

# Decision Problems

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## 1 Introduction

## 2 Rewards that depend on the outcome of an experiment

- Formalisation of the problem setting
- Statistical estimation
- Convexity of the Bayes-optimal utility\*

## 3 Decision problems with observations

- Decisions  $d \in \mathcal{D}$
- Experiments with outcomes in  $\Omega$ .
- Reward  $r \in \mathcal{R}$  depending on experiment and outcome.
- Utility  $U : \mathcal{R} \rightarrow \mathbb{R}$ .

### Example 1 (Taking the umbrella)

- There is some probability of rain.
- We don't like carrying an umbrella.
- We **really** don't like getting wet.

- Random outcome  $\omega \sim P$ .
- Decision  $d \in D$

## Definition 2 (Reward function)

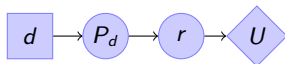
When we take decision  $d$ , then  $\omega$  is randomly chosen, and we obtain a reward:

$$r = \rho(\omega, d). \quad (2.1)$$

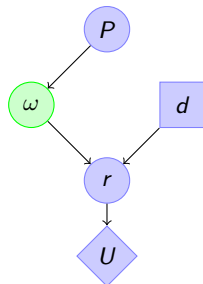
For every  $d \in \mathcal{D}$ , the function  $\rho : \Omega \times D \rightarrow \mathcal{R}$  induces a probability distribution  $P_d$  on  $\mathcal{R}$ .

$$P_d(B) \triangleq P(\{\omega \mid \rho(\omega, d) \in B\}). \quad (2.2)$$

Thus, instead of directly choosing some distribution of rewards, we choose a decision  $d$ , which corresponds to a particular distribution  $P_d$ .



(a) The combined decision problem



(b) The separated decision problem

## Expected utility

$$\mathbb{E}_{P_d}(U) = \sum_{r \in \mathcal{R}} U(r) P_d(r) = \sum_{\omega \in \Omega} U[\rho(\omega, d)] P(\omega). \quad (2.3)$$

### Example 3

You are going to work, and it might rain. The forecast said that the probability of rain ( $\omega_1$ ) was 20%. What do you do?

- $d_1$ : Take the umbrella.
- $d_2$ : Risk it!

$\rho(\omega, d)$	$d_1$	$d_2$
$\omega_1$	dry, carrying umbrella	wet
$\omega_2$	dry, carrying umbrella	dry
$U[\rho(\omega, d)]$	$d_1$	$d_2$
$\omega_1$	0	-10
$\omega_2$	0	1
$\mathbb{E}_P(U \mid d)$	0	-1.2

Table : Rewards, utilities, expected utility for 20% probability of rain.

# Application to statistical estimation

## Example 4 (Voting)

Let us say for example that you wish to estimate the number of votes for different candidates in an election. The *unknown parameters* of the problem mainly include: the percentage of likely voters in the population, the probability that a likely voter is going to vote for each candidate. One simple way to estimate this is by polling.

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## Definition 4 (Simplified expected utility of a given decision)

$$U(P, d) \triangleq \sum_{\omega \in \Omega} U[\rho(\omega, d)]P(\omega). \quad (2.4)$$

## Definition 5 (Bayes-optimal utility)

$$U^*(P) \triangleq \max_d U(P, d) \quad (2.5)$$

# Voting example

- Consider a nation with  $k$  political parties.
- Let  $\omega = (\omega_1, \dots, \omega_k) \in [0, 1]^k$  be the voting percentages for each party.
- We wish to make a guess  $d \in [0, 1]^k$ .
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## Squared error

We can set  $\rho(\omega, d) = (\omega_1 - d_1, \dots, \omega_k - d_k)$ , our error vector  $r \in [0, 1]^k$ . Then we set  $U(r) \triangleq -\|r\|^2$ , where  $\|r\|^2 = \sum_i |x_i|^2$ .

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## Predicting the winner

In that case  $\rho(\omega, d) = 1$  if  $\arg \max_i \omega_i = \arg \max_i d_i$  and 0 otherwise, and  $U(r) = r$ .

## Example 6 (Squared error)

Consider the case  $\Omega = D = \mathbb{R}$ . Our problem is:

$$\max_d U(P, d), \quad U(P, d) \triangleq - \int_{\mathbb{R}} |\omega - d|^2 dP(\omega).$$

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Under some technical assumptions, we can write

$$\frac{\partial}{\partial d} \int_{\mathbb{R}} |\omega - d|^2 dP(\omega) = \int_{\mathbb{R}} \frac{\partial}{\partial d} |\omega - d|^2 dP(\omega)$$

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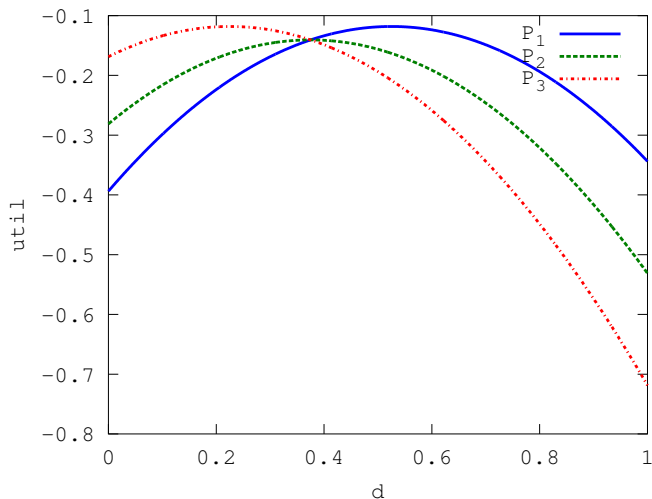
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$$= 2 \int_{\mathbb{R}} d dP(\omega) - 2 \int_{\mathbb{R}} \omega dP(\omega) \quad (2.8)$$

$$= 2d - 2\mathbb{E}(\omega), \quad (2.9)$$

so the optimal decision is  $d = \mathbb{E}(\omega)$ .

# The utility for quadratic loss



**Figure :** Fixed distribution, varying decision. The decision utility under three different distributions.

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These define two alternative distributions for  $\omega$ . For any  $P, Q$  and  $\alpha \in [0, 1]$ , we define

$$Z_\alpha = \alpha P + (1 - \alpha)Q$$

to mean the probability measure such that

$$Z_\alpha(A) = \alpha P(A) + (1 - \alpha)Q(A)$$

for any  $A \in \mathfrak{F}_\Omega$ .

# Convexity of the Bayes-optimal utility

## Theorem 7

For probability measures  $P, Q$  on  $\Omega$  and any  $\alpha \in [0, 1]$ ,

$$U^*[Z_\alpha] \leq \alpha U^*(P) + (1 - \alpha) U^*(Q), \quad (2.10)$$

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Proof.





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## Proof.

From the definition of the expected utility (2.4), for any decision  $d \in \mathcal{D}$ ,

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Hence, by definition (2.5) of the Bayes-optimal utility:

$$U^*(Z_\alpha) = \max_{d \in \mathcal{D}} [\alpha U(P, d) + (1 - \alpha) U(Q, d)].$$



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$$U^*(Z_\alpha) = \max_{d \in D} [\alpha U(P, d) + (1 - \alpha) U(Q, d)].$$

Use  $\max_x [f(x) + g(x)] \leq \max_x f(x) + \max_x g(x)$  to bound r.h.s:

$$U^*[Z_\alpha] \leq \alpha \max_{d \in D} U(P, d) + (1 - \alpha) \max_{d \in D} U(Q, d)$$



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# Convexity of the Bayes utility

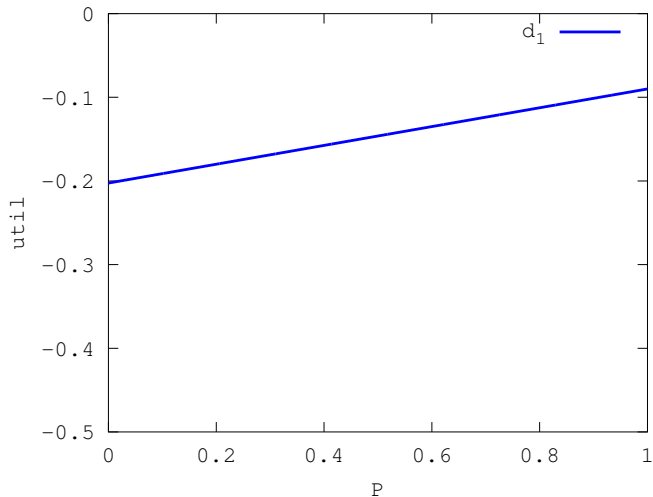


Figure : Fixed decision, varying distribution. The util of a fixed decision is a linear function of  $P$

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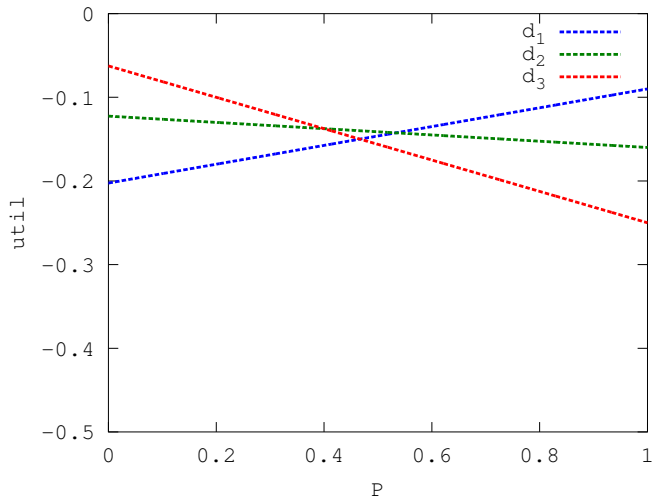


Figure : The util of a few decisions as  $P$  varies. Each decision corresponds to one of these lines.

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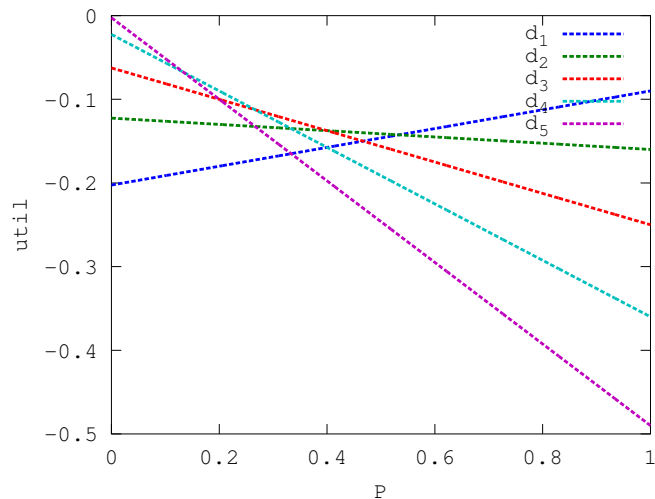


Figure : For each  $P$ , there is at least one decision maximising the util.



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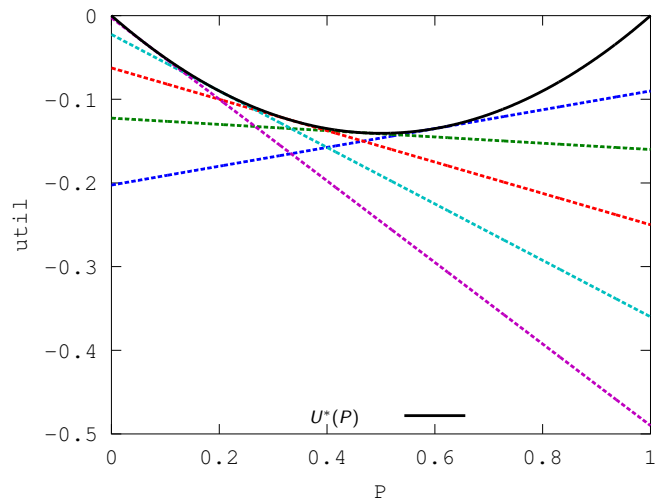


Figure : The Bayes util is convex and the maximising decision is tangent to it.

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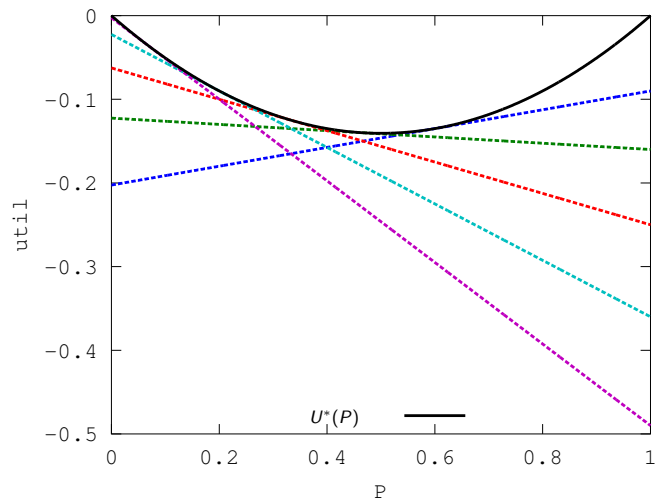
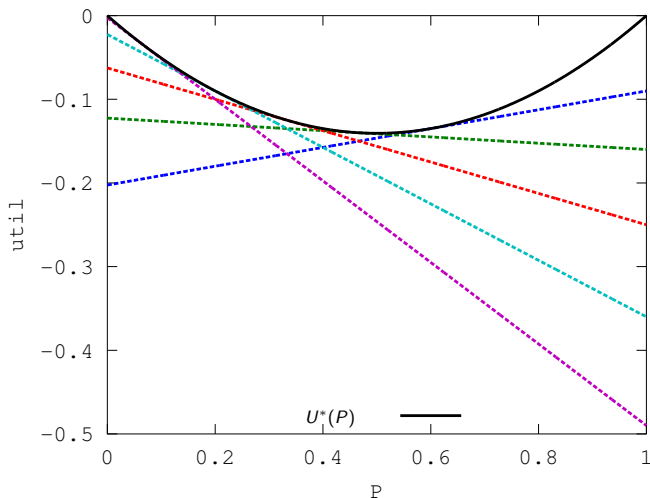


Figure : If we are not very wrong about  $P$ , then we are not far from optimal.

# Convexity of the Bayes utility



**Figure :** We can approximate the Bayes util by taking the maximum of a finite number of decisions.

# Only prior information

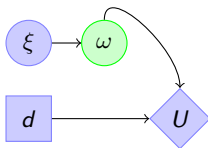


Figure : Statistical decision problem without observations

- 1 There is an **unknown parameter**  $\omega \in \Omega$  with  $\omega \sim \xi$ .

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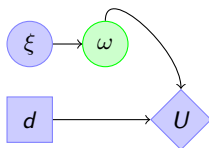


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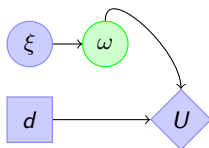


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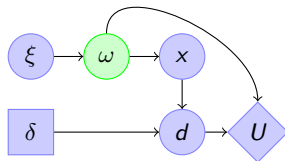


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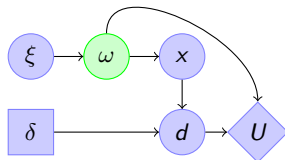


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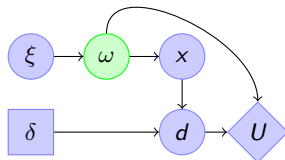


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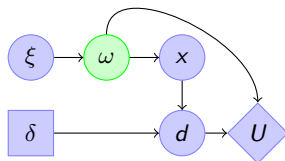


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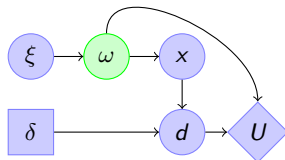


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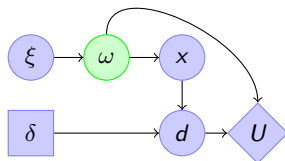


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- 5 We want to choose  $d \in \mathcal{D}$ , taking into account both  $\xi$  and the evidence  $x$ .
- 6 We want to find a **decision function**  $\delta : \mathcal{S} \rightarrow D$  maximising expected utility

# Maximising expected utility a posteriori

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- Bayes decision rule:

$$\delta^*(x) = \arg \max_{d \in D} \mathbb{E}_{\xi}(U \mid d, x).$$

# Exercise

Abdul Alhazred claims that he is **psychic** and can **always predict a coin toss**. Let  $P(A) = 2^{-16}$  be your prior belief that AA is a psychic.

- Abdul bets you 100 CU that he can predict the **next four** coin tosses. How much are you willing to bet against that (assuming that you are using a fair coin).
- You throw the coin 4 times, and AA guesses correctly all four times. Abdul now bets you another 100 CU that he can predict the **next** four coin tosses. Up to how much would you bet now?

## Assumption 1

- You use a **fair coin**, such that the probability of it coming heads is  $1/2$ .
- Your utility for money is linear, i.e.  $U(x) = x$  for any amount of money  $x$ .

# Quick summary

- We want to make a decision against an unknown parameter  $\omega$ .
- The Bayes utility is the maximum expected utility, and it is convex with respect to the distribution of  $\omega$ .
- Our decisions can depend on observations, via a decision function.
- We can construct a complete decision function by computing  $U(\xi, \delta)$  for all **decision functions** (normal form).
- We can instead wait until we observe  $x$  and compute  $U[\xi(\cdot | x), d]$  for all **decisions** (extensive form).