

# **Normalization by Evaluation for Untyped Combinatory Logic**

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## Untyped normalization by evaluation: previous work

- Mogensen 1992: “Efficient self-interpretation in lambda calculus”
- Aehlig and Joachimski 2004: “Operational aspects of untyped normalization by evaluation”
- Filinski and Rohde 2004: “Denotational aspects of untyped normalization by evaluation”
- Devautour 2004: “Untyped normalization by evaluation” (for combinatory logic)

Related issues appear in Danvy’s and Filinski’s “Type-directed partial evaluation” for typed languages with general recursion.

# Formalizing typed combinatory logic in Martin-Löf type theory (AgdaLight)

Constructors for `Ty :: Set`:

```
X      :: Ty          -- base type
(=>)   :: Ty -> Ty -> Ty -- function types
```

Constructors for `Exp :: Ty -> Set`:

```
K      :: (a,b :: Ty) -> Exp (a => b => a)
S      :: (a,b,c :: Ty) -> Exp ((a => b => c) => (a => b) => a => c)
App    :: (a,b :: Ty) -> Exp (a => b) -> Exp a -> Exp b
```

In this way we only generate well-typed terms.

## The glueing model

```
Sem :: Ty -> Set
Sem X      = Exp X
Sem (a => b) = (Exp (a => b), (Sem a) -> (Sem b))
```

The normalization function is obtained by evaluating an expression in the glueing model, and then “reifying” this interpretation

```
nbe :: (a :: Ty) -> Exp a -> Exp a
nbe a e = reify a (eval a e)
```

```
eval :: (a :: Ty) -> Exp a -> Sem a
```

```
reify :: (a :: Ty) -> Sem a -> Exp a
```

## Evaluation and reification

Evaluation is defined by induction on  $\text{Exp } a$ , eg

```
eval :: (a :: Ty) -> Exp a -> Sem a
eval (a => b => a) (K a b)
= (K a b, \x -> (App a (b => a) (K a b) (reify a x), \y -> x))
```

Reification is defined by induction on  $\text{Ty}$ , eg

```
reify :: (a :: Ty) -> Sem a -> Exp a
reify (a => b) (e,f) = e
```

It is tempting to “hide” the type information, but note that it is used in the computation.

## A decision procedure for convertibility

Let  $e, e' :: \text{Exp } a$ .

- Prove that  $e \text{ conv } e'$  implies  $\text{eval } a \ e = \text{eval } a \ e'$ !
- It follows that  $e \text{ conv } e'$  implies  $\text{nbe } a \ e = \text{nbe } a \ e'$
- Prove that  $e \text{ conv } (\text{nbe } a \ e)$  using the glueing (reducibility) method!
- Hence  $e \text{ conv } e'$  iff  $\text{nbe } a \ e = \text{nbe } a \ e'$
- Hence  $e \text{ conv } e'$  iff  $(\text{nbe } a \ e == \text{nbe } a \ e') = \text{True}$

# Formalizing syntax and semantics in Haskell

The Haskell type of untyped combinatory expressions:

```
data Exp = K | S | App Exp Exp
```

(We will later use  $e@e'$  for `App e e'`.)

Note that Haskell types contain programs which do not terminate at all or lazily compute infinite values, such as `App K (App K (App K ... ))`.

The untyped glueing model as a Haskell type:

```
data Sem = Gl Exp (Sem -> Sem)
```

A reflexive type!

## The nbe program in Haskell

```
nbe :: Exp -> Exp
nbe e = reify (eval e)
```

```
eval :: Exp -> Sem
eval K = Gl K (\x -> Gl (App K (reify x)) (\y -> x))
eval S = Gl S (\x -> Gl (App S (reify x))
                      (\y -> Gl (App (App S (reify x)) (reify y))))
                      (\z -> appsem (appsem x z) (appsem (y z))))
eval (App e e') = appsem (eval e) (eval e')
```

```
reify :: Sem -> Exp
reify (Gl e f) = e
```



## Application in the model

```
appsem :: Sem -> Sem -> Sem  
appsem (G1 e f) x = f x
```

## The nbe program computes the Böhm tree of a term

**Theorem.** (Devautour 2004)  $\text{nbe } e$  computes the combinatory Böhm tree of  $e$ . In particular,  $\text{nbe } e$  computes the normal form of  $e$  iff it exists.

**Proof.** Following categorical method of Pitts 1993 and Filinski and Rohde 2004 using “invariant relations”.

What is the combinatory Böhm tree of an expression? An *operational* notion: the Böhm tree is defined by repeatedly applying the *inductively defined* head normal form relation.

Note that  $\text{nbe}$  gives a *denotational (computational)* definition of the Böhm tree of  $e$ , so the theorem is to relate an operational (inductive) and a denotational (computational) definition.

## Combinatory head normal form

Inductive definition of relation between terms in Exp

$$\begin{array}{c}
 K \Rightarrow^h K \qquad S \Rightarrow^h S \\
 \\
 \frac{e \Rightarrow^h K}{e@e' \Rightarrow^h K@e'} \qquad \frac{e \Rightarrow^h K@e' \quad e' \Rightarrow^h v}{e@e'' \Rightarrow^h v} \\
 \\
 \frac{e \Rightarrow^h S}{e@e' \Rightarrow^h S@e'} \qquad \frac{e \Rightarrow^h S@e'}{e@e'' \Rightarrow^h (S@e')@e''} \\
 \\
 \frac{e \Rightarrow^h (S@e')@e'' \quad (e'@e''')@e''@e'' \Rightarrow^h v}{e@e''' \Rightarrow^h v}
 \end{array}$$

## Formal neighbourhoods

To formalize the notion of combinatory Böhm tree we make use of Martin-Löf 1983 - the domain interpretation of type theory. Notions of

- formal neighbourhood = finite approximation of the canonical form of a program (lazily evaluated); in particular  $\Delta$  means no information about the canonical form of a program.
- The denotation of a program is the set of all formal neighbourhoods approximating its canonical form (applied repeatedly to its parts). Two possibilities: *operational neighbourhoods* and *denotational neighbourhoods*. Different because of the *full abstraction problem*, Plotkin 1976.

## Expression neighbourhoods

An expression neighbourhood  $U$  is a finite approximation of the canonical form of a program of type `Exp`. Operationally,  $U$  is the set of all programs of type `Exp` which approximate the canonical form of the program. Notions of *inclusion*  $\supseteq$  and *intersection*  $\cap$  of neighbourhoods.

A grammar for expression neighbourhoods:

$$U ::= \Delta \mid K \mid S \mid U@U$$

A grammar for the sublanguage of normal form neighbourhoods:

$$U ::= \Delta \mid K \mid K@U \mid S \mid S@U \mid (S@U)@U$$

# Combinatory Böhm trees

A (combinatory) Böhm tree is a *filter* of normal form neighbourhoods. A filter is a set  $\alpha$  of neighbourhoods satisfying:

- $U \in \alpha$  and  $U' \supseteq U$  implies  $U' \in \alpha$ ;
- $\Delta \in \alpha$ ;
- $U, U' \in \alpha$  implies  $U \cap U' \in \alpha$ .

## Approximations of head normal forms

$$e \triangleright^{\text{Bt}} \Delta$$

$$\frac{e \Rightarrow^{\text{h}} K}{e \triangleright^{\text{Bt}} K}$$

$$\frac{e \Rightarrow^{\text{h}} K@e' \quad e' \triangleright^{\text{Bt}} U'}{e \triangleright^{\text{Bt}} K@U'}$$

$$\frac{e \Rightarrow^{\text{h}} S}{e \triangleright^{\text{Bt}} S}$$

$$\frac{e \Rightarrow^{\text{h}} S@e' \quad e' \triangleright^{\text{Bt}} U'}{e \triangleright^{\text{Bt}} S@U'}$$

$$\frac{e \Rightarrow^{\text{h}} (S@e')@e'' \quad e' \triangleright^{\text{Bt}} U' \quad e'' \triangleright^{\text{Bt}} U''}{e \triangleright^{\text{Bt}} (S@U')@U''}$$

## The Böhm tree of a combinatory expression

The Böhm tree of an expression  $e$  in  $\text{Exp}$  is the set

$$\{U \mid e \triangleright^{\text{Bt}} U\}$$

One can prove that it is a filter of normal form neighbourhoods, by induction on the definition of  $\triangleright^{\text{Bt}}$ . (Note that the head normal form of an expression is unique.)

One can also prove that two convertible expressions have the same Böhm tree.



## Combinatory conversion

Conversion is inductively generated by the rules of reflexivity, symmetry, and transitivity, together with:

$$(K@e)@e' \text{ conv } e$$

$$((S@e)@e')@e'' \text{ conv } (e@e')@(e@e'')$$

$$\frac{e_0 \text{ conv } e_1 \quad e'_0 \text{ conv } e'_1}{e_0@e'_0 \text{ conv } e_1@e'_1}$$

## Operational neighbourhoods of nbe

$\text{nbe } e \in U$  iff  $U$  is a finite approximation of the canonical form of  $\text{nbe } e$  when evaluated lazily. For example,

- $\text{nbe } e \in \Delta$ , for all  $e$
- $\text{nbe } K \in K$
- $\text{nbe } (Y@K) \in K@\Delta$
- $\text{nbe } (Y@K) \in K@(K@\Delta)$ , etc

$Y$  is a fixed point combinator.

## Definition of the operational neighbourhood relation

Is this operational semantics or denotational semantics?

The definition of the operational neighbourhood relation follows the computation rules (operational semantics) of a program. So to define the relation  $\text{nbe } e \in U$ , we must first define the relations  $\text{eval } e \in V$  and  $\text{reify } x \in U$ . Here  $V$  is a neighbourhood of the reflexive type

```
data Sem = Gl Exp (Sem -> Sem)
```

We need to consider *function neighbourhoods*.

## Function neighbourhoods

If  $(U_i)_{i < n}$  and  $(V_i)_{i < n}$  are families of neighbourhoods of types  $\sigma$  and  $\tau$ , respectively, then

$$\bigcap_{i < n} [U_i; V_i]$$

is a function neighbourhood of the type  $\sigma \rightarrow \tau$ . We write  $\Delta = \bigcap_{i < n} [U_i; V_i]$ .

If  $f$  is a program of type  $\sigma \rightarrow \tau$ , then

$$f \in \bigcap_{i < n} [U_i; V_i]$$

iff for all  $i < n$ ,  $a \in U_i$  implies  $f a \in V_i$ . In addition to inclusion and meet we consider *consistency (inhabitedness)* of function neighbourhoods.

## Neighbourhoods in Sem

- $\Delta$  is a Sem-neighbourhood.
- If  $U$  is an Exp-neighbourhood and  $(V_i)_{i < n}$  and  $(W_i)_{i < n}$  are families of Sem-neighbourhoods, then

$$\text{Gl } U \left( \bigcap_{i < n} [V_i; W_i] \right)$$

is a Sem-neighbourhood.

## Operational neighbourhoods of $\text{eval } e$

$\text{eval } e \in \Delta$ , as always.

For  $e = K$  we have the equation

$$\text{eval } K = \text{G1 } K (\lambda x. \text{G1 } (K@(\text{reify } x)) (\lambda y. x))$$

Hence,

$$\text{eval } K \in \text{G1 } U \left( \bigcap_i [V_i; W_i] \right)$$

iff  $K \in U$  and for all  $i$  and for all  $x \in V_i$ , we have  $\text{G1 } (K@(\text{reify } x)) (\lambda y. x) \in W_i$ . This is the case iff either  $W_i = \Delta$  or  $W_i = \text{G1 } U_i \left( \bigcap_j [V_{ij}; W_{ij}] \right)$  and  $K@(\text{reify } x) \in U_i$  and  $x \in W_{ij}$  for all  $j$ .

## Operational neighbourhoods of $\text{eval}(e@e')$

Recursion equations

$$\begin{aligned}\text{eval}(e@e') &= \text{appsem}(\text{eval } e)(\text{eval } e') \\ \text{appsem}(\text{Gl } e f) x &= f x\end{aligned}$$

One can prove that  $\text{eval}(e@e') \in W$  iff either  $W = \Delta$  or there exist  $U$  and  $V$  such that  $\text{eval } e \in \text{Gl } U [V; W]$  and  $\text{eval } e' \in V$

## Operational neighbourhoods of nbe

Equations:

$$\begin{aligned} \text{nbe } e &= \text{reify } (\text{eval } e) \\ \text{reify } (\text{Gl } e f) &= e \end{aligned}$$

Thus,  $\text{nbe } e \in U$  iff  $U = \Delta$  or  $\text{eval } e \in \text{Gl } U \Delta$ .



## Nbe maps convertible terms into equal Böhm trees

We can prove that  $\text{nbe } e \in U$  implies that  $U$  is a normal form neighbourhood, and hence the denotation of  $\text{nbe } e$  is a Böhm tree.

We can also prove that if  $e \text{ conv } e'$  and  $\text{nbe } e \in U$ , then  $\text{nbe } e' \in U$ , that is,  $\text{nbe}$  maps convertible terms to equal Böhm trees (cf “uniqueness of normal forms”). As in the typed case this follows by induction on the definition of convertibility, using a lemma that `eval` maps convertible terms into equal denotations.

## Completeness of nbe

Any finite part of the Böhm tree is returned:

$$e \triangleright^{\text{Bt}} U \text{ implies } \text{nbe } e \in U$$

The proof is by induction on the derivation of  $e \triangleright^{\text{Bt}} U$ .

Consider eg the case when  $e \triangleright^{\text{Bt}} K$  comes from  $e \Rightarrow^{\text{h}} K$ . Since  $\text{nbe } K \in K$  and convertible terms have equal Böhm trees it follows that  $\text{nbe } e \in K$ .

## Soundness of nbe

Only approximations of the Böhm tree are returned by nbe:

$$\text{nbe } e \in U \text{ implies } e \triangleright^{\text{Bt}} U$$

We need a lemma (cf reducibility/glueing method)

$$\text{eval } e \in V \text{ implies } e \triangleright^{\text{G1}} V$$

where  $e \triangleright^{\text{G1}} V$  iff either  $V = \Delta$  or  $V = \text{G1 } U (\bigcap_i [V_i; W_i])$  where  $e \triangleright^{\text{Bt}} U$  and for all  $i$  and  $e'$ ,  $e' \triangleright^{\text{G1}} V_i$  implies  $e @ e' \triangleright^{\text{G1}} W_i$ .

This lemma is proved by induction on  $e$ . Soundness then follows immediately.

## Definition of $e \triangleright^{G1} U$

The property on the previous page is not directly acceptable as an inductive definition because of negative occurrence of  $e \triangleright^{G1} U$ .

Instead we define it as the union of an infinite sequence of approximations:  $e \triangleright^{G1} V$  iff there exists an  $n$  such that  $e \triangleright_n^{G1} V$ , where

$$e \triangleright_0^{G1} V \text{ iff } V = \Delta.$$

$e \triangleright_{n+1}^{G1} V$  iff either  $V = \Delta$  or  $V = G1 U (\bigcap_i [V_i; W_i])$  where  $e \triangleright^{Bt} U$  and for all  $i$  and  $e'$ ,  $e' \triangleright_n^{G1} V_i$  implies  $e @ e' \triangleright_n^{G1} W_i$ .

The set  $\{V \mid e \triangleright^{G1} V\}$  is a filter of Sem-neighbourhoods, and is invariant under convertibility.

## Case K: $\text{eval } K \in V$ implies $K \triangleright^{\text{G1}} V$

Proof by analyzing the neighbourhoods of  $\text{eval } K$ .

Case  $V = \Delta$  is immediate.

Case  $V = \text{G1 } U (\bigcap_i [V_i; W_i])$ , where  $K \in U$  and for all  $i$  and  $x \in V_i$ , we have  $\text{G1 } (K@(\text{reify } x)) (\lambda y.x) \in W_i$ . We need to prove two things:

- $K \triangleright^{\text{Bt}} U$ . This follows from  $K \in U$ .
- For all  $i$ ,  $e' \triangleright^{\text{G1}} V_i$  implies  $K@e' \triangleright^{\text{G1}} W_i$ .

Case  $W_i = \Delta$ , and we are done.

Case  $W_i = \text{G1 } U_i (\bigcap_j [V_{ij}; W_{ij}])$ , where  $K@(\text{reify } x) \in U_i$  and  $x \in W_{ij}$  for all  $j$ . We need to show two things:

- $K@e' \triangleright^{\text{Bt}} U_i$ .  
 Case  $V_i = \Delta$ . It follows that  $U_i \supseteq K@\Delta$  and hence  $K@e' \triangleright^{\text{Bt}} U_i$ .  
 Case  $V_i = G1 U'_i (\bigcap_j [V'_{ij}; W'_{ij}])$ . It follows that  $U_i \supseteq K@U'_i$ . We know  $e' \triangleright^{\text{Bt}} U'_i$  and hence  $K@e' \triangleright^{\text{Bt}} U_i$ .
- For all  $j$ ,  $e'' \triangleright^{G1} V_{ij}$  implies  $(K@e')@e'' \triangleright^{G1} W_{ij}$ . Because of closure of convertibility it suffices to prove  $e' \triangleright^{G1} W_{ij}$ . But this follows from  $W_{ij} \supseteq V_i$  and upward closure of  $\triangleright^{G1}$  in the right argument, since we know  $e' \triangleright^{G1} V_i$ .

## Case $e@e'$ :

Prove that  $\text{eval}(e@e') \in W$  implies  $(e@e') \triangleright^{G1} W$  from the induction hypotheses that  $\text{eval } e \in W$  implies  $e \triangleright^{G1} W$  and  $\text{eval } e' \in W'$  implies  $e' \triangleright^{G1} W'$ .

Either  $W = \Delta$  and we are done.

Or there exist  $U$  and  $V$  such that  $\text{eval } e \in G1 U [V; W]$  and  $\text{eval } e' \in V$ . We can now use the induction hypotheses to conclude that  $e \triangleright^{G1} G1 U [V; W]$  and  $e' \triangleright^{G1} V$ . Hence it follows by the second property of  $\triangleright^{G1}$  that  $(e@e') \triangleright^{G1} W$ .

## Conclusion

The proof could presumably be carried out in a similar way using denotational neighbourhoods. Can we isolate the abstract properties of function neighbourhoods which are needed for the proof?