

Embedded system programming: HCS12

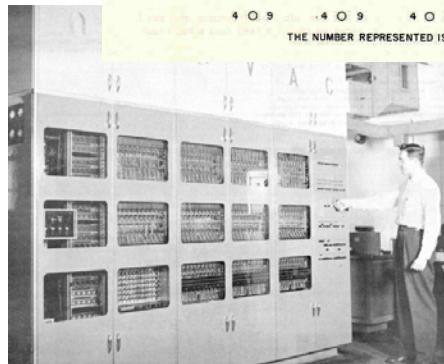
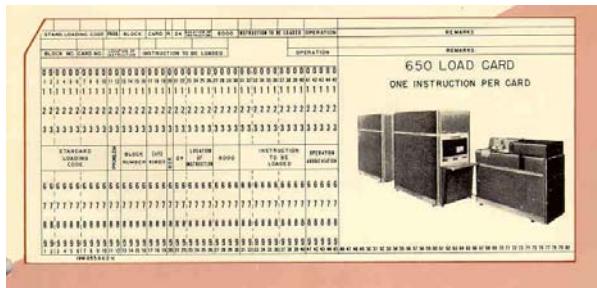
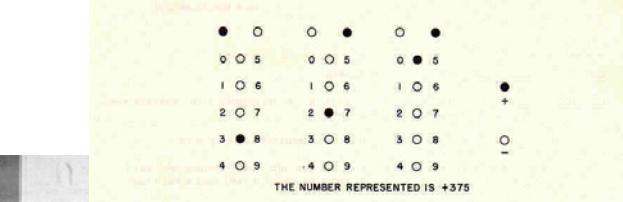
- Cross developments environments and tools
- XCC12 cross C compiler in particular
- Low level programming in 'C'

Low level programming in C

- Short history
- Cross development
- Software libraries
- Embedded assembly code
- Interrupts

Display Lights: These are ten sets of seven lights and one set of two lights located across the upper portion of the control console. Each set of seven lights has two binary lights arranged horizontally and five quinary lights arranged vertically. The digit values 0, 5 are associated with their corresponding quinary light; digit values 1, 6 are associated with their corresponding quinary lights, and similarly for 2; 7; 3; 8; and 4; 9. The binary light indicates which of the two values indicated by the quinary light is represented. This arrangement makes it very easy to tell at a glance what number is represented.

The sign lights indicate the sign of the number represented by the Display lights. The following example illustrates this method of indication:



The program language 'C'

"The philosophy of BCPL is not one of the tyrant who thinks he knows best and lays down the law on what is and what is not allowed; rather, BCPL acts more as a servant offering his services to the best of his ability without complaint, even when confronted with apparent nonsense. The programmer is always assumed to know what he is doing and is not hemmed in by petty restrictions."



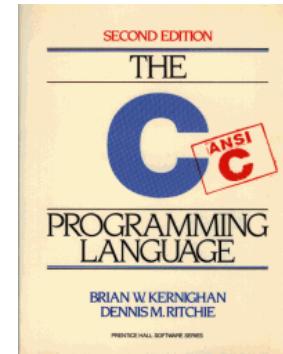
Martin
Richards



Brian
Kernighan



Dennis
Ritchie



'BCPL' Basic Combined Programming Language – (Martin Richards) 1966

'B' - (Johnson/Kernighan) 1973

'C' – (Kernighan/Ritchie) 1978

'ANSI C' – 1983, first standardisation

'C++' – (Stroustrup) 1986

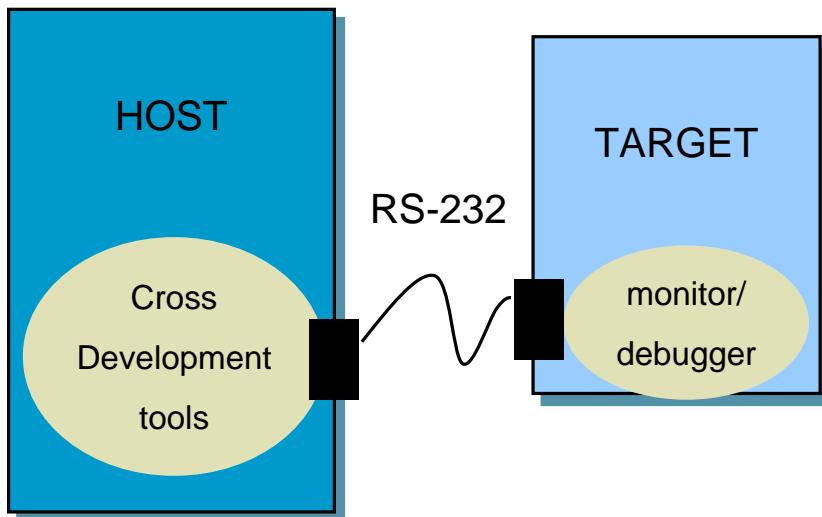
'ISO' – 1995, 1999

Cross development

- Development for one type of computer (target computer) with another type of computer (host computer)
- Tools:
 - Cross assembler
 - Cross compiler
 - ...

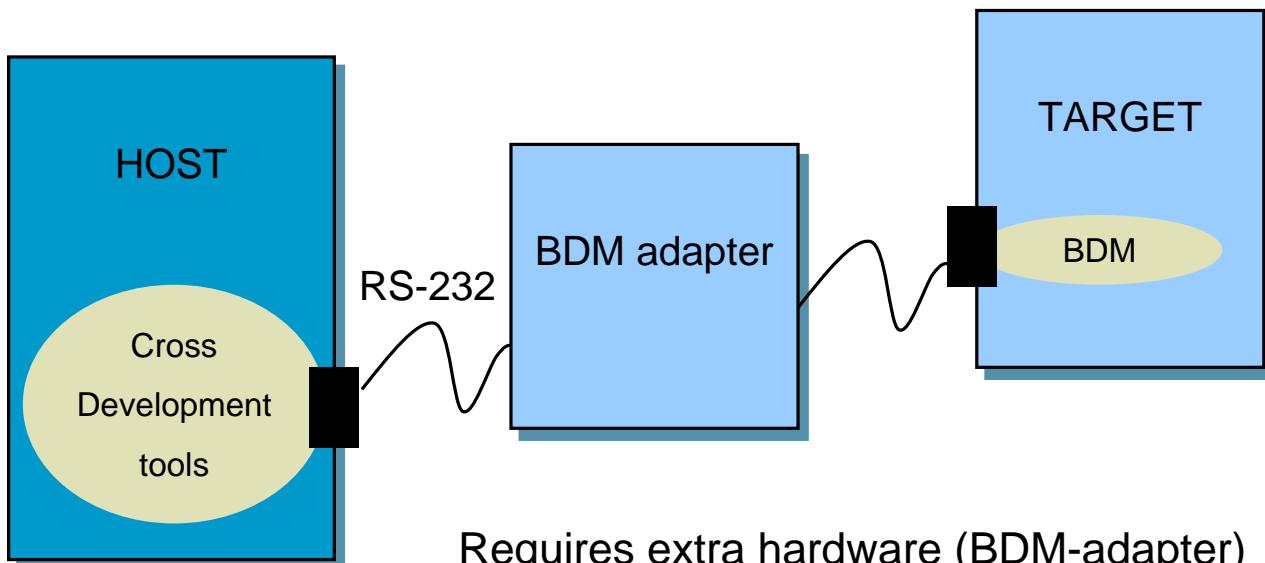


Cross development environment



Requires a resident software debugger in the target

Cross development environment



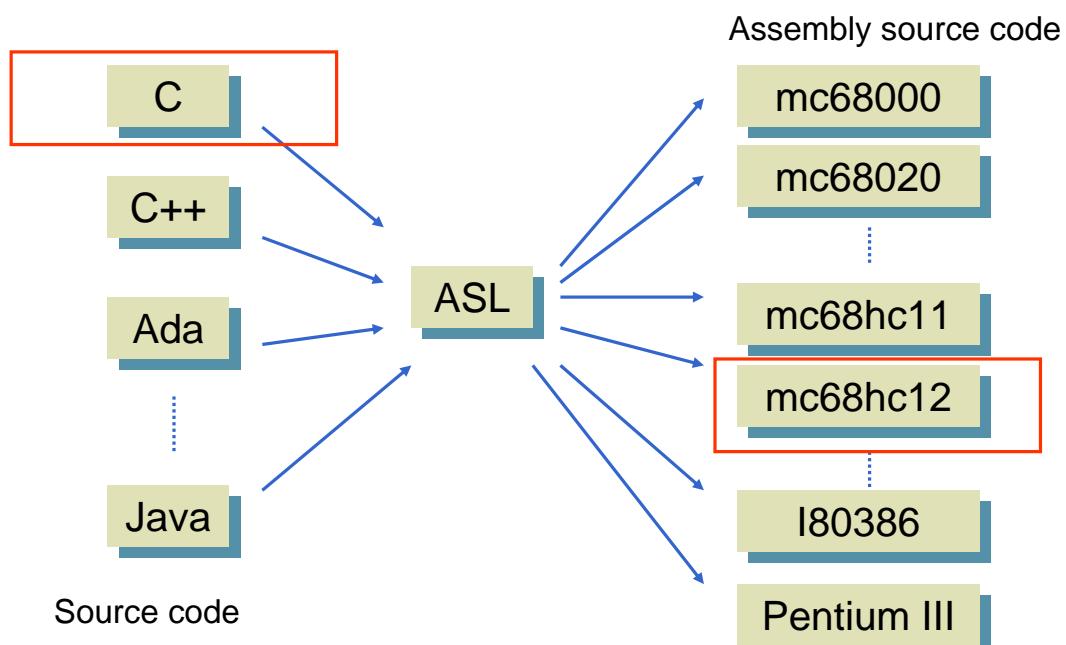
Requires extra hardware (BDM-adapter)

Cross development tools

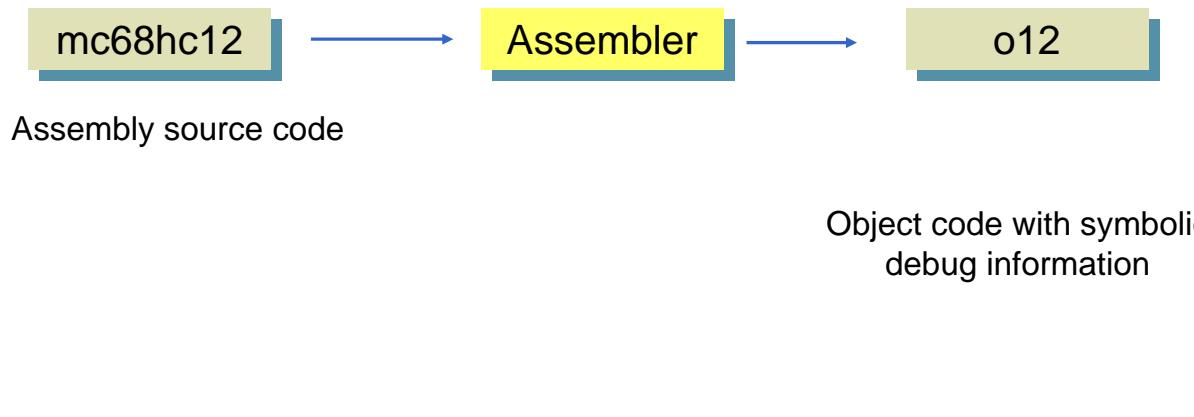
Host system

- Cross compilers (C/C++/Java/Ada/Fortran...)
- Cross assemblers
- Linker
- Terminal emulation, download
- Simulators
- Debug adapters and software

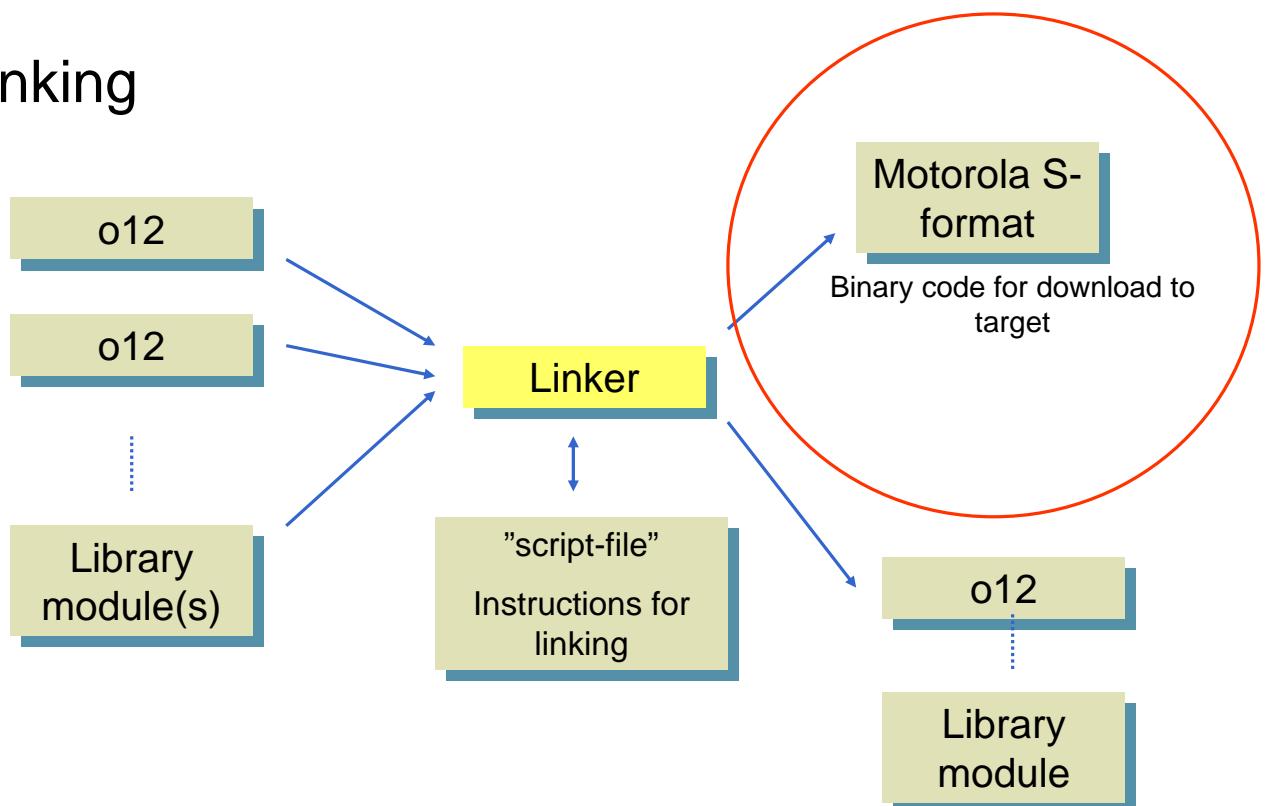
The compiler



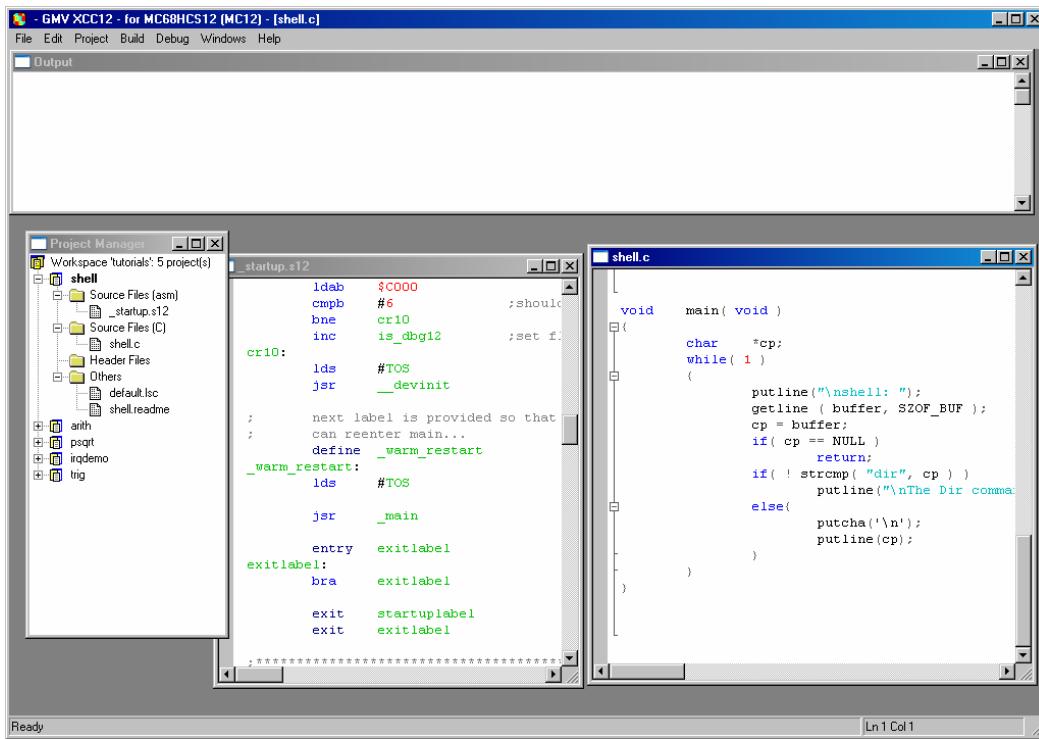
The assembler



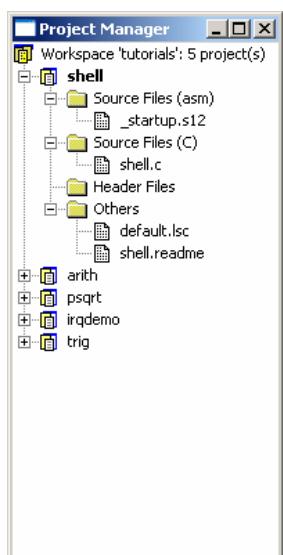
Linking



Software development with XCC12



XCC12 'Project Manager'



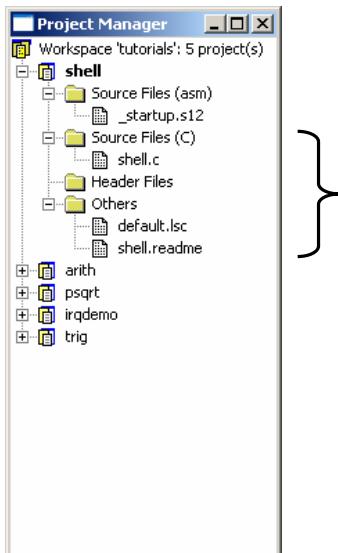
'Project'

All source code files belonging to an application.
Result is an executable program

'Workspace'

A practical way of grouping related
projects.

XCC12 'Application'



Any application requires a startup procedure. The procedure can often be standardised, i.e. several applications use the same startup.

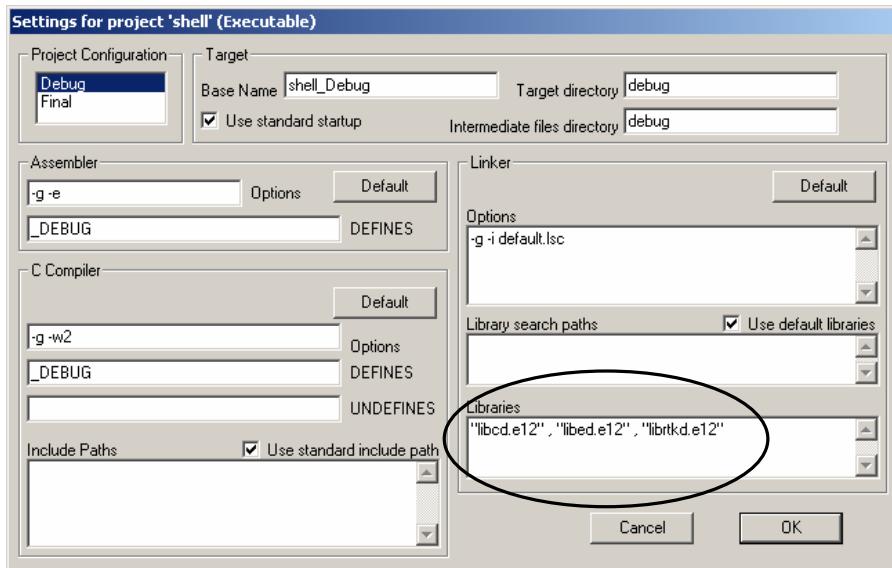
XCC12 Compiler libraries

Performs standard operations which cannot be handled by a single instruction in CPU12. For example addition of 32-bit numbers.

```
* long int la,lb,lc;
* lc = la + lb;
ldd 2+_lb
ldx _lb
pshd
pshx
ldd 2+_la
ldx _la
pshd
pshx
jsr add32
leas 8,sp
std 2+_lc
stx _lc
```

'add32' a function in
the precompiled
library

XCC12 Standard libraries



Three different
libraries with
common
functions

CC12 'segment'

The compiler distinguishes the generated code by placing it in one of four possible *segments*.

text – this is the segment for machine instructions (executable code)

data – this is the segment for initialised variables. These variables have user defined values when the program starts but they may be changed by the program.

cdata - this segment is also for initialised variables. These variables have user defined values when the program starts and they can *not* be changed by the program.

bss – this segment provides space for variables which don't have initialised values

CC12 'segment' - EXAMPLE

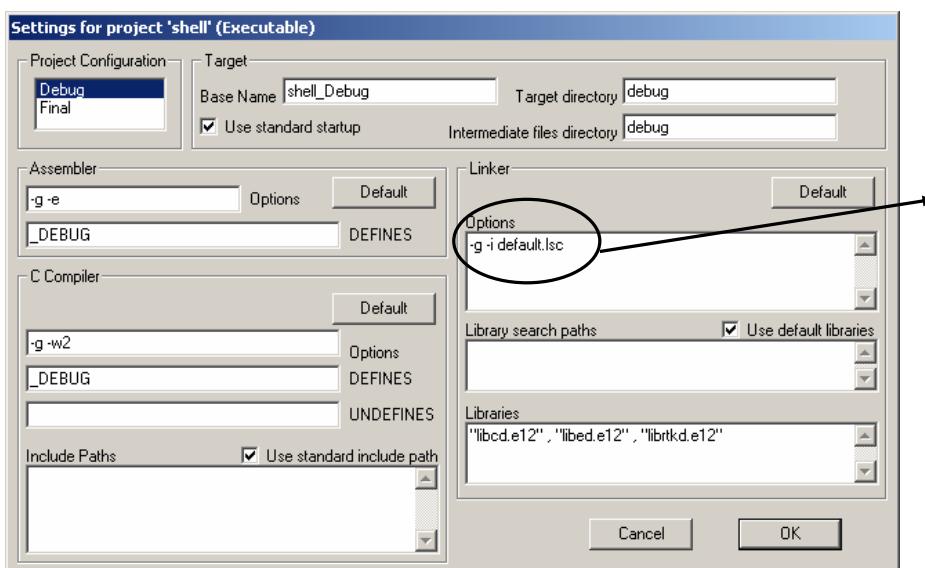
```
int      var;
const int novar = 1;
int      init_var = 2;
```

```
segment data
.stab sym
G:init_var:_init_var:(typ11)
define _init_var
_init_var:
fdb $2
```

```
segment bss
define _var
_var:
rmb 2
.stab sym G:var:_var:(typ11)
```

```
segment cdata
.stab sym G:novar:_novar:(typ11)
define _novar
_novar:
fdb $1
```

XCC12 linker instructions



```
///
// default.lsc
// script for QLD
// for XCC12 applications in RWM
// ...

```

XCC12 'default.lsc'

```
//      OPTIONS SECTION
-M          // generate listfile <basename>.map

//      define program entry for debugger
entry( __start )

group( c , const_group )
{
    abs
}
group( r , test_group )
{
    startupseg,
    text,
    cdata,
    data,
    bss
}
group( r, interrupt_vectors )
{
    vectors
}
layout
{
    0x1000,0x3C80 <= test_group,
    0x3F80,0x3FFF <= interrupt_vectors
}
```

XCC12 Embedded assembly code

Operations, which cannot be accomplished with 'C'-syntax, requires "embedded assembly code":

```
/* EXAMPLE */
void main( void )
{
    __asm( " andcc #$F0" ); /* clear condition flags */
}
```

NOTE: This is not a part of the 'C'-language and may be compiler dependent.

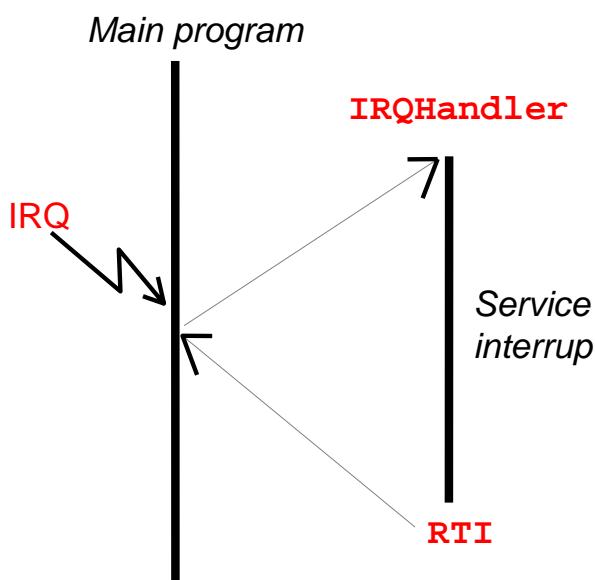
XCC12 Embedded assembly code

Variables and parameters can be referenced by name in embedded assembly code.

```
void callfunc( int aa , int ab )
{
    aa = 1;
    ab = 2;
}
```

```
void callfunc( int aa , int ab )
{
    __asm( " movw #1,%a", aa );
    __asm( " movw #2,%a", ab );
}
```

Remapping interrupt handlers



ROM

Address (hex)	Function
FFFE	RESET, Startvector
FFFC	Clock Monitor Fail, JMP [3FFE]
FFFA	COP Watchdog Timeout, JMP [3FFC]
FFF8	Illegal Op Code, JMP [3FFA]
FFF6	SWI, JMP [3FF6]
FFF4	XIRQ, JMP [3FF4]
FFF2	IRQ, JMP [3FF2]
FF8C	...
FFFO	JMP [3Fxx]

RWM

Address (hex)	Funktion
3FFE	Not used
3FFC	ClockFailHandler
3FFA	COPFailHandler
3FF8	IllegalOpHandler
3FF6	SWIHandler
3FF4	XIRQHandler
3FF2	IRQHandler
3F8C	...
3FF0	

Specification of interrupt handler

```
__interrupt void name( void );
```

Keyword “`__interrupt`” is the first word in the specification.

An interrupt handler can neither have parameters nor return values.

Interrupt vector table in XCC12

```
#pragma DATA      vectors
/* 3F80 - 3FFF */
__interrupt void(*irqvecs[])() =
{
    .....
    PWMEShutdownHandler,
    PortPIntHandler,
    TimerCh1Handler,
    TimerCh0Handler,
    RTIHandler,
    IRQHandler,
    XIRQHandler,
    SWIHandler,
    IllopHandler,
    COPFailHandler,
    ClockFailHandler,
    ResetHandler
};
```

script file for the application

```
.....
group( r, interrupt_vectors )
{
    vectors
}
.....
layout
{
    ....,
    0x3F80,0x3FFF <= interrupt_vectors
}
```

Interrupt vector table, static initialisation

```
__interrupt void IRQHandler( void )
{
    /* Interrupt service routine */
}

#pragma DATA vectors
__interrupt void *irqvecs = IRQHandler;
```

declarations

script file

```
group( r, interrupt_vectors )
{
    vectors
}
layout
{
    ....,
    0x3FF2, 0x3FF4 <= interrupt_vectors
}
```

Interrupt vector table, run time initialisation

```
__interrupt void IRQHandler( void )
{
    /* Interrupt service routine */
}

#pragma DATA vectors
__interrupt void *irqvecs;

#pragma DATA data

void main(void)
{
    irqvecs = IRQHandler;
    ...
}
```

Run time initialisation no vector table

```
__interrupt void IRQHandler( void )
{
    /* Interrupt service routine */
}

void main(void)
{
    *(unsigned short *) 0x3FF2 = (unsigned short) IRQHandler;
    ...
}
```

alternatively...

```
#define SET_IRQ_VECTOR(x,y) *(unsigned short *) y = (unsigned short) x

void main(void)
{
    SET_IRQ_VECTOR( IRQHandler , 0x3FF2 ) ;
    ...
}
```

Function call conventions in XCC12

EXAMPLE: Function call

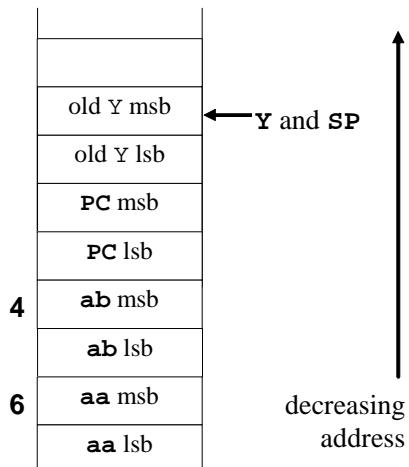
```
int      a,b;
main()
{
    callfunc( a,b );
}
```

The following assembly code is generated by the compiler:

```
...
* 0009 |      callfunc( a,b );
  ldd _b
  pshd
  ldd _a
  pshd
  jsr _callfunc
```

Function conventions in XCC12

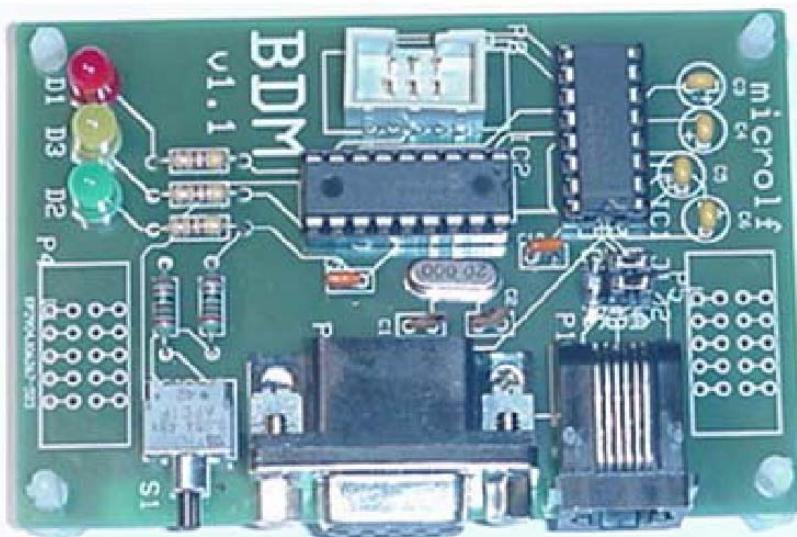
```
callfunc( aa , ab )
{
    aa = 1;
    ab = 2;
}
```



The following assembly code is generated by the compiler:

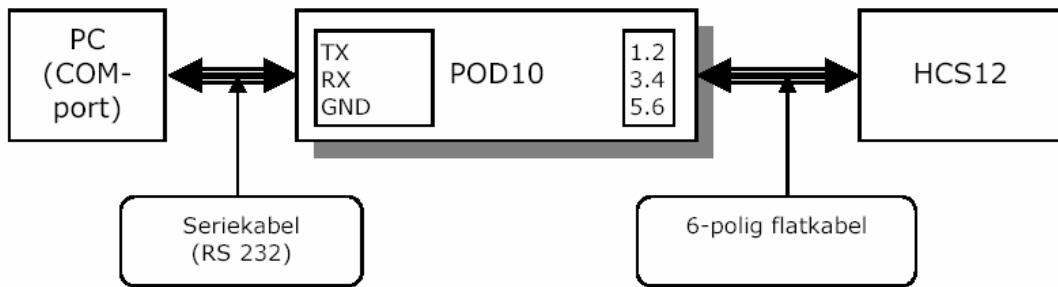
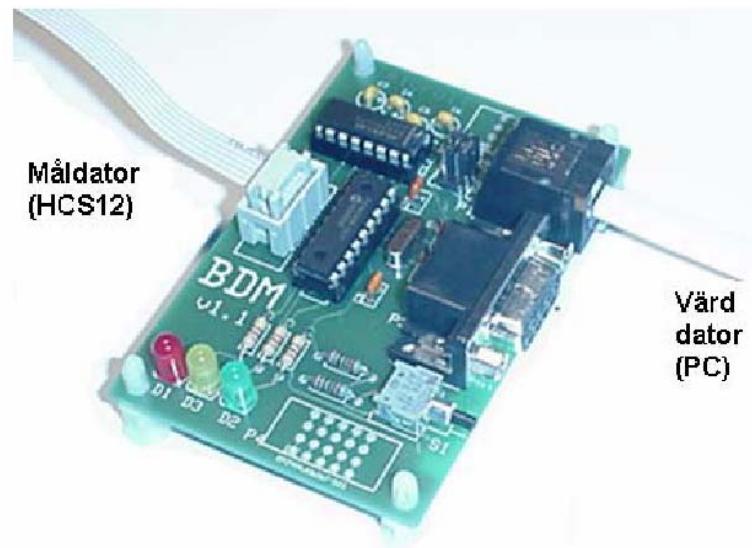
```
...
* 0007 |callfunc( aa , ab )
segment text
define _callfunc
_callfunc:
    pshy
    tfr sp,y
* 0008 |{
* 0009 |      aa = 1;
    movw #1,4,y
* 0010 |      ab = 2;
    movw #2,6,y
* 0011 |}
    puly
    rts
```

Background Debug Mode –BDM adapter



- Single wire electrical interface
- Used for debugging and programming the FLASH memory in HCS12

BDM adapter ("pod")



Embedded system programming: HCS12

31

Summary

we have got a brief introduction to

- Low level programming in 'C'
- Cross developments environments and tools in general
- XCC12 cross C compiler in particular

which finishes today's lecture ...