

Lecture 2 Domain Specific Embedded Languages

Patrik Jansson
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(slides by Norell and Bernardy)

Anatomy of a DSEL

- A set of types modeling concepts in the domain
- *Constructor functions* constructing elements of these types
- *Combinators* combining and modifying elements
- *Run functions* making observations of the elements

`newtype Signal a = Signal (Time -> a)`

`constS :: a -> Signal a`
`timeS :: Signal Time`

`($$) :: Signal (a -> b) -> Signal a -> Signal b`
`mapS :: (a -> b) -> Signal a -> Signal b`

`sample :: Signal a -> (Time -> a)`

Primitive and Derived operations

- A *primitive operation* is defined exploiting the definitions of the involved types

`timeS :: Signal Time`
`timeS = Signal (\t -> t)`

- A *derived operation* can be defined purely in terms of other operations

`mapS :: (a -> b) -> Signal a -> Signal b`
`mapS f s = constS f $$ s`

Try to keep the set of primitive operations as small as possible! (Why?)

Think about

Answer: Awkwardly!
`addS x y = mapS (\t -> sample x t + sample y t) timeS`

- **Compositionality**
 - Combining elements into more complex ones should be easy and natural

Suppose we didn't have `($$)` in our Signal language. How would you define `addS x y = constS (+) $$ x $$ y`

- **Abstraction**
 - The user shouldn't have to know (or be allowed to exploit) the underlying implementation of your types

Changing implementation shouldn't break user code!

Implementation of a DSEL

- **Shallow embedding**
 - Represent elements by their semantics (what observations they support)
 - Constructor functions and combinators do most of the work, run functions for free
- **Deep embedding**
 - Represent elements by how they are constructed
 - Most of the work done by the run functions, constructor functions and combinators for free
- Or something in between...

Is the signal library a deep or shallow embedding?

A deep embedding of Signals

`data Signal a where`
`ConstS :: a -> Signal a`
`TimeS :: Signal Time`
`(:$$) :: Signal (a -> b) -> Signal a -> Signal b`

Generalized Algebraic Datatype (GADT). More on these in another lecture.

`constS = ConstS`
`timeS = TimeS`
`($$) = (:$$)`

Simple constructors and combinators.

`sample :: Signal a -> (Time -> a)`
`sample (ConstS x) = const x`
`sample TimeS = id`
`sample (f :$$ x) = \t -> sample f t $ sample x t`

All the work happens in the run function.

-- Start of derived operations
`mapS :: (a -> b) -> Signal a -> Signal b`
`mapS f x = constS f $$ x`

Derived operations are unaffected by implementation style.

Deep vs. Shallow

- A shallow embedding (when it works out) is often more elegant
 - When there is an obvious semantics, embeddings usually work out nicely!
- A deep embedding is easier to extend
 - Adding new operations
 - Adding new run functions
 - Adding optimizations

Like in the Signal example

Working out the type might be very difficult...

Most of the time you get a mix between deep and shallow!

Deep embedding may give you an easier start

More on this in another lecture.

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Case Study: A language for Shapes

- Step 1: Design the interface

```

type Shape
-- Constructor functions
empty :: Shape
circle :: Shape
square :: Shape
-- Combinators
translate :: Vec -> Shape -> Shape
scale :: Vec -> Shape -> Shape
rotate :: Angle -> Shape -> Shape
Union :: Shape -> Shape -> Shape
intersect :: Shape -> Shape -> Shape
difference :: Shape -> Shape -> Shape
-- Run functions
inside :: Point -> Shape -> Bool
    
```

Unit circle and unit square. Use translate and scale to get more interesting circles and rectangles.

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Interface, continued

- Think about primitive/derived operations
 - No obvious derived operations
 - Sometimes introducing additional primitives makes the language nicer

```

invert :: Shape -> Shape
transform :: Matrix -> Shape -> Shape
    
```

We need a language for working with matrices!

```

scale :: Vec -> Shape -> Shape
scale v = transform (matrix (vecX v) 0 0 (vecY v))
    
```

```

rotate :: Angle -> Shape -> Shape
rotate a = transform (matrix (cos a) (-sin a) (sin a) (cos a))
    
```

```

difference :: Shape -> Shape -> Shape
difference a b = a `intersect` invert b
    
```

Do you remember your linear algebra course?

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Side track: A matrix library

```

type Matrix
type Vector
type Point

-- Constructor functions
point :: Double -> Double -> Point
vec :: Double -> Double -> Vec
matrix :: Double -> Double -> Double -> Double -> Matrix
-- Combinators
mulPt :: Matrix -> Point -> Point
mulVec :: Matrix -> Vec -> Vec
inv :: Matrix -> Matrix
subtract :: Point -> Vec -> Point
-- Run functions
ptX, ptY :: Point -> Double
vecX, vecY :: Vec -> Double
    
```

This should do for our purposes.

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Shallow embedding

- What are the observations we can make of a shape?
 - inside :: Point -> Shape -> Bool
 - So, let's go for

```

newtype Shape = Shape (Point -> Bool)
    
```

```

inside :: Point -> Shape -> Bool
inside p (Shape f) = f p
    
```

In general, it's not this easy. In most cases you need to generalize the type of the run function a little to get a compositional shallow embedding.

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Shallow embedding, cont.

- If we picked the right implementation the operations should now be easy to implement

Trick: move the point instead of the shape

```

empty = Shape $ \p -> False
circle = Shape $ \p -> ptX p ^ 2 + ptY p ^ 2 <= 1
square = Shape $ \p -> abs (ptX p) <= 1 && abs (ptY p) <= 1

transform m a = Shape $ \p -> mulPt (inv m) p `inside` a
translate v a = Shape $ \p -> subtract p v `inside` a

union a b = Shape $ \p -> inside p a || inside p b
intersect a b = Shape $ \p -> inside p a && inside p b
invert a = Shape $ \p -> not (inside p a)
    
```

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Deep embedding

- Representation is easy, just make a datatype of the primitive operations

```
data Shape where
  -- Constructor functions
  Empty  :: Shape
  Circle :: Shape
  Square :: Shape
  -- Combinators
  Translate :: Vec -> Shape -> Shape
  Transform :: Matrix -> Shape -> Shape
  Union     :: Shape -> Shape -> Shape
  Intersect :: Shape -> Shape -> Shape
  Invert    :: Shape -> Shape

empty = Empty; circle = Circle; ...
```

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Deep embedding

- ... the same datatype without GADT notation:

```
data Shape = Empty | Circle | Square
           | Translate Vec Shape
           | Transform Matrix Shape
           | Union Shape Shape | Intersect Shape Shape
           | Invert Shape

empty  = Empty
circle = Circle
translate = Translate
transform = Transform
union    = Union
intersect = Intersect
invert   = Invert
```

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Deep embedding, cont.

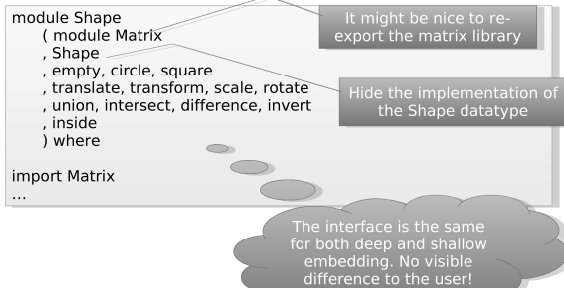
- All the work happens in the run function:

```
inside :: Point -> Shape -> Bool
p `inside` Empty      = False
p `inside` Circle     = ptX p ^ 2 + ptY p ^ 2 <= 1
p `inside` Square     = abs (ptX p) <= 1 && abs (ptY p) <= 1
p `inside` Translate v a = subtract p v `inside` a
p `inside` Transform m a = mulPt (inv m) p `inside` a
p `inside` Union a b   = inside p a || inside p b
p `inside` Intersect a b = inside p a && inside p b
p `inside` Invert a   = not (inside p a)
```

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Abstraction!



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More interesting run function: render to ASCII-art

```
module Render where

import Shape

data Window = Window
  { bottomLeft :: Point
  , topRight   :: Point
  , resolution :: (Int, Int)
  }

defaultWindow :: Window
pixels :: Window -> [[Point]]

render :: Window -> Shape -> String
render win a = unlines $ map (concatMap putPixel) (pixels win)
  where
    putPixel p | p `inside` a = "[]"
               | otherwise   = "  "
```

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Some action

```
module Animate where

import Shape
import Render
import Signal

animate :: Window -> Time -> Time -> Signal Shape -> IO ()
```

- Go live!

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Discussion

- Adding coloured shapes
 - Go back and discuss what changes would need to be made
- Bad shallow implementations
 - Looking at the render run function we might decide to go for
- Other questions/comments..?

```
newtype Shape = Shape (Window -> String)
```

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Summary

- Different kinds of operations
 - constructor functions / combinators / run functions
 - primitive / derived
- Implementation styles
 - Shallow - representation given by semantics
 - Deep - representation given by operations
- Remember
 - Compositionality
 - Abstraction

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