Formal Methods for Software Development Reasoning about Programs with Loops and Method Calls

Wolfgang Ahrendt

17 October 2017

Calculus realises symbolic interpreter:

works on first active statement

- works on first active statement
- decomposition of complex statements into simpler ones

$$\Gamma \Rightarrow \langle \mathbf{t=j;j=j+1;i=t;if}(isValid) \{ok=true;\}...\rangle \phi$$

$$\Gamma \Rightarrow \langle i=j++;if(isValid) \{ok=true;\}...\rangle \phi$$

- works on first active statement
- decomposition of complex statements into simpler ones
- simple assignments to updates

```
\Gamma \Rightarrow \{\mathbf{t} := \mathbf{j}\} \langle \mathbf{j} = \mathbf{j} + 1; \mathbf{i} = \mathbf{t}; \mathbf{i} \mathbf{f} (\mathbf{i} \mathbf{s} \mathbf{Valid}) \{\mathbf{o} \mathbf{k} = \mathbf{t} \mathbf{r} \mathbf{u} \mathbf{e}; \} \dots \rangle \phi
\Gamma \Rightarrow \langle \mathbf{t} = \mathbf{j}; \mathbf{j} = \mathbf{j} + 1; \mathbf{i} = \mathbf{t}; \mathbf{i} \mathbf{f} (\mathbf{i} \mathbf{s} \mathbf{Valid}) \{\mathbf{o} \mathbf{k} = \mathbf{t} \mathbf{r} \mathbf{u} \mathbf{e}; \} \dots \rangle \phi
\Gamma \Rightarrow \langle \mathbf{i} = \mathbf{j} + +; \mathbf{i} \mathbf{f} (\mathbf{i} \mathbf{s} \mathbf{Valid}) \{\mathbf{o} \mathbf{k} = \mathbf{t} \mathbf{r} \mathbf{u} \mathbf{e}; \} \dots \rangle \phi
```

- works on first active statement
- decomposition of complex statements into simpler ones
- simple assignments to updates
- accumulated update captures changed program state

```
\Gamma \Rightarrow \{\mathbf{t} := \mathbf{j} || \mathbf{j} := \mathbf{j} + \mathbf{1} || \mathbf{i} := \mathbf{j} \} \langle \mathbf{if}(\mathbf{isValid}) \{ \mathbf{ok=true}; \} \dots \rangle \phi
\vdots
\Gamma \Rightarrow \{\mathbf{t} := \mathbf{j} \} \langle \mathbf{j} = \mathbf{j} + \mathbf{1}; \mathbf{i=t}; \mathbf{if}(\mathbf{isValid}) \{ \mathbf{ok=true}; \} \dots \rangle \phi
\Gamma \Rightarrow \langle \mathbf{t} = \mathbf{j}; \mathbf{j} = \mathbf{j} + \mathbf{1}; \mathbf{i=t}; \mathbf{if}(\mathbf{isValid}) \{ \mathbf{ok=true}; \} \dots \rangle \phi
\Gamma \Rightarrow \langle \mathbf{i} = \mathbf{j} + \mathbf{j}; \mathbf{if}(\mathbf{isValid}) \{ \mathbf{ok=true}; \} \dots \rangle \phi
```

- works on first active statement
- decomposition of complex statements into simpler ones
- simple assignments to updates
- lacktriangle accumulated update captures changed program state (abbr. w. \mathcal{U})

```
\Gamma \Rightarrow \{\mathcal{U}\} \langle \mathbf{if}(\mathbf{isValid}) \{ \mathbf{ok=true}; \} \dots \rangle \phi
\dots
\Gamma \Rightarrow \{\mathbf{t} := \mathbf{j}\} \langle \mathbf{j} = \mathbf{j} + 1; \mathbf{i} = \mathbf{t}; \mathbf{if}(\mathbf{isValid}) \{ \mathbf{ok=true}; \} \dots \rangle \phi
\Gamma \Rightarrow \langle \mathbf{t} = \mathbf{j}; \mathbf{j} = \mathbf{j} + 1; \mathbf{i} = \mathbf{t}; \mathbf{if}(\mathbf{isValid}) \{ \mathbf{ok=true}; \} \dots \rangle \phi
\Gamma \Rightarrow \langle \mathbf{i} = \mathbf{j} + +; \mathbf{if}(\mathbf{isValid}) \{ \mathbf{ok=true}; \} \dots \rangle \phi
```

- works on first active statement
- decomposition of complex statements into simpler ones
- simple assignments to updates
- accumulated update captures changed program state
- control flow branching induces proof splitting

Calculus realises symbolic interpreter:

- works on first active statement
- decomposition of complex statements into simpler ones
- simple assignments to updates
- accumulated update captures changed program state
- control flow branching induces proof splitting

 $\Gamma' \Longrightarrow \{\mathcal{U}'\}\phi$

ightharpoonup application of update computes weakest precondition of \mathcal{U}' wrt. ϕ

$$\begin{array}{ccc} & \dots & & \dots \\ \text{`branch1'} & \Gamma, \{\mathcal{U}\} (\text{isValid} = \text{TRUE}) \Longrightarrow \{\mathcal{U}\} \langle \{\text{ok=true};\}\dots \rangle \phi \\ \text{`branch2'} & \Gamma, \{\mathcal{U}\} (\text{isValid} = \text{FALSE}) \Longrightarrow \{\mathcal{U}\} \langle \dots \rangle \phi \\ & \Gamma \Longrightarrow \{\mathcal{U}\} \langle \text{if} (\text{isValid}) \{\text{ok=true};\}\dots \rangle \phi \end{array}$$

```
\Gamma \Longrightarrow \{\mathsf{t} := \mathsf{j}\} \langle \mathsf{j} = \mathsf{j} + 1; \mathsf{i} = \mathsf{t}; \mathsf{i} \mathsf{f} (\mathsf{i} \mathsf{s} \mathsf{Valid}) \{\mathsf{o} \mathsf{k} = \mathsf{true}; \} \dots \rangle \phi
\Gamma \Longrightarrow \langle \mathsf{t} = \mathsf{j}; \mathsf{j} = \mathsf{j} + 1; \mathsf{i} = \mathsf{t}; \mathsf{i} \mathsf{f} (\mathsf{i} \mathsf{s} \mathsf{Valid}) \{\mathsf{o} \mathsf{k} = \mathsf{true}; \} \dots \rangle \phi
\Gamma \Longrightarrow \langle \mathsf{i} = \mathsf{j} + +; \mathsf{i} \mathsf{f} (\mathsf{i} \mathsf{s} \mathsf{Valid}) \{\mathsf{o} \mathsf{k} = \mathsf{true}; \} \dots \rangle \phi
```

An Example

```
\javaSource "src/";
\programVariables{
Person p;
int j;
\problem {
  (\forall int i;
    (!p=null ->
      ({j := i}\<{p.setAge(j);}\>(p.age = i))))
```

Method Call with actual parameters arg_0, \ldots, arg_n

$$\langle o.m(arg_0, \ldots, arg_n); \omega \rangle \phi$$

assume m declared as void $m(\tau_0 p_0, \ldots, \tau_n p_n)$

Method Call with actual parameters arg_0, \ldots, arg_n

$$\langle o.m(arg_0, \ldots, arg_n); \omega \rangle \phi$$

assume m declared as void $m(\tau_0 p_0, \ldots, \tau_n p_n)$

Actions of rule methodCall

1. Declare new local variables p#i, initialize them with actual parameter: $\tau_i p\#i = arg_i$;

Method Call with actual parameters arg_0, \ldots, arg_n

```
\langle o.m(arg_0, \ldots, arg_n); \omega \rangle \phi
```

assume m declared as void $m(\tau_0 p_0, \ldots, \tau_n p_n)$

Actions of rule methodCall

- 1. Declare new local variables p#i, initialize them with actual parameter: $\tau_i p\#i = arg_i$;
- Look-up implementing class C of m;
 split proof if implementation cannot be uniquely determined.

Method Call with actual parameters arg_0, \ldots, arg_n

$$\langle o.m(arg_0, \ldots, arg_n); \omega \rangle \phi$$

assume m declared as void $m(\tau_0 p_0, \ldots, \tau_n p_n)$

Actions of rule methodCall

- 1. Declare new local variables p#i, initialize them with actual parameter: $\tau_i p\#i = arg_i$;
- Look-up implementing class C of m;
 split proof if implementation cannot be uniquely determined.
- 3. Replace method call with implementation invocation o.m(p#0,...,p#n)@C

Method Calls Cont'd

After executing the initialisers: $\tau_i p\#i = arg_i$; apply:

Method Body Expand

Call rule methodBodyExpand

$$\Gamma \Longrightarrow \langle \texttt{method-frame(source=m($\tau_0,...,\tau_n)} \texttt{ OC, this=o): } \{ \textit{body} \} \, \omega \rangle \phi, \Delta$$

$$\Gamma \Rightarrow \langle \text{o.m(p#0,...,p#n)@C;} \omega \rangle \phi, \Delta$$

- 1. Replaces method invocation by method frame with method body
- 2. Renames p_i in body to p#i

Method Calls Cont'd

After executing the initialisers: $\tau_i p\#i = arg_i$; apply:

Method Body Expand

Call rule methodBodyExpand

$$\Gamma \Longrightarrow \langle \texttt{method-frame}(\texttt{source=m}(\tau_0,...,\tau_n) \texttt{ 0C, this=o}) : \{ \textit{body} \} \, \omega \rangle \phi, \Delta$$

$$\Gamma \Longrightarrow \langle exttt{o.m(p#0,...,p#n)@C;} \hspace{0.1cm} \omega
angle \phi, \Delta$$

- 1. Replaces method invocation by method frame with method body
- **2.** Renames p_i in body to p#i

Method frames:

Required in proof to represent call stack

Method Calls Cont'd

After executing the initialisers: $\tau_i p\#i = arg_i$; apply:

Method Body Expand

Call rule methodBodyExpand

$$\Gamma \Longrightarrow \langle \texttt{method-frame}(\texttt{source=m}(\tau_0,...,\tau_n) \texttt{ 0C, this=o}) : \{ \textit{body} \} \, \omega \rangle \phi, \Delta = 0$$

$$\Gamma \Longrightarrow \langle \text{o.m(p#0,...,p#n)@C; } \omega \rangle \phi, \Delta$$

- 1. Replaces method invocation by method frame with method body
- **2.** Renames p_i in body to p#i

Method frames:

Required in proof to represent call stack

Demo

methods/instanceMethodInlineSimple.key
methods/inlineDynamicDispatch.key

Localisation of Fields and Method Implementations

JAVA has complex rules for localisation of fields and method implementations

- Polymorphism
- ► Late binding (dynamic dispatch)
- Scoping (class vs. instance)
- Visibility (private, protected, public)

Proof split into cases if implementation not statically determined

Object initialization

JAVA has complex rules for object initialization

- ► Chain of constructor calls until Object
- ► Implicit calls to super()
- Visibility issues
- Initialization sequence

Coding of initialization rules in methods <createObject>(), <init>(),... which are then symbolically executed

Limitations of Method Inlining: methodBodyExpand

- ► Source code might be unavailable
 - ► API method implementation vendor-specific
 - Source code often unavailable for commercial APIs
- Method is invoked multiple times in a program
 - Avoid multiple symbolic execution of identical code
- Cannot handle unbounded recursion
- ► Not modular:

Changing a method requires re-verification of all callers

Limitations of Method Inlining: methodBodyExpand

- Source code might be unavailable
 - ► API method implementation vendor-specific
 - Source code often unavailable for commercial APIs
- Method is invoked multiple times in a program
 - ▶ Avoid multiple symbolic execution of identical code
- Cannot handle unbounded recursion
- ► Not modular:

Changing a method requires re-verification of all callers

Use method contract instead of method implementation:

- 1. Show that requires clause is satisfied
- 2. Continue after method call:
 - assume ensures clause
 - forget prestate values of modifiable locations

Warning: Simplified version

```
/*@ public normal_behavior
@ requires preNormal;
@ ensures postNormal;
@ assignable mod;
@*/ // implementation contract of m()
```

Warning: Simplified version

```
/*@ public normal_behavior
  @ requires preNormal;
  @ ensures postNormal;
  @ assignable mod;
  @*/ // implementation contract of m()
```

$$\Gamma \Longrightarrow \mathcal{U}\langle \pi \, \mathtt{result} = \mathtt{m}(\mathtt{a_1},\ldots,\mathtt{a_n});\, \omega
angle \phi, \Delta$$

 \blacktriangleright π are openings of try blocks and method frames

Warning: Simplified version

/*@ public normal_behavior

```
@ requires preNormal;
@ ensures postNormal;
@ assignable mod;
@*/ // implementation contract of m()
\Gamma \Rightarrow \mathcal{UF}(\text{preNormal}), \Delta \quad \text{(precondition)}
```

 \blacktriangleright π are openings of try blocks and method frames

 $\Gamma \Longrightarrow \mathcal{U}\langle \pi \text{ result} = m(a_1, \ldots, a_n); \omega \rangle \phi, \Delta$

 \blacktriangleright $\mathcal{F}(\cdot)$: translation from JML to Java DL

JML Method Contracts Revisited

```
/*@ public normal_behavior
  @ requires preNormal;
  @ ensures postNormal;
  @ assignable mod;
  @*/
T m(T1 a1, ..., Tn an) { ... }
```

Implicit Preconditions and Postconditions

► The object referenced by this is not null: this!=null (precondition only; this cannot be changed by method)

JML Method Contracts Revisited

```
/*@ public normal_behavior
  @ requires preNormal;
  @ ensures postNormal;
  @ assignable mod;
  @*/
T m(T1 a1, ..., Tn an) { ... }
```

Implicit Preconditions and Postconditions

- ► The object referenced by this is not null: this!=null (precondition only; this cannot be changed by method)
- ► The heap is wellformed: wellFormed(heap) (precondition only)

JML Method Contracts Revisited

```
/*@ public normal_behavior
  @ requires preNormal;
  @ ensures postNormal;
  @ assignable mod;
  @*/
T m(T1 a1, ..., Tn an) { ... }
```

Implicit Preconditions and Postconditions

- ► The object referenced by this is not null: this!=null (precondition only; this cannot be changed by method)
- ► The heap is wellformed: wellFormed(heap) (precondition only)
- ► Invariant for 'this': \invariant_for(this)

Warning: Simplified version

/*@ public normal_behavior

```
@ requires preNormal;
@ ensures postNormal;
@ assignable mod;
@*/ // implementation contract of m()

Γ ⇒ UF(preNormal), Δ (precondition)
```

 \blacktriangleright π are openings of try blocks and method frames

 $\Gamma \Longrightarrow \mathcal{U}\langle \pi \text{ result} = m(a_1, \ldots, a_n); \omega \rangle \phi, \Delta$

 $ightharpoonup \mathcal{F}(\cdot)$: translation from JML to Java DL

Warning: Simplified version

```
/*@ public normal_behavior
@ requires preNormal;
@ ensures postNormal;
@ assignable mod;
@*/ // implementation contract of m()

\frac{\Gamma \Rightarrow \mathcal{UF}(\text{preNormal}), \Delta \quad (\text{precondition})}{\Gamma \Rightarrow \mathcal{UV}_{mod}(\mathcal{F}(\text{postNormal}) \rightarrow \langle \pi \; \omega \rangle \phi), \Delta \quad (\text{normal})}{\Gamma \Rightarrow \mathcal{UV}_{mod}(\mathcal{F}(\text{postNormal}), \omega \rangle \phi, \Delta}
```

- \blacktriangleright π are openings of try blocks and method frames
- \blacktriangleright $\mathcal{F}(\cdot)$: translation from JML to Java DL
- V_{mod}: anonymising update, forgetting prevalues of modifiable locations

lacktriangle Want to keep part of prestate ${\cal U}$ that is unmodified by called method

- ightharpoonup Want to keep part of prestate ${\cal U}$ that is unmodified by called method
- ▶ assignable clause of contract tells what can possibly be modified

@ assignable mod;

- ightharpoonup Want to keep part of prestate $\mathcal U$ that is unmodified by called method
- ▶ assignable clause of contract tells what can possibly be modified

@ assignable mod;

► How to erase all values of **assignable** locations in state *U* ?

- ightharpoonup Want to keep part of prestate $\mathcal U$ that is unmodified by called method
- ▶ assignable clause of contract tells what can possibly be modified

@ assignable mod;

- ► How to erase all values of **assignable** locations in state U?
- ightharpoonup Anonymising updates $\mathcal V$ erase information about modified locations

Define anonymising function anon: Heap \times LocSet \times Heap \rightarrow Heap The resulting heap anon(...) coincides with the first heap on all locations except for those specified in the location set. Those locations attain the value specified by the second heap.

Define anonymising function anon: Heap \times LocSet \times Heap \to Heap The resulting heap anon(...) coincides with the first heap on all locations except for those specified in the location set. Those locations attain the value specified by the second heap.

Definition:

$$select(anon(h1, locs, h2), o, f) = \begin{cases} select(h2, o, f) & \text{if } (o, f) \in locs \\ select(h1, o, f) & \text{otherwise} \end{cases}$$

Define anonymising function anon: Heap \times LocSet \times Heap \to Heap The resulting heap anon(...) coincides with the first heap on all locations except for those specified in the location set. Those locations attain the value specified by the second heap.

Definition:

$$select(anon(h1, locs, h2), o, f) =$$

$$\begin{cases} select(h2, o, f) & \text{if } (o, f) \in locs \\ select(h1, o, f) & \text{otherwise} \end{cases}$$

Usage:

$$\mathcal{V}_{mod} = \{ \text{heap} := \text{anon(heap}, locs_{mod}, h_{an}) \}$$

where h_{an} a new (not yet used) constant of type Heap

Define anonymising function anon: Heap \times LocSet \times Heap \to Heap The resulting heap anon(...) coincides with the first heap on all locations except for those specified in the location set. Those locations attain the value specified by the second heap.

Definition:

$$select(anon(h1, locs, h2), o, f) =$$

$$\begin{cases} select(h2, o, f) & \text{if } (o, f) \in locs \\ select(h1, o, f) & \text{otherwise} \end{cases}$$

Usage:

$$\mathcal{V}_{mod} = \{ \texttt{heap} := \texttt{anon}(\texttt{heap}, \textit{locs}_{mod}, \texttt{h}_{\textit{an}}) \}$$

where h_{an} a new (not yet used) constant of type Heap

Effect: After V_{mod} , modfied locations have unknown values

Anonymising Heap Locations: Example

```
@ assignable o.a, this.*;
```

Anonymising Heap Locations: Example

```
@ assignable o.a, this.*;
```

To erase all knowledge about the values of the locations of the assignable expression:

▶ Anonymise the current heap on the designated locations:

```
\texttt{anon}(\texttt{heap}, \{(\texttt{o}, \texttt{a})\} \cup \texttt{allFields}(\texttt{this}), \texttt{h}_{\textit{an}})
```

▶ Make that anonymised current heap the new current heap.

```
\mathcal{V}_{mod} = \{ \texttt{heap} := \texttt{anon}(\texttt{heap}, \{(\texttt{o}, \texttt{a})\} \cup \texttt{allFields}(\texttt{this}), \texttt{h}_{\textit{an}}) \}
```

Warning: Simplified version

```
/*@ public exceptional_behavior
  @ requires preExc;
  @ signals (Exception exc) postExc;
  @ assignable mod;
  @*/
```

Warning: Simplified version

```
/*@ public exceptional_behavior
  @ requires preExc;
  @ signals (Exception exc) postExc;
  @ assignable mod;
  @*/
```

$$\Gamma \Longrightarrow \mathcal{U}\langle \pi \text{ result} = m(a_1, \dots, a_n); \omega \rangle \phi, \Delta$$

 \blacktriangleright π are openings of try blocks and method frames

Warning: Simplified version

```
/*@ public exceptional_behavior
  @ requires preExc;
  @ signals (Exception exc) postExc;
  @ assignable mod;
  @*/
```

$$\Gamma \Longrightarrow \mathcal{UF}(\mathtt{preExc}), \Delta \quad (\mathsf{precondition})$$

$$\mathsf{\Gamma} \Longrightarrow \mathcal{U}\langle \pi \, \mathtt{result} = \mathtt{m}(\mathtt{a_1}, \ldots, \mathtt{a_n}); \, \omega
angle \phi, \Delta$$

- \blacktriangleright π are openings of try blocks and method frames
- \blacktriangleright $\mathcal{F}(\cdot)$: translation from JML to Java DL

Warning: Simplified version

```
/*@ public exceptional_behavior
    @ requires preExc;
    @ signals (Exception exc) postExc;
    @ assignable mod;
   0*/
 \Gamma \Longrightarrow \mathcal{UF}(\mathtt{preExc}), \Delta \quad (\mathtt{precondition})
 \Gamma \Longrightarrow \mathcal{UV}_{mod}((\mathcal{F}(postExc) \land exc \neq null)
                                         \rightarrow \langle \pi \, \text{throw exc}; \, \omega \rangle \phi \rangle, \Delta (exceptional)
\Gamma \Longrightarrow \mathcal{U}\langle \pi \operatorname{result} = m(a_1, \ldots, a_n); \omega \rangle \phi, \Delta
```

- \blacktriangleright π are openings of try blocks and method frames
- $ightharpoonup \mathcal{F}(\cdot)$: translation from JML to Java DL
- $\triangleright \mathcal{V}_{mod}$: anonymising update

(background only, no need to remember)

KeY uses actually one rule for both kinds of cases.

(background only, no need to remember)

KeY uses actually one rule for both kinds of cases.

```
\begin{array}{lll} \phi_{\textit{post\_n}} & \equiv & \mathcal{F}\big(\old(\texttt{normalPre})\big) \land \mathcal{F}\big(\texttt{normalPost}\big) \\ \phi_{\textit{post\_e}} & \equiv & \mathcal{F}\big(\old(\texttt{excPre})\big) \land \mathcal{F}\big(\texttt{excPost}\big) \end{array}
```

(background only, no need to remember)

KeY uses actually one rule for both kinds of cases.

$$\begin{array}{lll} \phi_{\textit{post_n}} & \equiv & \mathcal{F}\big(\old(\texttt{normalPre})\big) \land \mathcal{F}\big(\texttt{normalPost}\big) \\ \phi_{\textit{post_e}} & \equiv & \mathcal{F}\big(\old(\texttt{excPre})\big) \land \mathcal{F}\big(\texttt{excPost}\big) \end{array}$$

$$\Gamma \Longrightarrow \mathcal{U}(\mathcal{F}(\texttt{normalPre}) \vee \mathcal{F}(\texttt{excPre})), \Delta \quad (\mathsf{precondition})$$

$$\Gamma \Longrightarrow \mathcal{U}\langle \pi \, \text{result} = \mathtt{m}(\mathtt{a}_1,\ldots,\mathtt{a}_\mathtt{n}); \, \omega \rangle \phi, \Delta$$

- $\triangleright \mathcal{F}(\cdot)$: translation to Java DL
- $\triangleright V_{mod}$: anonymising update

(background only, no need to remember)

KeY uses actually one rule for both kinds of cases.

$$\begin{array}{lll} \phi_{\textit{post_n}} & \equiv & \mathcal{F}\big(\ensuremath{\backslash} \texttt{old}(\texttt{normalPre})\big) \land \mathcal{F}\big(\texttt{normalPost}\big) \\ \phi_{\textit{post_e}} & \equiv & \mathcal{F}\big(\ensuremath{\backslash} \texttt{old}(\texttt{excPre})\big) \land \mathcal{F}\big(\texttt{excPost}\big) \end{array}$$

$$\begin{split} \Gamma &\Rightarrow \mathcal{U}(\mathcal{F}(\texttt{normalPre}) \vee \mathcal{F}(\texttt{excPre})), \Delta \quad (\texttt{precondition}) \\ \Gamma &\Rightarrow \mathcal{U} \underset{\textit{mod}_\textit{normal}}{\mathcal{V}} (\phi_\textit{post_n} \rightarrow \langle \pi \; \omega \rangle \phi), \Delta \quad (\texttt{normal}) \end{split}$$

$$\Gamma \Longrightarrow \mathcal{U}\langle \pi \, \text{result} = \mathtt{m}(\mathtt{a}_1,\ldots,\mathtt{a}_\mathtt{n}); \, \omega \rangle \phi, \Delta$$

- $\triangleright \mathcal{F}(\cdot)$: translation to Java DL
- $\triangleright V_{mod}$: anonymising update

(background only, no need to remember)

KeY uses actually one rule for both kinds of cases.

```
\begin{array}{lll} \phi_{\textit{post\_n}} & \equiv & \mathcal{F}\big(\ensuremath{\backslash} \texttt{old}(\texttt{normalPre})\big) \land \mathcal{F}\big(\texttt{normalPost}\big) \\ \phi_{\textit{post\_e}} & \equiv & \mathcal{F}\big(\ensuremath{\backslash} \texttt{old}(\texttt{excPre})\big) \land \mathcal{F}\big(\texttt{excPost}\big) \end{array}
```

```
\begin{split} \Gamma &\Rightarrow \mathcal{U}(\mathcal{F}(\mathsf{normalPre}) \vee \mathcal{F}(\mathsf{excPre})), \Delta \quad (\mathsf{precondition}) \\ \Gamma &\Rightarrow \mathcal{UV}_{mod_{normal}}(\phi_{post\_n} \to \langle \pi \; \omega \rangle \phi), \Delta \quad (\mathsf{normal}) \\ \Gamma &\Rightarrow \mathcal{UV}_{mod_{exc}}((\phi_{post\_e} \land \mathsf{exc} \neq \mathsf{null}) \\ &\qquad \qquad \rightarrow \langle \pi \; \mathsf{throw} \; \mathsf{exc}; \; \omega \rangle \phi), \Delta \quad (\mathsf{exceptional}) \\ \hline \Gamma &\Rightarrow \mathcal{U}\langle \pi \; \mathsf{result} = \mathtt{m}(\mathtt{a}_1, \ldots, \mathtt{a}_n); \; \omega \rangle \phi, \Delta \end{split}
```

- $\triangleright \mathcal{F}(\cdot)$: translation to Java DL
- $\triangleright V_{mod}$: anonymising update

Method Contract Rule: Example

```
class Person {
private /*@ spec_public @*/ int age;
 /*@ public normal_behavior
   @ requires age < 29;
   @ ensures age == \old(age) + 1;
   @ assignable age;
   0 also
   @ public exceptional_behavior
   @ requires age >= 29;
   @ signals_only ForeverYoungException;
   @ assignable \nothing;
   @//allows object creation (not \strictly_nothing)
   0*/
 public void birthday() {
   if (age >= 29) throw new ForeverYoungException();
   age++;
```

Method Contract Rule: Example Cont'd

Demo

methods/useContractForBirthday.key

- Prove without contracts
 - Method treatment: Expand
- Prove with contracts (until method contract application)
 - Method treatment: Contract
- Prove used contracts
 - Method treatment: Expand
 - ▶ Select contracts for birthday() in src/Person.java
 - Prove both specification cases

Symbolic execution of loops: unwind

$$\begin{array}{c} \text{unwindLoop} \ \ \frac{\Gamma \Longrightarrow \mathcal{U}[\pi \, \text{if(b)} \{p; \, \, \text{while(b)} \, \, p\} \, \, \omega]\phi, \Delta}{\Gamma \Longrightarrow \mathcal{U}[\pi \, \text{while(b)} \, \, p \, \, \omega]\phi, \Delta} \end{array}$$

Symbolic execution of loops: unwind

$$\begin{array}{c} \text{unwindLoop} \ \ \frac{\Gamma \Longrightarrow \mathcal{U}[\pi \ \text{if(b)} \{p; \ \text{while(b)} \ p\} \ \omega] \phi, \Delta}{\Gamma \Longrightarrow \mathcal{U}[\pi \ \text{while(b)} \ p \ \omega] \phi, \Delta} \end{array}$$

How to handle a loop with...

▶ 0 iterations?

Symbolic execution of loops: unwind

$$\begin{array}{c} \text{unwindLoop} \ \ \frac{\Gamma \Longrightarrow \mathcal{U}[\pi \ \text{if(b)} \{p; \ \text{while(b)} \ p\} \ \omega] \phi, \Delta}{\Gamma \Longrightarrow \mathcal{U}[\pi \ \text{while(b)} \ p \ \omega] \phi, \Delta} \end{array}$$

How to handle a loop with...

▶ 0 iterations? Unwind 1×

Symbolic execution of loops: unwind

$$\begin{array}{c} \text{unwindLoop} \ \ \frac{\Gamma \Longrightarrow \mathcal{U}[\pi \ \text{if(b)} \{p; \ \text{while(b)} \ p\} \ \omega] \phi, \Delta}{\Gamma \Longrightarrow \mathcal{U}[\pi \ \text{while(b)} \ p \ \omega] \phi, \Delta} \end{array}$$

- ▶ 0 iterations? Unwind 1×
- ▶ 10 iterations?

Symbolic execution of loops: unwind

$$\begin{array}{c} \text{unwindLoop} \ \ \frac{\Gamma \Longrightarrow \mathcal{U}[\pi \ \text{if(b)} \{p; \ \text{while(b)} \ p\} \ \omega] \phi, \Delta}{\Gamma \Longrightarrow \mathcal{U}[\pi \ \text{while(b)} \ p \ \omega] \phi, \Delta} \end{array}$$

- ▶ 0 iterations? Unwind 1×
- ▶ 10 iterations? Unwind 11×

Symbolic execution of loops: unwind

$$\begin{array}{c} \text{unwindLoop} & \frac{\Gamma \Longrightarrow \mathcal{U}[\pi \, \text{if(b)} \{ p; \, \, \text{while(b)} \, \, p \} \, \, \omega] \phi, \Delta}{\Gamma \Longrightarrow \mathcal{U}[\pi \, \text{while(b)} \, \, p \, \, \omega] \phi, \Delta} \end{array}$$

- ▶ 0 iterations? Unwind 1×
- ▶ 10 iterations? Unwind 11×
- ▶ 10000 iterations?

Symbolic execution of loops: unwind

$$\begin{array}{c} \text{unwindLoop} & \frac{\Gamma \Longrightarrow \mathcal{U}[\pi \, \text{if(b)} \{ p; \, \, \text{while(b)} \, \, p \} \, \, \omega] \phi, \Delta}{\Gamma \Longrightarrow \mathcal{U}[\pi \, \text{while(b)} \, \, p \, \, \omega] \phi, \Delta} \end{array}$$

- ▶ 0 iterations? Unwind 1×
- ▶ 10 iterations? Unwind 11×
- ▶ 10000 iterations? Unwind 10001×
- an unknown number of iterations?

Symbolic execution of loops: unwind

$$\begin{array}{c} \text{unwindLoop} \ \ \, \frac{\Gamma \Longrightarrow \mathcal{U}[\pi \, \text{if(b)} \{ \text{p; while(b) p} \} \, \omega] \phi, \Delta}{\Gamma \Longrightarrow \mathcal{U}[\pi \, \text{while(b) p} \, \omega] \phi, \Delta} \end{array}$$

How to handle a loop with...

- ▶ 0 iterations? Unwind 1×
- ▶ 10 iterations? Unwind 11×
- ▶ 10000 iterations? Unwind 10001×
- an unknown number of iterations?

We need an invariant rule (or some form of induction)

Idea behind loop invariants

► A formula *Inv* whose validity is preserved by loop body whenever the loop guard is true

Idea behind loop invariants

- ► A formula *Inv* whose validity is preserved by loop body whenever the loop guard is true
- ► Consequence: if *Inv* was valid at start of the loop, then it still holds after arbitrarily many loop iterations

Idea behind loop invariants

- ► A formula *Inv* whose validity is preserved by loop body whenever the loop guard is true
- ► Consequence: if *Inv* was valid at start of the loop, then it still holds after arbitrarily many loop iterations
- ▶ In particular, if the loop terminates, then *lnv* holds afterwards

Idea behind loop invariants

- ► A formula *Inv* whose validity is preserved by loop body whenever the loop guard is true
- ► Consequence: if *Inv* was valid at start of the loop, then it still holds after arbitrarily many loop iterations
- ▶ In particular, if the loop terminates, then *lnv* holds afterwards
- ► Challenge: construct *Inv* such that, *together with loop exit* condition, it implies postcondition of loop

Idea behind loop invariants

- ▶ A formula *Inv* whose validity is preserved by loop body whenever the loop guard is true
- ► Consequence: if *Inv* was valid at start of the loop, then it still holds after arbitrarily many loop iterations
- ▶ In particular, if the loop terminates, then *Inv* holds afterwards
- ► Challenge: construct *Inv* such that, *together with loop exit* condition, it implies postcondition of loop

Basic Invariant Rule

loopInvariant

$$\Gamma \Longrightarrow \mathcal{U}[\pi \text{ while (b) p } \omega]\phi, \Delta$$

Idea behind loop invariants

- ► A formula *Inv* whose validity is preserved by loop body whenever the loop guard is true
- ► Consequence: if *Inv* was valid at start of the loop, then it still holds after arbitrarily many loop iterations
- ▶ In particular, if the loop terminates, then *lnv* holds afterwards
- ► Challenge: construct *Inv* such that, *together with loop exit* condition, it implies postcondition of loop

Basic Invariant Rule

$$\Gamma \Longrightarrow \mathcal{U} Inv, \Delta$$

(valid when entering loop)

loopInvariant

$$\Gamma \Longrightarrow \mathcal{U}[\pi \text{ while (b) p } \omega]\phi, \Delta$$

Idea behind loop invariants

- ▶ A formula *Inv* whose validity is preserved by loop body whenever the loop guard is true
- ► Consequence: if *Inv* was valid at start of the loop, then it still holds after arbitrarily many loop iterations
- ▶ In particular, if the loop terminates, then *lnv* holds afterwards
- ► Challenge: construct *Inv* such that, *together with loop exit* condition, it implies postcondition of loop

Basic Invariant Rule

$$\begin{array}{ll} \Gamma \Longrightarrow \mathcal{U} \textit{Inv}, \Delta & \text{(valid when entering loop)} \\ \textit{Inv}, \ b = \texttt{TRUE} \Longrightarrow [\texttt{p}] \textit{Inv} & \text{(preserved by p)} \end{array}$$

loopInvariant

$$\Gamma \Longrightarrow \mathcal{U}[\pi \text{ while (b) p } \omega]\phi, \Delta$$

Idea behind loop invariants

- ▶ A formula *Inv* whose validity is preserved by loop body whenever the loop guard is true
- Consequence: if *Inv* was valid at start of the loop, then it still holds after arbitrarily many loop iterations
- ▶ In particular, if the loop terminates, then *Inv* holds afterwards
- ► Challenge: construct *Inv* such that, *together with loop exit* condition, it implies postcondition of loop

Basic Invariant Rule

$$\begin{array}{ccc} \Gamma \Rightarrow \mathcal{U} \textit{Inv}, \Delta & \text{(valid when entering loop)} \\ \textit{Inv}, \ b = \texttt{TRUE} \Rightarrow [\texttt{p}] \textit{Inv} & \text{(preserved by p)} \\ \textit{IoopInvariant} & & & & & & & \\ \hline \textit{Inv}, \ b = \texttt{FALSE} \Rightarrow [\pi \ \omega] \phi & & & & & \\ \hline \Gamma \Rightarrow \mathcal{U} [\pi \ \texttt{while} (\texttt{b}) \ \texttt{p} \ \omega] \phi, \Delta & & & & \\ \hline \end{array} \right.$$

How to Derive Loop Invariants Systematically?

Example (Active statement of symbolic execution is loop)

```
n >= 0 & wellFormed(heap)
-> {i := 0}
    \[{ while (i < n) {
        i = i + 1;
    }
}\] i = n</pre>
```

Look at desired postcondition i = n

What, in addition to negated guard $i \ge n$, is needed?

How to Derive Loop Invariants Systematically?

Example (Active statement of symbolic execution is loop)

```
n >= 0 & wellFormed(heap)
-> \{i := 0\}
      f  while (i < n) {
             i = i + 1:
        1 = n
```

Look at desired postcondition i = n

What, in addition to negated guard $i \ge n$, is needed? $i \le n$

How to Derive Loop Invariants Systematically?

Example (Active statement of symbolic execution is loop)

```
n >= 0 & wellFormed(heap)
-> {i := 0}
    \[{ while (i < n) {
        i = i + 1;
    }
}\] i = n</pre>
```

Look at desired postcondition i = n

What, in addition to negated guard $i \ge n$, is needed? $i \le n$

Is i <= n preserved by loop body? Does it hold when entering loop?

Yes! We have found a suitable loop invariant!

Demo loops/simple.key (auto after inv)

Obtaining Invariants by Strengthening

Example (Slightly changed problem)

```
n >= 0 & n = m & wellFormed(heap)
-> {i := 0}
    \[{ while (i < n) {
        i = i + 1;
     }
}\] i = m</pre>
```

Look at desired postcondition i = m

What, in addition to negated guard $i \ge n$, is needed?

Obtaining Invariants by Strengthening

Example (Slightly changed problem)

```
n >= 0 & n = m & wellFormed(heap)
-> {i := 0}
    \[{ while (i < n) {
        i = i + 1;
     }
}\] i = m</pre>
```

Look at desired postcondition i = m

What, in addition to negated guard $i \ge n$, is needed?

```
i \le n \& n = m
```

Obtaining Invariants by Strengthening

Example (Slightly changed problem)

```
n >= 0 & n = m & wellFormed(heap)
-> {i := 0}
    \[{ while (i < n) {
        i = i + 1;
     }
}\] i = m</pre>
```

Look at desired postcondition i = m

What, in addition to negated guard $i \ge n$, is needed?

```
i \le n \& n = m
```

Is $i \le n \& n = m$ preserved by loop body? Does it hold when entering loop?

Yes! We have found a suitable loop invariant!

Generalization

Example (Addition: x,y program variables, x0,y0 rigid constants)

```
x = x0 & y = y0 & y0 >= 0 & wellFormed(heap) ==>
\[{
    while (y > 0) {
        x = x + 1;
        y = y - 1;
    }
}\] (x = x0 + y0)
```

Example (Addition: x,y program variables, x0,y0 rigid constants)

```
x = x0 & y = y0 & y0 >= 0 & wellFormed(heap) ==>
\[{
    while (y > 0) {
        x = x + 1;
        y = y - 1;
    }
}\] (x = x0 + y0)
```

Finding the invariant

First attempt: use postcondition x = x0 + y0

Example (Addition: x,y program variables, x0,y0 rigid constants)

```
x = x0 & y = y0 & y0 >= 0 & wellFormed(heap) ==>
\[{
    while (y > 0) {
        x = x + 1;
        y = y - 1;
    }
}\] (x = x0 + y0)
```

Finding the invariant

First attempt: use postcondition x = x0 + y0

- ▶ Not true at start whenever y0 > 0
- ▶ Not preserved by loop, because x is increased

Example (Addition: x,y program variables, x0,y0 rigid constants)

```
x = x0 & y = y0 & y0 >= 0 & wellFormed(heap) ==>
\[{
    while (y > 0) {
        x = x + 1;
        y = y - 1;
    }
}\] (x = x0 + y0)
```

Finding the invariant

What stays invariant?

Example (Addition: x,y program variables, x0,y0 rigid constants)

```
x = x0 & y = y0 & y0 >= 0 & wellFormed(heap) ==>
\[{
    while (y > 0) {
        x = x + 1;
        y = y - 1;
    }
}\] (x = x0 + y0)
```

Finding the invariant

What stays invariant?

- ► The sum of x and y: x + y = x0 + y0 "Generalization"
- ▶ Can help to think of " δ " between x and x0 + y0

Example (Addition: x,y program variables, x0,y0 rigid constants)

```
x = x0 & y = y0 & y0 >= 0 & wellFormed(heap) ==>
\[{
    while (y > 0) {
        x = x + 1;
        y = y - 1;
    }
}\] (x = x0 + y0)
```

Checking the invariant

Is x + y = x0 + y0 a good invariant?

Example (Addition: x,y program variables, x0,y0 rigid constants)

```
x = x0 & y = y0 & y0 >= 0 & wellFormed(heap) ==>
\[{
    while (y > 0) {
        x = x + 1;
        y = y - 1;
    }
}\] (x = x0 + y0)
```

Checking the invariant

Is x + y = x0 + y0 a good invariant?

▶ Holds in the beginning and is preserved by loop

Example (Addition: x,y program variables, x0,y0 rigid constants)

```
x = x0 & y = y0 & y0 >= 0 & wellFormed(heap) ==>
\[{
    while (y > 0) {
        x = x + 1;
        y = y - 1;
    }
}\] (x = x0 + y0)
```

Checking the invariant

Is x + y = x0 + y0 a good invariant?

- ▶ Holds in the beginning and is preserved by loop
- ▶ But postcondition not achieved by x + y = x0 + y0 and exit condition $y \le 0$

Example (Addition: x,y program variables, x0,y0 rigid constants)

```
x = x0 & y = y0 & y0 >= 0 & wellFormed(heap) ==>
\[{
    while (y > 0) {
        x = x + 1;
        y = y - 1;
    }
}\] (x = x0 + y0)
```

Strenghtening the invariant

Postcondition holds if y = 0

▶ Add y >= 0 to invariant: x + y = x0 + y0 & y >= 0

Demo loops/simple3.key

Problems with the Basic Invariant Rule

$$\begin{array}{c} \Gamma \Longrightarrow \mathcal{U} \textit{Inv}, \Delta & \text{(initially valid)} \\ \textit{Inv}, \ b = \texttt{TRUE} \Longrightarrow [\texttt{p}] \textit{Inv} & \text{(preserved)} \\ \\ \textit{loopInvariant} & \frac{\textit{Inv}, \ b = \texttt{FALSE} \Longrightarrow [\pi \ \omega] \phi}{\Gamma \Longrightarrow \mathcal{U}[\pi \, \texttt{while} \, (\texttt{b}) \, \texttt{p} \ \omega] \phi, \Delta} & \text{(use case)} \\ \end{array}$$

Problems with the Basic Invariant Rule

$$\begin{array}{c} \Gamma \Rightarrow \mathcal{U} \textit{Inv}, \Delta & \text{(initially valid)} \\ \textit{Inv}, \ b = \texttt{TRUE} \Rightarrow [\texttt{p}] \textit{Inv} & \text{(preserved)} \\ \\ \textit{loopInvariant} & \frac{\textit{Inv}, \ b = \texttt{FALSE} \Rightarrow [\pi \ \omega] \phi}{\Gamma \Rightarrow \mathcal{U}[\pi \, \texttt{while} \, (\texttt{b}) \, \texttt{p} \, \omega] \phi, \Delta} & \text{(use case)} \end{array}$$

Context Γ, Δ, U must be omitted in 2nd and 3rd premise:
 Γ,¬Δ cannot be assumed for arbitrary iterations or at loop exit
 2nd premise State after some loop iterations is not U
 3rd premise State at loop exit is not U

Problems with the Basic Invariant Rule

$$\begin{array}{c} \Gamma \Rightarrow \mathcal{U} \textit{Inv}, \Delta & \text{(initially valid)} \\ \textit{Inv}, \ b = \texttt{TRUE} \Rightarrow [\texttt{p}] \textit{Inv} & \text{(preserved)} \\ \\ \textit{IoopInvariant} & \frac{\textit{Inv}, \ b = \texttt{FALSE} \Rightarrow [\pi \ \omega] \phi}{\Gamma \Rightarrow \mathcal{U}[\pi \, \texttt{while} \, (\texttt{b}) \, \texttt{p} \ \omega] \phi, \Delta} & \text{(use case)} \\ \end{array}$$

- Context Γ, Δ, U must be omitted in 2nd and 3rd premise:
 Γ,¬Δ cannot be assumed for arbitrary iterations or at loop exit
 2nd premise State after some loop iterations is not U
 3rd premise State at loop exit is not U
- ► Context contains preconditions and class invariants

Problems with the Basic Invariant Rule

$$\begin{array}{c} \Gamma \Rightarrow \mathcal{U} \textit{Inv}, \Delta & \text{(initially valid)} \\ \textit{Inv}, \ b = \texttt{TRUE} \Rightarrow [\texttt{p}] \textit{Inv} & \text{(preserved)} \\ \\ \textit{loopInvariant} & \frac{\textit{Inv}, \ b = \texttt{FALSE} \Rightarrow [\pi \ \omega] \phi}{\Gamma \Rightarrow \mathcal{U}[\pi \, \texttt{while} \, (\texttt{b}) \, \texttt{p} \, \omega] \phi, \Delta} & \text{(use case)} \end{array}$$

- Context Γ, Δ, U must be omitted in 2nd and 3rd premise:
 Γ,¬Δ cannot be assumed for arbitrary iterations or at loop exit
 2nd premise State after some loop iterations is not U
 3rd premise State at loop exit is not U
- Context contains preconditions and class invariants
- ▶ Only way to propagate context: add to loop invariant *Inv*

```
int i = 0;
while(i < a.length) {
    a[i] = 1;
    i++;
}</pre>
```

Precondition: $a \neq null$

```
int i = 0;
while(i < a.length) {
    a[i] = 1;
    i++;
}</pre>
```

Precondition: $a \neq null$

```
int i = 0;
while(i < a.length) {
    a[i] = 1;
    i++;
}</pre>
```

Precondition: $a \neq null$

```
int i = 0;
while(i < a.length) {
    a[i] = 1;
    i++;
}</pre>
```

Postcondition: $\forall int x$; $(0 \le x \& x < a.length \rightarrow a[x] = 1)$

Loop invariant: $0 \le i \& i \le a.length$

Precondition: $a \neq null$

```
int i = 0;
while(i < a.length) {
    a[i] = 1;
    i++;
}</pre>
```

Postcondition: $\forall int x$; $(0 \le x \& x < a.length \rightarrow a[x] = 1)$

Loop invariant: $0 \le i \& i \le a.length$

```
Precondition: a \neq null
```

```
int i = 0;
while(i < a.length) {
    a[i] = 1;
    i++;
}</pre>
```

Loop invariant:
$$0 \le i \& i \le a.length$$
 & $\forall int x$; $(0 \le x \& x < i \rightarrow a[x] = 1)$

```
Precondition: a ≠ null

int i = 0;
while(i < a.length) {
    a[i] = 1;
    i++;
}</pre>
```

```
Loop invariant: 0 \le i \& i \le a.length \& \forall int x; (0 \le x \& x < i \to a[x] = 1) \& a \ne null
```

```
Precondition: a \neq null \& ClassInv
```

```
int i = 0;
while(i < a.length) {
    a[i] = 1;
    i++;
}</pre>
```

```
Loop invariant: 0 \le i & i \le a.length & \forall int x; (0 \le x \& x < i \rightarrow a[x] = 1) & a \ne null & ClassInv
```

► Want to keep part of the context that is not modified by loop

- ▶ Want to keep part of the context that is not modified by loop
- ▶ assignable clauses for loops tell what can possibly be modified

```
@ assignable i, a[*];
```

- ▶ Want to keep part of the context that is not modified by loop
- ▶ assignable clauses for loops tell what can possibly be modified

```
@ assignable i, a[*];
```

► How to erase all values of **assignable** locations?

- ▶ Want to keep part of the context that is not modified by loop
- ▶ assignable clauses for loops tell what can possibly be modified

```
@ assignable i, a[*];
```

- How to erase all values of assignable locations?
- ightharpoonup Anonymising updates ${\cal V}$ erase information about modified locations

Anonymising Java Locations

```
@ assignable i, a[*];
```

To erase all knowledge about these assignable lactions:

- ▶ introduce a new (not yet used) constant of type int, e.g., c
- ▶ introduce a new (not yet used) constant of type Heap, e.g., h_{an}
 - ▶ anonymise the current heap: $anon(heap, allFields(a), h_{an})$
- compute anonymizing update for assignable locations

$$\mathcal{V} = \{\mathtt{i} := \mathtt{c} \mid\mid \mathtt{heap} := \mathtt{anon}(\mathtt{heap}, \mathtt{allFields}(\mathtt{a}), \mathtt{h}_{\mathit{an}})\}$$

Anonymising Java Locations

To erase all knowledge about these assignable lactions:

- ▶ introduce a new (not yet used) constant of type int, e.g., c
- \blacktriangleright introduce a new (not yet used) constant of type Heap, e.g., h_{an}
 - \blacktriangleright anonymise the current heap: anon(heap, allFields(a), h_{an})
- compute anonymizing update for assignable locations

$$\mathcal{V} = \{\mathtt{i} := \mathtt{c} \mid\mid \mathtt{heap} := \mathtt{anon}(\mathtt{heap}, \mathtt{allFields}(\mathtt{a}), \mathtt{h}_{\mathit{an}})\}$$

For local program variables (e.g., i) KeY computes assignable clause automatically

$$\Gamma \Longrightarrow \mathcal{U}[\pi \text{ while (b) p } \omega]\phi, \Delta$$

Improved Invariant Rule

$$\Gamma \Longrightarrow \mathcal{U}$$
Inv, Δ

(initially valid)

$$\Gamma \Longrightarrow \mathcal{U}[\pi \, \mathtt{while} \, (\mathtt{b}) \, \, \mathtt{p} \, \, \omega] \phi, \Delta$$

$$\Gamma \Rightarrow \mathcal{U} \underset{\mathsf{Inv}}{\mathsf{Inv}}, \Delta \qquad \qquad \text{(initially valid)}$$

$$\Gamma \Rightarrow \mathcal{U} \underset{\mathsf{V}}{\mathsf{V}} \underset{\mathsf{Inv}}{\mathsf{Inv}} \& \ b = \mathtt{TRUE} \rightarrow [\mathtt{p}] \underset{\mathsf{Inv}}{\mathsf{Inv}}, \Delta \qquad \text{(preserved)}$$

$$\Gamma \Rightarrow \mathcal{U} \underset{\mathsf{Inv}}{\mathsf{Inv}} \underset{\mathsf{While}(\mathtt{b})}{\mathsf{p}} \underset{\omega]\phi, \Delta}{\mathsf{p}} \underset{\mathsf{Inv}}{\mathsf{Inv}} \underset{\mathsf{Inv}}{\mathsf{In$$

$$\Gamma \Rightarrow \mathcal{U} | \mathbf{nv}, \Delta \qquad \text{(initially valid)}$$

$$\Gamma \Rightarrow \mathcal{U} \mathcal{V} (\mathbf{nv} \& b = \text{TRUE} \rightarrow [\mathbf{p}] \mathbf{nv}), \Delta \qquad \text{(preserved)}$$

$$\Gamma \Rightarrow \mathcal{U} \mathcal{V} (\mathbf{nv} \& b = \text{FALSE} \rightarrow [\pi \ \omega] \phi), \Delta \qquad \text{(use case)}$$

$$\Gamma \Rightarrow \mathcal{U} [\pi \text{ while (b) } \mathbf{p} \ \omega] \phi, \Delta$$

$$\Gamma \Rightarrow \mathcal{U} \underset{\text{Inv}}{\textit{Inv}}, \Delta \qquad \text{(initially valid)}$$

$$\Gamma \Rightarrow \mathcal{U} \underset{\text{V}}{\textit{V}} \underset{\text{Inv}}{\textit{(Inv}} \& b = \text{TRUE} \rightarrow [p] \underset{\text{Inv}}{\textit{Inv}}), \Delta \qquad \text{(preserved)}$$

$$\Gamma \Rightarrow \mathcal{U} \underset{\text{V}}{\textit{V}} \underset{\text{Inv}}{\textit{(Inv}} \& b = \text{FALSE} \rightarrow [\pi \ \omega] \phi, \Delta \qquad \text{(use case)}$$

$$\Gamma \Rightarrow \mathcal{U} \underset{\text{T}}{\textit{mhile}} \underset{\text{(b)}}{\textit{(b)}} p \ \omega \underset{\text{(b)}}{\textit{(b)}} \phi, \Delta$$

- Context is kept as far as possible:
 V erases only information in locations assignable in the loop
- ▶ Invariant *Inv* does not need to include unmodified locations
- ► For assignable \everything (the default):
 - ▶ heap := anon(heap, allLocs, h_{an}) wipes out all heap information
 - Equivalent to basic invariant rule
 - Avoid this! Always give a specific assignable clause

```
int i = 0;
while(i < a.length) {
    a[i] = 1;
    i++;
}</pre>
```

Precondition: $a \neq null$

```
int i = 0;
while(i < a.length) {
    a[i] = 1;
    i++;
}</pre>
```

Precondition: $a \neq null$

```
int i = 0;
while(i < a.length) {
    a[i] = 1;
    i++;
}</pre>
```

Precondition: $a \neq null$

```
int i = 0;
while(i < a.length) {
    a[i] = 1;
    i++;
}</pre>
```

Postcondition: $\forall int x$; $(0 \le x \& x < a.length \rightarrow a[x] = 1)$

Loop invariant: $0 \le i \& i \le a.length$

```
Precondition: a \neq null
```

```
int i = 0;
while(i < a.length) {
    a[i] = 1;
    i++;
}</pre>
```

```
Loop invariant: 0 \le i \& i \le a.length \& \forall int x; (0 \le x \& x < i \rightarrow a[x] = 1)
```

Example with Improved Invariant Rule

Precondition: $a \neq null$

```
int i = 0;
while(i < a.length) {
    a[i] = 1;
    i++;
}</pre>
```

Postcondition: \forall int x; $(0 \le x \& x < a.length \rightarrow a[x] = 1)$

Loop invariant:
$$0 \le i \& i \le a.length \& \forall int x; (0 \le x \& x < i \rightarrow a[x] = 1)$$

Example with Improved Invariant Rule

Precondition: $a \neq null \& ClassInv$

```
int i = 0;
while(i < a.length) {
    a[i] = 1;
    i++;
}</pre>
```

Postcondition: \forall int x; $(0 \le x \& x < a.length \rightarrow a[x] = 1)$

Loop invariant:
$$0 \le i \& i \le a.length \& \forall int x; (0 \le x \& x < i \rightarrow a[x] = 1)$$



```
public int[] a;
/*@ public normal_behavior
    ensures (\forall int x; 0 \le x \& x \le 1 = 1);
  0 diverges true;
  0*/
public void m() {
  int i = 0:
  /*@ loop_invariant
    0 0 <= i && i <= a.length &&
    @ (\forall int x; 0<=x && x<i; a[x]==1);</pre>
    @ assignable a[*];
    0*/
  while(i < a.length) {</pre>
    a[i] = 1;
    i++:
```

```
∀ int x;
(x = n ∧ x >= 0 →
[ i = 0; r = 0;
    while (i < n) { i = i + 1; r = r + i;}
    r = r + r - n;
] (r = x * x)</pre>
```

How can we prove that the above formula is valid (i.e., satisfied in all states)?

```
∀ int x;
(x = n ∧ x >= 0 →
[ i = 0; r = 0;
  while (i < n) { i = i + 1; r = r + i;}
  r=r+r-n;
] (r = x * x)</pre>
```

How can we prove that the above formula is valid (i.e., satisfied in all states)?

Needed Invariant:

```
∀ int x;
(x = n ∧ x >= 0 →
[ i = 0; r = 0;
  while (i < n) { i = i + 1; r = r + i;}
  r = r + r - n;
] (r = x * x)</pre>
```

How can we prove that the above formula is valid (i.e., satisfied in all states)?

Needed Invariant:

- @ loop_invariant
- 0 $i \ge 0$ && $i \le n$ && 2*r == i*(i + 1);
- @ assignable \nothing; // no heap locations changed

```
∀ int x;
(x = n ∧ x >= 0 →
[ i = 0; r = 0;
    while (i < n) { i = i + 1; r = r + i;}
    r = r + r - n;
] (r = x * x)</pre>
```

How can we prove that the above formula is valid (i.e., satisfied in all states)?

Needed Invariant:

- @ loop_invariant
- 0 i>=0 && i <= n && 2*r == i*(i + 1);
- @ assignable \nothing; // no heap locations changed

Demo Loop2.java

Hints

Proving assignable

- Invariant rule above assumes that assignable is correct E.g., possible to prove nonsense with incorrect assignable \nothing;
- Invariant rule of KeY generates proof obligation that ensures correctness of assignable
 This proof obligation is part of 'Body Preserves Invariant' branch

Hints

Proving assignable

- Invariant rule above assumes that assignable is correct
 E.g., possible to prove nonsense with incorrect
 assignable \nothing;
- Invariant rule of KeY generates proof obligation that ensures correctness of assignable
 This proof obligation is part of 'Body Preserves Invariant' branch

Setting in the KeY Prover when proving loops w. given invariant

- ► Loop treatment: Invariant
- Quantifier treatment: No Splits with Progs
- ▶ If program contains *, /: Arithmetic treatment: DefOps
- Is search limit high enough (time out, rule apps.)?
- ► To prove only partial correctness, add diverges true;

Is the sequent

$$\Rightarrow$$
 [i = -1; while (true){}]i = 4711

provable?

Is the sequent

$$\Rightarrow$$
 [i = -1; while (true){}]i = 4711

provable?

Yes, e.g.,

- @ loop_invariant true;
- @ assignable \nothing;

Is the sequent

$$\Rightarrow$$
 [i = -1; while (true){}]i = 4711

provable?

Yes, e.g.,

- @ loop_invariant true;
- @ assignable \nothing;

With this, correctness of non-terminating loop is provable:

- ► Invariant trivially initially valid and preserved:
 - Initial Case and Preserved Case close immediately
- Negated loop condition is false: Use case close immediately

Is the sequent

$$\Rightarrow$$
 [i = -1; while (true){}]i = 4711

provable?

Yes, e.g.,

- @ loop_invariant true;
- @ assignable \nothing;

With this, correctness of non-terminating loop is provable:

- ▶ Invariant trivially initially valid and preserved:
 - Initial Case and Preserved Case close immediately
- Negated loop condition is false: Use case close immediately

But need a method to prove termination of loops

Mapping Loop Execution to Well-Founded Order

```
if (b) \{ body \}_1
while (b) {
  body
                      if (b) { body }_{17}
                      if (b) { body }_{18}
```

Need to find expression getting smaller wrt $\ensuremath{\mathbb{N}}$ in each iteration

Such an expression is called a decreasing term or variant

Find a decreasing integer term *v* (called variant)

Add the following premisses to the invariant rule:

- $\nu \geq 0$ is initially valid
- $v \ge 0$ is preserved by the loop body
- v is strictly decreased by the loop body

Find a decreasing integer term v (called variant)

Add the following premisses to the invariant rule:

- $\triangleright v \ge 0$ is initially valid
- $v \ge 0$ is preserved by the loop body
- v is strictly decreased by the loop body

Proving termination in JML/JAVA

- ▶ Remove diverges true; from contract
- ► Add decreasing v; to loop invariant
- KeY creates suitable invariant rule and PO (with $\langle \ldots \rangle \phi$)

Find a decreasing integer term *v* (called variant)

Add the following premisses to the invariant rule:

- \triangleright $v \ge 0$ is initially valid
- $v \ge 0$ is preserved by the loop body
- v is strictly decreased by the loop body

Proving termination in JML/JAVA

- ► Remove diverges true; from contract
- ► Add decreasing v; to loop invariant
- KeY creates suitable invariant rule and PO (with $\langle \ldots \rangle \phi$)

Example (The array loop)

@ decreasing

Find a decreasing integer term v (called variant)

Add the following premisses to the invariant rule:

- $\nu \geq 0$ is initially valid
- $v \ge 0$ is preserved by the loop body
- v is strictly decreased by the loop body

Proving termination in JML/JAVA

- ▶ Remove diverges true; from contract
- ► Add decreasing v; to loop invariant
- KeY creates suitable invariant rule and PO (with $\langle \ldots \rangle \phi$)

Example (The array loop)

@ decreasing a.length - i;

Find a decreasing integer term v (called variant)

Add the following premisses to the invariant rule:

- $\nu \geq 0$ is initially valid
- $v \ge 0$ is preserved by the loop body
- v is strictly decreased by the loop body

Proving termination in JML/JAVA

- ► Remove diverges true; from contract
- ► Add decreasing v; to loop invariant
- KeY creates suitable invariant rule and PO (with $\langle \ldots \rangle \phi$)

Example (The array loop)

@ decreasing a.length - i;

Files:

- ► LoopT.java
- ► Loop2T.java

Final Example: Computing the GCD(see 16.3.8 [KeYbook])

```
public class Gcd {
 /*@ public normal behavior
   @ requires _small>=0 && _big>=_small;
   @ ensures _big!=0 ==>
   @ (_big % \result == 0 && _small % \result == 0 &&
        (\forall int x; x>0 && _big % x == 0
           && _small % x == 0; \result % x == 0));
   @ assignable \nothing;
  0*/
private static int gcdHelp(int _big, int _small) {
   int big = _big; int small = _small;
  while (small != 0) {
     final int t = big % small;
    big = small;
     small = t:
   return big;
```

```
public class Gcd {
  /*@ public normal_behavior
  @ requires _small>=0 && _big>=_small;
  @ ensures _big!=0 ==>
  @ (_big % \result == 0 && _small % \result == 0 &&
  @ (\forall int x; x>0 && _big % x == 0
  @ && _small % x == 0; \result % x == 0));
  @ assignable \nothing;
  @*/
private static int gcdHelp(int _big, int _small) {...}
```

```
public class Gcd {
 /*@ public normal_behavior
   @ requires _small>=0 && _big>=_small;
   @ ensures _big!=0 ==>
   @ (_big % \result == 0 && _small % \result == 0 &&
       (\forall int x; x>0 \&\& _big % x == 0
         && _{small} % x == 0; \result % x == 0));
   @ assignable \nothing;
   0*/
 private static int gcdHelp(int _big, int _small) {...}
   requires normalization assumptions on method parameters
           (both non-negative and _big ≥ _small)
```

```
public class Gcd {
 /*@ public normal_behavior
   @ requires _small>=0 && _big>=_small;
   @ ensures _big!=0 ==>
   @ (_big % \result == 0 && _small % \result == 0 &&
       (\forall int x; x>0 \&\& _big % x == 0
         && _{small} % x == 0; \result % x == 0));
   @ assignable \nothing;
   0*/
 private static int gcdHelp(int _big, int _small) {...}
   requires normalization assumptions on method parameters
           (both non-negative and _big ≥ _small)
   ensures if _big positive, then
```

```
public class Gcd {
 /*@ public normal_behavior
   @ requires _small>=0 && _big>=_small;
   @ ensures _big!=0 ==>
   @ (_big % \result == 0 && _small % \result == 0 &&
       (\forall int x; x>0 \&\& _big % x == 0
          && _small % x == 0; \result % x == 0));
   @ assignable \nothing;
   0*/
 private static int gcdHelp(int _big, int _small) {...}
   requires normalization assumptions on method parameters
            (both non-negative and _big ≥ _small)
    ensures if _big positive, then
              ▶ the return value \result is a divisor of both arguments
```

```
public class Gcd {
 /*@ public normal_behavior
   @ requires _small>=0 && _big>=_small;
   @ ensures _big!=0 ==>
   @ (_big % \result == 0 && _small % \result == 0 &&
        (\forall int x; x>0 \&\& _big % x == 0
          && _small % x == 0; \result % x == 0));
   @ assignable \nothing;
   0*/
 private static int gcdHelp(int _big, int _small) {...}
   requires normalization assumptions on method parameters
            (both non-negative and _{\text{big}} \ge _{\text{small}})
    ensures if _big positive, then
```

- ▶ the return value \result is a divisor of both arguments
- ▶ all other divisors x of the arguments are also dividers of \result and thus smaller or equal to \result

```
int big = _big; int small = _small;
while (small != 0) {
  final int t = big % small;
  big = small;
  small = t;
}
return big;
```

Which locations are changed (at most)?

```
int big = _big; int small = _small;
   while (small != 0) {
     final int t = big % small;
     big = small;
     small = t;
   }
   return big;
Which locations are changed (at most)?
  @ assignable \nothing; // no heap locations changed
What is the variant?
```

```
int big = _big; int small = _small;
   while (small != 0) {
     final int t = big % small;
     big = small;
     small = t;
   }
   return big;
Which locations are changed (at most)?
  @ assignable \nothing; // no heap locations changed
What is the variant?
  @ decreases small;
```

```
int big = _big; int small = _small;
while (small != 0) {
   final int t = big % small;
   big = small;
   small = t;
}
return big;
```

```
int big = _big; int small = _small;
while (small != 0) {
   final int t = big % small;
   big = small;
   small = t;
}
return big;
```

Loop Invariant

▶ Order between small and big preserved by loop: big>=small

```
int big = _big; int small = _small;
while (small != 0) {
  final int t = big % small;
  big = small;
  small = t;
}
return big;
```

- ▶ Order between small and big preserved by loop: big>=small
- Possible for big to become 0 in a loop iteration?

```
int big = _big; int small = _small;
while (small != 0) {
  final int t = big % small;
  big = small;
  small = t;
}
return big;
```

- Order between small and big preserved by loop: big>=small
- ▶ Possible for big to become 0 in a loop iteration? No.

```
int big = _big; int small = _small;
while (small != 0) {
  final int t = big % small;
  big = small;
  small = t;
}
return big;
```

- Order between small and big preserved by loop: big>=small
- Adding big>0 to loop invariant?

```
int big = _big; int small = _small;
while (small != 0) {
   final int t = big % small;
   big = small;
   small = t;
}
return big;
```

- ▶ Order between small and big preserved by loop: big>=small
- ► Adding big>0 to loop invariant? No. Not initially valid.

```
int big = _big; int small = _small;
while (small != 0) {
  final int t = big % small;
  big = small;
  small = t;
}
return big;
```

- Order between small and big preserved by loop: big>=small
- Weaker condition necessary: big==0 ==> _big==0

```
int big = _big; int small = _small;
while (small != 0) {
  final int t = big % small;
  big = small;
  small = t;
}
return big;
```

- Order between small and big preserved by loop: big>=small
- Weaker condition necessary: big==0 ==> _big==0
- What does the loop preserve?

Computing the GCD: Specify the Loop Body Cont'd

```
int big = _big; int small = _small;
while (small != 0) {
  final int t = big % small;
  big = small;
  small = t;
}
return big;
```

Loop Invariant

- ▶ Order between small and big preserved by loop: big>=small
- Weaker condition necessary: big==0 ==> _big==0
- ► What does the loop preserve? The set of dividers!

 All common dividers of _big, _small are also dividers of big, small

Computing the GCD: Specify the Loop Body Cont'd

```
int big = _big; int small = _small;
while (small != 0) {
   final int t = big % small;
   big = small;
   small = t;
}
return big;
```

Loop Invariant

- Order between small and big preserved by loop: big>=small
- ► Weaker condition necessary: big==0 ==> _big==0
- What does the loop preserve? The set of dividers!

All common dividers of _big, _small are also dividers of big, small

Computing the GCD: Final Specification

```
int big = _big; int small = _small;
/*@ loop_invariant small >= 0 && big >= small &&
 @
      (big == 0 ==> _big == 0) \&\&
      (\forall int x; x > 0; (_big % x == 0 && _small % x == 0)
 0
                              <==>
 0
                              (big % x == 0 && small <math>% x == 0);
 @ decreases small:
 @ assignable \nothing;
 0*/
 while (small != 0) {
    final int t = big % small;
   big = small;
    small = t:
 return big; // assigned to \result
```

Computing the GCD: Final Specification

```
int big = _big; int small = _small;
/*@ loop_invariant small >= 0 && big >= small &&
      (big == 0 ==> _big == 0) &&
 @
      (\forall int x; x > 0; (_big % x == 0 && _small % x == 0)
 0
                              <==>
 0
                              (big % x == 0 && small <math>% x == 0);
 @ decreases small:
 @ assignable \nothing;
 0*/
 while (small != 0) {
    final int t = big % small;
   big = small;
    small = t:
 return big; // assigned to \result
```

Why does big divides _small and _big follow from the loop invariant?

Computing the GCD: Final Specification

```
int big = _big; int small = _small;
/*@ loop_invariant small >= 0 && big >= small &&
      (big == 0 ==> _big == 0) &&
 @
      (\forall int x; x > 0; (_big % x == 0 && _small % x == 0)
 0
                              <==>
 0
                              (big % x == 0 && small <math>% x == 0);
 @ decreases small:
 @ assignable \nothing;
 0*/
 while (small != 0) {
    final int t = big % small;
   big = small;
    small = t;
 return big; // assigned to \result
```

Why does big divides _small and _big follow from the loop invariant? If big is positive, one can instantiate x with it, and use small == 0

Computing the GCD: Demo

Demo loops/Gcd.java

- 1. Show Gcd. java and gcd(a,b)
- 2. Ensure that "DefOps" and "Contract" is selected, $\geq 10,000$ steps
- 3. Proof contract of gcd(), using contract of gcdHelp()
- 4. Note KeY check sign in parentheses:
 - **4.1** Click "Proof Management"
 - 4.2 Choose tab "By Proof"
 - **4.3** Select proof of gcd()
 - **4.4** Select used method contract of gcdHelp()
 - 4.5 Click "Start Proof"
- 5. After finishing proof obligations of gcdHelp() parentheses are gone

Some Hints On Finding Invariants

General Advice

- ▶ Invariants must be developed, they don't come out of thin air!
- ▶ Be as systematic in deriving invariants as when debugging a program

- Good starting point: desired postcondition (of the loop!)
 - What, in addition to negated loop guard, is needed for it to hold?

- Good starting point: desired postcondition (of the loop!)
 - ▶ What, in addition to negated loop guard, is needed for it to hold?
- ▶ If the invariant candidate is not preserved by the loop body:
 - Can you add stuff from the precondition?
 - Does it need strengthening?
 - ▶ Try to express the relation between partial and final result

- Good starting point: desired postcondition (of the loop!)
 - What, in addition to negated loop guard, is needed for it to hold?
- ▶ If the invariant candidate is not preserved by the loop body:
 - Can you add stuff from the precondition?
 - Does it need strengthening?
 - Try to express the relation between partial and final result
- ► Simulate a few loop body executions to discover invariant patterns

- Good starting point: desired postcondition (of the loop!)
 - What, in addition to negated loop guard, is needed for it to hold?
- ▶ If the invariant candidate is not preserved by the loop body:
 - Can you add stuff from the precondition?
 - Does it need strengthening?
 - ▶ Try to express the relation between partial and final result
- Simulate a few loop body executions to discover invariant patterns
- If the invariant is not initially valid:
 - Can it be weakened such that the postcondition still follows?
 - Did you forget an assumption in the requires clause?

- Good starting point: desired postcondition (of the loop!)
 - What, in addition to negated loop guard, is needed for it to hold?
- ▶ If the invariant candidate is not preserved by the loop body:
 - Can you add stuff from the precondition?
 - Does it need strengthening?
 - ▶ Try to express the relation between partial and final result
- Simulate a few loop body executions to discover invariant patterns
- If the invariant is not initially valid:
 - Can it be weakened such that the postcondition still follows?
 - Did you forget an assumption in the requires clause?
- Several "rounds" of weakening/strengthening might be required

Technical Hints

- Good starting point: desired postcondition (of the loop!)
 - What, in addition to negated loop guard, is needed for it to hold?
- ▶ If the invariant candidate is **not preserved** by the loop body:
 - Can you add stuff from the precondition?
 - Does it need strengthening?
 - ▶ Try to express the relation between partial and final result
- Simulate a few loop body executions to discover invariant patterns
- If the invariant is not initially valid:
 - Can it be weakened such that the postcondition still follows?
 - Did you forget an assumption in the requires clause?
- Several "rounds" of weakening/strengthening might be required
- Use the KeY tool to iteratively try invariants:
 - Loop treatment: None
 - lacktriangle apply Loop Invariant o Enter Loop Specification
 - After each change of invariant make sure all cases are ok
 - ► If not, prue and retry

FMSD: Reasoning about Loops & Methods

Understanding Unclosed Proofs (see also p.528ff [KeYbook])

Reasons why a proof may not close

- Buggy or incomplete specification
- ▶ Bug in program
- ► Maximal number of steps reached: restart or increase # of steps
- ▶ Automatic proof search fails: manual rule applications necessary

Understanding Unclosed Proofs (see also p.528ff [KeYbook])

Reasons why a proof may not close

- Buggy or incomplete specification
- ▶ Bug in program
- ► Maximal number of steps reached: restart or increase # of steps
- ▶ Automatic proof search fails: manual rule applications necessary

Understanding open proof goals

- ▶ Follow the control flow from the proof root to the open goal
- ▶ Branch labels give useful hints
- ▶ Identify unprovable part of post condition or invariant
- ► Sequent remains always in "pre-state"

 Constraints on program variables refer to value at start of program

 (exception: formula is behind update or modality)
- ▶ NB: $\Gamma \Longrightarrow o = null, \Delta$ is equivalent to $\Gamma, o \neq null \Longrightarrow \Delta$

Literature for this Lecture

KeYbook W. Ahrendt, B. Beckert, R. Bubel, R. Hähnle, P. Schmitt, M. Ulbrich, editors.
Deductive Software Verification - The KeY Book Vol 10001 of LNCS, Springer, 2016
(E-book at link.springer.com)

- W. Ahrendt, S. Grebing, Using the KeY Prover
 Chapter 15 in [KeYbook], p.528ff + Section 15.3 (also for Lab2)
- B. Beckert, R. Hähnle, M. Hentschel, P.H. Schmitt,
 Formal Verification with KeY: A Tutorial
 Chapter 16 in [KeYbook], except Section 16.6

further reading:

 B. Beckert, V. Klebanov, B. Weiß, Dynamic Logic for Java Chapter 3 in [KeYbook], Section 3.7

Master's Thesis Projects in Formal Methods

Examples:

- Extracting tests from runtime traces
- ▶ JM²L: a library of specification models for Java
- ► Tests from failed proofs
- Dynamic invariants for runtime verification
- Runtime verification of reactive systems
- Compositional runtime enforcement of reactive systems
- Learning automata (properties) from example traces
- Application of runtime monitoring for automotive systems
- Malware on Chrome: Modifying Secure Preferences
- Browser Extensions Metadata Correlation
- ▶ Chromium Modification to Parallelise Browser Extensions
- ▶ Various master theses on Blockchain, Bitcoin, and Smart Contracts

Master's Thesis Projects in Formal Methods

see Formal Methods Master Theses on the web (cklick here). (and come back, many edits on that page these days)