



Parallel linked lists

Lecture 10 of TDA384/DIT391
Principles of Concurrent Programming

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Chalmers University of Technology | University of Gothenburg SP3 2018/2019

Based on course slides by Carlo A. Furia

Today's menu

The burden of locking

Linked set implementations

Nodes, lists, and sets

Sequential access

Parallel linked sets

Coarse-grained locking

Fine-grained locking

Optimistic locking

Lazy node removal

Lock-free access

The burden of locking

Synchronization costs

A number of factors challenge designing correct and efficient parallelizations:

- · sequential dependencies
- · synchronization costs
- · spawning costs
- · error proneness and composability

Synchronization costs

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- · spawning costs
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In this class, we focus on reducing the synchronization costs associated with locking.

The trouble with locks

Standard techniques for concurrent programming are ultimately based on locks. Programming with locks has several drawbacks:

- · performance overhead
- · lock granularity is hard to choose:
 - · not enough locking: race conditions
 - too much locking: not enough parallelism
- · risk of deadlock and starvation
- lock-based implementations do not compose
- · lock-based programs are hard to maintain and modify

Message-passing programming is higher-level, but it also inevitably incurs synchronization costs – of magnitude comparable to those associated with locks.

Breaking free of locks

Lock-free programming takes a fresh look at the problems of concurrency and tries to dispense with using locks altogether.

- Lock-based programming is pessimistic: be prepared for the worst possible conditions:
 if things can go wrong, they will.
- Lock-free programming is optimistic: do what you have to do without worrying about race conditions:

if things go wrong, just try again.

Lock-free programming

Lock-free programming relies on:

- using stronger primitives for atomic access,
- building optimistic algorithms using those primitives.

Compare-and-set operations are an example of stronger primitives:

```
public class AtomicInteger {
    // atomically set to 'update' if current value is 'expect'
    // otherwise do not change value and return false
    boolean compareAndSet(int expect, int update)
}
```

To update an AtomicInteger variable k:

```
do { // keep trying until no one changes k in between
  int oldValue = k.get();
  int newValue = compute(oldValue);
} while (!k.compareAndSet(oldValue, newValue));
```

Compare-and-set is not free

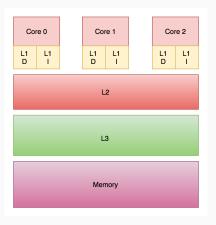


Diagram by Avadlam3, Wikipedia (2016).

CAS operations are not free: they involve memory barrier operations to synchronize caches (~100-1000 cycles).

Compare-and-set is not free

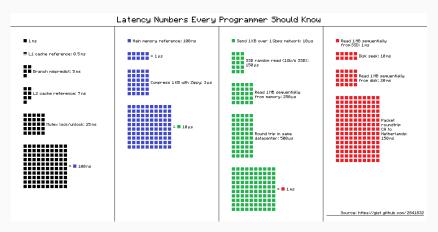


Chart by ayshen, based on Peter Norvig's "Teach Yourself Programming in Ten Years".

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Lock-free vs. wait-free

Two classes of lock-free algorithms, collectively called non-blocking:

lock-free: guarantee system-wide progress: infinitely often, some

process makes progress,

wait-free: guarantee per-process progress: every process

eventually makes progress.

Wait-free is stronger than lock-free:

· Lock-free algorithms are free from deadlock.

· Wait-free algorithms are free from deadlock and starvation.

Thread-safe data structures

Programming correctly without using locks is challenging.

Instead of trying to develop general techniques, we focus on implementing reusable data structures that make minimal usage of locking. The effort involved in developing correct implementations pays off since very many applications can then use such thread-safe data structure implementations to synchronize safely and implicitly by accessing the structures through their APIs.

A data structure is thread safe if its operations are free from race conditions when executed by multi-threaded clients.

Our lock-free and wait-free algorithms are some of those used in the implementations of thread safe structures in <code>java.util.concurrent</code> (non-blocking data structures atomically accessible in parallel).

Linked set implementations

Parallel linked lists

In the rest of this class, we go through several implementations of linked lists that support parallel access; the implementations differ in how much locking they use to guarantee correctness and, correspondingly, in how much parallelism they allow.

We will use pseudo-code that is very close to <u>regular Java syntax</u> but occasionally takes some liberties to simplify the notation. On the course website you can download fully working implementations of some of the classes.

Linked set implementations

Nodes, lists, and sets

The interface of a set

We use <u>linked lists</u> to implement a set data structure with interface:

```
public interface Set<T>
{
  // add 'item' to set; return false if 'item' is already in the set
  boolean add(T item);
  // remove 'item' from set; return false if 'item' not in the set
  boolean remove(T item);
  // is 'item' in set?
  boolean has(T item);
```

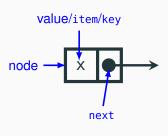
Nodes

The underlying implementations of sets use singly-linked lists, which are made of chains of nodes. Every node:

- stores an item its value
- has a unique key the value's hash code
- · points to the next node in the chain

In the graphical representations of nodes, we do not distinguish between items and their keys – and represent both by characters:

```
interface Node<T>
{
    // value of node
    T item();
    // hash code of value
    int key();
    // next node in chain
    Node<T> next();
}
```



Lists as chains of nodes

A list with special head and tail nodes implements a set:

- the elements of the set are items in different nodes
- to facilitate searching, the nodes are maintained sorted in ascending keys
- to facilitate searching, the head has the <u>smallest</u> possible key, the tail has the <u>largest</u> possible key, and all elements have <u>finitely</u> many keys that are in between

For example, the set $\{b, e, a, f, g\}$ is implemented by:



Relaxing these assumptions is possible at the cost of complicating the implementations a bit.

Linked set implementations

Sequential access

Sequential set: basic linked implementation

We start with a standard linked-list-based implementation of sets, which only works for sequential access.

```
class SequentialSet<T> implements Set<T>
 // nodes at beginning and end
  protected Node<T> head, tail;
  // empty set
  public SequentialSet() {
    head = new SequentialNode<>(Integer.MIN_VALUE); // smallest key
    tail = new SequentialNode<>(Integer.MAX_VALUE); // largest key
    head.setNext(tail):
  }
```

Empty set: head

→

tail

Nodes in a sequential set

A node's implementation uses private attributes with getters and setters; this is a bit tedious now (we could just let the set implementations access the attributes directly), but it will lead to nicer designs in the several variants of set implementations we'll describe.

```
class SequentialNode<T> implements Node<T> {
  private T item; // value stored in node
  private int key; // hash code of item
  private Node<T> next; // next node in chain
    // getters
  T item() { return item; }
  int key() { return key; }
  Node<T> next() { return next; }
    // setters
  void setItem(T item) { this.item = item; }
  void setKey(int key) { this.key = key; }
  void setNext(Node<T> next) { this.next = next; }
```

Since we maintain nodes in order of key, and every item has a unique key, we can search for the position of any given key by going through the list from head to tail.

The method find implements this frequently used operation of finding the position of a key inside a list. The position of key is a pair (pred, curr) of adjacent nodes, such that pred.key() < key <= curr.key().

For example, the position of c in the following list is:

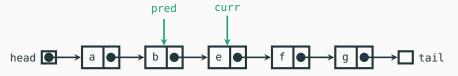


Thanks to the boundary keys chosen for head and tail, searching for any value key returns a valid position in the list.

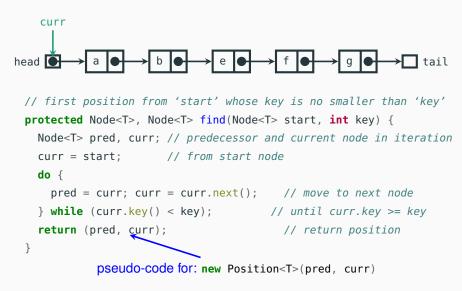
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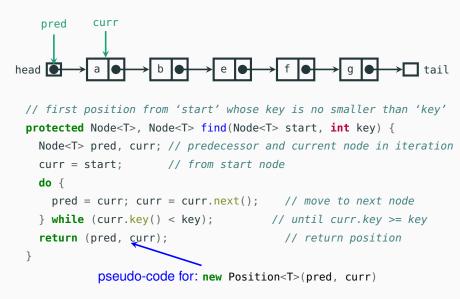
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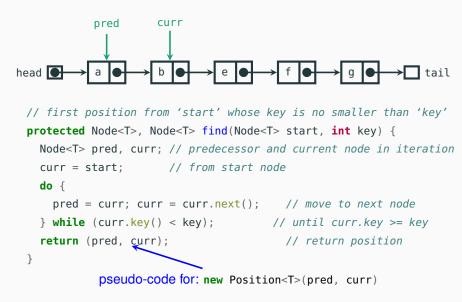
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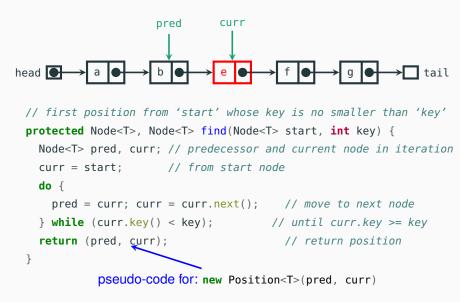


Thanks to the boundary keys chosen for head and tail, searching for any value key returns a valid position in the list.









A set has item if and only if item is (equal to) the first element in the set whose key is greater than or equal to item's.

```
a \longrightarrow b \longrightarrow e \longrightarrow f \longrightarrow g \longrightarrow
// is 'item' in set?
public boolean has(T item) {
  int key = item.key();
                          // item's key
    // find position of key from head
  Node<T> pred, curr = find(head, key);
    // curr.key() >= key
  return curr.key() == key; // item can only appear here!
```

A set has item if and only if item is (equal to) the first element in the set whose key is greater than or equal to item's.

```
pred
                          curr
// is 'item' in set?
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   // find position of key from head
 Node<T> pred, curr = find(head, key);
   // curr.key() >= key
  return curr.key() == key; // item can only appear here!
```

A new item must be added between pred and curr, where (pred, curr) is item's position in the list.

```
public boolean add(T item) {
  Node<T> node = new Node<>(item);  // new node
  Node<T> pred, curr = find(head, item.key()); // curr.key >= item.key()
  if (curr.key() == item.key()) return false; // item already in set
  else // item not already in set: add node between pred and curr
  { node.setNext(curr); pred.setNext(node); return true; }
}
```

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head $\bullet \rightarrow a \rightarrow b \rightarrow e \rightarrow f \rightarrow g \rightarrow tail$

```
head  a b b e f g tail
```

```
node: c
```

```
head a b e f g a tail
```

```
head a b e f g tail
```

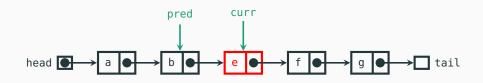
Sequential set: method remove

An element item is removed from a set by redirecting pred.next to skip over curr, where (pred, curr) is item's position in the list.



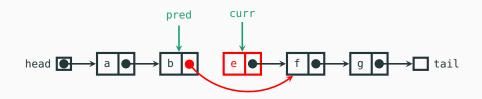
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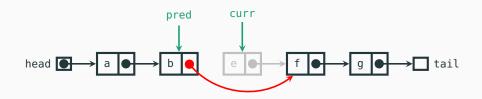
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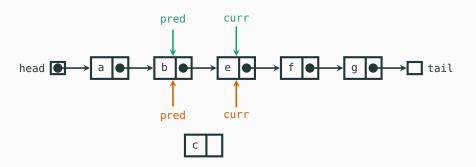
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If multiple threads are active on the same instance of SequentialSet, they can easily interfere with each other's operations — and possibly leave the set in an inconsistent state.

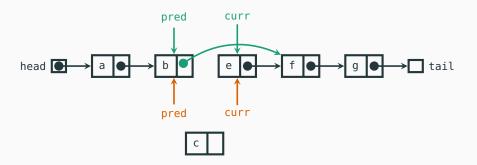
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For example, if thread t runs remove(e) while thread u runs add(c): in some interleavings, remove is reverted:



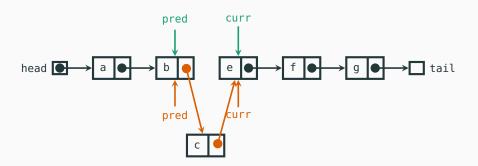
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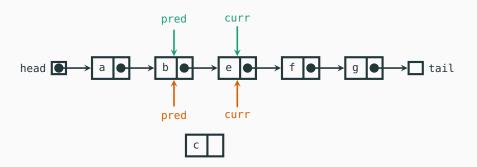
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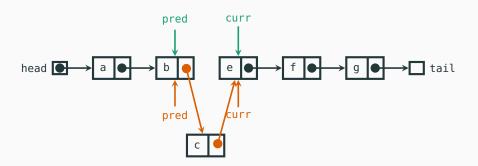
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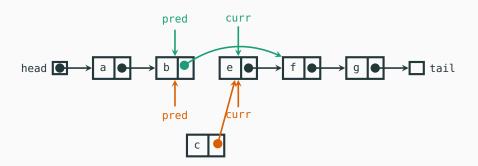
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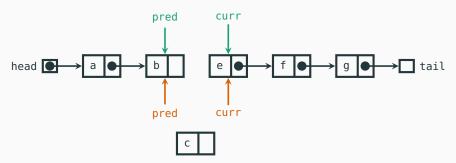
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If find goes through the list while another thread is modifying it, even more subtle errors may occur.

Parallel linked sets

Parallel linked sets

Coarse-grained locking

Concurrent set with coarse-grained locking

A straightforward way to make SequentialSet work correctly under concurrency is using a lock to ensure that at most one thread at a time is operating on the structure.

```
class CoarseSet<T> extends SequentialSet<T>
{
    // lock controlling access to the whole set
    private Lock lock = new ReentrantLock();

    // overriding of add, remove, and has
```

Every method add, remove, and has simply works as follows:

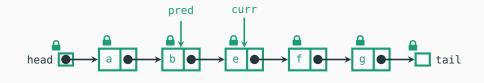
- 1. acquires the lock on the set
- 2. performs the operation as in Sequential Set
- 3. releases the lock on the set



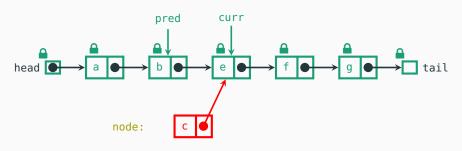
```
node: c
```

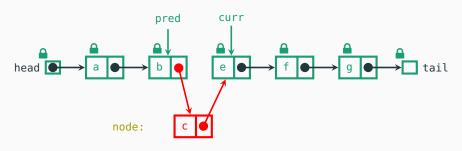


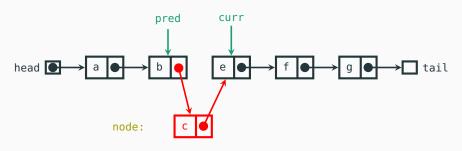
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```

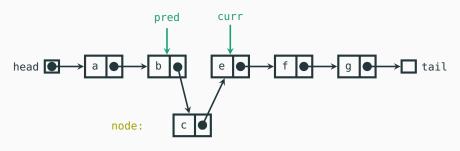


```
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```



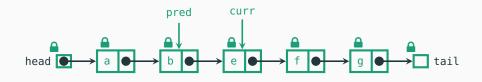


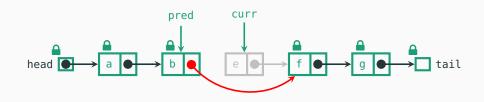




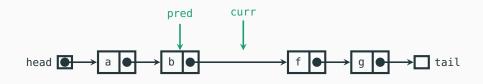






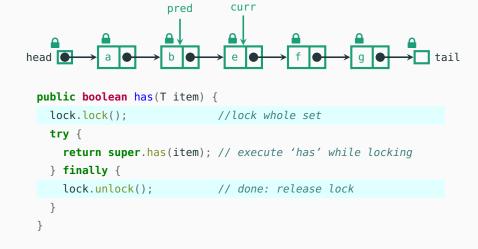


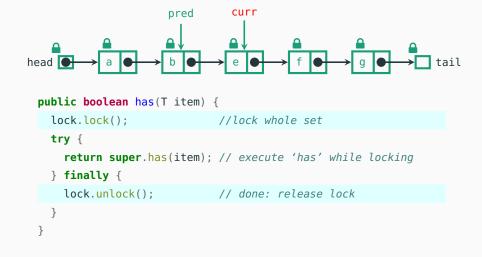


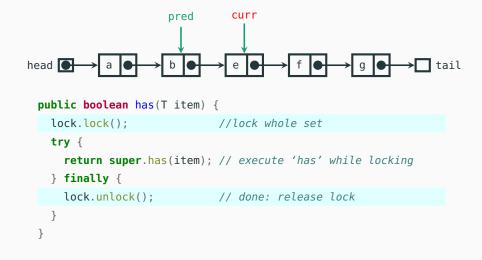












Coarse-locking set: pros and cons

Pros:

- obviously correct it avoids race conditions and deadlocks
- · if the lock is fair, so is access to the set
- if contention is low (not many threads accessing the set concurrently), CoarseSet is quite efficient

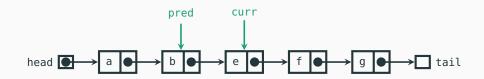
Cons:

- access to the set is essentially sequential missing opportunities for parallelization
- if contention is high (many threads accessing the set concurrently), CoarseSet is quite slow

Locking after finding?

Can we reduce the <u>size of the critical sections</u> by executing <u>find</u> without locking, and then acquiring the lock only before modifying the list? No, because the list may be modified between when a thread performs <u>find</u> and when it acquires the lock.

For example, suppose thread t runs remove(e) while thread u runs add(c), and t acquires the lock first:

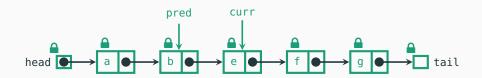




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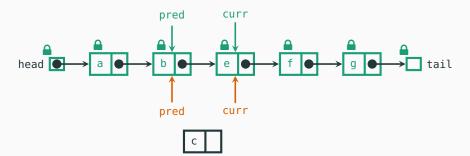




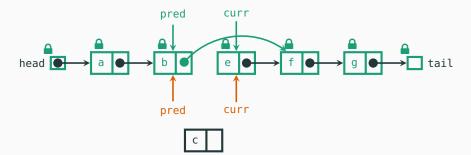
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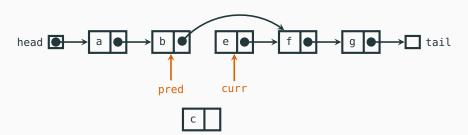
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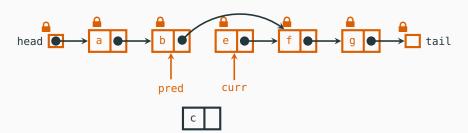
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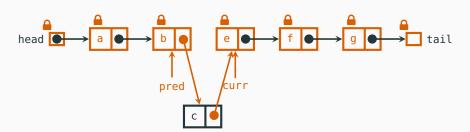
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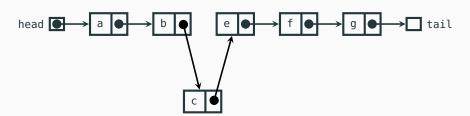
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Parallel linked sets

Fine-grained locking

Concurrent set with fine-grained locking

Rather than locking the whole linked list at once, we add a lock to each node. Then, threads only lock the individual nodes on which they are operating.

```
public class FineSet<T> extends SequentialSet<T>
  // empty set
  public FineSet() {
    head = new LockableNode<>(Integer.MIN_VALUE); // smallest key
    tail = new LockableNode<>(Integer.MAX_VALUE); // largest key
    head.setNext(tail);
  // overriding of find, add, remove, and has
```

Nodes in a fine-locking set

Each node includes a lock object, and lock and unlock methods that access the lock.

```
class LockableNode<T> extends SequentialNode<T>
{
   private Lock lock = new ReentrantLock();

   void lock() { lock.lock(); } // lock node
   void unlock() { lock.unlock(); } // unlock node
}
```

How many nodes do we have to lock?

We have seen (in CoarseSet) that we have to lock as soon as we start executing find. Thus, we start locking the head node and pass the lock along the chain of nodes.

How many nodes do we have to hold locked at once? Even though pred's node is the only node that is actually modified, only locking pred is not enough.

For example, if thread t runs remove(e) while thread u runs remove(b), it may happen that only b's removal takes place:

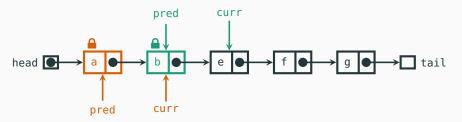


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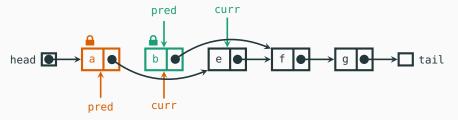


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For example, if thread t runs remove(e) while thread u runs remove(b), it may happen that only b's removal takes place:



Thus, we lock both pred and curr at once.

```
a \longrightarrow b \longrightarrow e \longrightarrow f \longrightarrow g \longrightarrow
// find while locking pred and curr, return locked position
protected Node<T>, Node<T> find(Node<T> start, int key) {
  Node<T> pred, curr; // predecessor and current node in iteration
  pred = start; curr = start.next(); // from start node
  pred.lock(); curr.lock(); // lock pred and curr nodes
  while (curr.key < key) {</pre>
    pred.unlock();
                                     // unlock pred node
    pred = curr; curr = curr.next(); // move to next node
    curr.lock():
                                    // lock next node
  } // until curr.key >= key
  return (pred, curr); // return position
           pseudo-code for: new Position<T>(pred, curr)
```

```
pred
           curr
                     b \longrightarrow e \longrightarrow f \longrightarrow g \longrightarrow
// find while locking pred and curr, return locked position
protected Node<T>, Node<T> find(Node<T> start, int key) {
  Node<T> pred, curr; // predecessor and current node in iteration
  pred = start; curr = start.next(); // from start node
  pred.lock(); curr.lock(); // lock pred and curr nodes
  while (curr.key < key) {</pre>
    pred.unlock();
                                     // unlock pred node
    pred = curr; curr = curr.next(); // move to next node
    curr.lock():
                                    // lock next node
  } // until curr.key >= key
  return (pred, curr); // return position
           pseudo-code for: new Position<T>(pred, curr)
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```
pred
                     curr
                           → e • → f •
head 
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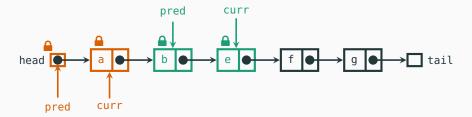
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                              curr
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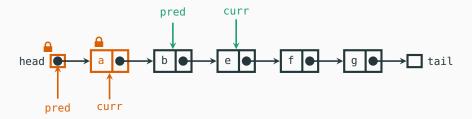
The lock acquisition protocol used by find in FineSet is called hand-over-hand locking or lock coupling.



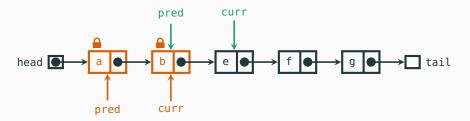
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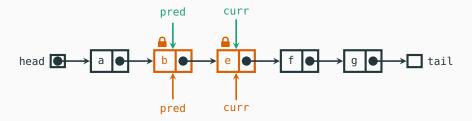
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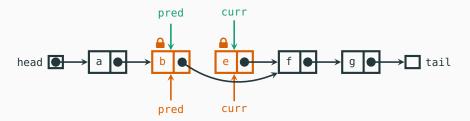
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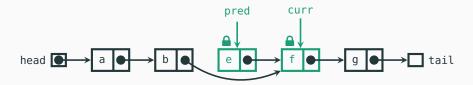
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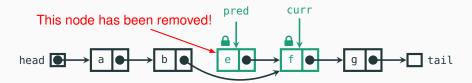
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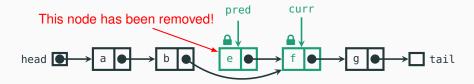
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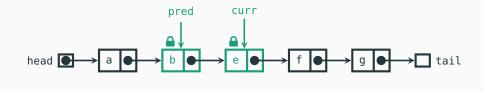
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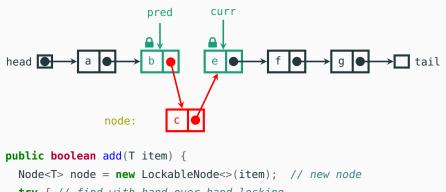
- Locking two nodes at once is sufficient to prevent problems with conflicting operations: threads proceed along the linked list in order, without one thread "overtaking" another thread that is further out
- The protocol ensures that locks are acquired by all threads in the same order, thus avoiding deadlocks

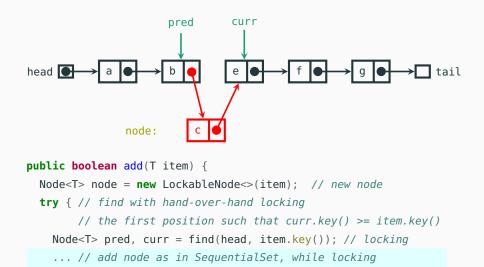


```
node: c
```

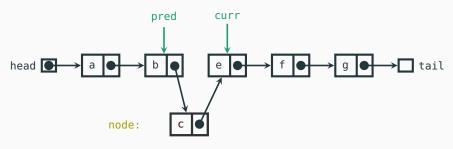


```
node: C
```



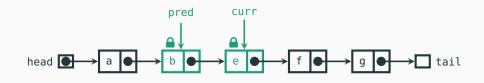


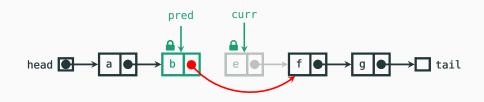
} finally { pred.unlock(); curr.unlock(); } // done: unlocking

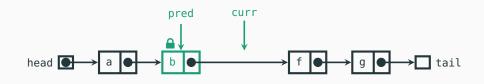


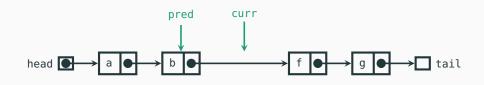
Fine-locking set: method remove

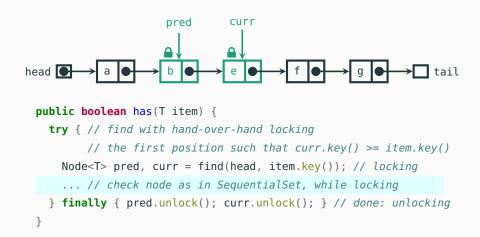


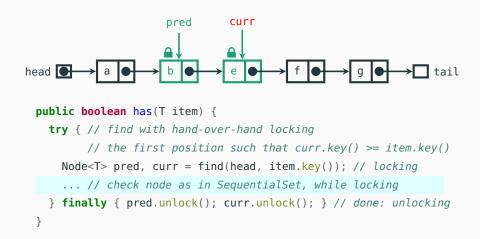


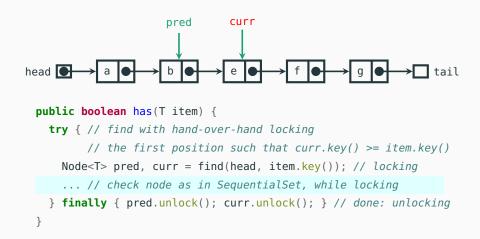












Fine-locking set: pros and cons

Pros:

- if locks are fair, so is access to the set, because threads proceed along the list one after the other without changing order
- threads operating on disjoint portions of the list may be able to operate in parallel

Cons:

- it is still possible that one thread prevents another thread from operating in parallel on a disjoint portion of the list – for example, if one thread wants to access the end of the list but another thread blocks it while locking the beginning of the list
- the hand-over-hand locking protocol may be quite slow, as it involves a significant number of lock operations

Parallel linked sets

Optimistic locking

Concurrent set with optimistic locking

Let us revisit the idea of performing find without locking. We have seen that problems may occur if the list is modified between when a threads finds a position and when it acquires locks on that position. Thus, we validate a position after finding it and while the nodes are locked, to verify that no interference took place.

```
public class OptimisticSet<T> extends SequentialSet<T>
  public FineSet()
  { head = new ReadWriteNode<>(Integer.MIN_VALUE); // smallest key
    tail = new ReadWriteNode<>(Integer.MAX_VALUE); // largest key
    head.setNext(tail); }
 // is (pred, curr) a valid position?
  protected boolean valid(Node<T> pred, Node<T> curr) // ...
 // overriding of find, add, remove, and has
```

Nodes in an optimistic-locking set

Since we need to be able to follow the chain of next references without locking, attribute next must be declared volatile in Java — so that modifications to it (which occur while the node is locked) are propagated to all threads (even if they have not locked a node). Other than for this detail, a ReadWriteNode is the same as a LockableNode.

With a little abuse of notation, we can pretend that ReadWriteNode inherits from LockableNode and overrides its next attribute. Overriding of attributes is however not possible in Java (shadowing takes place instead); the actual implementation that we make available does not reuse LockableNode's code through inheritance.

```
class ReadWriteNode<T> extends LockableNode<T>
{
   private volatile Node<T> next; // next node in chain
}
```

Delayed locking as optimistic locking

In OptimisticSet, operations work as follows:

- find the item's position inside the list without locking as in SequentialSet
- 2. lock the position's nodes pred and curr
- 3. validate the position while the nodes are locked:
 - 3.1 if the position is <u>valid</u>, <u>perform the operation</u> while the nodes are locked, then release locks
 - 3.2 if the position is <u>invalid</u>, release locks and <u>repeat the operation</u> from scratch

This approach is optimistic because it works well when validation is often successful (so we don't have to repeat operations).

Delayed locking as optimistic locking

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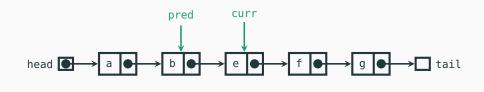
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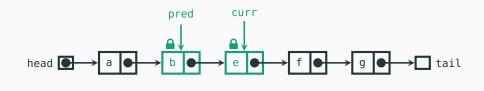


```
node: c
```

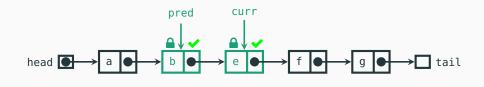


```
node: c
```

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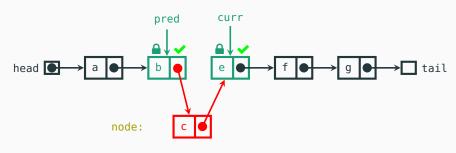


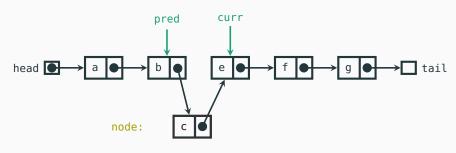
```
node: c
```



```
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```

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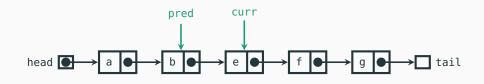




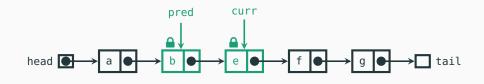
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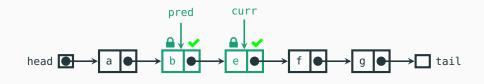
```
public boolean remove(T item) {
    do { Node<T> pred, curr = find(head, item.key()); // no locking
        pred.lock(); curr.lock(); // now lock position
        try { // if position still valid, while locked:
            if (valid(pred, curr)) { ... } // physically remove node
        } finally { pred.unlock(); curr.unlock(); }// done: unlock
    } while (true); // if not valid: try again!
}
```



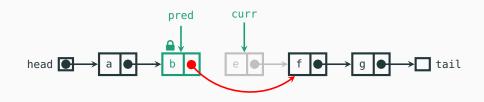
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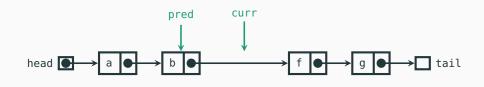
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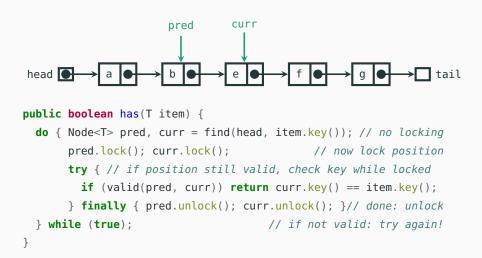


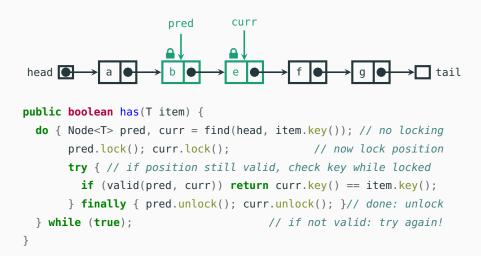
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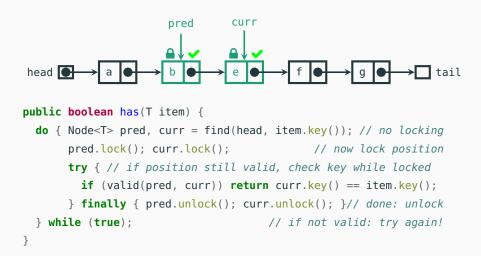


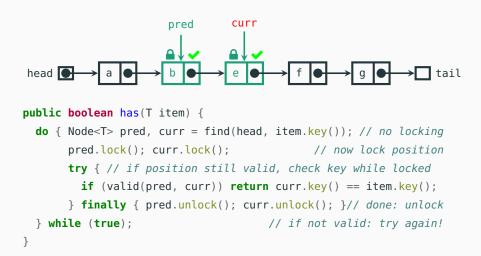
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}
```

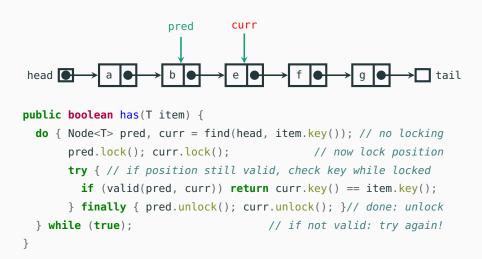
```
head \bigcirc a \bigcirc b \bigcirc e \bigcirc f \bigcirc g \bigcirc tail
public boolean has(T item) {
  do { Node<T> pred, curr = find(head, item.key()); // no locking
      pred.lock(); curr.lock(); // now lock position
      try { // if position still valid, check key while locked
        if (valid(pred, curr)) return curr.key() == item.key();
      } finally { pred.unlock(); curr.unlock(); }// done: unlock
 } while (true);
                                     // if not valid: try again!
```



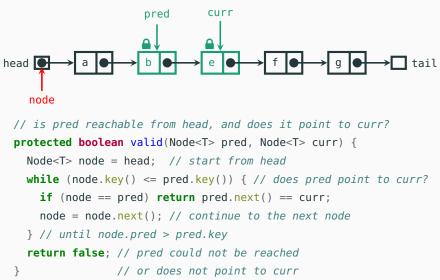




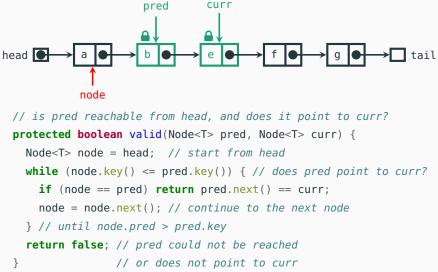




Validation goes through the nodes until it reaches the given position.



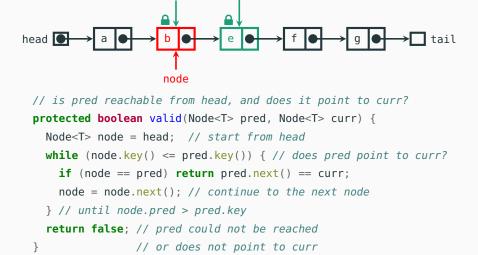
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pred

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curr

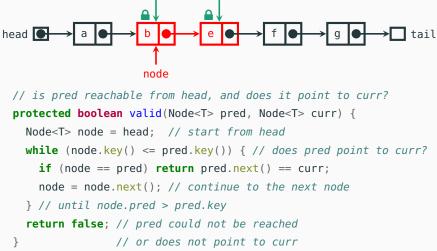


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pred

Validation goes through the nodes until it reaches the given position.

curr



How validation works

What can happen between the time when a thread finds a position (pred, curr) and when it locks nodes pred and curr?

- Node pred is removed: validation fails because pred is not reachable
- Node curr is removed: validation fails because pred does not point to curr
- A node is added between pred and curr: validation fails because pred does not point to curr
- Any other modification of the set: validation succeeds because operations leave the set in a consistent state

Is validation safe?

What happens if the set is being modified while a thread is validating a locked position (pred, curr)?

- If a node following curr is modified: validation is not affected because it only goes up until curr
- If a node n before pred is removed: validation succeeds even if it goes through n, since n still leads back to pred
- If a node n is added before pred: validation succeeds even if it skips over n

Optimistic-locking set: pros and cons

Pros:

- threads operating on disjoint portions of the list can operate in parallel
- when validation often succeeds, there is much less locking involved than in FineSet

Cons:

- OptimisticSet is not starvation free: a thread t may fail validation forever if other threads keep removing and adding pred/curr between when t performs find and when it locks pred and curr
- if traversing the list twice without locking is not significantly faster than traversing it once with locking, OptimisticSet does not have a clear advantage over FineSet

Parallel linked sets

Lazy node removal

Testing membership without locking

In many applications, the operation has is executed many more times than add and remove. Can has work correctly without locking?

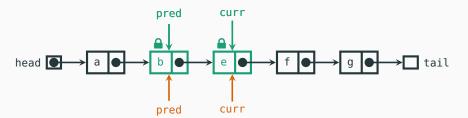
Problems may occur if another thread removes curr between find and has's check: since remove is not atomic without locking, if has does not acquire locks it may not notice that curr is being removed.

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Problems may occur if another thread removes curr between find and has's check: since remove is not atomic without locking, if has does not acquire locks it may not notice that curr is being removed.

For example, if thread t runs remove(e) while thread u runs has(e) without locking, u may incorrectly think that e is in the list even if t is about to remove it — that is thread t is in its critical section:



Nodes in a lazy-removal set

We need a way to atomically share the information that a node is being removed, but without locking.

To this end, each node includes a flag valid with setters and getters:

```
• valid() == true: the node is part of the set
```

```
    valid() == false: the node is being (or has been) removed
```

```
class ValidatedNode<T> extends ReadWriteNode<T>
{
   private volatile boolean valid;

   boolean valid() { return valid; } // is node valid?
   void setValid() { valid = true; } // mark valid
   void setInvalid() { valid = false; } // mark invalid
}
```

Nodes of type ValidatedNode can also be locked, since ValidatedNode inherits from ReadWriteNode.

Concurrent set with lazy node removal

In a lazy set:

- Validation only needs to check the mark valid
- Operation remove marks a node invalid before removing it
- · Operation has is lock free
- Operation add works as in OptimisticSet

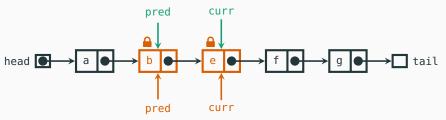
```
public class LazySet<T> extends OptimisticSet<T>
{
   public LazySet() {
     head = new ValidatedNode<>(Integer.MIN_VALUE); // smallest key
     tail = new ValidatedNode<>(Integer.MAX_VALUE); // largest key
     head.setNext(tail);
}

// overriding of valid, remove, and has
```

Validation becomes a constant-time operation:

- Node pred is reachable from the head iff it has not been removed iff it is marked valid
- Node curr follows pred in the list iff pred.next() == curr and curr is marked valid

Scenario: *t*'s validation of curr succeeds:

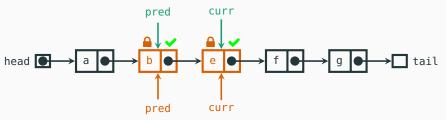


```
// is pred reachable from head, and does it point to curr?
protected boolean valid(Node<T> pred, Node<T> curr) {
  return pred.valid() && curr.valid() && pred.next() == curr;
}
```

Validation becomes a constant-time operation:

- Node pred is reachable from the head iff it has not been removed iff it is marked valid
- Node curr follows pred in the list iff pred.next() == curr and curr is marked valid

Scenario: t's validation of curr succeeds:

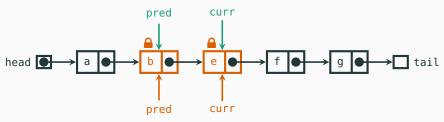


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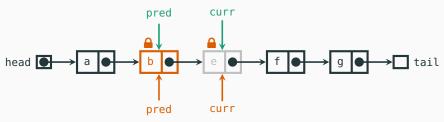


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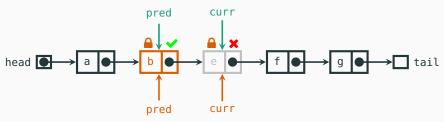


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protected boolean valid(Node<T> pred, Node<T> curr) {
  return pred.valid() && curr.valid() && pred.next() == curr;
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Validation becomes a constant-time operation:

- Node pred is reachable from the head iff it has not been removed iff it is marked valid
- Node curr follows pred in the list iff pred.next() == curr and curr is marked valid

Scenario: t's validation of curr fails:



```
// is pred reachable from head, and does it point to curr?
protected boolean valid(Node<T> pred, Node<T> curr) {
  return pred.valid() && curr.valid() && pred.next() == curr;
}
```

Method has runs without locking: it finds the position (pred, curr), validates curr, and checks whether curr's key is equal to item's.

```
public boolean has(T item) {
    // find position without locking
    Node<T> pred, curr = find(head, item.key());
    // check validity and item without locking
    return curr.valid() && curr.key() == item.key();
}
```

Method has runs without locking: it finds the position (pred, curr), validates curr, and checks whether curr's key is equal to item's.

```
pred
                               curr
                            → e •
head 
   public boolean has(T item) {
       // find position without locking
     Node<T> pred, curr = find(head, item.key());
       // check validity and item without locking
     return curr.valid() && curr.key() == item.key();
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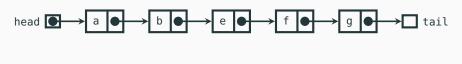
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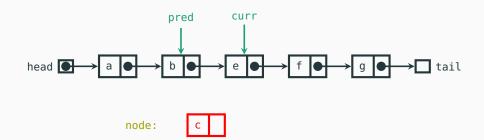
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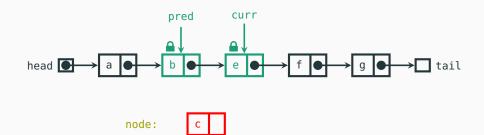
Method add works as in OptimisticSet, but using the overridden version of valid — which works in constant time.

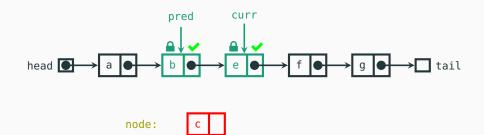


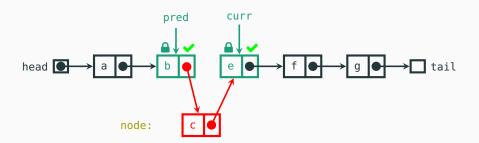
node:

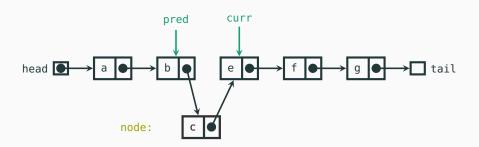












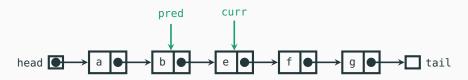
After finding the position of a node to be removed, the actual removal consists of two steps:

- 1. logical removal: mark the node to be removed as invalid
- 2. physical removal: skip over the node by redirecting its predecessor's next



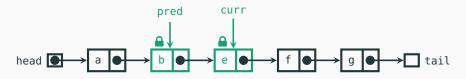
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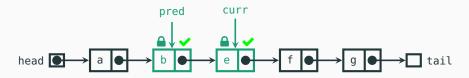
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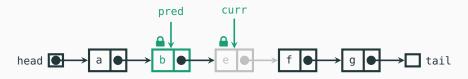
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- 1. logical removal: mark the node to be removed as invalid
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```
public boolean remove(T item) {
 do { Node<T> pred, curr = find(head, item.key()); // no locking
      pred.lock(); curr.lock(); // now lock position
      try { // if position still valid, while locking:
        if (valid(pred, curr)) {
          if (curr.key() != item.key())
             return false; // item not in the set
          else { // item in the set at curr: remove it
             curr.setInvalid(); // logical removal
             pred.setNext(curr.next()); // physical removal
             return true;
      } finally { pred.unlock(); curr.unlock(); }// done: unlock
 } while (true);
                                    // if not valid: try again!
```

Lazy-removal set: pros and cons

Pros:

- · validation is constant time
- membership checking does not require any locking it's even wait free (it traverses the list once without locking)
- physical removal of logically removed nodes could be batched and performed when convenient – thus reducing the number of times the physical chain of nodes is changed, in turn reducing the expensive propagation of information between threads

Cons:

 operations add and remove still require locking (as in OptimisticSet), which may reduce the amount of parallelism

Parallel linked sets

Lock-free access

Atomic references

To implement a set that is correct under concurrent access without using any locks we need to rely on synchronization primitives more powerful than just reading and writing shared variables.

We are going to use a variant of the compare-and-set operation.

Atomic lock-free access: first naive attempt

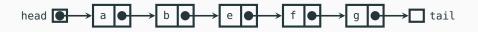
As a first attempt, we make attribute next of type AtomicReference<Node<T>>, and use compareAndSet to update it: if one thread changes next when another thread is also trying to change it, we repeat the operation.

An implementation of remove() following this idea:

```
public boolean remove(T item) {
  boolean done;
  do {
    Node<T> pred, curr = find(head, item.key());
    if (curr.key() >= item.key()) return false; // item not in set
    else
      // try to remove curr by setting pred.next using compareAndSet
      done = pred.next().compareAndSet(pred.next(), curr.next());
  } while (!done); return true;
                                   pred.next may have changed
                                   when compareAndSet() executes
```

Atomic lock-free access: first naive attempt

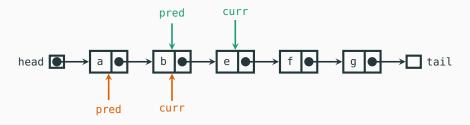
Unfortunately, the first attempt does not work: for example, if thread t runs remove(e) while thread u runs remove(b), it may happen that only b's removal takes place.



We have seen a similar problem before: modifications of the list need to have control of both pred and curr – even if it is only the former node that is actually modified.

Atomic lock-free access: first naive attempt

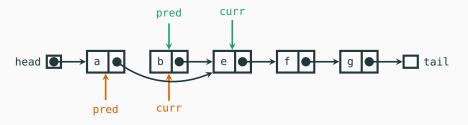
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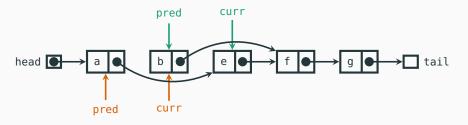
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Atomic markable references

As in LazySet, nodes can be marked valid or invalid; an invalid node is logically removed. In addition, we need to access the information of both attributes valid and next atomically; to this end, every node includes an attribute nextValid of type

AtomicMarkableReference<Node<T>>, which provides methods to both update a reference and a mark it, atomically.

```
class AtomicMarkableReference<V> {
                   // current reference and mark
 V, boolean get();
  // if reference == expectRef set mark to newMark and return true
  // otherwise do not change anything and return false
 boolean attemptMark(V expectRef, boolean newMark);
  // if reference == expectRef and mark == expectMark,
  // set reference to newRef, mark to newMark and return true;
  // otherwise, do not change anything and return false
 boolean compareAndSet(V expectRef, V newRef,
                       boolean expectMark, boolean newMark);
```

Nodes in a lock-free set

Every node includes an attribute nextValid of type

AtomicMarkableReference<Node<T>>. The node interface provides
methods to retrieve and conditionally update the current value of
nextValid, which includes a reference (corresponding to next) and a
mark (corresponding to valid).

```
class LockFreeNode<T> extends SequentialNode<T> {
   // reference to next node and validity mark of current node
  private AtomicMarkableReference<Node<T>> nextValid;
   // return next and valid as a pair
  Node<T>, boolean nextValid() { return nextValid.get(); }
  Node<T> next()
    { Node<T> next, boolean valid = nextValid(); return next; }
  boolean valid()
    { Node<T> next, boolean valid = nextValid(); return valid; }
```

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nextValid, which includes a reference (corresponding to next) and a
mark (corresponding to valid).

```
class LockFreeNode<T> extends SequentialNode<T> {
 // try to set invalid; return true if successful
boolean setInvalid()
  { Node<T> next = next():
    return nextValid.compareAndSet(next, next, true, false); }
 // try to update to newNext if valid; return true if successful
boolean setNextIfValid(Node<T> expectNext, Node<T> newNext)
  { return nextValid.compareAndSet(expectNext, newNext, true, true); }
      update next only if the node is valid
```

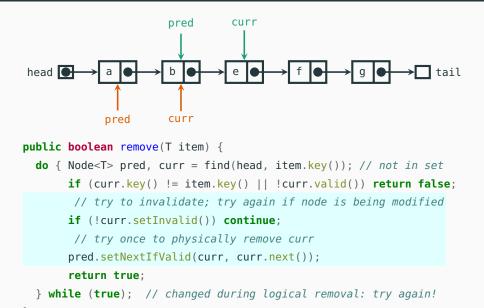
Concurrent set with lock-free access

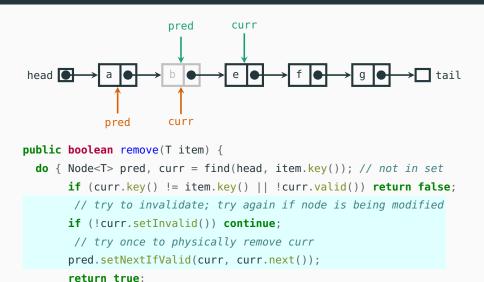
In a lock-free set:

- Operation remove marks a node invalid before removing it
- Operations that modify nodes complete successfully only if the nodes are valid and not concurrently modified by another thread
- Failed operations are repeated until success (no interference)

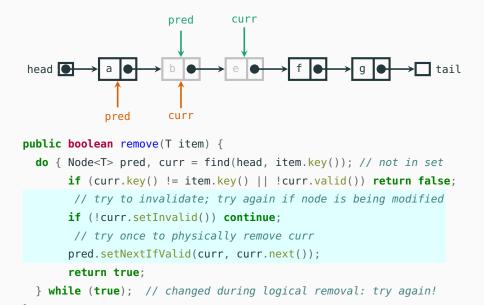


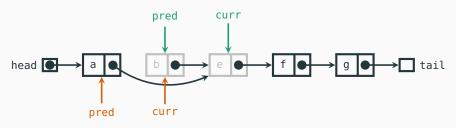
```
public boolean remove(T item) {
  do { Node<T> pred, curr = find(head, item.key()); // not in set
       if (curr.key() != item.key() || !curr.valid()) return false;
       // try to invalidate; try again if node is being modified
       if (!curr.setInvalid()) continue;
       // try once to physically remove curr
       pred.setNextIfValid(curr, curr.next());
       return true:
  } while (true); // changed during logical removal: try again!
```



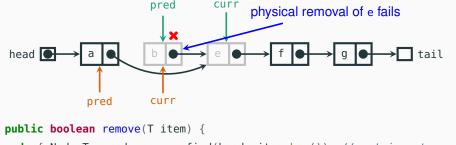


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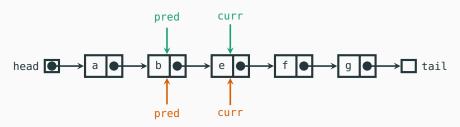


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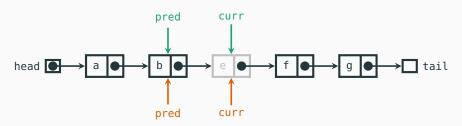




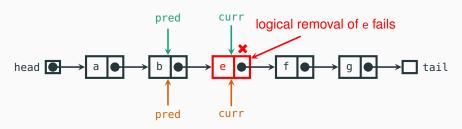
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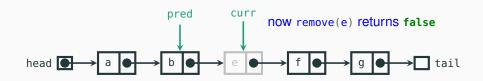
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                                                logical removal
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                                                of e fails: retry!
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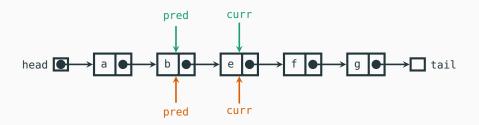
If two threads both try to mark a node invalid, only one can succeed – so it is guaranteed that no other thread is touching the node.

If this property was not enforced:



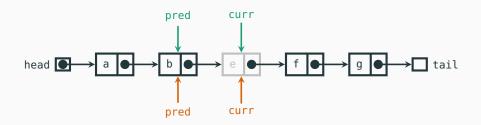
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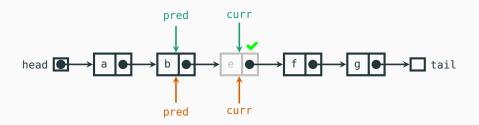
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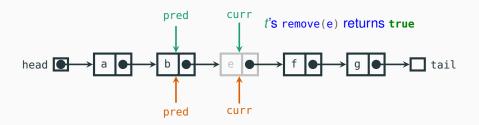
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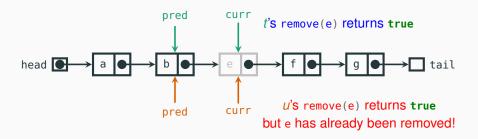
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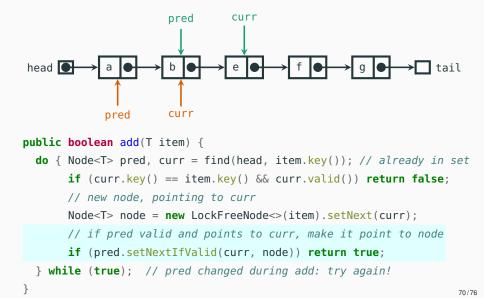
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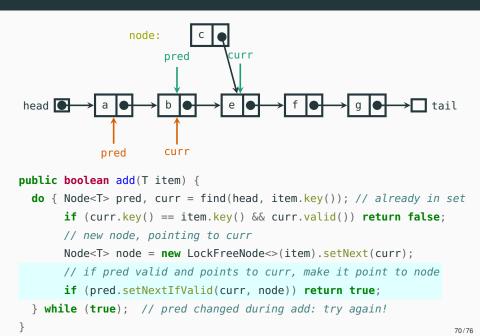
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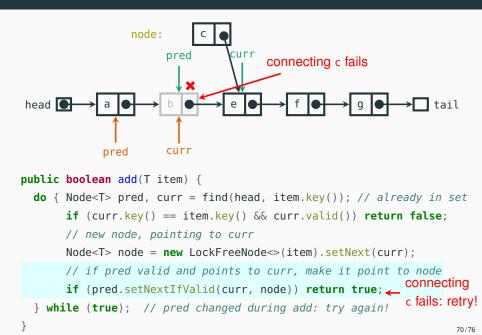




```
public boolean add(T item) {
    do { Node<T> pred, curr = find(head, item.key()); // already in set
        if (curr.key() == item.key() && curr.valid()) return false;
        // new node, pointing to curr
        Node<T> node = new LockFreeNode<>(item).setNext(curr);
        // if pred valid and points to curr, make it point to node
        if (pred.setNextIfValid(curr, node)) return true;
    } while (true); // pred changed during add: try again!
}
```

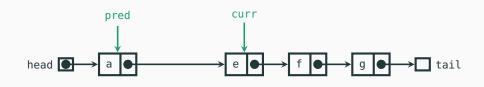




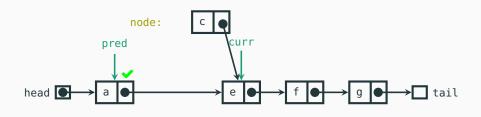




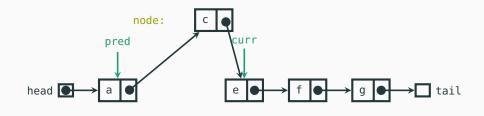
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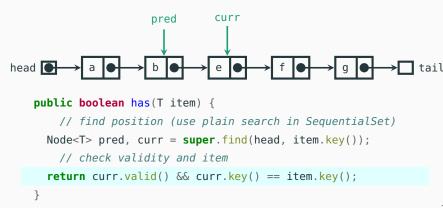


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        Node<T> node = new LockFreeNode<>(item).setNext(curr);
        // if pred valid and points to curr, make it point to node
        if (pred.setNextIfValid(curr, node)) return true;
    } while (true); // pred changed during add: try again!
}
```

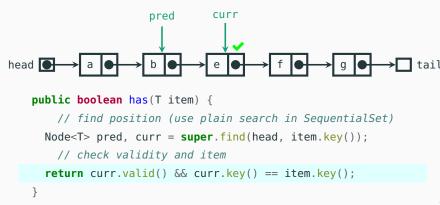
Method has works as in LazySet: it finds the position (pred, curr), validates curr, and checks whether curr's key is equal to item's. Unlike add and remove (which use a new version of find), has traverses both valid and invalid nodes, and makes no attempt at removing the latter.

```
public boolean has(T item) {
    // find position (use plain search in SequentialSet)
    Node<T> pred, curr = super.find(head, item.key());
    // check validity and item
    return curr.valid() && curr.key() == item.key();
}
```

Method has works as in LazySet: it finds the position (pred, curr), validates curr, and checks whether curr's key is equal to item's. Unlike add and remove (which use a new version of find), has traverses both valid and invalid nodes, and makes no attempt at removing the latter.

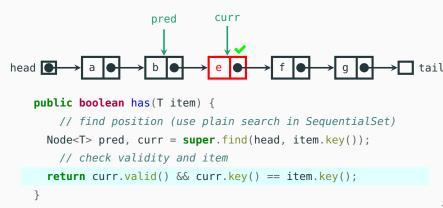


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Lock-free set: method has

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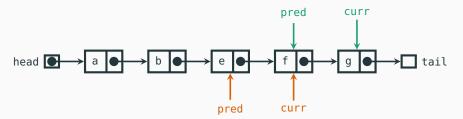
Method has does not modify the set, so it can safely traverse valid and invalid nodes without changing the node structure.

In contrast, methods add and remove physically remove all logically removed nodes encountered by find. This is a convenient time to perform physical removal, because it avoids the buildup of long chains of invalid nodes.



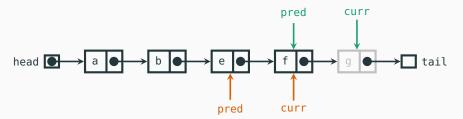
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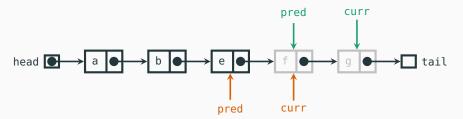
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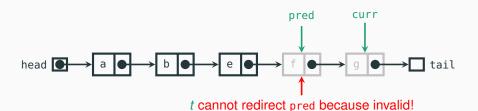
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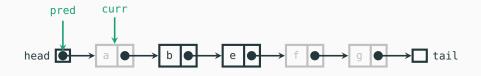


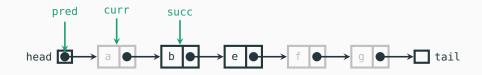
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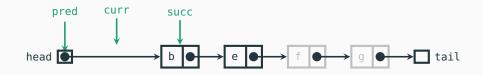
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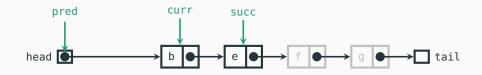


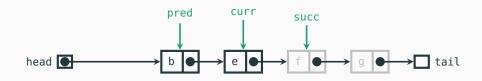


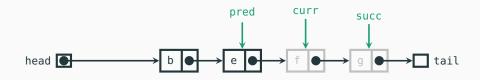


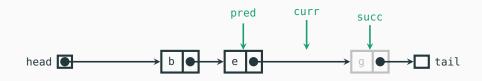


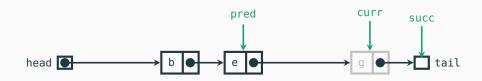


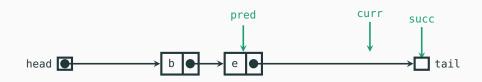


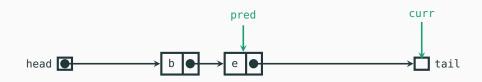


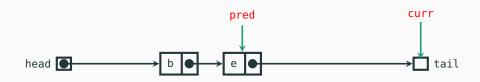












A run of find(k) that also physically removes three invalid nodes.



Threads may interfere with find, requiring to restart it; in the worst case, starvation may occur with a thread continuously restarting find while others make progress modifying the list.

Lock-free set: method find

```
protected Node<T>, Node<T> find(Node<T> start, int key) {
 boolean valid:
                      // is curr valid?
 Node<T> pred, curr, succ; // consecutive nodes in iteration
  retry: do {
   pred = start; curr = start.next(); // from start node
   do { // succ is curr's successor; valid is curr's validity
     succ, valid = curr.nextValid();
     while (!valid) { // while curr is not valid, try to remove it
         // if pred is modified while trying to redirect it, retry
       if (!pred.setNextIfValid(curr, succ)) continue retry;
         // curr has been physically removed: move to next node
       curr = succ; succ, valid = curr.nextValid();
     } // now curr is valid (and so is pred)
     if (curr.key() >= key) return (pred, curr);
     pred = curr; curr = succ; // continue search
   } while (true):
  } while (true):
```

Lock-free set: pros and cons

Pros:

- · no operations require locking: maximum potential for parallelism
- membership checking does not require any locking it's even wait free (it traverses the list once without locking)

Cons:

- the implementation needs test-and-set-like synchronization primitives, which have to be supported and come with their own performance costs
- operations add and remove are lock free but not wait free: they
 may have to repeat operations, and they may be delayed while
 they physically remove invalid nodes, with the risk of introducing
 contention on nodes that have been already previously logically
 deleted

To lock or not to lock?

Each of the different implementations of concurrent set is the **best** choice for certain applications and not for others:

- CoarseSet works well with low contention
- FineSet works well when threads tend to access the list orderly
- OptimisticSet works well to let threads operate on disjoint portions of the list
- LazySet works well when batching invalid node removal is convenient
- LockFreeSet works well when locking is quite expensive

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