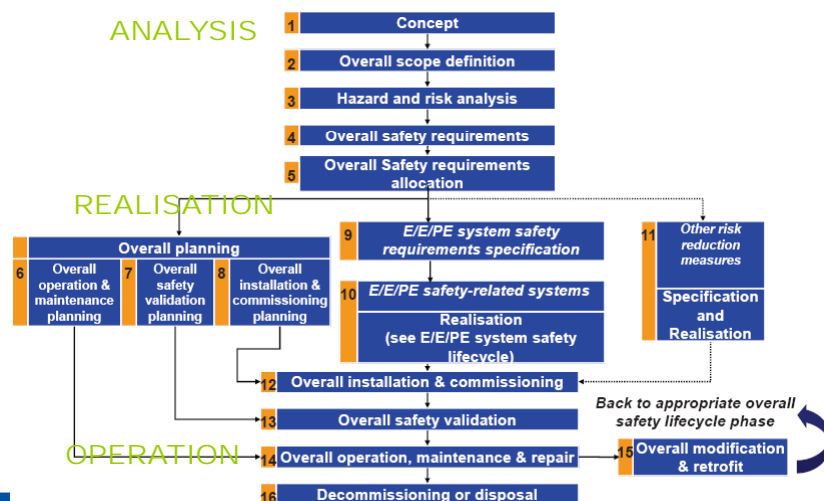
## IEC 61508

- Generic standard, i.e. used as a base for generation of sector-specific standards
- Part 1-4 are "basic safety publications". These parts must be considered when developing sector-specific standards.
- IEC 61508 can be used when sector-specific standards do not exist
- Presently under maintenance
- Also as European standard (EN 61508) and national standards (e.g. DS/EN 61508 'Funktionel sikkerhed for elektriske/elektroniske/programmerbare sikkerhedsrelaterede systemer')



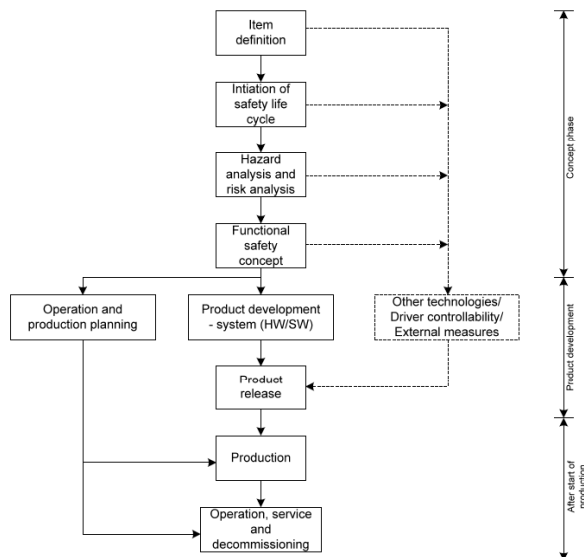
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## Overall safety lifecycle



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## Overall Safety Lifecycle



## Example: Engineer microwaves hand

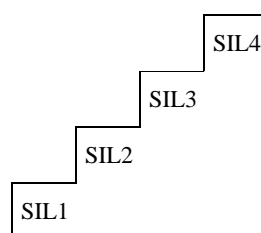


- commercial 10.5 kW microwave oven
- ‘.. a sensation of warmth in his hands..’
- electric interlocks at oven doors
- single channel control system
- 4 times per day?
- 200 times per day
- contacts welded
- HSE ‘Out of Control’



## Measures and techniques to control failures

- Target : To control failures during operation
- A combination of techniques and measures
- HR = Highly Recommended
- R = Recommended
- NR = Not Recommended
- - = No statement



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## IEC 61508-2, Table A16

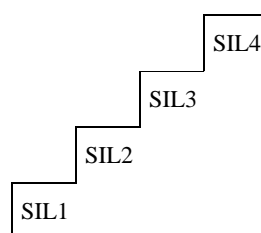
Technique/ measure	SIL 1	SIL 2	SIL 3	SIL 4
Programme sequence monitoring	HR Low coverage	HR Low coverage	HR Medium coverage	HR High coverage
On-line monitoring	R Low coverage	R Low coverage	R Medium coverage	R High coverage
.....				
Diverse hardware	-	-	R Medium coverage	R High coverage
.....				



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## Measures and techniques to avoid failures

- Target : To avoid failures during the different phases of the safety life cycle.
- A combination of techniques and measures
- HR = Highly Recommended
- R = Recommended
- NR = Not Recommended
- - = No statement



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## IEC 61508-2, Table B1 (during specification)

Technique/ measure	SIL 1	SIL 2	SIL 3	SIL 4
Project mangement	HR Low	HR Low	HR Medium	HR High
.....				
Semi-formal methods	R Low	R Low	HR Medium	HR High
.....				
Formal methods	-	-	R Medium	R High



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### IEC 61508-2, Table B5 (during validation)

Technique/ measure	SIL 1	SIL 2	SIL 3	SIL 4
Functional testing	HR mandatory	HR mandatory	HR mandatory	HR mandatory
.....				
Static analysis	-	R Low	R Medium	R High
.....				
Field experience	R Low	R Low	R Medium	NR



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### ISO 26262 for the automotive industry



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## Draft International Standard ISO 26262

### ISO 26262 Functional Safety – Road Vehicles

- Part 1: Vocabulary
- Part 2: Management of functional safety
- Part 3: Concept phase
- Part 4: Product development: system level
- Part 5: Product development: hardware level
- Part 6: Product development: software level
- Part 7: Production and operation
- Part 8: Supporting processes
- Part 9: ASIL-oriented and safety-oriented

*350 pages*

*550 requirements*



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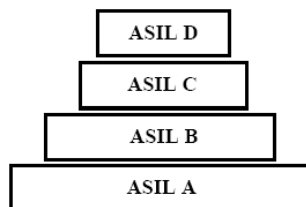
## Motivation for a sector-specific standard

- Control and safety functions usually inseparable (not separate safety functions)
- Mass-market products, not low-volume
- How to handle subcontracting?
- Life cycle: Validation before start-of-production (not validation before installation)
- Risk analysis for road vehicles
- "Techniques and measures" more suitable for road vehicles
- Human factors, driver part of the control loop



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## Automotive Safety Integrity Level



Draft standard ISO 26262

- All safety-related functions are expected to be assigned to an ASIL.
- ASIL D provides the highest risk reduction.



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## ASIL and Risk Classification (draft ISO 26262)

		C1	C2	C3
S1	E1	QM	QM	QM
	E2	QM	QM	QM
	E3	QM	QM	A
	E4	QM	A	B
S2	E1	QM	QM	QM
	E2	QM	QM	A
	E3	QM	A	B
	E4	A	B	C
S3	E1	QM	QM	A
	E2	QM	A	B
	E3	A	B	C
	E4	B	C	D

- QM: Quality management => 26262 not applicable



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## Examples of Hazard Analysis Using ISO 26262

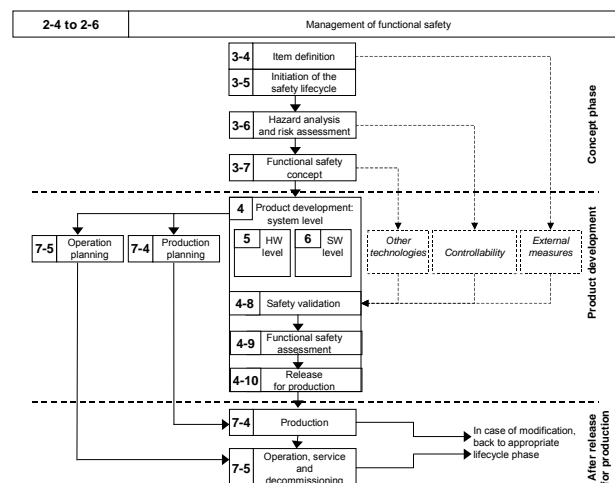
- Airbag
  - Loss of airbag functionality in a crash situation is typically QM or ASIL A
  - Unintended airbag activation under normal driving is typically ASIL B or C
- Brake-by-wire
  - Unintended braking with maintained stability is typically ASIL B or C
  - Unintended braking on single wheel is typically ASIL D
  - Total symmetric loss of brake function (assume p-brake and engine-brake) is typically ASIL D
- Steer-by-wire
  - Loss of steer-by-wire functionality (S3, C3 and E4) gives ASIL D
- Head-lights
  - Loss of high-beam (assume low-beam functional) (S2, E3, C1) gives ASIL A

N.B. The hazard analysis may be different for other vehicles, drivers or traffic situations.  
The above are only examples. There is no “always true ASIL”.



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## Safety lifecycle according to draft ISO 26262



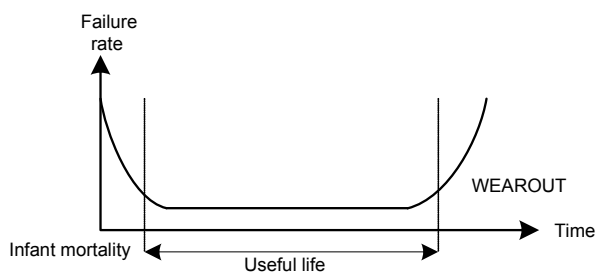
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## Failure rate



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## Failure rate as a function of time



- Electronic components can be often described by the above curve.
- The failure rate is assumed constant during the useful life.
- Exponential distribution is assumed.

$$f(t) = \lambda e^{-\lambda t} \quad \text{"Exponential probability density function"}$$



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## Safe/dangerous and detected/undetected faults

The failure rate may be described through the consequences of a fault

S – Safe

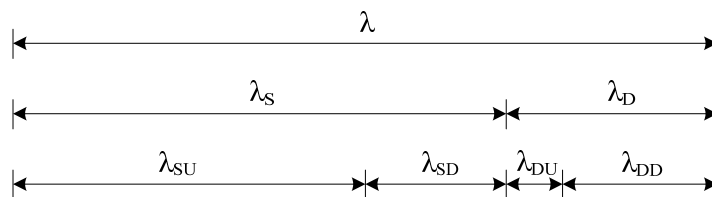
D – Dangerous

SU – Safe Undetected

SD – Safe Detected

DU – Dangerous Undetected

DD – Dangerous Detected



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## Diagnostic Coverage

- "fractional decrease in the probability of dangerous hardware failures resulting from the operation of the automatic diagnostic tests"

$$DC = \frac{\sum \lambda_{DD}}{\sum (\lambda_{DU} + \lambda_{DD})}$$

- $0 \leq DC \leq 100\%$



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## Safe Failure Fraction

- "fraction of the overall random hardware failure rate of a device that results in either a safe failure or a detected dangerous failure"

$$SFF = \frac{\sum \lambda_S + \sum \lambda_{DD}}{\sum \lambda_S + \sum \lambda_{DD} + \sum \lambda_{DU}}$$

- $0 \leq SFF \leq 100\%$



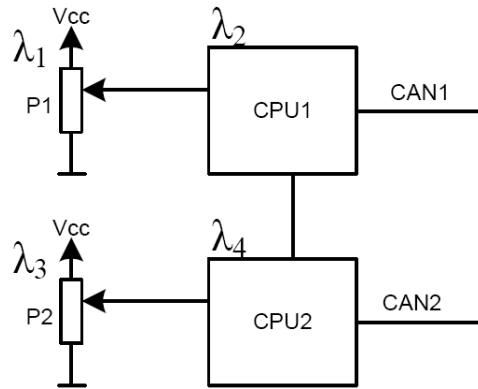
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## An example of calculation of probability of failure



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### Example: Brake pedal sensing



- Failure rates:
- $\lambda_1, \lambda_2, \lambda_3, \lambda_4$
- (Failures/hour)

- What will be the
- total probability of
- dangerous failure
- per hour?



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### Example: Brake pedal sensing

- FMEA Failure Mode and Effects Analysis

Monitoring function	Description
A- Comparison between redundant CPUs	The function continuously compares the potentiometer feedback position values, performs control-flow tests of the CPUs and compares the communication channels. Any deviation between the redundant channels is handled by a special algorithm which forces the most incorrect channel into a passive safe-state.

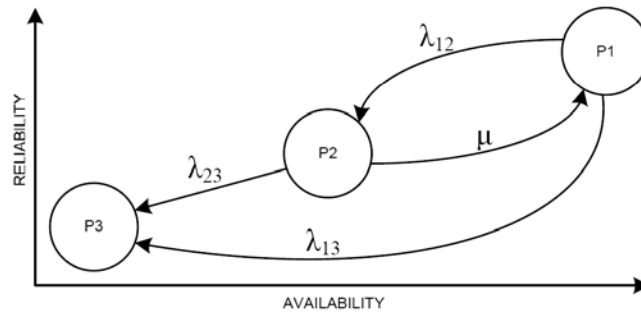
Part 1 – Without considering monitoring functions							Part 2 – Taking the monitoring functions into account	
Comp.	Mode	Rate [FITs]	Distr. [%]	Effect	S [%]	D [%]	Monitoring function.	Coverage [%]
P1	SC	[700]	0.5	Either stuck at max or min position, or reduced range of the potentiometer	10	90	A	90
	OC		25	Floating feedback voltage	50	50	A	90
	D		65	Indicating the wrong position – continuously	30	70	A	90
	F		9.5	Indicating the wrong position - instantaneously	10	90	A	90
CPU1	F	[1300]	100	Indicating the wrong position	50	50	A	90



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### Example: Brake pedal sensing

The Markov model



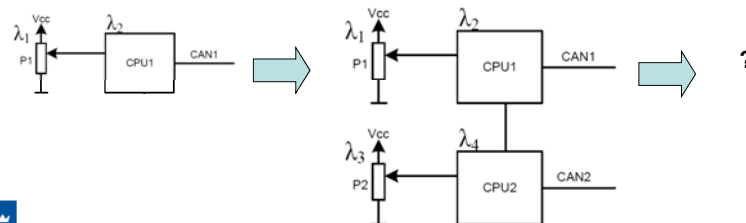
- State P1: Normal operation
- State P2: Degraded operation (Safe-state. Only one channel operating)
- State P3: Dangerous operation



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### Example: Brake pedal sensing

- FMEA, Markov modelling and calculations give
- the probability of failure per hour =  $3,87 \cdot 10^{-7}$
- Will this be acceptable?
- Do we have to reduce the risk further?



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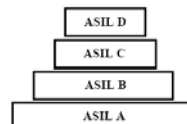
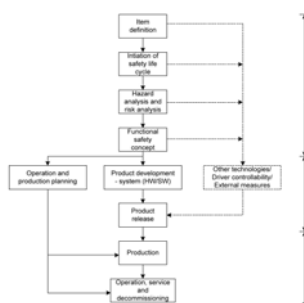
## Experiences regarding dependable systems



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## How to achieve functional safety?

- Overall safety lifecycle
- Risk management
- Safety functions
- Safety Integrity Level
- Avoid faults
- Control faults



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### Some important conclusions

- "Zero risk" can never be achieved
- It is important to understand the risks associated with the system
- Risks impossible to tolerate must be reduced (ALARP)
- Safety thinking must be applied from the beginning
- Correct function does not necessarily imply a safe system



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### Some views on IEC 61508

- The probability-based thinking may be hard to learn
- Not perfect for automotive applications
- Large differences compared with earlier sector-specific standards
- The decision to apply IEC61508 must be taken early in a development project
- An extensive standard, hard for many small or medium-sized organisations to learn
- Large amounts of documentation generated



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## More to read ...



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## Sector-specific standards

- IEC 62061 Machinery
- IEC 61511 Process industry
- IEC 61513 Nuclear industry
- ISO 26262 Road vehicles



Källa: [www.euromation.se](http://www.euromation.se)



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### More to read ...

[www.iec.ch/functionalsafety](http://www.iec.ch/functionalsafety)

(the web site of the International Electrotechnical Commission includes "A basic guide" och FAQ)

<http://www.sp.se/en/index/research/safeprod/Sidor/default.aspx>

(SafeProd - a research project on functional safety in complex products)

DS-håndbog 148:2004, *Functional Safety* at DKK 712,-.

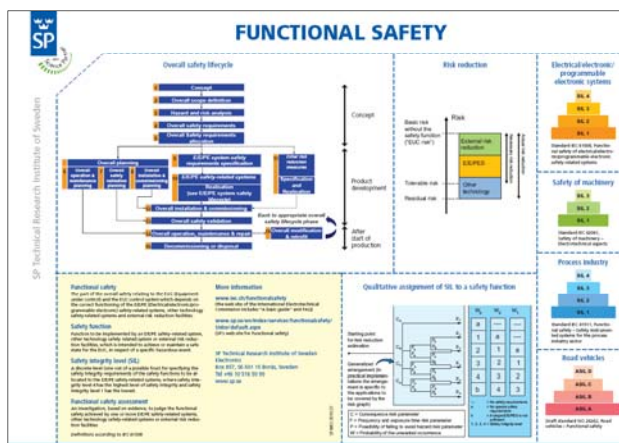
([www.ds.dk](http://www.ds.dk))



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### Functional Safety poster

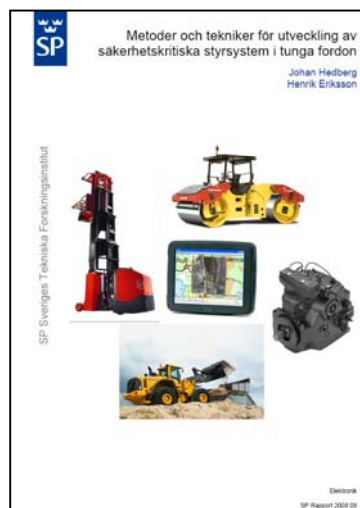
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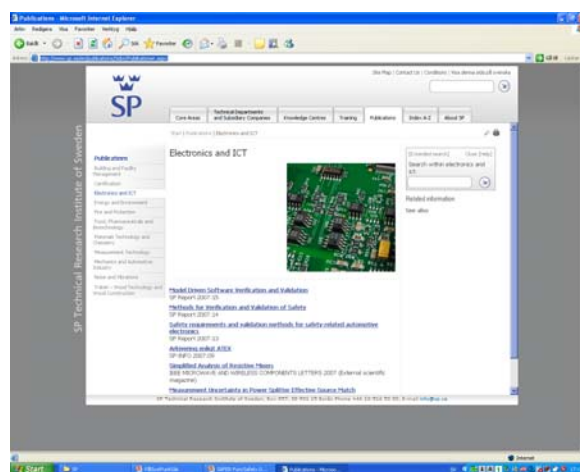
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2007:14  
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- To be found at [www.sp.se](http://www.sp.se) under "Publications" and "Electronics and ICT"

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