

Testing, Debugging, and Verification

Testing, Part III

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¹Slides based on material from Wolfgang Aherndt,...

Overview of this Lecture

This lecture is all about **unit testing**

Specific topics:

- ▶ **Recap:** JUnit- a framework for rapid unit testing
- ▶ **Recap:** Integrating test units
- ▶ Principles of test set construction
- ▶ Quality criteria for test sets

JUnit (Recap.)

- ▶ JAVA testing framework to write and run automated tests
- ▶ JUnit features include:
 - ▶ Assertions for testing expected results
 - ▶ Annotations to designate test cases
 - ▶ Sharing of common test data
 - ▶ Graphical and textual test runners
- ▶ JUnit is widely used in industry
- ▶ JUnit used from command line or within an IDE (e.g., Eclipse)

Recap: JUnit and Extreme Testing

- ▶ Extreme testing
 - ▶ Test-cases first: Clear idea of what program should do before coding.
 - ▶ Understanding of specification and requirements.
 - ▶ Write test-cases first then implementation.
- ▶ Regression testing
 - ▶ re-run after changes to code.

Recap: Integrating Test Units

Testing a unit may require:

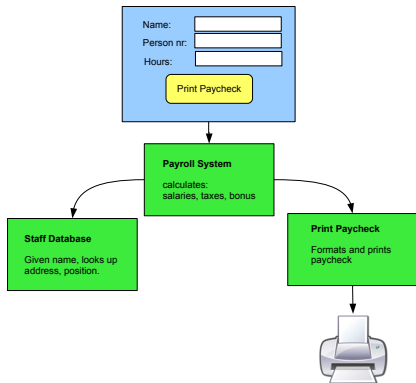
Stubs (top-down) to replace called procedures

- ▶ Simulate behaviour of component not yet developed.
- ▶ E.g. test code that calls a method not yet implemented.

Drivers (bottom-up) to replace calling procedures

- ▶ Simulate environment from where procedure is called.
- ▶ E.g. test harness.

Recap: Top-down vs Bottom-up Testing



- ▶ Bottom-up?
start from e.g. Print Paycheck, Staff Database
 - ▶ Driver replacing the caller, here Payroll System, Interface.
- ▶ Top-down?
start from e.g. Interface, then Payroll System
 - ▶ Stubs replacing called procedures, i.e. Payroll System, Staff Database, Print Paycheck.

Terminology recap

- ▶ Specification
- ▶ Test case
- ▶ Test suite

Today: Principles of test suite construction

How do we pick test cases? When do we know we have enough test cases?

Test Suite

A test suite is a set of test cases.

Most central activity of testing is the **creation of test suites**

How do we know if we have

- ▶ Enough test cases?
- ▶ The right test cases?
- ▶ **Quality of test suites** defines **quality of overall testing effort**

When do we have enough tests

Example

```
public static boolean and(boolean a, boolean b)
```

The output is true if and only if both the inputs are true and false otherwise.

Tests

- ▶ `and(false,false) == false`
- ▶ `and(false,true) == false`
- ▶ `and(true,false) == false`
- ▶ `and(true,true) == true`

When do we have enough tests

Example

```
public static Integer[] sort(Integer[] a) {  
    ...  
}
```

- ▶ Complete/exhaustive testing is impossible in general.
- ▶ When do we have enough tests? (an answer: **coverage criteria**)
- ▶ **Coverage criteria**: How much of the code is covered by the set of tests?
- ▶ Different ways to define **covered**.

Coverage Criteria

Most **metrics** used as **quality criteria for test suites** describe the **degree of** some kind of **coverage**.

These metrics are called **coverage criteria**.

Crucial for testing **safety critical software**.
Requirements of testing to certain coverage criteria.

Categories of Coverage Criteria

Following the categorisation of [AmmannOffutt] (simplified), we group coverage criteria as follows:

Coverage Criteria Grouping

- ▶ Control flow graph coverage
- ▶ Logic coverage
- ▶ Input space partitioning

Control Flow Graph

Represent implementation under test as graph:

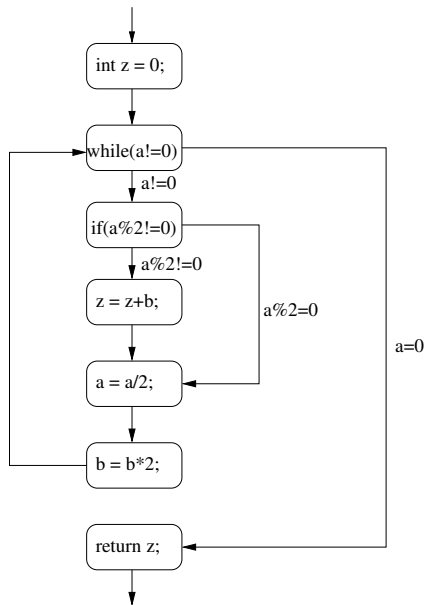
- ▶ Every **statement** represented by a **node**
- ▶ **Edges** describe **control flow** between statements
- ▶ Edges can be constrained by **conditions**

Example

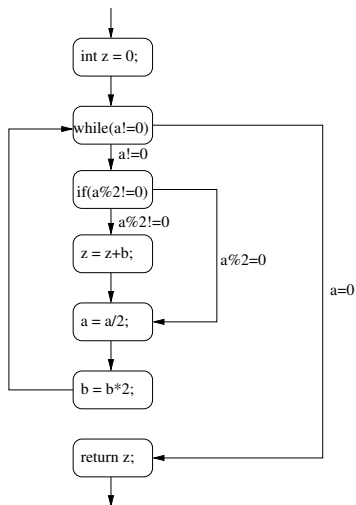
```
int russianMultiplication(int a, int b){
    int z = 0;
    while(a != 0){
        if(a%2 != 0){
            z = z+b;
        }
        a = a/2;
        b = b*2;
    }
    return z;
}
```

[example and graph by Christian Engel]

Control Flow Graph of russianMultiplication()



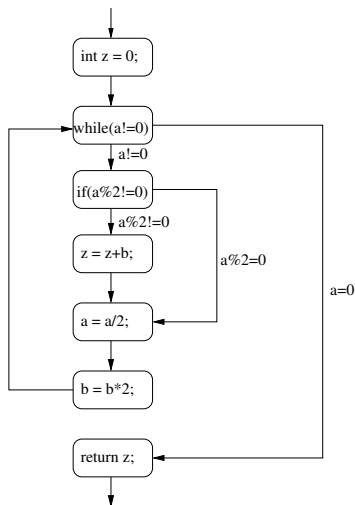
Control Flow Graph Notions



Execution Path

A path through a control flow graph, that starts at the entry point and is either infinite or ends at one of the exit points.

Statement Coverage



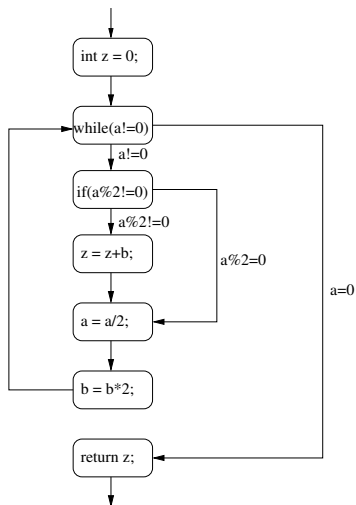
Statement Coverage (SC)

SC is satisfied by a test suite TS , iff for every **node** n in the control flow graph there is at least one test in TS causing an execution path via n .

For `russianMultiplication()`:

- ▶ $TS = \{(a = 1, b = 0)\}$ satisfies statement coverage

Branch Coverage



Branch Coverage (BC)

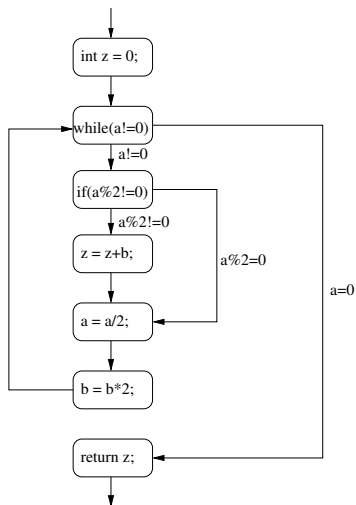
BC is satisfied by a test suite TS , iff for every **edge** e in the control flow graph there is at least one test in TS causing an execution path via e .

BC subsumes SC.

For `russianMultiplication()`:

- ▶ $TS = \{(a = 2, b = 0)\}$ satisfies branch coverage

Path Coverage



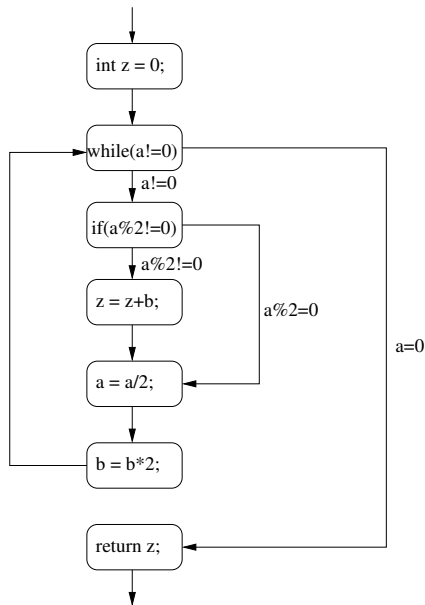
Path Coverage (PC)

PC is satisfied by a test suite TS , iff for every **execution path** ep of the control flow graph there is at least one test in TS causing ep .

PC subsumes BC.

- ▶ PC cannot be achieved in practice
- ▶ For `russianMultiplication()`, number of execution paths is $\gg 2^{31}$

Mini Quiz: Graph Coverage



Does the following test cases satisfy **Statement Coverage**, **Branch Coverage** and/or **Path Coverage**?

- ▶ `[a=3, b=3]` **SC**
- ▶ `[a=0, b=2]` **neither**
- ▶ `[a=4, b=1]` **SC and BC**

Logical (boolean) expressions can come from many sources:

1. Decisions in source code (e.g., `if`, `while`)
2. Decisions in software models (FSMs and statecharts)
3. Case distinctions in requirements

We focus on 1.

Decision Coverage

Let the **decisions of a program p** , $D(p)$, be the set of all boolean expressions which p branches on.

Decision Coverage (DC)

For a given **decision d** , DC is satisfied by a test suite TS if it

- ▶ Contains at least two tests
- ▶ one where d evaluates to *false*
- ▶ one where d evaluates to *true*

For a given **program p** , DC is satisfied by TS if it satisfies DC for all decisions $d \in D(p)$.

Decision Coverage

Example

For decision $((a < b) \parallel D) \&\& (m \geq n * o)$,
DC is satisfied for instance if *TS* triggers executions with:

$a = 5, b = 10, D = true, m = 1, n = 1, o = 1$

and

$a = 10, b = 5, D = false, m = 1, n = 1, o = 1$

Inner Value Problem

- ▶ the above values are not test case inputs, but values at the time of executing the decision
- ▶ finding corresponding input values

Condition Coverage

Let the **conditions of a program** p , $C(p)$, be the set of all boolean **sub**-expressions c of decisions in $D(p)$, such that c does not contain other boolean sub-expressions.

Given the decision $((a < b) \parallel D) \&\& (m \geq n * o)$, the conditions are: $(a < b)$, D , and $(m \geq n * o)$.

Condition Coverage (CC)

For a given **condition** c , CC is satisfied by a test suite TS if it

- ▶ contains at least two tests
- ▶ one where c evaluates to *false*
- ▶ one where c evaluates to *true*

For a given **program** p , CC is satisfied by TS if it satisfies CC for all conditions $c \in C(p)$.

Condition Coverage

Example

For *each condition* in $((a < b) \parallel D) \ \&\& \ (m \geq n * o)$,
CC is satisfied for instance if *TS* triggers executions with:

$a = 5, b = 10, D = \text{true}, m = 1, n = 1, o = 1$

and

$a = 10, b = 5, D = \text{false}, m = 1, n = 2, o = 2$

No subsumption

- ▶ Consider $p \parallel q$, tests = $\{(true, false), (false, true)\}$
- ▶ Note that condition coverage does not imply decision coverage or vice versa, above example has no decision coverage.

Modified Condition Decision Coverage, MCDC

For a given **condition** c in decision d , MCDC is satisfied by a test suite TS if it

- ▶ contains at least two tests,
- ▶ one where c evaluates to *false*,
- ▶ one where c evaluates to *true*,
- ▶ d evaluates differently in both, and
- ▶ other conditions in d evaluate identically in both

For a given **program** p , MCDC is satisfied by TS if it satisfies MCDC for all $c \in C(p)$.

Modified Condition Decision Coverage, MCDC

Example

For condition $a < b$ in decision $((a < b) \parallel D) \&\& (m \geq n * o)$, MCDC is satisfied for instance if *TS* triggers executions with:

$a = 5, b = 10, D = \text{false}, m = 1, n = 1, o = 1$

and

$a = 10, b = 5, D = \text{false}, m = 8, n = 2, o = 3$

Note: To have MCDC for whole decision also need test-cases for conditions D and $(m \geq n * o)$

(Note that the examples on slides 23 and 25 do *not* guarantee MCDC.)

MCDC in industrial certification standard

MCDC is required in the avionics certification standard DO-178 as the criterion to test adequately Level A software (failure of which is classified as 'Catastrophic').

Mini Quiz: Logical Coverage

Suppose a program contains the decision $\text{if}(x < 1 \ || \ y > z)$
Does the following test sets satisfy **Decision Coverage**, **Condition Coverage** and/or **MCDC**?

- ▶ $[x=0, y=0, z=1]$ and $[x=2, y=2, z=1]$
CC
- ▶ $[x=2, y=2, z=1]$ and $[x=2, y=0, z=1]$
DC
- ▶ $[x=2, y=2, z=2]$, $[x=0, y=0, z=1]$,
 $[x=2, y=0, z=0]$, $[x=2, y=2, z=1]$
DC, CC, MCDC

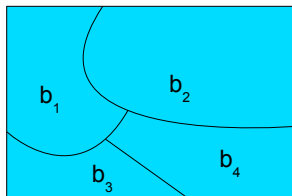
Input Space Partitioning

- ▶ Ultimately all testing is about choosing elements from input space
- ▶ **Input space partitioning** takes that view in a more direct way
- ▶ Input space partitioned into regions that are assumed to contain 'equally useful values'
- ▶ Test cases contain values from each region

Partitioning Domains

A partitioning q of a domain D defines a set of blocks, $B_q = \{b_1, \dots, b_n\}$, such that:

- ▶ the blocks b_i are pairwise disjoint (no overlap)
- ▶ together the blocks cover the domain D (complete)



Normally, different partitionings are combined (example later)

Examples

Consider the domain of integer arrays.

Are the following blocks a partitioning?

- ▶ b_1 = sorted in ascending order
- ▶ b_2 = sorted in descending order
- ▶ b_3 = arbitrary order

Answer: no!

- ▶ The array [1] belongs to all blocks

Combining Partitionings

When creating test cases for `findElement (int[] arr, int elem)`

partitioning q : `arr` is null (b_{q1}) or not (b_{q2})

partitioning r : `arr` is empty (b_{r1}) or not (b_{r2})

partitioning s : number of `elem` in `arr` is 0 (b_{s1}), 1 (b_{s2}), or >1 (b_{s3})

Note:

- ▶ r is a **sub-partitioning** of b_{q2}
- ▶ b_{s2} and b_{s3} are **sub-blocks** of b_{r2}
- ▶ b_{s1} overlaps with b_{r1} and b_{q2}
(fine, as r and s are different partitionings)

Strategies for Identifying Values

After partitioning, one still has to choose values from the blocks.

Strategies

- ▶ Include valid, invalid and special values
- ▶ Sub-partition some blocks
- ▶ Explore boundaries of domains

Discussion: Input Space Partitionings

Recall the method `russianMultiplication(int a, int b)`.

Suggest some input space partitionings.

E.g.

- ▶ $a \geq 0$ or $a < 0$
- ▶ $b \geq 0$ or $b < 0$
- ▶ $a \geq b$ or $a < b$

Example

Example

```
public static int binarySearch(int [] arr, int  
elem)
```

Specification

requires: $arr \neq null$, arr is sorted ascendingly

ensures: if there exists an element of arr that is equal to $elem$ then $arr[result] == elem$, otherwise $result == -1$

- ▶ **Partition 1:** $elem$ in array, $elem$ not in array
 - ▶ **Sub-partition of not in array:** $elem < \min(array)$, $\min(array) \leq elem \leq \max(array)$, $\max(array) < elem$
 - ▶ **Sub-partition of in array:** left of middle, middle, right of middle

Example (cont.)

- ▶ **Partition 1:** elem in array, elem not in array
 - ▶ **Sub-partition of not in array:** $\text{elem} < \min(\text{array}), \min(\text{array}) \leq \text{elem} \leq \max(\text{array}), \max(\text{array}) < \text{elem}$
 - ▶ **Sub-partition of in array:** left of middle, middle, right of middle

- ▶ **Not in array:**
 - ▶ `binarySearch({1, 3, 5, 8}, 0); <`
 - ▶ `binarySearch({2, 4, 76, 40}, 3); in`
 - ▶ `binarySearch({34, 64, 75, 100}, 101); >`

- ▶ **In array:**
 - ▶ `binarySearch({0, 2, 4, 6, 44}, 0); left border`
 - ▶ `binarySearch({4, 5, 34, 55, 66}, 5); left/middle`
 - ▶ `binarySearch({4, 5, 34, 55, 66}, 34); middle`
 - ▶ `binarySearch({4, 5, 34, 55, 66}, 55); right/middle`
 - ▶ `binarySearch({3, 4, 5, 6, 432, 1000}, 1000); rightborder`

Input Space Partitioning

- ▶ Look at specification
- ▶ Divide input space into regions with for which the program acts **similar**
- ▶ Take some inputs from regions, especially from **borders**

Use multiple partitions, subdivide partitions when sensible

This is a guideline, not a formal procedure: use common sense to define **similar**, **border** and **sensible**

Black-box Vs. White-box testing

Black-box testing

Deriving test suites from **external descriptions** of the software, e.g.

- ▶ Specifications
- ▶ Requirements / Design
- ▶ Input space knowledge

Does not require knowledge of internals (i.e., source code)

White-box testing

Deriving test suites from the **source code internals** of the software, e.g.

- ▶ Conditions
- ▶ Branches in execution
- ▶ Statements

- ▶ **Control Flow Graph Coverage**
 - ▶ Statement coverage: every node visited.
 - ▶ Branch coverage: every edge traversed.
 - ▶ Path coverage: every execution path (usually too many!)
- ▶ **Logic Based Coverage**
 - ▶ Decision coverage: test for each decision true/false.
 - ▶ Condition coverage: each sub-expression true/false.
 - ▶ MCDC: sub-expression true/false AND affecting decision.
- ▶ **Input Space Partitioning**
 - ▶ Input space split into disjoint regions.

- ▶ Introduction to Software Testing - by Paul Ammann, Jeff Offutt
 - ▶ Graph coverage (Chapter 2),
 - ▶ Logic coverage (Chapter 3), and
 - ▶ Input space partitioning (Chapter 4).