# Lecture 8 Data Structures (DAT037)

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(with slides from Nick Smallbone and Nils Anders Danielsson)

### **Trees**

A **tree** is a hierarchical data structure Each node can have several children but only has one parent The root has no parents; there is only one root

Example: directory hierarchy

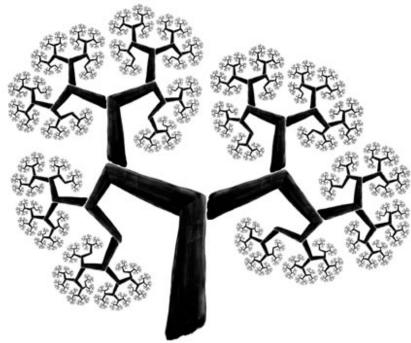


# Trees (as graphs)

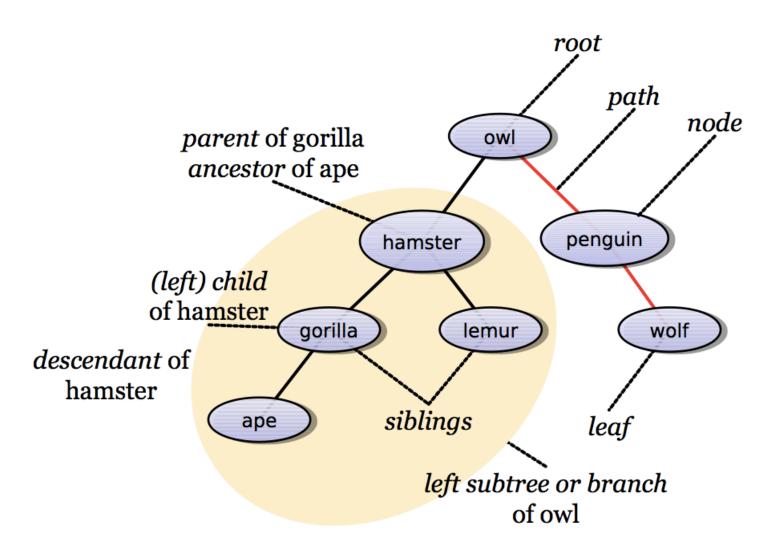
### **Also**

A tree is

+ undirected, unweighted, simple (not multi) acyclic graph



# Tree Terminology



### Tree Terminology

The depth of a node is the distance from the root
The height of a tree is the number of levels in the tree
The size of a tree is the number of nodes in it

# **Binary Trees**

A binary tree is a tree with at most two children for each node

```
Java:
class Tree<A> {
    class TreeNode {
        A contents;
        TreeNode left, right; }

Can be null if
    child is missing

A contents;

TreeNode left, right; }

Can be null if
    tree is empty
```

### Haskell:

```
data Tree a = Node a (Tree a) | Empty
```

# Height of (Binary) Trees

### Height:

- ► Empty trees have height -1.
- ▶ Otherwise: Number of steps from root to deepest leaf.

### Haskell:

```
height :: Tree a -> Integer
height Empty = -1
height (Node _ l r) = 1 + max (height l) (height r)
```

# Height of (Binary) Trees

### Height:

- ► Empty trees have height -1.
- ▶ Otherwise: Number of steps from root to deepest leaf.

### Java:

```
int height(TreeNode n) {
  if (n == null) return -1;
   else
      return 1 +
Math.max(height(n.left),height(n.right));}
```

### Question

What is the smallest and largest number of nodes for a binary tree of height *n* (computed with the function define before)?

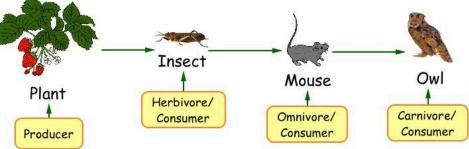
- 1. n+1 and 2^n-1
- 2. n and 2^n 1
- 3. n+1 and 2<sup>(n+1)-1</sup>
- 4. none of the above

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# **Balanced Binary Trees**

### A tree can be balanced or unbalanced





# **Balanced Binary Trees**

A tree can be balanced or unbalanced

If a tree of size n is

- balanced, its height is O(log n)
- unbalanced, its height could be O(n)

Many tree algorithms have complexity O(height of tree), so are efficient on balanced trees and less so on unbalanced trees

### Normally:

- balanced trees good ©
- unbalanced trees bad

# Traversal of (Binary) Trees

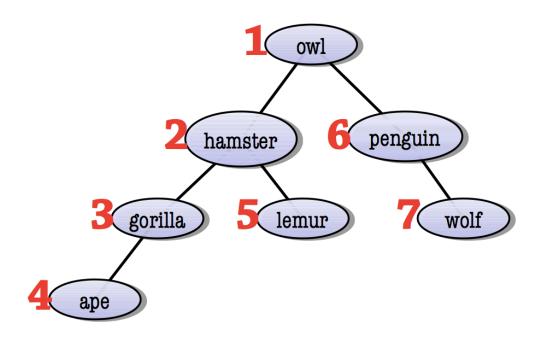
- Traversing a tree means visiting all its nodes in some order
- A traversal is a particular order that we visit the nodes in
- Four common traversals:
  - + preorder
  - + inorder
  - + postorder
  - + level-order
- For each traversal, you can define an iterator that traverses the nodes in that order

# Traversal of (Binary) Trees

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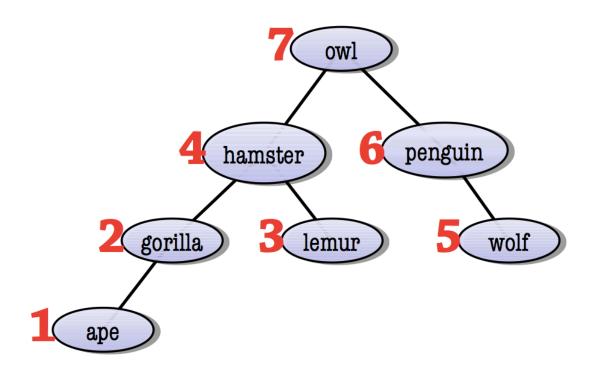
### **Preorder Traversal**

Visit root node, then left child, then right



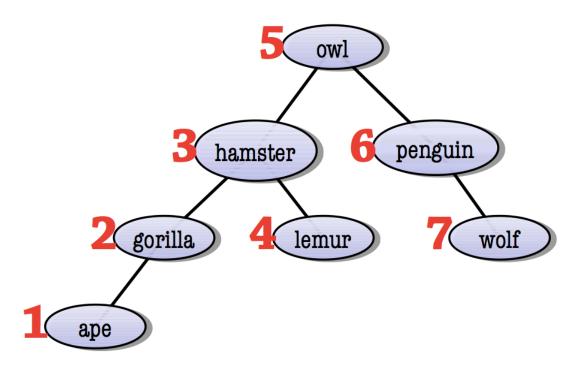
### Postorder Traversal

Visit left child, then right, then root node



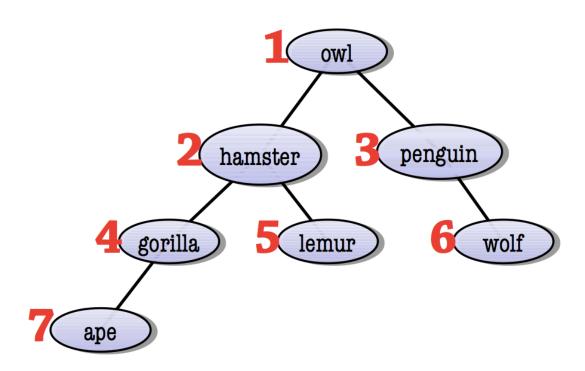
### **Inorder Traversal**

Visit left child, then root node, then right child



### Level-Order Traversal

Visit nodes left to right, top to bottom



### Question

Which of the tree traversal methods is equivalent to DFS?

- 1. Preorder
- 2. Postorder
- 3. Inorder
- 4. Traversal on levels

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# Implementing Tree Traversals

Implement the

others on your

Inefficient list

append

### **Preorder:**

### Java:

```
void preorder(Node<E> node) {
if (node == null) return;
System.out.println(node.value);
preorder(node.left); preorder(node.value);}
```

### Haskell:

```
preorder Empty = []
preorder (Node info l r) = info : (preorder l ++
preorder r)
```

### Question

Which of the following assertions about binary trees with distinct elements holds?

- 1. We can recreate a tree from its preorder and postorder
- 2. We can recreate a tree from its inorder and preorder
- 3. We can recreate a tree from only one of the traversals
- 4. We can't recreate a tree from any combination of two traversals

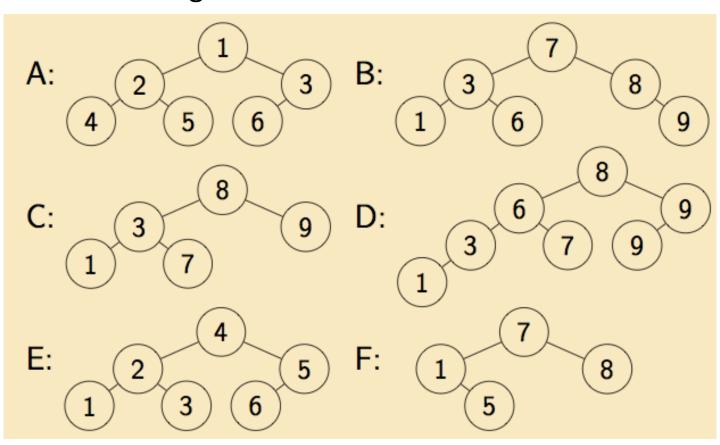
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# Binary Search Trees (BST)

In a binary search tree (BST), every node is greater than all its left descendants, and less than all its right descendants (recall that this is an invariant)

# Binary Search Trees (BST)

Which of the following trees is a BST?

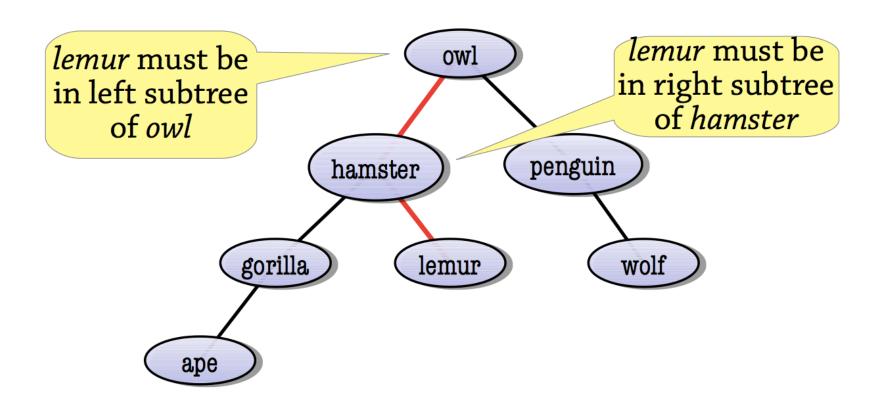


# Operations on BST

- Searching for a value
- Inserting a new value
- Deleting a value

# Searching in a BST

Finding an element in a BST is easy, because by looking at the root you can tell which subtree the element is in



### Searching in a BST

### To search for target in a BST:

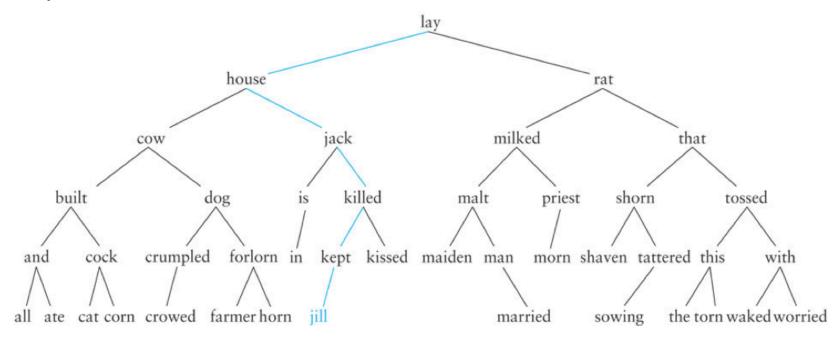
- If the target matches the root node's data, we've found it
- If the target is less than the root node's data, recursively search the left subtree
- If the target is greater than the root node's data, recursively search the right subtree
- If the tree is empty, fail

A BST can be used to implement a set, or a map from keys to values

### Inserting in a BST

### To insert a value into a BST:

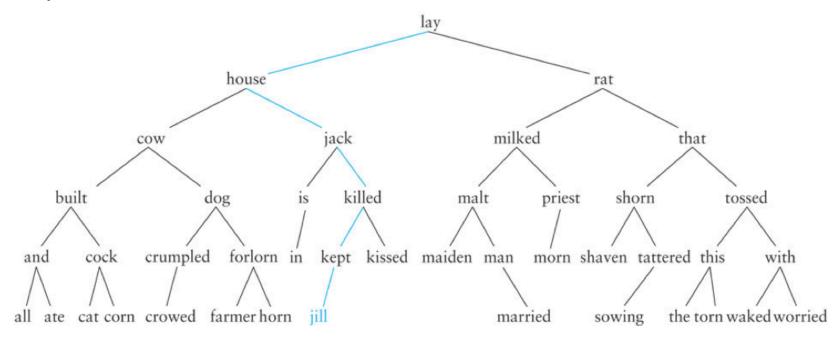
- Start by searching for the value
- But when you get to null (the empty tree), make a node for the value and place it there



### Inserting in a BST

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- Start by searching for the value
- But when you get to null (the empty tree), make a node for the value and place it there



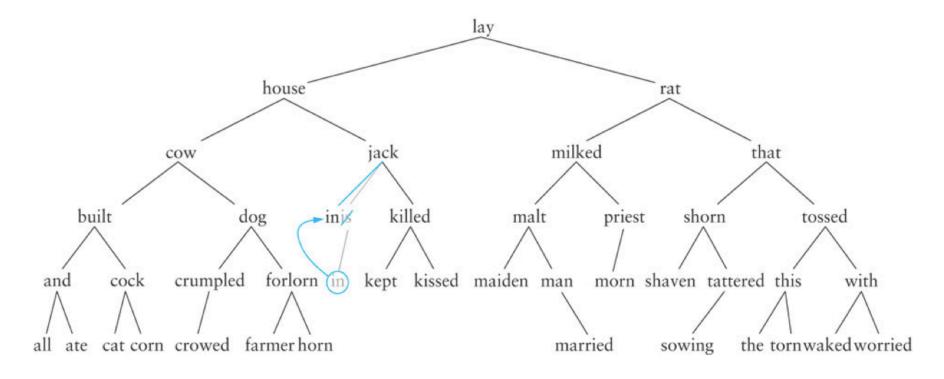
### Question

What is the order in which we should insert the values from a sorted array a[0]...a[N] into a BST in order to get a tree of minimal height?

- 1. a[0], a[1]...a[N]
- 2. a[N/2], a[N-1],...,a[N/2+1], a[0]...,a[N/2-1]
- 3. a[N/2], a[N/4], a[3N/4],a[N/8],...
- 4. None of the above

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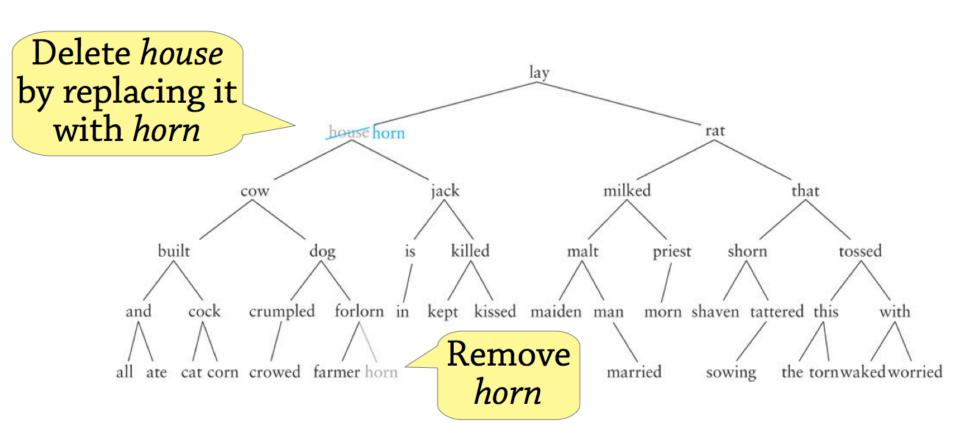
To delete a node with one child: Deleting *is*, which has one child, *in* – we connect *in* to *is*'s parent *jack* 



### To delete a value from a BST:

- Find the node and its parent
- If it has no children, just remove it from the tree (by disconnecting it from its parent)
- If it has one child, replace the node with its child (by making the node's parent point at the child)
- If it has two children...?

Replace the deleted value with the biggest value from its left subtree (or the smallest from the right subtree)



### Question

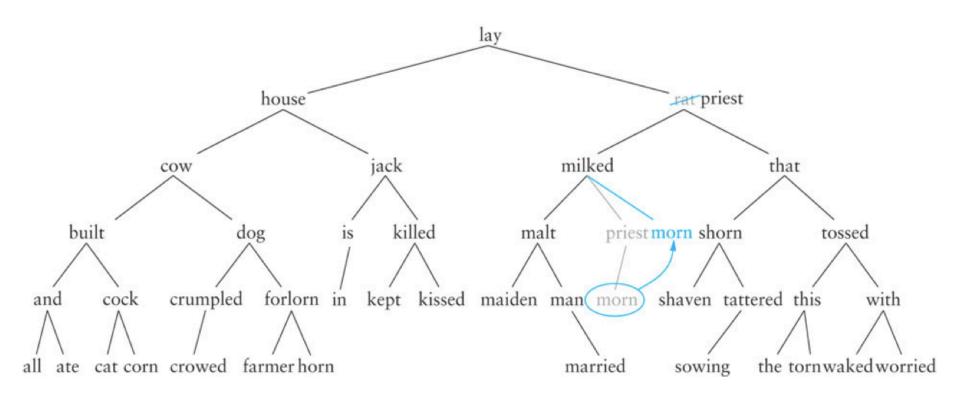
Which of the following statements about the node from the left subtree that we replace the deleted node with is generally true?

- 1. It can't have any children
- It could have two children
- It could have a left child
- 4. It could have a right child

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- Find the biggest value in the left subtree and put that value in the deleted node
- Using the biggest value preserves the invariant
- Biggest node = rightmost node
- Finally, delete the biggest value from the left subtree
- This node can't have two children (no right child), so deleting it is much easier

Deleting rat, we replace it with priest; now we have to delete priest which has a child, morn



# Complexity of BST Operations

All our operations are O(height of tree)
This means O(log n) if the tree is balanced, but O(n) if it's unbalanced.

Balanced BSTs add an extra invariant that makes sure the tree is balanced, then all operations are O(log n)

Coming up soon!

# Summary of BSTs

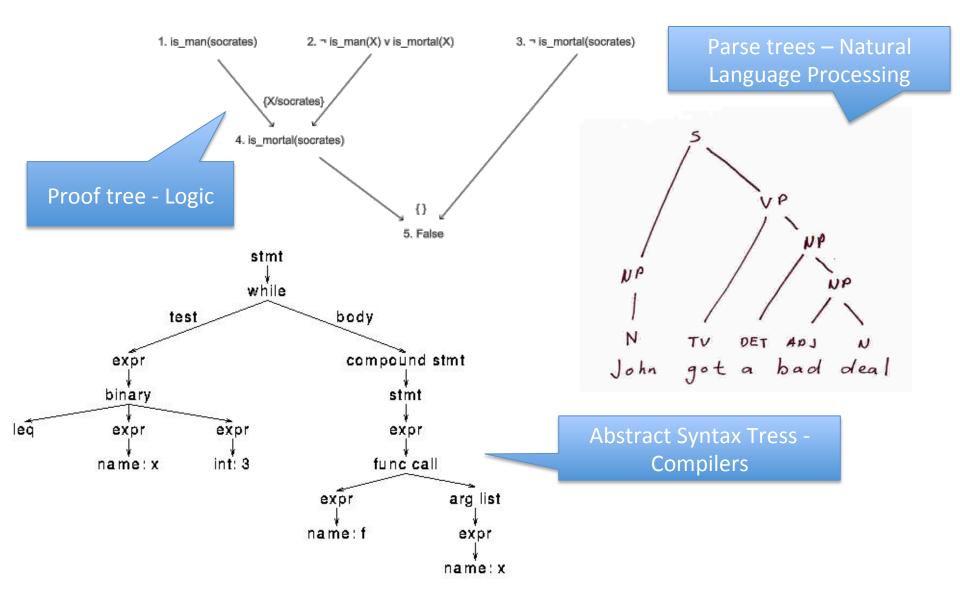
### Can be used to implement sets and maps

- lookup: can easily find a value in the tree
- insert: perform a lookup, then put the new value at the place where the lookup would terminate
- delete: find the value, then several cases depending on how many children the node has

### Complexity:

- all operations O(height of tree)
   that is, O(log n) if tree is balanced, O(n) if unbalanced
- inserting random data tends to give balanced trees, sequential data gives unbalanced ones

# More Trees in Computer Science



### To Do







### Read from the book:

+4.1 - 4.3

### Implement:

+ trees + the algorithms from today in your favourite programming language

# Della Duck

### Dugga next week:

http://www.cse.chalmers.se/edu/year/2014/course/DAT037 Datastrukturer/examination.html#dugga

### Coming up:

- + advanced data structures
  - minimum spanning tree (trees and graphs)
  - balanced trees
  - more on sorting

# Questions about dugga

