### Chalmers | GÖTEBORGS UNIVERSITET

# Concurrent Programming TDA384/DIT392

13 March 2023

Exam supervisor: G. Schneider (gersch@chalmers.se, 072 974 49 64) (Exam set by G. Schneider, based on the course given Jan-Mar 2023)

#### Material permitted during the exam (hjälpmedel):

Two textbooks; four sheets of A4 paper with notes (single or double-sided); English dictionary (no smart phones allowed).

**Grading:** You can score a maximum of 70 points. Exam grades are:

$\mathbf{points}$	in exam	$\mathbf{Grade}$
	28-41	3
	42 - 55	4
	56 - 70	5

Passing the course requires passing the exam and passing the labs. The overall grade for the course is determined as follows:

points in exam $+$ lab	os Grade
40-5	59 3
60-7	79 4
80-10	00 5

The exam **results** will be available in Ladok within 15 working days after the exam's date.

#### Instructions and rules:

- Please write your answers clearly and legibly: unnecessarily complicated solutions will lose points, and answers that cannot be read will receive no points!
- Justify your answers, and clearly state any assumptions that your solutions may depend on for correctness.
- Answer each question on a new page. Glance through the whole paper first; five questions, numbered Q1 through Q5. Do not spend more time on any question or part than justified by the points it carries.
- Be precise. In your answers, try to use the programming notation and syntax used in the questions. You can also use pseudo-code, *provided* the meaning is precise and clear. If need be, explain your notation.

Q1 (18p). This question is concerned with Peterson's algorithm (as seen in Lecture 3).

#### (Part a). (8p)

Fig. 1 shows Peterson's algorithm for 2 threads.

```
boolean[] enter = {false, false};
                                       int yield = 0 || 1;
           thread t_0
                                          thread t_1
while (true) {
                               while (true) {
                                                               10
                                // entry protocol
 // entry protocol
                                                              11
 enter[0] = true;
                                enter[1] = true;
                                                              12
 yield = 0;
                                yield = 1;
                                                              13
 await (!enter[1]
                        await (!enter[0]
                                       yield != 1);
       yield != 0);
critical section { ... }
                                critical section { ... }
                                                              15
// exit protocol
                                // exit protocol
                                                              16
enter[0] = false;
                                enter[1] = false;
                                                              17
}
                               }
                                                              18
```

Figure 1: Q1:Peterson's Algorithm for 2 threads.

Would the algorithm be correct if we make the simultaneous replacements below?

- Line 3 is replaced by enter[1] = true
- Line 12 is replaced by enter[0] = true
- Line 8 is replaced by enter[1] = false
- Line 17 is replaced by enter[0] = false

Justify your answer. If the answer is NO, explain what would be the new behaviour): give a concrete execution trace showing why this not the case. If the answer is YES, explain it.

### (Part b). (10p)

Does the generalised Peterson's algorithm (for n threads, shown in Fig. 2) when instantiated with n=2 behaves the same as Peterson's algorithm for 2 threads? If so, set n=2 in the generalised algorithm and explain how you get the original algorithm for 2 threads. You need to justify your answer (do not just give the instantiation of the algorithm).

```
int[] enter = new int[n]; // n elements, initially all 0s
     int[] yield = new int[n]; // use n - 1 elements 1..n-1
                           thread x
   while (true) {
    // entry protocol
    for (int i = 1; i < n; i++) {
      enter[x] = i; // want to enter level i
4
      yield[i] = x; // but yield first
5
6
      await (\forall t != x: enter[t] < i
             | | yield[i] != x);
7
    critical section { ... }
8
    // exit protocol
9
    enter[x] = 0; // go back to level 0
```

Figure 2: Q1:Generalised Peterson's Algorithm (for n threads).

Q2 (18p). This question is concerned with a car production line in which some robots produce brake pedals and put them on a circular belt. These pedals are taken by other robots along the production line and pass it on to be assembled in the car. Brake producer robots are called makers and the ones taking the brakes from the belt are called users.

The belt has a capacity Max and it is not possible to add more pedals if the belt is full. (Max is strictly positive, i.e., Max>0) Similarly, no user can take a pedal from the belt if this is empty.

You can assume that there are m makers and n users (n, m > 0).

A programmer who did not took the Principles of Concurrent Programming course was in charge of writing a program to handle the above with the explicit instruction that the program should be deadlock-free, starvation-free and it should work for an arbitrary number of makers and users. The programmer wrote the code in Fig. 3 defining a class Belt and two methods for putting pedals in the belt (put) and taking pedals from the belt (take).

```
(belt is defined as: Belt⟨pedal⟩ belt)
  public class Belt<T> {
    Semaphore nPedals = new Semaphore(0);
   Semaphore nFree = new Semaphore (Max);
   Lock lock = new Lock();
   Collection store = ...; // implem. of a collection of pedals
                                   8 public T take() {
public void put(T pedal) {
                                   9 lock.lock();
  nFree.down();
                                   nPedals.down();
  lock.lock();
                                   11 T pedal = store.remove();
   store.add(pedal);
                                   nFree.up();
  lock.unlock();
                                   13 lock.unlock();
  nPedals.up();
                                   14 return pedal;
7 }
                                   15 }
```

Figure 3: Q2: Car production code for makers and users.

Besides the shown code, there is a main program that creates m threads for makers and n threads for users. Each maker keeps creating pedals and putting them into the belt by calling belt.put(pedal) where users keep taking them from the belt by calling pedal = belt.take() and then passing them to the rest of the production line.

In what follows there are a number of assertions and questions. Please answer each one of them and justify your answer. A partially correct answer will not be given full points.

- 1 Is the following statement true or false: The program is correct but will only work if you have exactly the same amount of *makers* and *users*. Justify your answer. (2p)
- 2 Is the program deadlock-free? If it is, explain why this is the case. If not, explain which parts of the code are wrong, correct it and give a concrete execution trace showing the deadlock. (5p)
- 3 Is the following statement true or false: "Lines 5 and 6 should not be swapped because it might produce a deadlock"? Justify your answer. (3p)
- 4 Is the following statement true or false: "Swapping lines 12 and 13 is OK as the program will not deadlock"? Justify your answer. (3p)
- 5 The manager of the programmer claims that the program allows makers to add more pedals into the belt than its capacity. Is that true? Justify. (3p)
- 6 Is the following statement true or false: A correct implementation of the problem can be done with only one semaphore and one lock. Justify your answer. (2p)

Q3 (9p). A programmer has written the program below asserting that it guarantees mutual-exclusion between two processes. The solution is based on a *compare-and-set* (CAS) operation.

```
boolean turn= false; boolean flaga= false; boolean flagb= false;
     while(true) {
                                             while(true) {
       //NCS (non-critical section)
                                               //NCS (non-critical section)
p_1
                                        q_1
        flaga = true;
                                               flagb= true;
p_2:
                                        q_2:
       while(!turn.CAS(false,true)
                                               while(!turn.CAS(false,true)
p_3:
                                        q_3:
                     && flagb) { };
                                                            && flaga) \{ \};
        //CS (critical section)
                                               //CS (critical section)
p_4
                                        q_4
       turn= flaga= false;
                                               turn=flagb= false;
p_5:
                                        q_5:
```

For simplicity, we ignore the locations  $p_1$  and  $p_4$  and similarly  $q_1$  and  $q_4$ . Process p moves directly from  $p_3$  to  $p_5$  and from  $p_5$  to  $p_2$  and similarly for q. We treat  $p_5$  and  $q_5$  as the critical section.

## (Part a). (4p)

A full state of the program is of the form  $(p_i, q_j, \text{flaga}, \text{flagb}, \text{turn})$ , where i and j range over  $\{2, 3, 5\}$ , and flaga, flagb, and turn range over true and false.

Below you find a partial state transition table for the program above. Only 8 states are reachable from the initial state  $(p_2, q_2, f, f, f)$ .

Your task is to fill in the blank entries in the table.

	state	new state if p moves	new state if q moves
s1	(2,2,f,f,f)		(2,3,f,t,f) = s2
s2	(2,3,f,t,f)		
s3	(3,2,t,f,f)		
s4	(3,3,t,t,f)	(5,3,t,t,t) = s7	
s5	(2,5,f,t,t)		
s6	(5,2,t,f,t)		(5,3,t,t,t) = s7
s7	(5,3,t,t,t)		
s8	(3,5,t,t,t)		

(Part b). (2p) Does the protocol maintain mutual exclusion? Justify your answer.

(Part c). (3p) Consider the condition !turn.CAS(false, true)&&flaga guarding the loop for process q. Does the second conjunct (flaga) plays any role in the evaluation of the condition? Justify your answer.

Q4 (15p). The reduce function is a high-order function that can be defined in Erlang as follows:

```
reduce(_,A,[]) -> A;
reduce(F,A,[H|T]) -> F(H,reduce(F,A,T)).
```

We have seen the following parallel implementation of the reduce function in Lecture 9:

```
preduce(_, A, []) -> A;
preduce(F, A, [E]) -> F(A, E);
preduce(F, A, List) ->
    Mid = length(List) div 2,
    {L, R} = lists:split(Mid, List),
    Me = self(), % L ++ R =:= Listn
    Lp = spawn(fun() -> % on left half
        Me ! {self(), preduce(F, A, L)} end),
    Rp = spawn(fun() -> % on right half
        Me ! {self(), preduce(F, A, R)} end),
    % combine results of left, right half
    F(receive {Lp, Lr} -> Lr end, receive {Rp, Rr} -> Rr end).
```

## (Part a). (4p)

Apply both reduce and preduce to the list L = [2,4] with initial value 0 for A, where F is the plus/2 function defined as follows:

```
plus (X,Y) \rightarrow X+Y.
```

That is, write down ("simulate") the execution of the following calls: reduce(plus/2,0,[2,4]) and preduce(plus/2,0,[2,4]).

```
(Part b). (5p)
```

Does preduce always give the same answer as reduce when applied to the same function F, element A and list L? If so, explain how preduce is indeed a correct parallel implementation of reduce. If not, explain why is not the case and what is required for preduce to be a fully correct implementation of the original function. In case you answer that both functions may not compute the same thing, give a concrete example that shows the difference.

```
(Part c). (6p)
```

In preduce, why is A used in both sublists calls (left and right)? Wouldn't that mean that the function F will apply A on every element of the list and give a result different from the expected? Justify your answer (you can use Part a) and b) above as a way to explain your answer.)

Q5 (10p). A solution to concurrently access a list is to use a coarse-locking method, locking all elements of the list. In lecture 10 we saw that though this works it is not satisfactory since the access is essentially sequential, and we gave different alternative approaches. This question is about fine-grained locking.

Below it follows statements and situations concerning parallel linked lists implementing sets being accessed by 2 threads  $t_0$  and  $t_1$ . As in our lecture, we assume that the linked list is sorted by key.

(Part a) (4p) Answer whether the statements below concerning finegrained locking are true or false. Justify your answer in each case (an answer without justification would not be granted full points).

- 1) In order to guarantee that the concurrent access works well (i.e., there are no inconsistencies), it is enough that both threads lock only their *pred* pointed node when executing the find method. (2p)
- 2) If there are too many threads executing the validation process (to ensure no two threads are accessing the same node at the same time), the fine-grained locking does not work and inconsistencies may arise. (2p)

(Part b) (6p) A programmer has been given the task to implement the find method for a fine-grained locking solution (without validation) to access a parallel linked list. The programmer took an existing solution and slightly modified it, producing the following code:

```
1 protected Node<T>, Node<T> find(Node<T> start, int key) {
 2
     Node<T> pred, curr;
     pred = start; curr = start.next();
 3
     pred.lock();
 4
     while (curr.key < key) {</pre>
 5
 6
         curr.lock();
 7
         pred.unlock();
 8
         pred = curr;
 9
         curr = curr.next();
10
         curr.unlock();
      }
11
12 return (pred, curr);
13 }
```

The supervisor is not happy at all with the solution of the programmer claiming that the code is not correct.

Explain why the solution is wrong and provide a correct version so the find method can be used as expected in a fine-grained locking algorithm (with no validation).