# Subjective probability and utility

Christos Dimitrakakis

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### 1 Introduction

### 2 Types of probability

- Relative likelihood
- Subjective probability assumptions
- Conditional likelihoods

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### Goals of today's (?) lecture

### Subjective probability

- Understand the different interpretations of probability.
- Refresh the mathematical properties of probability.
- Understand how to use probability to represent your beliefs.
- Show why probability is the right thing for this job.
- See how you can update your beliefs using probability.

### Utility

- Understand the concept of preferences.
- See how utility can be used to formalize preferences.
- Show how we can combine utility and probability to deal with decision making under uncertainty.

#### The decision-theoretic foundations of artificial intelligence.

- Probability: how likely things are?
- Utility: which things do we want?

#### Interpretations of probability

- Objective: inherent randomness.
- Frequentist: long-term averages.
- Algorithmic: program complexity.
- Subjective: uncertainty.

#### Interpretations of utility

- Monetary.
- Psychological.
- "true" value of things?

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# **Objective Probability**



Figure : The double slit experiment

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■ Consider a binary string *x* = 10101000101110100101010101.

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- Intuitively, do you think that
  - A x is more likely than y.
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  - D The question is meaningless.

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Intuitively, y is "simpler"... perhaps it's generated by an algorithm! But which algorithm?

### Solomonoff induction

- Occam's razor: Prefer the simplest explanation (algorithm).
- Epicurus: Do not throw away any hypothesis (algorithm).
- Weigh algorithms according to
  - Simplicity.
  - How well they fit the data.

What about everyday life?

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Making decisions requires making predictions.

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- Making decisions requires making predictions.
- Outcomes of decisions are uncertain.

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### Subjective probability

- Describe which events we think are more likely.
- We quantify this with probability.

### Why probability?

- Quantifies uncertainty in a "natural" way.
- A framework for drawing conclusions from data.
- Computationally convenient for decision making.

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Example 1 (Experiment: give medication to a patient.)

- Does the patient recover?
- Does the medication have side-effects?

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The relative likelihood of two events A and B

- Do you think A is more likely than B? Write  $A \succ B$ .
- Do you think A is less likely than B? Write  $A \prec B$ .
- Do you think A is as likely as B? Write A = B.

We also use  $\succsim$  and  $\precsim$  for at least as likely as and for no more likely than.

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#### Functions on sets

A function *P* is said to agree with a relation  $A \preceq B$ , if it has the property that:  $P(A) \leq P(B)$  if and only if  $A \preceq B$ .

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We want such a function for all events of interest.



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#### Definition 2 ( $\sigma$ -field on S)

A family  $\mathcal{F}$  of sets, s.t.  $\forall A \in \mathcal{F}, A \subset \mathcal{S}$ , is called a  $\sigma$ -field on  $\mathcal{S}$  if and only if

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**1** 
$$S \in F$$
  
**2** if  $A \in F$ , then  $A^{\complement} \in F$ .

If 
$$A_i \in \mathcal{F}$$
 for  $i = 1, 2, ...$  then  $\bigcup_{i=1}^{\infty} A_i \in \mathcal{F}$ .

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1  $\mathcal{S} \in \mathcal{F}$ 

**2** if 
$$A \in \mathcal{F}$$
, then  $A^{\mathsf{L}} \in \mathcal{F}$ .

**3** If 
$$A_i \in \mathcal{F}$$
 for  $i = 1, 2, ...$  then  $\bigcup_{i=1}^{\infty} A_i \in \mathcal{F}$ .

Exercise 1  
Is 
$$\mathcal{F} = \left\{ \emptyset, A_1, A_1^{\complement}, \mathcal{S} \right\}$$
 a  $\sigma$ -field?

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**2** if 
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**3** If 
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 for  $i = 1, 2, ...$  then  $\bigcup_{i=1}^{\infty} A_i \in \mathcal{F}$ .

#### Example 3

The  $\sigma$ -field generated by  $\{\emptyset, A_1, A_2, \mathcal{S}\}$  is:

$$\begin{split} \mathcal{F} &= \{A_1, A_1^\complement, A_2, A_2^\complement, \\ A_1 \cap A_2, (A_1 \cap A_2)^\complement, A_1 \cup A_2, (A_1 \cup A_2)^\complement, A_2, \\ A_2 \backslash A_1, A_1 \backslash A_2, (A_2 \backslash A_1)^\complement, (A_1 \backslash A_2)^\complement, \emptyset, \mathcal{S} \}. \end{split}$$

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Our beliefs must be consistent. This can be achieved if they satisfy some assumptions:

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Assumption 1 (SP1)

For any events A, B, one of the following must hold:  $A \succ B$ ,  $A \prec B$ ,  $A \equiv B$ .

It is always possible to say whether one event is more likely than the other.

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Assumption 1 (SP1)

For any events A, B, one of the following must hold:  $A \succ B$ ,  $A \prec B$ ,  $A \equiv B$ .

Assumption 2 (SP2)

Let  $A = A_1 \cup A_2$ ,  $B = B_1 \cup B_2$  with  $A_1 \cap A_2 = B_1 \cap B_2 = \emptyset$ . If  $A_i \preceq B_i$  then  $A \preceq B$ .

If we can split A, B in such a way that each part of A is less likely than its counterpart in B, then A is less likely than B.

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Assumption 3 (SP3)

For any event A, we have:  $\emptyset \preceq A$  For the certain event S, we have:  $\emptyset \prec S$ .

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# Resulting properties of relative likelihoods

### Theorem 4 (Transitivity)

If A, B, D such that  $A \preceq B$  and  $B \preceq D$ , then  $A \preceq D$ .

#### Theorem 5 (Complement)

For any  $A, B: A \preceq B$  iff  $A^{\complement} \succeq B^{\complement}$ .

Theorem 6 (Fundamental property of relative likelihoods)

If  $A \subset B$  then  $A \preceq B$ . Furthermore,  $\emptyset \preceq A \preceq S$  for any event A.

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What functions can agree with a relative likelihood?

- For any events P(A) > P(B), P(A) < P(B) or P(A) = P(B).
- If  $A_i$ ,  $B_i$  are disjoint sets,  $\forall i : P(A_i) \leq P(B_i) \Rightarrow P(A) \leq P(B)$ .
- For any A,  $P(\emptyset) \leq P(A)$  and  $P(\emptyset) < P(S)$ .

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### Measure theory primer



Figure : A fashionable apartment

Measure the sets:  $\mathcal{F} = \{\emptyset, A, B, C, A \cup B, A \cup C, B \cup C, A \cup B \cup C\}$ . Note that all those measures have an additive property.

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# Measure theory primer



Figure : A fashionable apartment

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# Measure and probability

## Definition 7 (Measure)

# A measure $\lambda$ on $(\mathcal{S},\mathcal{F})$ is a function $\lambda:\mathcal{F} o\mathbb{R}^+$ such that

- 1  $\lambda(\emptyset) = 0.$
- 2  $\lambda(A) \geq 0$  for any  $A \in \mathcal{F}$ .

**3** For any collection of subsets  $A_1, A_2, \ldots$  with  $A_i \in \mathcal{F}$  and  $A_i \cap A_j = \emptyset$ .

$$\lambda\left(\bigcup_{i=1}^{\infty}A_{i}\right)=\sum_{i=1}^{\infty}\lambda(A_{i})$$
(2.1)

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# Measure and probability

## Definition 7 (Probability measure)

A probability measure P on  $(\mathcal{S}, \mathcal{F})$  is a function  $P : \mathcal{F} \to [0, 1]$  such that:

- **1** P(S) = 1
- **2**  $P(\emptyset) = 0$
- $P(A) \geq 0 \text{ for any } A \in \mathcal{F}.$
- 4 If  $A_1, A_2, \ldots$  are disjoint then

$$P\left(\bigcup_{i=1}^{\infty}A_i\right) = \sum_{i=1}^{\infty}P(A_i)$$
 (union)

 $(S, \mathcal{F}, P)$  is called a *probability space*.

So, probability is just a special type of measure.

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# Logical interpretation: Mutually exclusive and independent events



#### Definition 8 (Mutually exclusive events)

If A, B are disjoint (i.e.  $A \cap B = \emptyset$ ) then they are *mutually exclusive*. Since P is a measure,

$$P(A \cup B) = P(A) + P(B).$$

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# Logical interpretation: Mutually exclusive and independent events



## Definition 8 (Independent events)

Events A, B are independent iff

$$P(A \cap B) = P(A)P(B). \tag{2.1}$$

Thus, the probability of either A occuring does not depend on whether B occurs.

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Logical interpretation: Mutually exclusive and independent events

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### Exercise 1

Can mutually exclusive events be independent?

You can think of  $A \cap B$  as  $A \wedge B$ , i.e. "A and B". You can think of  $A \cup B$  as  $A \vee B$ , i.e. "A or B". A probability measure can satisfy our assumptions

#### Exercise 2

- (i) For any events P(A) > P(B), P(A) < P(B) or P(A) = P(B).
- (ii) If  $A_i$ ,  $B_i$  are partitions of A, B,  $\forall i P(A_i) \leq P(B_i) \Rightarrow P(A) \leq P(B)$ .
- (iii) For any A,  $P(\emptyset) \leq P(A)$  and  $P(\emptyset) < P(S)$

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## From events to variables

Let  $\omega \sim P$  denote that  $\omega$  is selected according to P.

#### Events as indicator functions

Until now we were just considering simple events: where  $\omega \in A$ . Each event A can be seen as a functions  $\mathscr{K}_A : S \to \{0, 1\}$ 

$$\mathbb{I}_{\mathcal{A}}(\omega) = egin{cases} 1, & \omega \in \mathcal{A} \ 0, & ext{otherwise} \end{cases}$$

Then the probability that  $\omega \in A$  is simply P(A).

#### Definition 10 (Random variable)

However, we can also define some arbitrary other function  $x : S \to \mathbb{R}$ . This function is called a random variable, because it is a variable whose value depends on the random outcome  $\omega$ .

# Example 11 (Functions of the patient state) Temperature, blood pressure, heart rate, ...

## Probabilities and expectations of random variables

Given a random variable  $x : S \to \mathbb{R}$ , we can naturally ask things such as what value x takes on average:

Definition 12 (Expectation of a random variable)

If  $\omega \sim P$ , then:

$$\mathbb{E}_{P}(x) \triangleq \sum_{\omega \in S} x(\omega) P(\omega) \qquad (\text{discrete case})$$

(general case)

(For the discrete case, it is usual to write  $P(\omega)$  to mean  $P(\{\omega\})$ ).

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$$\mathbb{E}_{P}(x) \triangleq \int_{S} x(\omega) \, \mathrm{d}P(\omega) \qquad (\text{general case})$$

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Definition 13 (Distribution of a random variable)

If  $\omega \sim P$ , then  $x \sim P_x$  with:

$$P_x(A) \triangleq \sum_{\omega \in S} \mathbb{1}_A(x(\omega))P(\omega)$$
 (discrete case)

# Recap of fundamental probability

- Subjective probability can be used to represent uncertainty.
- Events can be represented as sets in a space of outcomes  $\mathcal{S}$ .
- The set of all possible events  $\mathcal{F}$  is a field in  $\mathcal{S}$ .
- Subjective relative likelihoods of events can be represented by probabilities.
- Probabilities are measures, e.g. similar to area, length, mass, etc.
- Mutually exclusive events are disjoint.
- Independent events have product joint probability.
- Random variables are simply functions on outcomes.
- The expectation of a r.v. is the sum of its values for each outcome, weighed by the outcome's probability.

- A likelihood relation encodes our prior opinions.
- Sometimes we need to take into account evidence.
- For example, ordinarily we may think that  $A \preceq B$ .
- However, we may have additional information *D* ....

## Example 14

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#### Example 14

• Say that A is the event that it rains in Gothenburg tomorrow.

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- Clearly,  $A \succeq A^{\complement}$ .

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- However, we may have additional information *D* ....

#### Example 14

- Say that A is the event that it rains in Gothenburg tomorrow.
- Clearly,  $A \succeq A^{\complement}$ .
- Let *D* denote a good forecast!
- I personally believe that  $(A \mid D) \preceq (A^{\complement} \mid D)$ .

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Assumption 4 (CP)

For any events A, B, D,

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(A \mid D) \precsim (B \mid D) iff A \cap D \precsim B \cap D.
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#### Theorem 15

If a relation  $\leq$  satisfies assumptions SP1 to SP5 and CP, then P is the unique probability distribution such that:

For any A, B, D such that P(D) > 0,

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(A \mid D) \precsim (B \mid D) iff P(A \mid D) \le P(B \mid D)
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Definition 16 (Conditional probability)

$$P(A \mid D) \triangleq \frac{P(A \cap D)}{P(D)}$$
(2.2)

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Forecaster	Saturday	Sunday	Monday	Tuesday
A	Rain	Rain	Rain	Rain
В	Sun	Rain	Rain	Sun
С	Clouds	Clouds	Rain	Storms
D	Sun	Clouds	Rain	Clouds
E	Clouds	Rain	Clouds	Sun
Outcome				

Table : Five weather forecasters

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Forecaster	Saturday	Sunday	Monday	Tuesday
A	Rain	Rain	Rain	Rain
В	Sun	Rain	Rain	Sun
С	Clouds	Clouds	Rain	Storms
D	Sun	Clouds	Rain	Clouds
E	Clouds	Rain	Clouds	Sun
Outcome	Clouds			

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Outcome	Clouds	Rain	Rain	

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Outcome	Clouds	Rain	Rain	Sun

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## Theorem 17 (Bayes' theorem)

Let  $A_1, A_2, ...$  be a (possibly infinite) sequence of disjoint events such that  $\bigcup_{i=1}^n A_i = S$ and  $P(A_i) > 0$  for all *i*. Let *B* be another event with P(B) > 0. Then

$$P(A_i \mid B) = \frac{P(B \mid A_i)P(A_i)}{\sum_{j=1}^{n} P(B \mid A_j)P(A_j)}$$
(2.3)

## Proof.

By definition,  $P(A_i | B) = P(A_i \cap B)/P(B)$ , and  $P(A_i \cap B) = P(B | A_i)P(A_i)$ , so:

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$$P(B) = P\left(\bigcup_{j=1}^{n} (B \cap A_j)\right) = \sum_{j=1}^{n} P(B \cap A_j) = \sum_{j=1}^{n} P(B \mid A_j) P(A_j).$$

# Updating beliefs: addendum

Interpreting Bayes's theorem

$$P(A \mid B) = \frac{P(B \mid A)P(A)}{P(B)}$$

- *P*(*A*): our prior belief that hypothesis *A* is true (use Occam's razor!)
- $P(B \mid A)$ : how much does hypothesis A agree with the evidence B?
- P(B): probability of the evidence B according to all hypotheses (Epicurean principle)
- P(A | B): our posterior belief that hypothesis A is true given evidence B.

#### Exercise 3

Recall that

$$P(A \mid B) \triangleq \frac{P(A \cap B)}{P(B)}$$

is only a definition. Give plausible alternatives.

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Consider the forecasters actually giving probabilities for rain.

Forecaster	Saturday	Sunday	Monday	Tuesday
$A_1$	60%	70%	80%	90%
A <sub>2</sub>	10%	50%	60%	20%
A <sub>3</sub>	20%	25%	40%	100%
$A_4$	10%	15%	30%	25%
$A_5$	30%	40%	35%	10%
Outcome				

Table · Five weather forecasters

Let  $P(A_i) = 1/5$  be our prior belief that  $A_i$  is correct. Then:  $A_1 \mid A_2 \mid A_3 \mid A_4 \mid A_5$ 

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Outcome	Clouds			

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Let  $P(A_i) = 1/5$  be our prior belief that  $A_i$  is correct. Then:  $A_1$  $A_2$  $A_3$  $A_4$  $A_5$ 0.35 0.25 0.13 0.08 0.2

DQC

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Outcome	Clouds	Rain	Rain	Sun

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DQC

# Simplified notation and capturing dependencies

Consider random variables  $x_i : S \to S_i$ , i = 1, ..., n. As a shorthand, especially in computer science, we may write their joint distribution as

$$P(x_1,\ldots,x_n),$$

instead of

 $P_{x_1,\ldots,x_n}(\cdot),$ 

as is usually done in statistics.

Graphs can be used to capture independence between these variables. For example:

 $x_1 \longrightarrow x_2 \longrightarrow x_3$ 

Means that  $P(x_3, x_2, x_1) = P(x_3 | x_2)P(x_2 | x_1)P(x_1)$ 

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#### Marginalisation (variable elimination)

Consider the example network  $P(x_3, x_2, x_1) = P(x_3 \mid x_2)P(x_2 \mid x_1)P(x_1)$ .



This means that to express the joint distribution of the variables  $x_i(\omega)$  we only need to model the conditional distributions  $P(x_i | x_i)$ .

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#### Inference via marginalisation

What is the distribution of  $x_3$ , ignoring the other variables?

$$P(x_3) = \sum_{x_1 \in S_1} \sum_{x_2 \in S_2} P(x_1, x_2, x_3) = \sum_{x_1 \in S_1} \sum_{x_2 \in S_2} P(x_3 \mid x_2) P(x_2 \mid x_1) P(x_1).$$
(2.5)

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This follows from the disjoint property of measures, as illustrated in the proof of Bayes' theorem.

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(2.5)

This follows from the disjoint property of measures, as illustrated in the proof of Bayes' theorem. What is the distribution of  $x_3$ , given  $x_1$ ?

$$P(x_3 \mid x_1) = \sum_{x_2 \in S_2} P(x_2, x_3 \mid x_1) = \sum_{x_2 \in S_2} P(x_3 \mid x_2) P(x_2 \mid x_1)$$
(2.6)

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## Application to Bayesian inference

Consider now that you have a set of models  $\{\mu_i \mid i = 1, ...\}$ , each making a different prediction for tomorrow's weather  $x_{t+1}$ , given the weather in the past  $x_1, ..., x_t$ .

$$P(x_{t+1} \mid x_1, \ldots, x_t, \mu_i)$$

Let  $P(\mu_i)$  be your prior probability on each model. Then the marginal probability is going to be

$$P(x_{t+1}) = \sum_i P(x_{t+1} \mid \mu_i) P(\mu_i).$$

Given some weather observations, you can now estimate a posterior distribution

$$P(\mu_i \mid x_1, \ldots, x_t) = \frac{P(x_1, \ldots, x_t \mid \mu_i) P(\mu_i)}{\sum_j P(x_1, \ldots, x_t \mid \mu_i) P(\mu_j)}$$

You can now calculate a new marginal probability for the weather,

$$P(x_{t+1} \mid x_1,...,x_t) = \sum_i P(x_{t+1} \mid x_1,...,x_t,\mu_i)P(\mu_i \mid x_1,...,x_t).$$

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Abdul Alhazred claims that he is psychic and can always predict a coin toss. You use a fair coin, such that the probability of it coming heads is 1/2. You throw the coin 4 times, and AA guesses correctly all four times. If  $P(A) = 2^{-16}$  is your prior belief that AA is a psychic, then what is your posterior belief (approximately), given that AA has guessed correctly?

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# Recap of conditional likelihood and probability

- Conditional likelihood represents the likelihood of an event given another event.
- If A is a hypothesis, and B is a predicted event, (A | B) is the likelihood of the event under hypothesis A.
- Conditional probabilities  $P(A \mid B)$  can be defined analogously to normal probabilities.
- This gives us a numerical procedure for updating our beliefs about which hypotheses are true.
- This is easy to perform for finite numbers of events and hypotheses.
- Finally, the conditional structure of a problem can be captured via a graph.

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