Formal Methods for Software Development Modeling Distributed Systems

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You know you have a distributed system when the crash of a computer you've never heard of stops you from getting any work done.-Leslie Lamport

Using **PROMELA** channels for modeling distributed systems

Modeling Distributed Systems

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- interacting via communication channels,
- protocols dictate how nodes communicate with each other.

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- protocols dictate how nodes communicate with each other.

Distributed systems are very complex.

Models of distributed systems abstract away from details of networks/protocols/nodes.

In PROMELA:

- ▶ nodes modeled by **PROMELA** processes,
- communication channels modeled by PROMELA channels,
- protocols modeled by algorithm distributed over processes.

$\textbf{Channels in } \operatorname{Promela}$

In PROMELA, channels are first class citizens.

Data type chan with two operations for sending and receiving

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A variable of channel type is declared by initializer:

chan name = [capacity] of $\{type_1, ..., type_n\}$

| name | name of channel variable |
|-------------------|-------------------------------------|
| capacity | non-negative integer constant |
| type _i | $\operatorname{PROMELA}$ data types |

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Example:

chan ch = [2] of { mtype, byte, bool }

Meaning of Channels

chan *name* = [capacity] of $\{type_1, ..., type_n\}$

Creates channel, stored in variable name

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Creates channel, stored in variable name

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Can buffer up to *capacity* messages, if *capacity* \geq 1 \Rightarrow *"buffered channel"*

The channel has *no* buffer if *capacity* = 0 ⇒ *"rendezvous channel"*

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Given, e.g., mtype = {red, yellow, green},
an example message on ch can be:
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Given, e.g., mtype = {red, yellow, green}, an example message on ch can be: green, 20, false

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Creates channel, stored in variable ch

Messages communicated via ch are 3-tuples \in mtype \times byte \times bool

Given, e.g., mtype = {red, yellow, green}, an example message on ch can be: green, 20, false

ch is a buffered channel, buffering up to 2 messages

send statement has the form:

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name ! $expr_1, \dots, expr_n$

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- name: channel variable
- var₁, ..., var_n: sequence of variables, where number and types match name's type
- assigns values of message to var_1, \dots, var_n
- example: ch ? color, time, flash

```
chan request = [0] of { byte };
active proctype Client0() {
  request ! 0
}
active proctype Client1() {
  request ! 1
}
```

. . .

```
chan request = [0] of { byte };
active proctype Client0() {
  request ! 0
}
active proctype Client1() {
  request ! 1
}
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```

Client0 and Client1 send messages 0 resp. 1 to channel request

```
chan request = [0] of { byte };
active proctype Client0() {
  request ! 0
}
active proctype Client1() {
  request ! 1
}
....
```

Client0 and Client1 send messages 0 resp. 1 to channel request Order of sending is nondeterministic

```
chan request = [0] of { byte };
...
active proctype Server() {
   byte num;
   do
      :: request ? num;
      printf("servinguclientu%d\n", num)
   od
}
```

```
chan request = [0] of { byte };
...
active proctype Server() {
   byte num;
   do
      :: request ? num;
      printf("serving_client_%d\n", num)
   od
}
```

Server loops on

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chan request = [0] of { byte };
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active proctype Server() {
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    receiving first message from request,
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Server loops on

- receiving first message from request, storing value in num
- printing

rendezvous1 random simulation

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request ? num

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```
do
    :: request ? num ->
        printf("serving_client_%d\n", num)
    od
("->" equivalent to ";")
```

Rendezvous Channels

```
chan ch = [0] of { byte, byte };
```

```
/* global only to make visible in SpinSpider */
byte hour, minute;
```

```
active proctype Sender() {
    printf("ready\n");
    ch ! 11, 45;
    printf("Sent\n")
}
```

```
active proctype Receiver() {
    printf("steady\n");
    ch ? hour, minute;
    printf("Received\n")
}
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Which interleavings can occur?
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}
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Which interleavings can occur? \Rightarrow ask SPINSPIDER

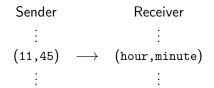
through JSPIN: SPINSPIDER on ReadySteady.pml

On a rendezvous channel:

Transfer of message from sender to receiver is synchronous, i.e., one single operation.

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In both case, the next step is:

Location counter of both processes is incremented in one step.

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In both case, the next step is:

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Only place where 2 PROMELA processes execute at once

Reconsider Client Server

```
chan request = [0] of { byte };
active proctype Server() {
  byte num;
  do :: request ? num ->
        printf("serving_client_%d\n", num)
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active proctype Client0() {
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active proctype Client0() {
  request ! 0
}
active proctype Client1() {
  request ! 1
}
```

So far no reply to clients

Reply Channels

```
chan request = [0] of { byte };
chan ack = [0] of \{bool\}:
active proctype Server() {
 byte num;
 do :: request ? num ->
        printf("serving_client_%d\n", num);
        ack ! true
 od
}
active proctype Client0() {
  request ! 0; ack ? _; printf("acknowledged\n")
}
active proctype Client1() {
  request ! 1; ack ? _; printf("acknowledged\n")
}
```

Reply Channels

```
chan request = [0] of { byte };
chan ack = [0] of \{bool\}:
active proctype Server() {
 bvte num;
 do :: request ? num ->
        printf("serving_client_%d\n", num);
        ack ! true
 od
}
active proctype Client0() {
  request ! 0; ack ? _; printf("acknowledged\n")
}
active proctype Client1() {
  request ! 1; ack ? _; printf("acknowledged\n")
}
```

(Anonymous variable "_": data from message not stored anywhere)

```
mtype = { nice, rude };
chan request = [0] of { mtype };
chan reply = [0] of { mtype };
active proctype Server() {
  mtype msg;
  do :: request ? msg; reply ! msg
  od
}
active proctype NiceClient() {
  mtype msg;
  request ! nice; reply ? msg;
}
active proctype RudeClient() {
  mtype msg;
  request ! rude; reply ? msg
}
```

```
mtype = { nice, rude };
chan request = [0] of { mtype };
chan reply = [0] of { mtype };
active proctype Server() {
  mtype msg;
  do :: request ? msg; reply ! msg
  od
}
active proctype NiceClient() {
  mtype msg;
  request ! nice; reply ? msg;
  assert(msg == nice)
}
active proctype RudeClient() {
  mtype msg;
  request ! rude; reply ? msg
}
```

```
mtype = { nice, rude };
chan request = [0] of { mtype };
chan reply = [0] of { mtype };
active proctype Server() {
  mtype msg;
  do :: request ? msg; reply ! msg
  od
}
active proctype NiceClient() {
  mtype msg;
  request ! nice; reply ? msg;
  assert(msg == nice)
                                  Is the assertion valid?
}
active proctype RudeClient() {
  mtype msg;
  request ! rude; reply ? msg
}
```

```
mtype = { nice, rude };
chan request = [0] of { mtype };
chan reply = [0] of { mtype };
active proctype Server() {
  mtype msg;
  do :: request ? msg; reply ! msg
  od
}
active proctype NiceClient() {
  mtype msg;
  request ! nice; reply ? msg;
  assert(msg == nice)
                                  Is the assertion valid? Ask SPIN.
}
active proctype RudeClient() {
  mtype msg;
  request ! rude; reply ? msg
}
```

```
active [2] proctype Server() {
 mtype msg;
 do :: request ? msg; reply ! msg
  od
}
active proctype NiceClient() {
  mtype msg;
  request ! nice; reply ? msg;
}
active proctype RudeClient() {
 mtype msg;
  request ! rude; reply ? msg
}
```

```
active [2] proctype Server() {
 mtype msg;
 do :: request ? msg; reply ! msg
  od
}
active proctype NiceClient() {
  mtype msg;
  request ! nice; reply ? msg;
  assert(msg == nice)
}
active proctype RudeClient() {
  mtype msg;
  request ! rude; reply ? msg
}
```

```
active [2] proctype Server() {
 mtype msg;
 do :: request ? msg; reply ! msg
  od
}
active proctype NiceClient() {
  mtype msg;
  request ! nice; reply ? msg;
                                   And here?
  assert(msg == nice)
}
active proctype RudeClient() {
  mtype msg;
  request ! rude; reply ? msg
}
```

```
active [2] proctype Server() {
 mtype msg;
 do :: request ? msg; reply ! msg
  od
}
active proctype NiceClient() {
  mtype msg;
  request ! nice; reply ? msg;
  assert(msg == nice)
                                   And here? Analyse with SPIN.
}
active proctype RudeClient() {
  mtype msg;
  request ! rude; reply ? msg
}
```

Sending Channels via Channels

To fix the protocol:

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clients declare local reply channel + send it to server

Sending Channels via Channels

```
mtype = { nice, rude };
chan request = [0] of { mtype, chan };
active [2] proctype Server() {
 mtype msg; chan ch;
 do :: request ? msg, ch;
        ch ! msg
 od
}
active proctype NiceClient() {
  chan reply = [0] of { mtype }; mtype msg;
  request ! nice, reply; reply ? msg;
  assert( msg == nice )
}
active proctype RudeClient() {
  chan reply = [0] of { mtype }; mtype msg;
  request ! rude, reply; reply ? msg
}
```

Sending Channels via Channels

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active proctype NiceClient() {
  chan reply = [0] of { mtype }; mtype msg;
  request ! nice, reply; reply ? msg;
  assert( msg == nice )
}
active proctype RudeClient() {
  chan reply = [0] of { mtype }; mtype msg;
  request ! rude, reply; reply ? msg
}
      verify with SPIN
```

FMSD: Modeling Distributed Systems

Global channel

All processes can send and/or receive messages

Local channel

- Can model 'private' communication & security issues
- Example:

Local channel can be passed through a global channel

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- inflexible
- doesn't scale

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Alternative:

Processes send their own, unique process ID, _pid, as part of message

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Experiment with rendezvous3.pml

Sending Process IDs

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- doesn't scale

Alternative:

Processes send their own, unique process ID, _pid, as part of message

Experiment with rendezvous3.pml

Example, clients code:

```
chan reply = [0] of { byte, byte };
request ! _pid, reply;
reply ? serverID, serversClient;
```

Sending Process IDs

Used fixed constants used for identification (here nice, rude)

- inflexible
- doesn't scale

Alternative:

Processes send their own, unique process ID, _pid, as part of message

Experiment with rendezvous3.pml

Example, clients code:

```
chan reply = [0] of { byte, byte };
request ! _pid, reply;
reply ? serverID, serversClient;
```

```
assert( serversClient == _pid )
```

Limitations of Rendezvous Channels

- Rendezvous too restrictive for many applications
- Servers and clients block each other too much
- Difficult to manage uneven workload (online shop: dozens of webservers serve thousands of clients)

Buffered Channel

Buffered channels queue messages. Requests/services block clients/servers less often.

Example: chan ch = [3] of { mtype, byte, bool }

Can hold up to cap messages

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- Are a FIFO (first-in-first-out) data structure: always the 'oldest' message in channel is retrieved by a receive

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- Can hold up to cap messages
- Are a FIFO (first-in-first-out) data structure: always the 'oldest' message in channel is retrieved by a receive
- (Normal) receive statement reads and removes message
- Sending and receiving to/from buffered channels is asynchronous, i.e. interleaved

Executability of Buffered Channel operations

```
Given channel ch, with capacity cap, currently containing n messages

receive statement ch ? msg

is executable iff ch is not empty, i.e., n > 0

send statement ch ! msg

is executable iff there is still 'space' in the message queue,

i.e., n < cap
```

A non-executable receive or send statement will block until it is executable again

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Given channel ch, with capacity cap, currently containing n messages

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A non-executable receive or send statement will block until it is executable again

(With option -m, SPIN has a different send semantics: Attempt to send to full channel doesn't block, but message gets lost.)

Checking Channel for Full/Empty

This can prevent unnecessary blocking:

Given channel ch:

full(ch) checks whether ch is full
nfull(ch) checks whether ch is not full
empty(ch) checks whether ch is empty
nempty(ch) checks whether ch is not empty

Illegal to negate those. Avoid combining with else.

Copy Message without Removing

Assume ch to be a buffered channel.

ch ? color, time, flash

- Assigns values from the message to color, time, flash
- Removes message from ch

Copy Message without Removing

Assume ch to be a buffered channel.

ch ? color, time, flash

- Assigns values from the message to color, time, flash
- Removes message from ch

ch ? <color, time, flash>

- Assign values from the message to color, time, flash
- Leaves message in ch

Recurring task: Dispatch action depending on message

```
Recurring task: Dispatch action depending on message
mtype = {hi, bye};
chan ch = [0] of {mtype};
active proctype Server () {
   mtype msg;
read:
  ch ? msg;
  do
    :: msg == hi -> printf("Hello.\n"); goto read
    :: msg == bye -> printf("See_you.\n"); break
  od
}
. . .
```

```
Recurring task: Dispatch action depending on message
mtype = {hi, bye};
chan ch = [0] of {mtype};
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read:
  ch ? msg;
  do
    :: msg == hi -> printf("Hello.\n"); goto read
    :: msg == bye -> printf("See_you.\n"); break
  od
}
. . .
```

There is a better way!

```
Recurring task: Dispatch action depending on message type.
mtype = {hi, bye};
chan ch = [0] of {mtype};
active proctype Server () {
  do
    :: ch ? hi -> printf("Hello.\n")
    :: ch ? bye -> printf("See_you.\n"); break
  od
}
. . .
```

hi and bye are *values*, not variables!

Pattern Matching

Receive statement allows also non-variable expressions as arguments:

ch ? exp_1, \ldots, exp_n

- exp₁,..., exp_n any(!) expressions of correct type
- Receive statement is executable, iff
 - either of the following holds:
 - ch is buffered channel and not empty, or
 - ch is rendezvous channel and some process ready to send to ch
 - message v_1, \ldots, v_n in channel *ch* matches exp_1, \ldots, exp_n
- v_i matches exp_i iff
 - exp_i is a variable and v_i a value (of correct type)
 - exp_i is not a variable and exp_i == v_i

Assume

chan ch = [0] of {int, int}; int id = 5;

Assume

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Does ch ? 0, id match message

▶ [0, 5] ?

Assume

chan ch = [0] of {int, int}; int id = 5;

Does ch ? 0, id match message

▶ [0, 5] ? ✔

Assume

chan ch = [0] of {int, int}; int id = 5;

Does ch ? 0, id match message

▶ [0, 5] ? ✔ [0, 7] ?

Assume

chan ch = [0] of {int, int}; int id = 5;

Does ch ? 0, id match message

▶ [0, 5] ? ✔ [0, 7] ? ✔

Assume

chan ch = [0] of {int, int}; int id = 5;

Does ch ? 0, id match message

▶ [0, 5] ? ✔ [0, 7] ? ✔ [1, 7] ?

Assume

chan ch = [0] of {int, int}; int id = 5;

Does ch ? 0, id match message

▶ [0, 5] ? ✔ [0, 7] ? ✔ [1, 7] ? X

Assume

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chan ch = [0] of {int, int};
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```

Does ch ? 0, id match message

▶ [0, 5] ? ✔ [0, 7] ? ✔ [1, 7] ? ¥

Value of id afterwards?

```
Assume
    chan ch = [0] of {int, int};
    int id = 5;
Does ch ? 0, id match message
    [0, 5] ? ✓ [0, 7] ? ✓ [1, 7] ? ✗
    Value of id afterwards?
```

To match the value stored in a variable var use eval(var)

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Assume
    chan ch = [0] of {int, int};
    int id = 5;
Does ch ? 0, id match message
    [0, 5] ? ✓ [0, 7] ? ✓ [1, 7] ? ¥
    Value of id afterwards?
```

To match the value stored in a variable var use eval(var)

```
Does ch ? 0, eval(id) match message
```

```
▶ [0, 5] ?
```

```
Assume
    chan ch = [0] of {int, int};
    int id = 5;
Does ch ? 0, id match message
    [0, 5] ? ✓ [0, 7] ? ✓ [1, 7] ? ✗
    Value of id afterwards?
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Does ch ? 0, eval(id) match message

🕨 [0, 5] ? 🗸

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    chan ch = [0] of {int, int};
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Does ch ? 0, id match message
    [0, 5] ? ✓ [0, 7] ? ✓ [1, 7] ? ¥
    Value of id afterwards?
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To match the value stored in a variable var use eval(var)

Does ch ? 0, eval(id) match message

▶ [0, 5] ? ✔ [0, 7] ?

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    chan ch = [0] of {int, int};
    int id = 5;
Does ch ? 0, id match message
    [0, 5] ? ✓ [0, 7] ? ✓ [1, 7] ? ✗
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    chan ch = [0] of {int, int};
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    [0, 5] ? ✓ [0, 7] ? ✓ [1, 7] ? ✗
    Value of id afterwards?
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To match the value stored in a variable var use eval(var)

Does ch ? 0, eval(id) match message

▶ [0, 5] ? ✔ [0, 7] ? ¥ [1, 7] ?

```
Assume
    chan ch = [0] of {int, int};
    int id = 5;
Does ch ? 0, id match message
    [0, 5] ? ✓ [0, 7] ? ✓ [1, 7] ? ×
    Value of id afterwards?
```

To match the value stored in a variable var use eval(var)

Does ch ? 0, eval(id) match message ► [0, 5] ? ✓ [0, 7] ? ★ [1, 7] ? ★

```
Assume
    chan ch = [0] of {int, int};
    int id = 5;
Does ch ? 0, id match message
    [0, 5] ? ✓ [0, 7] ? ✓ [1, 7] ? ★
    Value of id afterwards?
```

To match the value stored in a variable var use eval(var)

Does ch ? 0, eval(id) match message

- ▶ [0, 5] ? ✔ [0, 7] ? ¥ [1, 7] ? ¥
- Value of id afterwards?

Dispatching Messages Revisited

Random receive ?? (for buffered channels)

Executable if matching message exists in channel.

If executed, first matching message removed from channel.

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If executed, first matching message removed from channel.

```
mtype = {hi, bye};
chan ch = [3] of {mtype};
active proctype Server () {
    do
        :: ch ?? bye -> printf("See_you.\n"); break
        :: else         -> printf("Hello.\n")
        od
}
...
```

Nicer Message Formatting

 $\operatorname{PROMELA}$ provides an alternative, but equivalent syntax for

ch ! exp1, exp2, exp3

Nicer Message Formatting

PROMELA provides an alternative, but equivalent syntax for

ch ! exp1, exp2, exp3

namely

ch ! exp1(exp2, exp3)

Increases readability for certain applications, e.g. protocol modelling: ch!send(msg,id) vs. ch!send,msg,id ch!ack(id) vs. ch!ack,id Buffered channels are part of the state! State space gets much bigger using buffered channels Use with care (and with small buffers).