

Building Multimodal Dialogue Systems in Grammatical Framework

Björn Bringert
Chalmers University of Technology

with Aarne Ranta and Robin Cooper

EU TALK Project, IST-507802

What are Dialogue Systems?

- User interaction
- Involve natural language
- Examples:
 - automated flight information
 - car navigation systems
 - “smart home” systems
- Running example: Gothenburg tram map

What is Multimodality?

- Using multiple modes of communication:
 - Speech
 - Pointing
 - Drawings
 - Text
 - ...

What is Grammatical Framework?

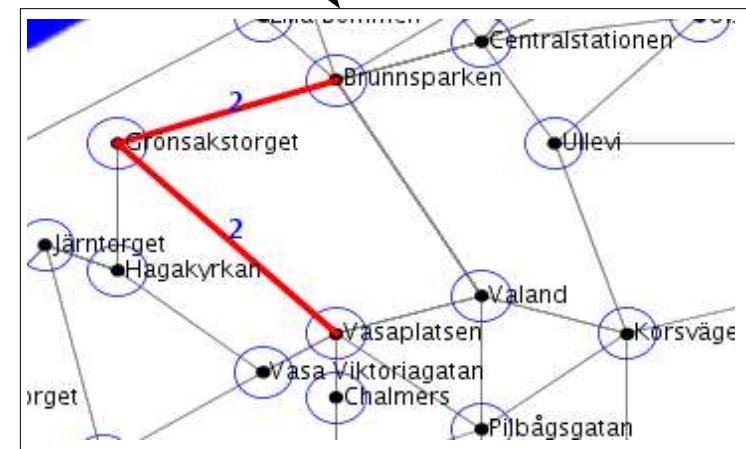
- Grammar formalism
- Based on type theory
- Abstract syntax
- Concrete syntax
 - Linearization functions
- Parsing for free

Parallel Multimodality

- Complete information in each modality:

Route 2 [Brunnsparken, Grönsakstorget, Vasaplatser]

“Take line three
from Brunnsparken
to Vasaplatser”

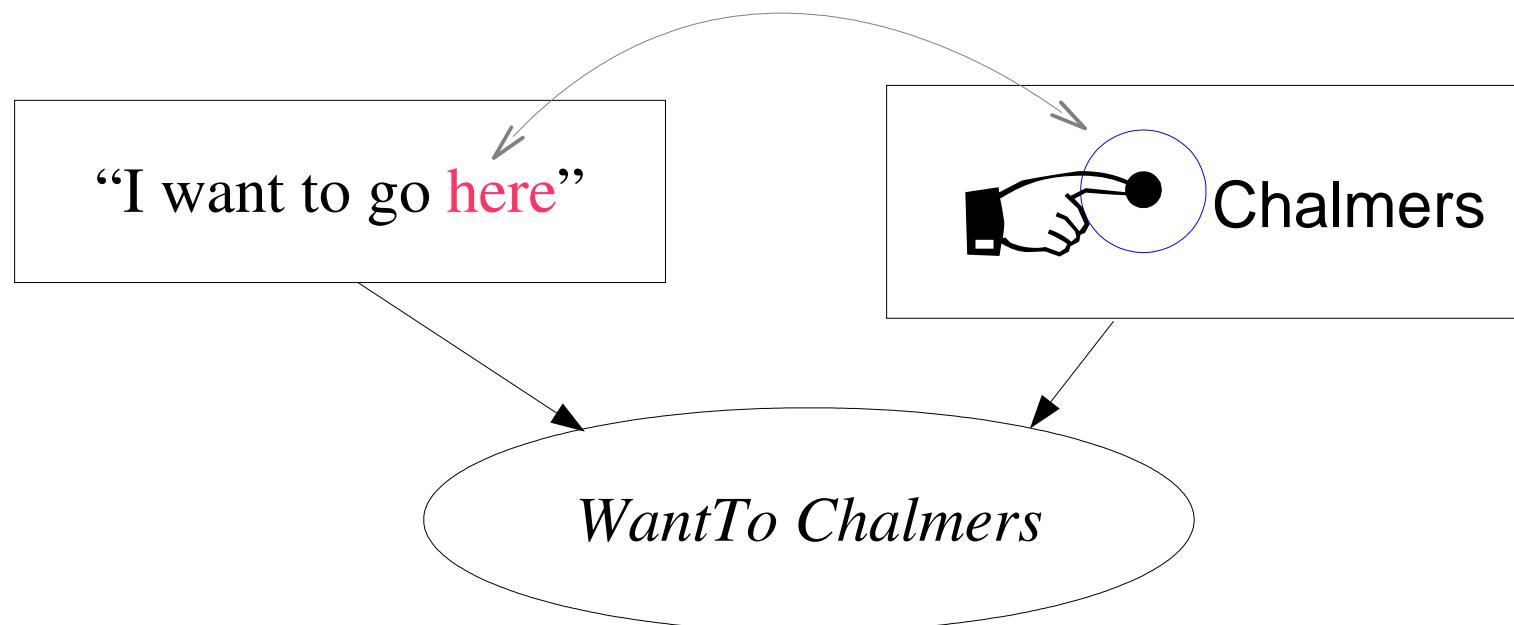


Parallel Multimodality in GF

- One concrete syntax / modality (like multilinguality):
 - Abstract syntax:
fun Leg : Line -> Stop -> Stop -> Route
 - English speech:
*lin Leg l f t = { s = “Take” ++ l.s ++ “from” ++ f.s
++ “to” ++ t.s }*
 - Map drawings:
*lin Leg l f t = { s = “drawEdge(“ ++ f.s ++ “,”
++ t.s ++ “,”
++ l.s ++ “)” }*

Integrated Multimodality

- Information presented by a combination of modalities:



Integrated Multimodality in GF

- Abstract syntax:

cat Input

cat Place

fun GoFromTo : Place -> Place -> Input

fun NamedPlace : String -> Place

fun ClickPlace : Click -> Place

Integrated Multimodality in GF

- English + clicks:

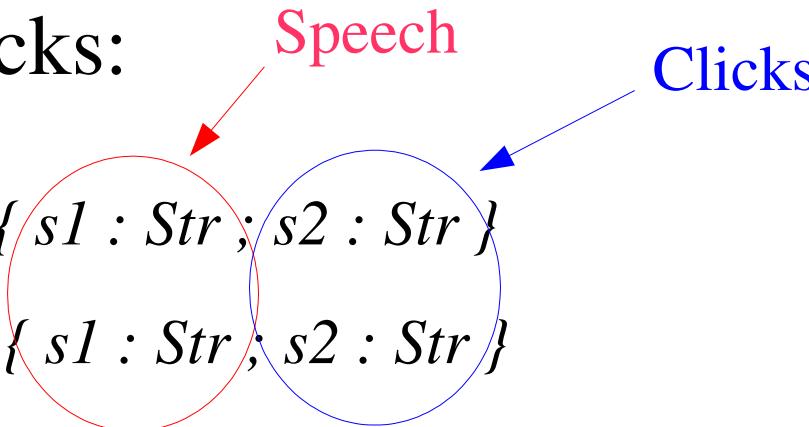
lincat Input = { s1 : Str ; s2 : Str }

lincat Place = { s1 : Str ; s2 : Str }

*lin GoFromTo x y = {
 s1 = ["I want to go from"] ++ x.s1 ++ "to" ++ y.s1;
 s2 = x.s2 ++ y.s2
}*

*lin NamedPlace p = { s1 = **p.s** ; s2 = "" }*

*lin ClickPlace c = { s1 = "**here**" ; s2 = **c.s** }*



Demo: Gothenburg tram map