Programs

Programs

$$M, A ::= v_k \mid M M \mid \lambda M \mid \Pi A A \mid M D \mid c \vec{M} \mid B \mid L$$

Definitions, Branches and Labelled Sums

$$D ::= [\vec{M} : \vec{A}] \quad B ::= c_1 \ M_1, \dots, c_k \ M_k \quad L ::= c_1 \ \vec{A_1}, \dots, c_k \ \vec{A_k}$$

Environments and Values

Environments and Values

 $\rho, \sigma ::= () \mid \rho, u \mid D\rho \qquad u, V ::= M\rho \mid u \mid u \mid X_l \mid \Pi \mid V \mid V$

Access rules

$$v_0(\sigma,u)=u \quad v_{k+1}(\sigma,u)=v_k\sigma$$
 and if $\rho=[\vec{M}:\vec{A}]\sigma$ then
$$v_i\rho=v_i(\sigma,\vec{M}\rho)$$

Evaluation rules

$$(M_1 \ M_2)\rho = M_1\rho \ (M_2\rho) \qquad (M \ D)\rho = M(D\rho)$$
$$(\Pi \ A \ F)\rho = \Pi \ (A\rho) \ (F\rho) \qquad (c \ \vec{M})\rho = c \ (\vec{M}\rho)$$
$$(\lambda \ M)\rho \ u = M(\rho, u) \qquad (c_1 \ N_1, \dots, c_k \ N_k)\rho \ (c_i \ \vec{u}) = N_i(\rho, \vec{u})$$

Programs, version with names

Programs

$$M, A ::= x | M M | \lambda x.M | \Pi x : A, A | M D | c \vec{M} | B | L$$
$$T ::= () | T' T' ::= A | (x : A, T')$$

Definitions, Branches and Labelled Sums

$$D ::= [\vec{x} : T = \vec{M}] \quad B ::= c_1 \ \vec{x_1} \to M_1, \dots, c_k \ \vec{x_k} \to M_k$$
$$L ::= c_1 \ T_1, \dots, c_k \ T_k$$

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Conversion test

Each branch B has a name f_B and each labelled sum L a name d_L associated to it. We test $A_1 = A_2$ by comparing $R_k A_1$ and $R_k A_2$

$$R_{k} X_{l} = v_{k-l-1}$$

$$R_{k} ((\lambda M)\rho) = \lambda R_{k+1}(M(\rho, X_{k})) \qquad R_{k} (u_{1} u_{2}) = R_{k} u_{1} (R_{k} u_{2})$$

$$R_{k} (\Pi V F) = \Pi (R_{k} V) (R_{k} F) \qquad R_{k} (c \vec{u}) = c (R_{k} \vec{u})$$

$$R_{k} (B\rho) = f_{B}(R_{k} \rho) \qquad R_{k} (L\rho) = d_{L}(R_{k} \rho)$$

$$R_{k} () = () \qquad R_{k} (\rho, u) = (R_{k} \rho, R_{k} u) \qquad R_{k} (D\rho) = R_{k} \rho$$

Conversion test

Here is the grammar for the normal forms produced by the readback function ${\cal R}_k$

$$t ::= \lambda t \mid d_L(t, \dots, t) \mid \Pi t t \mid f_B(t, \dots, t) \mid c(t, \dots, t) \mid n$$
$$n ::= v_l \mid n t \mid f_B(t, \dots, t) n$$

Type-checking

The judgements are of the form $\rho, \Gamma \vdash_k A$ and $\rho, \Gamma \vdash_k M : V$ where Γ is a list of type values and k the number of free variables. For instance

$$\frac{\overline{\rho, \Gamma \vdash_{k} v_{n} : \Gamma!n}}{\rho, \Gamma \vdash_{k} N : \Pi \ V \ F \ \rho, \Gamma \vdash_{k} M : V}}$$

$$\frac{\rho, \Gamma \vdash_{k} N \ M : F \ (M\rho)}{\rho, \Gamma \vdash_{k} N \ M : F \ (M\rho)}$$

$$\frac{(\rho, X_{k}), (\Gamma, V) \vdash_{k+1} N : F \ X_{k}}{\rho, \Gamma \vdash_{k} \lambda N : \Pi \ V \ F}$$

Examples

```
Nat : Set = 0 | S Nat
Bin : Set = 1 | SO Bin | S1 Bin
natrec : (P : Nat -> Set) ->
        P 0 -> ((i : Nat) -> P i -> P (S i)) ->
        (n : Nat) -> P n =
        \ P -> \ p0 -> \ pS ->
        [ 0 -> p0
        |S x -> pS x (natrec P p0 pS x) ]
```

Examples

Denotational Semantics

Formal neighbourhoods

$$W ::= \nabla \mid W \to W \mid W \cap W \mid c \vec{W} \mid [c_1 \ \vec{U_1}, \dots, c_n \ \vec{U_n}]$$
$$U ::= \Delta \mid W$$

Denotational Semantics

$$\frac{\Gamma, \vec{U}^{(0)} \vdash \vec{M} : \vec{U}^{(1)} \dots \Gamma, \vec{U}^{(l-1)} \vdash \vec{M} : \vec{U}^{(l)} \quad \Gamma, \vec{U}^{(l)} \vdash N : V}{\Gamma \vdash ND : V}$$

where D is $[\vec{M}:\vec{A}]$ and $\vec{U}^{(0)}$ is $\vec{\Delta}$.

Denotational Semantics

The elements of the domain D are either constructor terms $c \vec{u}$ or product $\Pi u f$ or labelled sums $[c_1 \vec{a_1}, \ldots, c_n \vec{a_n}]$ or functions f

Theorem: If the semantics of a term M is $\neq \perp$ then M is SN

Models

A *totality* on D is a subset $X \subseteq D$ such that $\perp \notin X$ and $\top \in X$. We write TP(D) the set of all totality on D.

A partial interpretation of type theory is a pair (X, El) with X in TP(D) and El in $X \to TP(D)$ such that $El(\top)$ is the singleton $\{\top\}$

We extend X and El to vectors: () in X and () $\in El()$ and (a, \vec{a}) in X iff $a \in X$ and $\vec{a} u$ in X for all $u \in El(a)$. Then (u, \vec{u}) in $El(a, \vec{a})$ iff $u \in El(a)$ and \vec{u} in $El(\vec{a} u)$

Models

(X, El) total interpretation: b in X iff

 $b = \Pi \ a \ f \ and \ a \in X \ and \ f \ u \in X \ for \ all \ u \in El(a) \ and \ w \in El(b) \ iff w \ u \in El(f \ u) \ for \ all \ u \in El(a)$

or $b = [c_1 \ \vec{a_1}, \dots, c_n \ \vec{a_n}]$ and $\vec{a_i} \in X$ and $w \in El(b)$ iff $w = c_i \ \vec{u}$ with $\vec{u} \in El(\vec{a_i})$

```
Bin : Set = 1 | SO Bin | S1 Bin
bsuc : Bin -> Bin =
[ 1 -> S0 1
|S0 x -> S1 x
|S1 x -> S0 (bsuc x) ]
```

"So that's that, except that it's a bit tricky and a bit higher-order and, worst of all, quite expensive in the *size* of the inductions involved. If we're being scrupulous about universe levels, we have to be careful about quantifying over arbitrary $P : Bin \to Set_i$. To be allowed such a thing we need to use our structural induction principal at Set_{i+1} ."

Induction principle in this version of type theory (with pattern-matching) works on an *arbitrary* type

Similar analysis in Lorenzen: induction principle is justified on an arbitrary formula

```
Peano : Bin -> Set where
  p1 : Peano 1
  ps : {x : Bin} -> Peano x -> Peano (bsuc x)
peano : (b : Bin) -> Peano b
double : {b : Peano} -> Peano b -> Peano (S0 b)
```

Other example

```
Lookup function on vectors
```

```
vec : (Nat -> Set) -> Nat -> Set
vec B 0 = One
```

```
vec B (S x) = (vec B x) * (B x)
```

```
get : (B : Nat -> Set) -> (n x : Nat) ->
x < n -> vec B n -> B x
```