

Large scale airline optimization

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Traditional steps in airline scheduling

1. timetable is determined
2. fleet assignment
3. crew pairing
4. crew rostering

Usually done by different departments.

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Carmen System screenshot

Window	01/11	02/11	03/11	04/11	05/11	06/11	07/11	08/11	09/11	10/11	11/11	12/11	13/11	14/11
	01/11	02/11	03/11	04/11	05/11	06/11	07/11	08/11	09/11	10/11	11/11	12/11	13/11	14/11



Crew pairing example

Leg number	From	To	Departure	Arrival
1	A	B	6.30	13.30
2	B	A	14.30	21.30
3	B	C	10.15	11.45
4	C	B	12.15	13.45
5	B	C	14.15	15.45
6	C	B	16.15	17.45

Rules:

- A pairing must start and end in A or B
- Max 2 day pairings
- Max duration 12 hours/day
- Layover min $1.5 \times$ duration of first day

PAROS

The two main steps of optimization

- 1) Model the problem, i.e. define it and formulate it so that a suitable algorithm can accept it.
- 2) Solve the resulting problem.

Both steps can be very challenging for large and complex real world problems. The steps must be carefully interfaced.

What is an optimization problem?

Example: shortest path problem

Minimize

the length

over

all paths from a to b in a graph

Minimize

the objective function

over

the set of feasible solutions

Mathematical optimization

Minimize

$$x_1 + 3x_2 + x_3$$

subject to

$$x_1 + x_2 = 1$$

$$x_1 + 2x_3 \leq 2$$

$$x_i \text{ binary}$$

Good standard software available

Standard optimization models in transportation

Polynomial:

- Assignment, transportation, transshipment.
- Single depot vehicle scheduling (SDVSP, scheduling= tasks fixed in time).
(can all be translated into network flow)

More difficult (polynomial or exponential depending on details):

- Multiple depot vehicle scheduling (translates into multicommodity flow).
- Shortest path with time windows and/or resource constraints (use dynamic programming),
- Vehicle routing (VRP), Vehicle routing with time windows (VRPTW), pickup/delivery, ... (try greedy+local search or two step approach),

Very difficult to model the rules mathematically.

Rules are defined in an application specific rule language (RAVE).

Compiles to test functions in C code.

Rules can be changed and tried out by users anytime!

```

RULE max_duty =
  %duty% <= 9:00;
  REMARK "Maximal
  duty";
END

```

```

rule max_duty_a =

%fdp_length% <= %max_duty_acclimatized%;

remark "Maximum scheduled FDP acclimatized";

end

%fdp_length% = last(leg, arrival) - first(leg, departure) + 2:00;

%max_duty_acclimatized% = matrix m_max_duty_acclimatized;

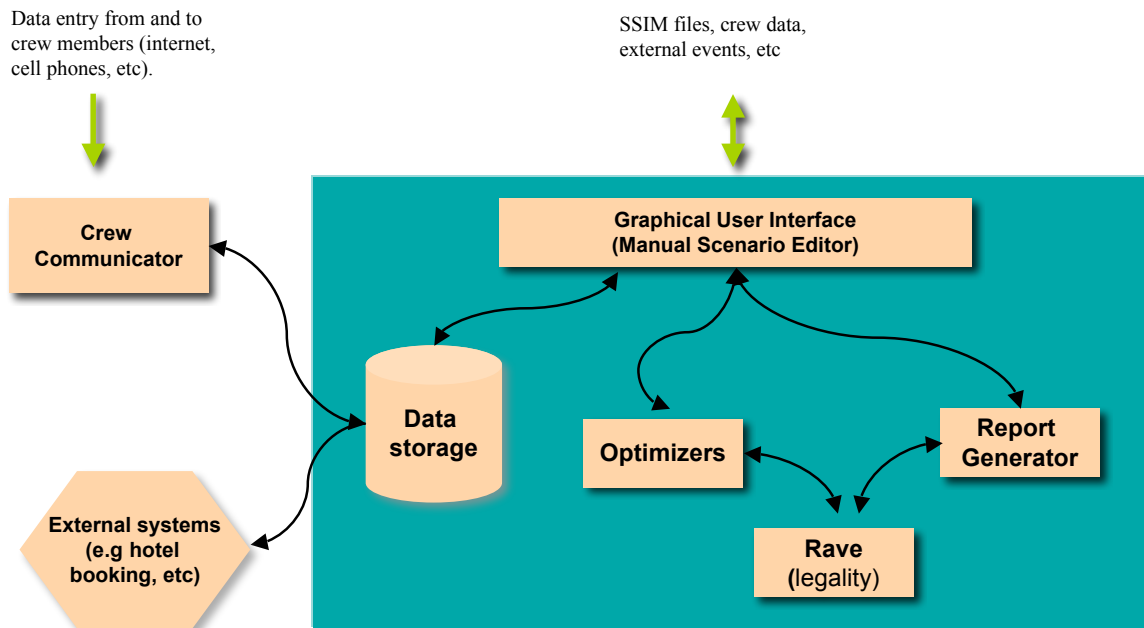
matrix m_max_duty_acclimatized =

%landings%, %local_checkin% -> %max_duty_acclimatized%;
(0,1), 2, 3, 4, 5, - ;
(06:00,07:59); 12:00, 11:45, 11:00, 10:15, 9:00, 0:00;
(08:00,12:59); 12:00, 12:00, 12:00, 11:45, 10:15, 0:00;
(13:00,17:59); 12:00, 12:00, 11:30, 10:45, 9:15, 0:00;
(18:00,21:59); 12:00, 11:15, 10:30, 9:45, 9:00, 0:00;
(22:00,05:59); 11:00, 10:15, 9:30, 9:00, 9:00, 0:00;

end

```

In this code, the rule %max_duty_a% specifies that the expression %fdp_length% must be less than the expression %max_duty_acclimatized%. These expressions are then defined, %fdp_length% by accessing some data in the line of work, and %max_duty_acclimatized% by the use of a "matrix", whose (scalar) value is determined by table lookup based on the values of %landings% and %local_checkin%.



Standard methods for solving transport optimization problems

1. Time-space networks and network flow, or special cases thereof (assignment, transportation, transshipment)
2. Construction heuristics with greedy and local search
3. Two-step approach for general task scheduling: generate separate paths first, then optimize how to combine them. Column generation

Attention to small details and special properties of the problem at hand is crucial for best performance.

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PAROS

Enumeration of all legal pairings

P1 1-1o-2 (2)	P7 5-6 (1)	P13 3-1o-4-5-6 (2)
P2 1-1o-3-4-2 (2)	P8 3-4-5-6 (1)	P14 3-4-5-1o-4 (2)
P3 1-5-1o-4-2 (2)	P9 2-1o-1 (2)	P15 3-4-5-1o-4-5-6
P4 1-5-6-1o-2 (2)	P10 2-1o-1-5-6 (2)	P16 5-1o-4 (2)
P5 3-4 (1)	P11 3-1o-4 (2)	P17 5-1o-4-5-6 (2)
P6 3-6 (1)	P12 3-1o-6 (2)	

1o: layover

PAROS

The resulting optimization problem

minimize $2x_1 + 2x_2 + 2x_3 + 2x_4 + x_5 + x_6 + x_7 + x_8 + 2x_9 + 2x_{10}$
 $+ 2x_{11} + 2x_{12} + 2x_{13} + 2x_{14} + 2x_{15} + 2x_{16} + 2x_{17}$

subject to

$$x_1 + x_2 + x_3 + x_4 + x_9 + x_{10} = 1$$

$$x_1 + x_2 + x_3 + x_4 + x_9 + x_{10} = 1$$

$$x_2 + x_5 + x_6 + x_8 + x_{11} + x_{12} + x_{13} + x_{14} + x_{15} = 1$$

$$x_2 + x_3 + x_5 + x_8 + x_{11} + x_{13} + 2x_{14} + 2x_{15} + x_{16} + x_{17} = 1$$

$$x_3 + x_4 + x_7 + x_8 + x_{10} + x_{13} + x_{14} + 2x_{15} + x_{16} + 2x_{17} = 1$$

$$x_4 + x_6 + x_7 + x_8 + x_{10} + x_{12} + x_{13} + x_{15} + x_{17} = 1$$

$$x_1, x_2, x_3, x_4, x_5, x_6, x_7, x_8, x_9, x_{10}, x_{11}, x_{12}, x_{13}, x_{14}, x_{15}, x_{16}, x_{17} \in \{0, 1\}$$

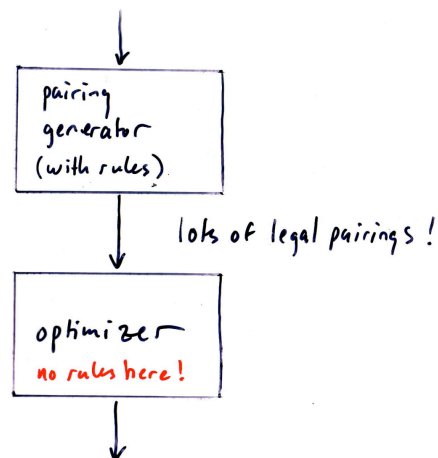
PAROS

Crew scheduling

Main design conflict:
rule modelling versus
optimization

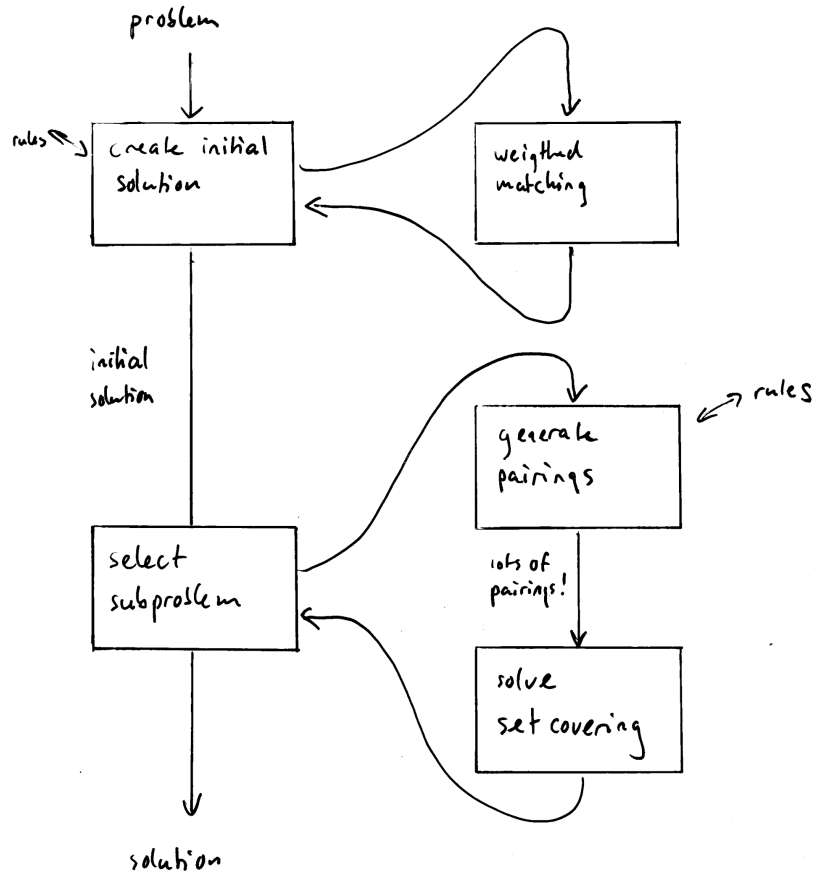
Try to separate them!

Classical hybrid solution:

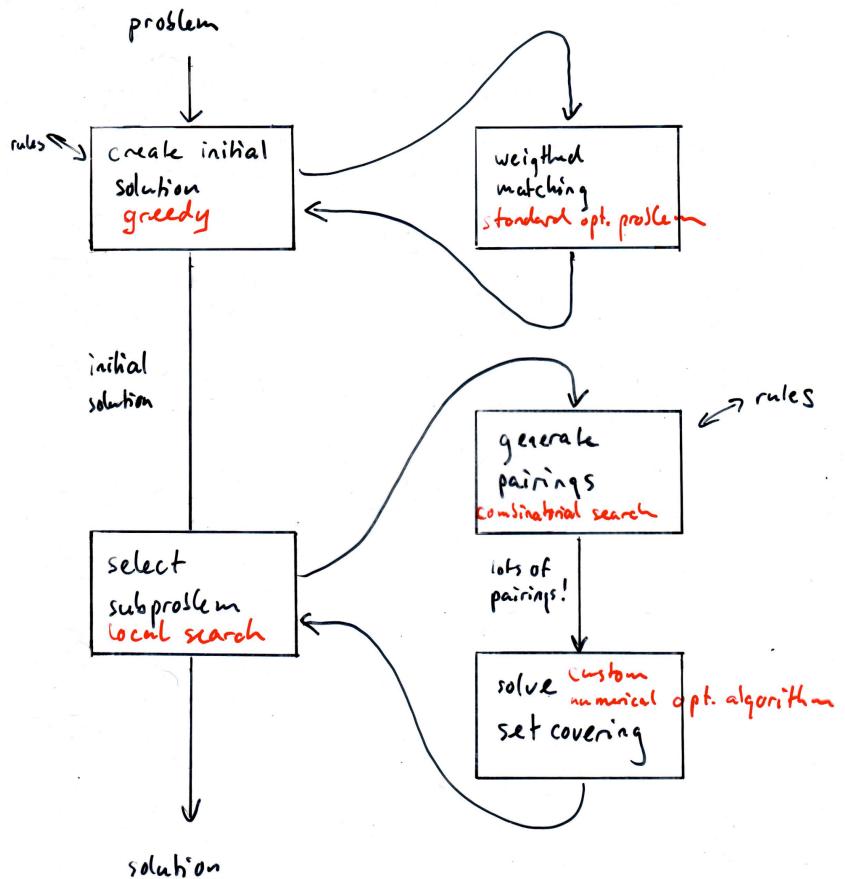


Combinatorial explosion in both steps!

Pairing optimization overview



Algorithm design techniques



How solve the large problems?

- Selection of daily subproblems.
- Generator search heuristics. E.g. generate pairings that follow the aircraft.
- Special purpose algorithm for the large optimization problems (10^6 variables, 10^4 constraints).
- Heuristic solution to deadheading

More recent developments

Send feedback from optimizer to generator.

The idea is to get new pairings that may improve current solution (solve constrained shortest path problem in generator).

Nice mathematical theory but tricky in practice.

A challenge to integrate with the separate rule system.

The set covering optimizer

Solves the problem

$$\min cx$$

$$Ax \geq 1$$

$$Cx \leq d \quad (\text{base capacity constraints})$$

Solved using numerical algorithms:

- CPLEX for small and medium sized problems
- propl or pags for large problems

developed at Chalmers!

The simple assignment problem

$$\min \sum_i \sum_j c_{ij} x_{ij}$$

subject to

$$\sum_j x_{ij} = 1$$

$$\sum_i x_{ij} = 1$$

$$x_{ij} \in \{0, 1\}$$

tasks

	5	6	2	9
	4	6	7	1
	1	5	3	6
persons	9	2	5	5

Observation 1: some instances are easy to solve just by inspecting the cost matrix

Some observations

4	-3	11	2
5	2	-8	7
-6	9	2	4
3	3	4	-1

Observation 2: the problem is invariant with respect to additions or subtractions of any constant to a row or column

Simple idea: use the invariants to make the problem easy!

Operational description

ex assignment problem

old \bar{c}			
5	2	9	7
6	1	11	8
1	9	5	3
4	5	0	6
r^+		r^-	

⇒

new \bar{c}			
5	2	9	7
6	1	11	8
1	9	5	3
2	3	-2	4

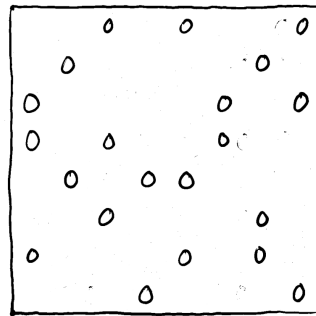
Look at each constraint separately and choose

$$y_i = -\frac{r^+ + r^-}{2}$$

Iterate!

What happens when we run this simple algorithm?

But for less trivial problems we get lots of zeros in \bar{C} :



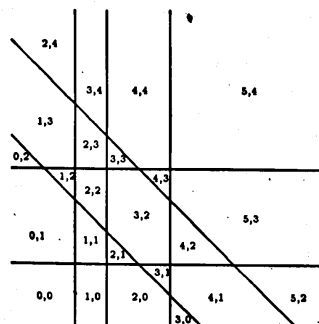
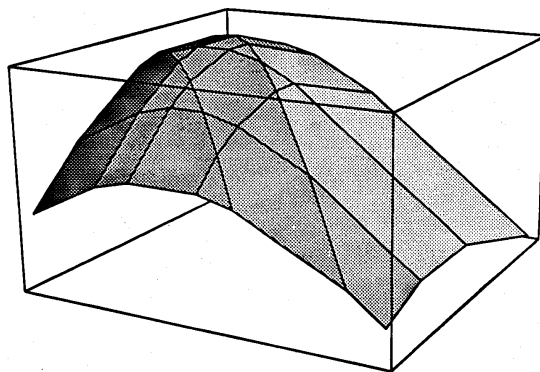
eg. 8-queens with diagonal constraints

For simple assignment it works fine!

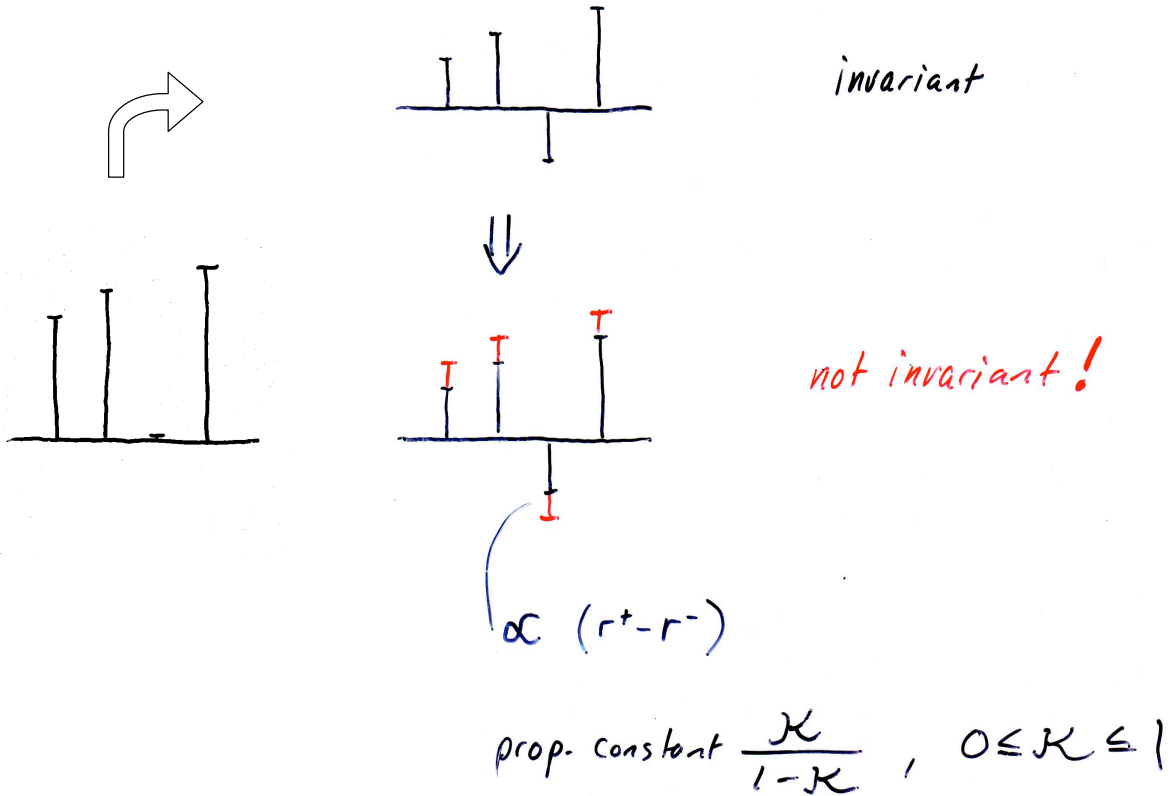
No unique solution \Rightarrow useless!

What shall we do?

Coordinate search in dual space



The heuristic



Now it suddenly works!

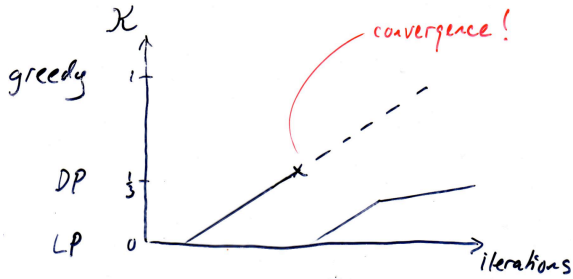
(weighted 8-queens problem)

1	3	7	5	8	3	2	9
5	3	8	7	5	1	1	9
4	3	7	5	8	2	3	8
7	1	2	4	1	4	6	2
2	6	2	8	4	4	4	1
3	5	4	5	4	5	4	5
1	2	3	4	5	6	7	8
3	2	2	2	2	2	6	8

0	0	0	0	1	0	0	0
0	0	0	0	0	0	0	1
0	0	0	1	0	0	0	0
1	0	0	0	0	0	0	0
0	0	0	0	0	0	1	0
0	1	0	0	0	0	0	0
0	0	0	0	0	1	0	0
0	0	1	0	0	0	0	0

Sweep mechanism

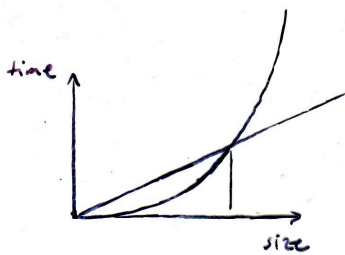
$K > 0$ gives fast convergence and usually a high quality integer solution!



Interpolation between different algorithmic design principles!

No exponential blowup \Rightarrow very large problems ok!

Performance



size after preprocessing		
rows	columns	nonzero
29	157	372
118	1165	4155
199	6931	31801
235	18753	82229
742	10370	42695
1366	25032	110881
1585	105804	566905

linear prob1

CPLEX	our method
0.2s	1.4s
1s	11s
23s	1m4s
2m12s	5m2s
23m	3m58s
5h53m	7m46s
-	36m10s

CPLEX	our method
92800	92800
5017500	5017500
529250	529250
565000	565000
4737768	4737892
4335780	4333450
-	4329750

same quality!

Same general picture supported by regular benchmarking (2004)

“Carmen is one of the best investments we have ever made”

British Airways



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Optimization trends

10 years ago - an overnight run,
today - within seconds.

Combined effect of faster algorithms and faster computers.

This makes it possible to:

improve modelling detail (gives larger problems)

integrate planning steps (gives larger problems)

approach day-of-operation planning (requires faster optimizers)

Carmen day of operation tools

The screenshot displays the Carmen day of operation tools interface, which is used for managing flight operations and disruptions. The interface is divided into several main sections:

- MONITOR:** Shows flight status for various routes, including MEX, ORD, and LHR. It includes columns for Tail No, Airport, and Date.
- Figures Aircraft Crew:** Provides a detailed view of flight schedules and crew assignments for specific aircraft (e.g., DAR 1307, 319, 320). It includes columns for Tail, Airp, Te, and Crew.
- Figures Aircraft Crew (Detailed):** Shows a more granular view of flight schedules and crew assignments, including columns for Tail, Airp, Te, and Crew.
- Disruptions for ILCPSK:** Lists various disruption events with columns for Reference Number, Status, Submitter, and Description. It also includes a table with columns for SHDM, AC, FC, CC, CDRM, and Total.
- Disruption ref. ILCPSK:** Provides detailed information about a specific disruption, including the Disruption ref. (ILCPSK), Disruption evaluation cost (2409), and Disruption evaluation cost (PVCAM) (24533).
- Delayed passengers per hour:** A bar chart showing the number of delayed passengers per hour for different disruption categories (0-2, 3-4, 4-6, 6-24, >24).
- Table of Flight Schedules:** A table showing flight schedules with columns for To, Flud. Dep., Flud. Arr., Departure, Arrival, Status, and Effect.

The interface is designed to provide a comprehensive overview of flight operations and disruptions, allowing users to monitor and manage their operations effectively.