# Formal Methods for Software Development Reasoning about Programs with Dynamic Logic 

Wolfgang Ahrendt

10 October 2017

## Dynamic Logic

## (Java) Dynamic Logic

Typed FOL

-     + (JAVA) programs p
-     + modalities $\langle\mathrm{p}\rangle \phi,[\mathrm{p}] \phi$ ( p program, $\phi \mathrm{DL}$ formula)
-     + ... (later)


## Dynamic Logic

## (Java) Dynamic Logic

Typed FOL

-     + (JAVA) programs p
-+ modalities $\langle\mathrm{p}\rangle \phi,[\mathrm{p}] \phi$ (p program, $\phi$ DL formula)
- $+\ldots$ (later)


## Remark on Hoare Logic and DL

In Hoare logic $\{\mathrm{Pre}\} \mathrm{p}\{$ Post $\}$
(Pre, Post must be FOL)

## Dynamic Logic

## (Java) Dynamic Logic

Typed FOL

-     + (JAVA) programs p
-+ modalities $\langle\mathrm{p}\rangle \phi,[\mathrm{p}] \phi$ (p program, $\phi$ DL formula)
-     + ... (later)


## Remark on Hoare Logic and DL

In Hoare logic $\{\mathrm{Pre}\} \mathrm{p}\{$ Post $\}$
In DL Pre $\rightarrow$ [p]Post
(Pre, Post must be FOL)
(Pre, Post any DL formula)

## Proving DL Formulas

An Example
$\forall$ int $x$;

$$
\begin{aligned}
& (x=\mathrm{n} \wedge x>=0 \rightarrow \\
& \quad[\mathrm{i}=0 ; \mathrm{r}=0 ; \\
& \quad \mathrm{while}(\mathrm{i}<\mathrm{n})\{\mathrm{i}=\mathrm{i}+1 ; \mathrm{r}=\mathrm{r}+\mathrm{i} ;\} \\
& \mathrm{r}=\mathrm{r}+\mathrm{r}-\mathrm{n} ; \\
& \quad] \mathrm{r}=x * x)
\end{aligned}
$$

How can we prove that the above formula is valid (i.e. satisfied in all states)?

## Semantics of DL Sequents

$\Gamma=\left\{\phi_{1}, \ldots, \phi_{n}\right\}$ and $\Delta=\left\{\psi_{1}, \ldots, \psi_{m}\right\}$ sets of DL formulas where all logical variables occur bound.

Recall: $\mathcal{S} \vDash(\Gamma \Longrightarrow \Delta) \quad$ iff $\quad \mathcal{S} \models\left(\phi_{1} \wedge \cdots \wedge \phi_{n}\right) \rightarrow\left(\psi_{1} \vee \cdots \vee \psi_{m}\right)$
Define semantics of DL sequents identical to semantics of FOL sequents

Definition (Validity of Sequents over DL Formulas)
A sequent $\Gamma \Longrightarrow \Delta$ over $D L$ formulas is valid iff

$$
\mathcal{S} \models(\Gamma \Longrightarrow \Delta) \text { in all states } \mathcal{S}
$$

## Semantics of DL Sequents

$\Gamma=\left\{\phi_{1}, \ldots, \phi_{n}\right\}$ and $\Delta=\left\{\psi_{1}, \ldots, \psi_{m}\right\}$ sets of DL formulas where all logical variables occur bound.

Recall: $\mathcal{S} \models(\Gamma \Longrightarrow \Delta) \quad$ iff $\quad \mathcal{S} \models\left(\phi_{1} \wedge \cdots \wedge \phi_{n}\right) \rightarrow\left(\psi_{1} \vee \cdots \vee \psi_{m}\right)$
Define semantics of DL sequents identical to semantics of FOL sequents

Definition (Validity of Sequents over DL Formulas)
A sequent $\Gamma \Longrightarrow \Delta$ over DL formulas is valid iff

$$
\mathcal{S} \models(\Gamma \Longrightarrow \Delta) \text { in all states } \mathcal{S}
$$

Consequence for program variables
Initial value of program variables implicitly "universally quantified"

## Symbolic Execution of Programs

Sequent calculus decomposes top-level operator in formula. What is "top-level" in a sequential program p; q; r; ?

## Symbolic Execution

- Follow the natural control flow when analysing a program
- Values of some variables unknown: symbolic state representation


## Symbolic Execution of Programs

Sequent calculus decomposes top-level operator in formula. What is "top-level" in a sequential program p; q; r; ?

## Symbolic Execution

- Follow the natural control flow when analysing a program
- Values of some variables unknown: symbolic state representation


## Example

Compute the final state after termination of

$$
x=x+y ; y=x-y ; x=x-y ;
$$

## Symbolic Execution of Programs Cont'd

Typical form of DL formulas in symbolic execution

$$
\langle\text { stmt; rest }\rangle \phi \quad[\text { stmt } ; \text { rest }] \phi
$$

- Rules symbolically execute first statement ("active statement")
- Repeated application of such rules corresponds to symbolic program execution


## Symbolic Execution of Programs Cont'd

Typical form of DL formulas in symbolic execution

$$
\langle\text { stmt; rest }\rangle \phi \quad[\text { stmt } ; \text { rest }] \phi
$$

- Rules symbolically execute first statement ("active statement")
- Repeated application of such rules corresponds to symbolic program execution

```
Example (symbolicExecution/simpleIf.key,
    Demo , active statement only)
\programVariables {
    int x; int y; boolean b;
}
\problem {
    \<{ if (b) { x = 1; } else { x = 2; } y = 3; }\> y > x
}
```


## Symbolic Execution of Programs Cont'd

Symbolic execution of conditional

$$
\text { if } \frac{\Gamma, \mathrm{b}=\mathrm{TRUE} \Rightarrow\langle\mathrm{p} ; \text { rest }\rangle \phi, \Delta \quad \Gamma, \mathrm{b}=\mathrm{FALSE} \Rightarrow\langle\mathrm{q} ; \text { rest }\rangle \phi, \Delta}{\Gamma \Rightarrow\langle\text { if (b) }\{\mathrm{p}\} \text { else }\{\mathrm{q}\} ; \text { rest }\rangle \phi, \Delta}
$$

Symbolic execution must consider all possible execution branches

## Symbolic Execution of Programs Cont'd

Symbolic execution of conditional

$$
\text { if } \frac{\Gamma, \mathrm{b}=\mathrm{TRUE} \Rightarrow\langle\mathrm{p} ; \text { rest }\rangle \phi, \Delta \quad \Gamma, \mathrm{b}=\text { FALSE } \Rightarrow\langle\mathrm{q} ; \text { rest }\rangle \phi, \Delta}{\Gamma \Longrightarrow\langle\text { if (b) }\{\mathrm{p}\} \text { else }\{\mathrm{q}\} ; \text { rest }\rangle \phi, \Delta}
$$

Symbolic execution must consider all possible execution branches

Symbolic execution of loops: unwind

$$
\text { unwindLoop } \frac{\Gamma \Longrightarrow\langle\text { if (b) }\{\mathrm{p} ; \text { while (b) p \}; rest }\rangle \phi, \Delta}{\Gamma \Longrightarrow\langle\text { while (b) }\{\mathrm{p}\} ; \text { rest }\rangle \phi, \Delta}
$$

## Updates for KeY-Style Symbolic Execution

## Needed: a Notation for Symbolic State Changes

- Symbolic execution should "walk" through program in natural forward direction
- Need succint representation of state changes, effected by each symbolic execution step
- Want to simplify effects of program execution early
- Want to apply state changes late (to branching conditions and post condition)


## Updates for KeY-Style Symbolic Execution

## Needed: a Notation for Symbolic State Changes

- Symbolic execution should "walk" through program in natural forward direction
- Need succint representation of state changes, effected by each symbolic execution step
- Want to simplify effects of program execution early
- Want to apply state changes late (to branching conditions and post condition)

> We use dedicated notation for state changes: updates

## Explicit State Updates

## Definition (Syntax of Updates, Updated Terms/Formulas)

If v is program variable, $t$ FOL term type-conformant to v ,
$t^{\prime}$ any FOL term, and $\phi$ any DL formula, then

- $\{\mathrm{v}:=t\}$ is an update
- $\{\mathrm{v}:=t\} t^{\prime}$ is DL term
- $\{\mathrm{v}:=t\} \phi$ is DL formula


## Definition (Semantics of Updates)

State $\mathcal{S}$ interprets program variables $v$ with $\mathcal{I}_{\mathcal{S}}(v)$
$\beta$ variable assignment for logical variables in $t$, define semantics $\rho$ as:
$\rho_{\beta}(\{\mathrm{v}:=t\})(\mathcal{S})=\mathcal{S}^{\prime}$ where $\mathcal{S}^{\prime}$ identical to $\mathcal{S}$ except $\mathcal{I}_{\mathcal{S}^{\prime}}(\mathrm{v})=$ val $\mathcal{S}_{\mathcal{S}, \beta}(t)$

## Explicit State Updates Cont'd

Facts about updates $\{\mathrm{v}:=t\}$

- Update semantics similar to that of assignment
- Value of update also depends on $\mathcal{S}$ and logical variables in $t$, i.e., $\beta$
- Updates are not assignments: right-hand side is FOL term
$\{\mathrm{x}:=n\} \phi$ cannot be turned into assignment ( $n$ logical variable)
$\langle\mathrm{x}=\mathrm{i}++;\rangle \phi$ cannot (immediately) be turned into update
- Updates are not equations: they change value of $v$


## Computing Effect of Updates (Automated)

Rewrite rules for update followed by ...
program variable $\left\{\begin{array}{lll}\{\mathrm{x}:=t\} \mathrm{x} & \rightsquigarrow & t \\ \{\mathrm{x}:=t\} \mathrm{y} & \rightsquigarrow & \mathrm{y}\end{array}\right.$
logical variable $\{\mathrm{x}:=t\} w \rightsquigarrow w$ complex term $\{\mathrm{x}:=t\} f\left(t_{1}, \ldots, t_{n}\right) \rightsquigarrow f\left(\{\mathrm{x}:=t\} t_{1}, \ldots,\{\mathrm{x}:=t\} t_{n}\right)$
(because $f$ is rigid)
atomic formula $\{\mathrm{x}:=t\} p\left(t_{1}, \ldots, t_{n}\right) \rightsquigarrow p\left(\{\mathrm{x}:=t\} t_{1}, \ldots,\{\mathrm{x}:=t\} t_{n}\right)$

$$
\text { FOL formula }\left\{\begin{aligned}
&\{\mathrm{x}:=t\}(\phi \& \psi) \rightsquigarrow\{\mathrm{x}:=t\} \phi \&\{\mathrm{x}:=t\} \psi \\
& \ldots \\
&\{\mathrm{x}:=t\}(\forall \tau y ; \phi) \rightsquigarrow \forall \tau y ;(\{\mathrm{x}:=t\} \phi)
\end{aligned}\right.
$$

## program formula No rewrite rule for $\{\mathrm{x}:=t\}(\langle\mathrm{p}\rangle \phi)$

unchanged!

Update rewriting delayed until p symbolically executed

## Assignment Rule Using Updates

Symbolic execution of assignment using updates

$$
\operatorname{assign} \frac{\Gamma \Longrightarrow\{\mathrm{x}:=t\}\langle\text { rest }\rangle \phi, \Delta}{\Gamma \Longrightarrow\langle\mathrm{x}=\mathrm{t} ; \text { rest }\rangle \phi, \Delta}
$$

- Simple! No variable renaming, etc.
- Works as long as $t$ is 'simple' (has no side effects)

Demo
updates/assignmentToUpdate.key

## Parallel Updates

## How to apply updates on updates?

## Example

Symbolic execution of

$$
\mathrm{t}=\mathrm{x} ; \mathrm{x}=\mathrm{y} ; \quad \mathrm{y}=\mathrm{t} ;
$$

yields:

$$
\{\mathrm{t}:=\mathrm{x}\}\{\mathrm{x}:=\mathrm{y}\}\{\mathrm{y}:=\mathrm{t}\}
$$

Need to compose three sequential state changes into a single one:

## Parallel Updates

## How to apply updates on updates?

## Example

Symbolic execution of

$$
\mathrm{t}=\mathrm{x} ; \mathrm{x}=\mathrm{y} ; \quad \mathrm{y}=\mathrm{t} ;
$$

yields:

$$
\{\mathrm{t}:=\mathrm{x}\}\{\mathrm{x}:=\mathrm{y}\}\{\mathrm{y}:=\mathrm{t}\}
$$

Need to compose three sequential state changes into a single one: parallel updates

## Parallel Updates Cont'd

## Definition (Parallel Update)

A parallel update has the form $\left\{v_{1}:=r_{1}\|\cdots\| v_{n}:=r_{n}\right\}$, where each $\left\{v_{i}:=r_{i}\right\}$ is simple update

- All $r_{i}$ computed in old state before update is applied
- Updates of all program variables $v_{i}$ executed simultaneously
- Upon conflict $v_{i}=v_{j}, r_{i} \neq r_{j} \quad$ later update ( $\max \{i, j\}$ ) wins


## Parallel Updates Cont'd

## Definition (Parallel Update)

A parallel update has the form $\left\{v_{1}:=r_{1}\|\cdots\| v_{n}:=r_{n}\right\}$, where each $\left\{v_{i}:=r_{i}\right\}$ is simple update

- All $r_{i}$ computed in old state before update is applied
- Updates of all program variables $v_{i}$ executed simultaneously
- Upon conflict $v_{i}=v_{j}, r_{i} \neq r_{j} \quad$ later update ( $\max \{i, j\}$ ) wins


## Definition (Parallelising Updates, Conflict Resolution)

$$
\left\{v_{1}:=r_{1}\right\}\left\{v_{2}:=r_{2}\right\}=\left\{v_{1}:=r_{1} \| v_{2}:=\left\{v_{1}:=r_{1}\right\} r_{2}\right\}
$$

## Parallel Updates Cont'd

## Definition (Parallel Update)

A parallel update has the form $\left\{v_{1}:=r_{1}\|\cdots\| v_{n}:=r_{n}\right\}$, where each $\left\{v_{i}:=r_{i}\right\}$ is simple update

- All $r_{i}$ computed in old state before update is applied
- Updates of all program variables $v_{i}$ executed simultaneously
- Upon conflict $v_{i}=v_{j}, r_{i} \neq r_{j} \quad$ later update ( $\max \{i, j\}$ ) wins


## Definition (Parallelising Updates, Conflict Resolution)

$$
\left\{v_{1}:=r_{1}\right\}\left\{v_{2}:=r_{2}\right\}=\left\{v_{1}:=r_{1} \| v_{2}:=\left\{v_{1}:=r_{1}\right\} r_{2}\right\}
$$

$$
\left\{v_{1}:=r_{1}\|\cdots\| v_{n}:=r_{n}\right\} \mathrm{x}= \begin{cases}\mathrm{x} & \text { if } \mathrm{x} \notin\left\{v_{1}, \ldots, v_{n}\right\} \\ r_{k} & \text { if } \mathrm{x}=v_{k}, \mathrm{x} \notin\left\{v_{k+1}, \ldots, v_{n}\right\}\end{cases}
$$

## Symbolic Execution with Updates (by Example)

$$
\Longrightarrow x<y \rightarrow\langle t=x ; x=y ; y=t ;\rangle y<x
$$

## Symbolic Execution with Updates

## (by Example)

$$
\begin{gathered}
x<y \Longrightarrow\{t:=x\}\langle x=y ; y=t ;\rangle y<x \\
\vdots \\
\Longrightarrow x<y \rightarrow\langle t=x ; x=y ; y=t ;\rangle y<x
\end{gathered}
$$

## Symbolic Execution with Updates

## (by Example)

$$
\begin{gathered}
\mathrm{x}<\mathrm{y} \Longrightarrow\{\mathrm{t}:=\mathrm{x}\}\{\mathrm{x}:=\mathrm{y}\}\langle\mathrm{y}=\mathrm{t} ;\rangle \mathrm{y}<\mathrm{x} \\
\vdots \\
\mathrm{x}<\mathrm{y} \Longrightarrow\{\mathrm{t}:=\mathrm{x}\}\langle\mathrm{x}=\mathrm{y} ; \mathrm{y}=\mathrm{t} ;\rangle \mathrm{y}<\mathrm{x} \\
\vdots \\
\Rightarrow \mathrm{x}<\mathrm{y} \rightarrow\langle\mathrm{t}=\mathrm{x} ; \mathrm{x}=\mathrm{y} ; \mathrm{y}=\mathrm{t} ;\rangle \mathrm{y}<\mathrm{x}
\end{gathered}
$$

## Symbolic Execution with Updates

$$
\begin{gathered}
\mathrm{x}<\mathrm{y} \Longrightarrow\{\mathrm{t}:=\mathrm{x} \| \mathrm{x}:=\mathrm{y}\}\{\mathrm{y}:=\mathrm{t}\}\langle \rangle \mathrm{y}<\mathrm{x} \\
\vdots \\
\mathrm{x}<\mathrm{y} \Longrightarrow\{\mathrm{t}:=\mathrm{x}\}\{\mathrm{x}:=\mathrm{y}\}\langle\mathrm{y}=\mathrm{t} ;\rangle \mathrm{y}<\mathrm{x} \\
\vdots \\
\mathrm{x}<\mathrm{y} \Longrightarrow\{\mathrm{t}:=\mathrm{x}\}\langle\mathrm{x}=\mathrm{y} ; \mathrm{y}=\mathrm{t} ;\rangle \mathrm{y}<\mathrm{x} \\
\vdots \\
\Rightarrow \mathrm{x}<\mathrm{y} \rightarrow\langle\mathrm{t}=\mathrm{x} ; \mathrm{x}=\mathrm{y} ; \mathrm{y}=\mathrm{t} ;\rangle \mathrm{y}<\mathrm{x}
\end{gathered}
$$

## Symbolic Execution with Updates

## (by Example)

$$
\begin{gathered}
\mathrm{x}<\mathrm{y} \Longrightarrow\{\mathrm{t}:=\mathrm{x}\|\mathrm{x}:=\mathrm{y}\| \mathrm{y}:=\mathrm{x}\}\langle \rangle \mathrm{y}<\mathrm{x} \\
\vdots \\
\mathrm{x}<\mathrm{y} \Rightarrow\{\mathrm{t}:=\mathrm{x} \| \mathrm{x}:=\mathrm{y}\}\{\mathrm{y}:=\mathrm{t}\}\langle \rangle \mathrm{y}<\mathrm{x} \\
\vdots \\
\mathrm{x}<\mathrm{y} \Longrightarrow\{\mathrm{t}:=\mathrm{x}\}\{\mathrm{x}:=\mathrm{y}\}\langle\mathrm{y}=\mathrm{t} ;\rangle \mathrm{y}<\mathrm{x} \\
\vdots \\
\mathrm{x}<\mathrm{y} \Longrightarrow\{\mathrm{t}:=\mathrm{x}\}\langle\mathrm{x}=\mathrm{y} ; \mathrm{y}=\mathrm{t} ;\rangle \mathrm{y}<\mathrm{x} \\
\vdots \\
\Rightarrow \mathrm{x}<\mathrm{y} \rightarrow\langle\mathrm{t}=\mathrm{x} ; \mathrm{x}=\mathrm{y} ; \mathrm{y}=\mathrm{t} ;\rangle \mathrm{y}<\mathrm{x}
\end{gathered}
$$

## Symbolic Execution with Updates

## (by Example)

$$
\begin{aligned}
& x<y \Rightarrow\{x:=y \| y:=x\}\langle \rangle y<x \\
& x<y \Rightarrow\{t:=x\|x:=y\| y:=x\}\langle \rangle y<x \\
& \mathrm{x}<\mathrm{y} \Rightarrow\{\mathrm{t}:=\mathrm{x} \| \mathrm{x}:=\mathrm{y}\}\{\mathrm{y}:=\mathrm{t}\}\langle \rangle \mathrm{y}<\mathrm{x} \\
& x<y \Rightarrow\{t:=x\}\{x:=y\}\langle y=t ;\rangle y<x \\
& \mathrm{x}<\mathrm{y} \Rightarrow\{\mathrm{t}:=\mathrm{x}\}\langle\mathrm{x}=\mathrm{y} ; \mathrm{y}=\mathrm{t} ;\rangle \mathrm{y}<\mathrm{x} \\
& \Rightarrow \mathrm{x}<\mathrm{y} \rightarrow\langle\mathrm{t}=\mathrm{x} ; \mathrm{x}=\mathrm{y} ; \mathrm{y}=\mathrm{t} ;\rangle \mathrm{y}<\mathrm{x}
\end{aligned}
$$

## Symbolic Execution with Updates

## (by Example)

$$
\begin{gathered}
\mathrm{x}<\mathrm{y} \Longrightarrow \mathrm{x}<\mathrm{y} \\
\vdots \\
\mathrm{x}<\mathrm{y} \Rightarrow\{\mathrm{x}:=\mathrm{y} \| \mathrm{y}:=\mathrm{x}\}\langle \rangle \mathrm{y}<\mathrm{x} \\
\vdots \\
\mathrm{x}<\mathrm{y} \Rightarrow\{\mathrm{t}:=\mathrm{x}\|\mathrm{x}:=\mathrm{y}\| \mathrm{y}:=\mathrm{x}\}\langle \rangle \mathrm{y}<\mathrm{x} \\
\vdots \\
\mathrm{x}<\mathrm{y} \Longrightarrow\{\mathrm{t}:=\mathrm{x} \| \mathrm{x}:=\mathrm{y}\}\{\mathrm{y}:=\mathrm{t}\}\langle \rangle \mathrm{y}<\mathrm{x} \\
\vdots \\
\mathrm{x}<\mathrm{y} \Longrightarrow\{\mathrm{t}:=\mathrm{x}\}\{\mathrm{x}:=\mathrm{y}\}\langle\mathrm{y}=\mathrm{t} ;\rangle \mathrm{y}<\mathrm{x} \\
\vdots \\
\mathrm{x}<\mathrm{y} \Longrightarrow\{\mathrm{t}:=\mathrm{x}\}\langle\mathrm{x}=\mathrm{y} ; \mathrm{y}=\mathrm{t} ;\rangle \mathrm{y}<\mathrm{x} \\
\vdots \\
\Longrightarrow \mathrm{x}<\mathrm{y} \rightarrow\langle\mathrm{t}=\mathrm{x} ; \mathrm{x}=\mathrm{y} ; \mathrm{y}=\mathrm{t} ;\rangle \mathrm{y}<\mathrm{x}
\end{gathered}
$$

## Parallel Updates Cont'd

Demo
updates/swap1.key

## Parallel Updates Cont'd

## Example

symbolic execution of $x=x+y ; y=x-y ; x=x-y$; gives

$$
(\{x:=x+y\}\{y:=x-y\})\{x:=x-y\}
$$

## Parallel Updates Cont'd

## Example

symbolic execution of $x=x+y ; y=x-y ; x=x-y$; gives

$$
\begin{aligned}
& (\{x:=x+y\}\{y:=x-y\})\{x:=x-y\} \\
& \{x:=x+y| | y:=(x+y)-y\}\{x:=x-y\}
\end{aligned}
$$

## Parallel Updates Cont'd

## Example

symbolic execution of $x=x+y ; y=x-y ; x=x-y$; gives

$$
\begin{aligned}
& (\{x:=x+y\}\{y:=x-y\})\{x:=x-y\} \\
& \{x:=x+y| | y:=(x+y)-y\}\{x:=x-y\} \\
& \{x:=x+y| | y:=(x+y)-y| | x:=(x+y)-((x+y)-y)\}
\end{aligned}
$$

## Parallel Updates Cont'd

## Example

symbolic execution of $x=x+y ; y=x-y ; x=x-y$; gives

$$
\begin{aligned}
& (\{x:=x+y\}\{y:=x-y\})\{x:=x-y\} \\
& \{x:=x+y \text { || } y:=(x+y)-y\}\{x:=x-y\} \\
& \{x:=x+y \text { || }:=(x+y)-y| | x:=(x+y)-((x+y)-y)\} \\
& \{x:=x+y \text { || } y:=x| | x:=y\}
\end{aligned}
$$

## Parallel Updates Cont'd

## Example

symbolic execution of $x=x+y ; y=x-y ; x=x-y$; gives

$$
\begin{aligned}
& (\{x:=x+y\}\{y:=x-y\})\{x:=x-y\} \\
& \{x:=x+y \text { || } y:=(x+y)-y\}\{x:=x-y\} \\
& \{x:=x+y| | y:=(x+y)-y| | x:=(x+y)-((x+y)-y)\} \\
& \{x:=x+y| | y:=x| | x:=y\} \\
& \{y:=x| | x:=y\}
\end{aligned}
$$

KeY automatically deletes overwritten (unnecessary) updates

## Parallel Updates Cont'd

## Example

symbolic execution of $x=x+y ; y=x-y ; x=x-y$; gives

$$
\begin{aligned}
& (\{x:=x+y\}\{y:=x-y\})\{x:=x-y\} \\
& \{x:=x+y \text { || } y:=(x+y)-y\}\{x:=x-y\} \\
& \{x:=x+y \text { || } y:=(x+y)-y| | x:=(x+y)-((x+y)-y)\} \\
& \{x:=x+y| | y:=x| | x:=y\} \\
& \{y:=x| | x:=y\}
\end{aligned}
$$

KeY automatically deletes overwritten (unnecessary) updates

Parallel updates store intermediate state of symbolic computation

## Another use of Updates

If you would like to quantify over a program variable ...

## Another use of Updates

If you would like to quantify over a program variable ...

Not allowed: $\quad \forall \tau$ i; $\langle\ldots$ i.... $\rangle \phi$
(program variables $\cap$ logical variables $=\emptyset$ )

## Another use of Updates

If you would like to quantify over a program variable ...

Not allowed: $\quad \forall \tau$ i; $\langle\ldots$..... $\rangle \phi$
(program variables $\cap$ logical variables $=\emptyset$ )

## Instead

Quantify over value, and assign it to program variable:
$\forall \tau x ;\{i:=x\}\langle\ldots i \ldots\rangle \phi$

## Modelling Java in FOL: Fixing a Type Hierarchy

Signature based on Java's type hierarchy


Each interface and class in API and in target program becomes type with appropriate subtype relation

## Modelling the Heap in FOL

The Java Heap
Objects are stored on (i.e., in) the heap.

- Status of heap changes during execution
- Each heap associates values to object/field pairs


## Modelling the Heap in FOL

The Java Heap
Objects are stored on (i.e., in) the heap.

- Status of heap changes during execution
- Each heap associates values to object/field pairs


## The Heap Model of KeY-DL

Each element of data type Heap represents a certain heap status. Two functions involving heaps:

## Modelling the Heap in FOL

The Java Heap
Objects are stored on (i.e., in) the heap.

- Status of heap changes during execution
- Each heap associates values to object/field pairs


## The Heap Model of KeY-DL

Each element of data type Heap represents a certain heap status.
Two functions involving heaps:

- in $F_{\Sigma}$ : Heap store(Heap, Object, Field, any) ;
store $(h, o, f, v)$ returns heap like $h$, but with $v$ associated to $(o, f)$


## Modelling the Heap in FOL

## The Java Heap

Objects are stored on (i.e., in) the heap.

- Status of heap changes during execution
- Each heap associates values to object/field pairs


## The Heap Model of KeY-DL

Each element of data type Heap represents a certain heap status.
Two functions involving heaps:

- in $F_{\Sigma}$ : Heap store(Heap, Object, Field, any) ; store $(h, o, f, v)$ returns heap like $h$, but with $v$ associated to $(o, f)$
- in $F_{\Sigma}$ : any select (Heap, Object, Field) ;
select ( $h, o, f$ ) returns value associated to $(o, f)$ in $h$


## Modelling the Heap in FOL

Modelling instance fields

| Person |
| :--- |
| int age <br> int id |
| int setAge(int newAge) <br> int getId() |

- for each Java reference type $C$ there is a type $C \in T_{\Sigma}$, for example, Person


## Modelling the Heap in FOL

Modelling instance fields

| Person |
| :--- |
| int age <br> int id |
| int setAge(int newAge) <br> int getId() |

- for each Java reference type $C$ there is a type $C \in T_{\Sigma}$, for example, Person
- for each field $f$ there is a unique constant $f$ of type Field, for example, id


## Modelling the Heap in FOL

Modelling instance fields

| Person |
| :--- |
| int age <br> int id |
| int setAge(int newAge) <br> int getId() |

- for each Java reference type C there is a type $C \in T_{\Sigma}$, for example, Person
- for each field $f$ there is a unique constant $f$ of type Field, for example, id
- domain of all Person objects: $\mathrm{D}^{\text {Person }}$


## Modelling the Heap in FOL

## Modelling instance fields

| Person |
| :--- |
| int age <br> int id |
| int setAge(int newAge) <br> int $\operatorname{getId}()$ |

- for each Java reference type C there is a type $C \in T_{\Sigma}$, for example, Person
- for each field $f$ there is a unique constant $f$ of type Field, for example, id
- domain of all Person objects: $\mathrm{D}^{\text {Person }}$
- a heap relates objects and fields to values


## Modelling the Heap in FOL

## Modelling instance fields

| Person |
| :--- |
| int age <br> int id |
| int setAge(int newAge) <br> int $\operatorname{getId}()$ |

- for each Java reference type $C$ there is a type $C \in T_{\Sigma}$, for example, Person
- for each field $f$ there is a unique constant $f$ of type Field, for example, id
- domain of all Person objects: $D^{\text {Person }}$
- a heap relates objects and fields to values

Reading Field id of Person $p$
FOL notation select( $h, \mathrm{p}, \mathrm{id}$ )

## Modelling the Heap in FOL

## Modelling instance fields

| Person |
| :--- |
| int age <br> int id |
| int setAge(int newAge) <br> int $\operatorname{getId}()$ |

- for each Java reference type $C$ there is a type $C \in T_{\Sigma}$, for example, Person
- for each field $f$ there is a unique constant $f$ of type Field, for example, id
- domain of all Person objects: $\mathrm{D}^{\text {Person }}$
- a heap relates objects and fields to values

Reading Field id of Person $p$
FOL notation select( $h, \mathrm{p}, \mathrm{id}$ )
KeY notation p.id@h (abbreviating select(h, p,id))

## Modelling the Heap in FOL

## Modelling instance fields

| Person |
| :--- |
| int age <br> int id |
| int setAge( int newAge) <br> int $\operatorname{getId}()$ |

- for each Java reference type C there is a type $C \in T_{\Sigma}$, for example, Person
- for each field $f$ there is a unique constant $f$ of type Field, for example, id
- domain of all Person objects: $\mathrm{D}^{\text {Person }}$
- a heap relates objects and fields to values

Reading Field id of Person $p$
FOL notation select( $h, \mathrm{p}, \mathrm{id}$ )
KeY notation p.ideh ( abbreviating select(h, p,id))
p.id ( abbreviating select(heap, p,id) ) a
${ }^{\text {a }}$ heap is special program variable for "current" heap; mostly implicit in o.f

## Modelling the Heap in FOL

Modelling instance fields

| Person |
| :--- |
| int age <br> int id |
| int setAge(int newAge) <br> int getId() |

- for each Java reference type C there is a type $C \in T_{\Sigma}$, for example, Person
- for each field $f$ there is a unique constant $f$ of type Field, for example, id
- domain of all Person objects: $D^{\text {Person }}$
- a heap relates objects and fields to values

Writing to Field id of Person p
FOL notation store( $h, \mathrm{p}, \mathrm{id}, 6238$ )

## Modelling the Heap in FOL

Modelling instance fields

| Person |
| :--- |
| int age <br> int id |
| int setAge(int newAge) <br> int getId() |

- for each Java reference type C there is a type $C \in T_{\Sigma}$, for example, Person
- for each field $f$ there is a unique constant $f$ of type Field, for example, id
- domain of all Person objects: $D^{\text {Person }}$
- a heap relates objects and fields to values

Writing to Field id of Person $p$
FOL notation store(h, p, id, 6238)
KeY notation $h[p . i d:=6238] \quad$ ( notation for store, not update )

## The Algebra of Heaps

We do not formalise the structure (implementation) of heaps. We formalise the behaviour, with an algebra of heap operations:

$$
\operatorname{select}(\operatorname{store}(h, o, f, v), o, f)=
$$

## The Algebra of Heaps

We do not formalise the structure (implementation) of heaps. We formalise the behaviour, with an algebra of heap operations:

$$
\operatorname{select}(\operatorname{store}(h, o, f, v), o, f)=v
$$

## The Algebra of Heaps

We do not formalise the structure (implementation) of heaps. We formalise the behaviour, with an algebra of heap operations:

$$
\begin{array}{r}
\text { select(store }(h, o, f, v), o, f)=v \\
\left(o \neq o^{\prime} \vee f \neq f^{\prime}\right) \rightarrow \operatorname{select}\left(\operatorname{store}(h, o, f, x), o^{\prime}, f^{\prime}\right)=
\end{array}
$$

## The Algebra of Heaps

We do not formalise the structure (implementation) of heaps.
We formalise the behaviour, with an algebra of heap operations:

$$
\begin{gathered}
\operatorname{select}(\operatorname{store}(h, o, f, v), o, f)=v \\
\left(o \neq o^{\prime} \vee f \neq f^{\prime}\right) \rightarrow \operatorname{select}\left(\operatorname{store}(h, o, f, x), o^{\prime}, f^{\prime}\right)=\operatorname{select}\left(h, o^{\prime}, f^{\prime}\right)
\end{gathered}
$$

## The Algebra of Heaps

We do not formalise the structure (implementation) of heaps.
We formalise the behaviour, with an algebra of heap operations:

$$
\begin{gathered}
\operatorname{select}(\operatorname{store}(h, o, f, v), o, f)=v \\
\left(o \neq o^{\prime} \vee f \neq f^{\prime}\right) \rightarrow \operatorname{select}\left(\operatorname{store}(h, o, f, x), o^{\prime}, f^{\prime}\right)=\operatorname{select}\left(h, o^{\prime}, f^{\prime}\right)
\end{gathered}
$$

Example

$$
\begin{aligned}
& \text { select }(\operatorname{store}(h, o, f, 15), o, f) \rightsquigarrow 15 \\
& \text { select }(\operatorname{store}(h, o, f, 15), o, g) \rightsquigarrow \operatorname{select}(h, o, g) \\
& \operatorname{select}(\operatorname{store}(h, o, f, 15), u, f) \rightsquigarrow \\
& \text { if }(o=u) \text { then }(15) \text { else }(\operatorname{select}(h, u, f))
\end{aligned}
$$

## Pretty Printing

## Shorthand Notations for Heap Operations

o.f@h
is $\operatorname{select}(h, o, f)$
$\mathrm{h}[\mathrm{o.f}:=\mathrm{v}$ ]
is store $(h, o, f, v)$

## Pretty Printing

## Shorthand Notations for Heap Operations

o.f@h
is $\operatorname{select}(\mathrm{h}, \mathrm{o}, \mathrm{f})$
$\mathrm{h}[\mathrm{o.f}:=\mathrm{v}$ ]
is store $(h, o, f, v)$
therefore:

$$
\begin{array}{ll}
\text { u.f@h[o.f:=v] } & \text { is } \operatorname{select}(\text { store }(h, o, f, v), u, f) \\
h[o . f:=v]\left[o^{\prime} . f^{\prime}:=v^{\prime}\right] & \text { is } \operatorname{store}\left(\operatorname{store}(h, o, f, v), o^{\prime}, f^{\prime}, v^{\prime}\right)
\end{array}
$$

## Pretty Printing

## Shorthand Notations for Heap Operations

o.f@h
is $\operatorname{select}(h, o, f)$
$\mathrm{h}[\mathrm{o.f}:=\mathrm{v}$ ]
is store $(h, o, f, v)$
therefore:

$$
\begin{array}{ll}
\text { u.f@h[o.f }:=\mathrm{v}] & \text { is } \operatorname{select}(\operatorname{store}(\mathrm{h}, \mathrm{o}, \mathrm{f}, \mathrm{v}), \mathrm{u}, \mathrm{f}) \\
\mathrm{h}[\mathrm{o} . \mathrm{f}:=\mathrm{v}]\left[\mathrm{o}^{\prime} . \mathrm{f}^{\prime}:=\mathrm{v}^{\prime}\right] & \text { is } \operatorname{store}\left(\operatorname{store}(\mathrm{h}, \mathrm{o}, \mathrm{f}, \mathrm{v}), \mathrm{o}^{\prime}, \mathrm{f}^{\prime}, \mathrm{v}^{\prime}\right)
\end{array}
$$

## Very-Shorthand Notations for Current Heap

Current heap always in special variable heap.

$$
\begin{array}{lll}
\text { o.f } & \text { is } & \text { select(heap,o,f) } \\
\{o . f:=v\} & \text { is update } & \{\text { heap }:=\text { heap }[o . f:=x]\}
\end{array}
$$

## Modelling the Heap in FOL-The Full Story

Is formula $\operatorname{select}(h, p, i d)>=0 \quad$ type-safe?

## Modelling the Heap in FOL-The Full Story

Is formula $\operatorname{select}(h, p, i d)>=0 \quad$ type-safe?

1. Return type is any-need to 'cast' to int
2. There can be many fields with name id

## Modelling the Heap in FOL-The Full Story

Is formula $\operatorname{select}(h, p, i d)>=0 \quad$ type-safe?

1. Return type is any-need to 'cast' to int
2. There can be many fields with name id

## Real Field Access

int::select( $h, \mathrm{p}$, Person::\$id) $>=0$ is type-safe

- int::select is a function name, not a cast
- can be understood intuitively as (int)select


## Modelling the Heap in FOL-The Full Story

Is formula $\operatorname{select}(h, p, i d)>=0 \quad$ type-safe?

1. Return type is any-need to 'cast' to int
2. There can be many fields with name id

## Real Field Access

int::select ( $h, \mathrm{p}$, Person::\$id) $>=0$ is type-safe

- int::select is a function name, not a cast
- can be understood intuitively as (int)select


## General

For each $T$ typed field f of class $\mathrm{C}, F_{\Sigma}$ contains

- a constant declared as Field C::\$f
- a function declared as T T::select(Heap, C, Field)


## Modelling the Heap in FOL-The Full Story

Is formula $\operatorname{select}(h, p, i d)>=0 \quad$ type-safe?

1. Return type is any-need to 'cast' to int
2. There can be many fields with name id

## Real Field Access

int::select ( $h, \mathrm{p}$, Person::\$id) $>=0$ is type-safe

- int::select is a function name, not a cast
- can be understood intuitively as (int) select


## General

For each $T$ typed field f of class $\mathrm{C}, F_{\Sigma}$ contains

- a constant declared as Field C::\$f
- a function declared as T T::select(Heap, C, Field)

Everything blue is a function name

## Modelling the Heap in FOL-The Full Story

## Writing to Fields

Declaration: Heap store (Heap, Object, Field, any) ;
Usage: $\quad$ store( $h, \mathrm{p}$, Person::\$id, 42)

## Field Update Assignment Rule

## Changing the value of fields

How to translate assignment to field, for example, p.age=18; ?

$$
\text { assign } \frac{\Gamma \Longrightarrow\{0 . \mathrm{f}:=t\}\langle\text { rest }\rangle \phi, \Delta}{\Gamma \Longrightarrow\langle 0 . \mathrm{f}=\mathrm{t} ; \text { rest }\rangle \phi, \Delta}
$$

Admit on left-hand side of update Java location expressions

## Field Update Assignment Rule

## Changing the value of fields

How to translate assignment to field, for example, p.age=18; ?

$$
\text { assign } \frac{\Gamma \Longrightarrow\{\text { heap }:=\text { store }(\text { heap }, \mathrm{p}, \text { age }, 18)\}\langle\text { rest }\rangle \phi, \Delta}{\Gamma \Longrightarrow\langle\text { p.age }=18 ; \text { rest }\rangle \phi, \Delta}
$$

Admit on left-hand side of update Java location expressions

## Field Update Assignment Rule

## Changing the value of fields

How to translate assignment to field, for example, p.age=18; ?

$$
\text { assign } \frac{\Gamma \Longrightarrow\{\text { p.age }:=18\}\langle\text { rest }\rangle \phi, \Delta}{\Gamma \Longrightarrow\langle\text { p.age }=18 ; \text { rest }\rangle \phi, \Delta}
$$

Admit on left-hand side of update Java location expressions

## Dynamic Logic: KeY input file

```
\javaSource "path to source code referenced in problem";
\programVariables { Person p; }
\problem {
    \<{ p.age = 18; }\> p.age = 18
}
```

KeY reads in all source files and creates automatically the necessary signature (types, program variables, field constants)

## Dynamic Logic: KeY input file

```
\javaSource "path to source code referenced in problem";
```

\programVariables \{ Person p; \}
\problem \{
$\backslash<\{$ p.age $=18 ; \quad\} \backslash>$ p.age $=18$
\}

KeY reads in all source files and creates automatically the necessary signature (types, program variables, field constants)

Demo
updates/firstAttributeExample.key

## Refined Semantics of Program Modalities

Does abrupt termination count as normal termination?
No! Need to distinguish normal and exceptional termination

## Refined Semantics of Program Modalities

Does abrupt termination count as normal termination?
No! Need to distinguish normal and exceptional termination

- $\langle\mathrm{p}\rangle \phi$ : p terminates normally and formula $\phi$ holds in final state (total correctness)


## Refined Semantics of Program Modalities

Does abrupt termination count as normal termination?
No! Need to distinguish normal and exceptional termination

- $\langle\mathrm{p}\rangle \phi$ : p terminates normally and formula $\phi$ holds in final state (total correctness)
- [p] $\phi$ : If p terminates normally then formula $\phi$ holds in final state (partial correctness)


## Refined Semantics of Program Modalities

Does abrupt termination count as normal termination?
No! Need to distinguish normal and exceptional termination

- $\langle\mathrm{p}\rangle \phi$ : p terminates normally and formula $\phi$ holds in final state (total correctness)
- [p] $\phi$ : If p terminates normally then formula $\phi$ holds in final state (partial correctness)

Abrupt termination on top-level counts as non-termination!

## Example Reconsidered: Exception Handling

\javaSource "path to source code";
\programVariables \{
\}
\problem \{

$$
\text { p != null -> \<\{ p.age = 18; \}\> p.age = } 18
$$

\}
Only provable when no top-level exception thrown
Demo
updates/secondAttributeExample.key

## The Self Reference

Modeling reference this to the receiving object
Special name for the object whose Java code is currently executed:
in JML: Object this;
in Java: Object this;
in KeY: Object self;
Default assumption in JML-KeY translation: self!= null

## Which Objects do Exist?

How to model object creation with new ?

## Which Objects do Exist?

How to model object creation with new ?

## Constant Domain Assumption

Assume that domain $\mathcal{D}$ is the same in all states $(\mathcal{D}, \delta, \mathcal{I}) \in$ States
Consequence:
Quantifiers and modalities commute:

$$
\vDash(\forall T x ;[\mathrm{p}] \phi) \leftrightarrow[\mathrm{p}](\forall T x ; \phi)
$$

## Object Creation (background; no need to remember this)

## Realizing Constant Domain Assumption

- Implicitly declared field boolean <created> in class Object
- <created> has value true iff argument object has been created
- Object creation modeled as $\{$ heap $:=$ create (heap, ob) $\}$ for not (yet) created ob (essentially sets <created> field of ob to true)


## Object Creation (background; no need to remember this)

## Realizing Constant Domain Assumption

- Implicitly declared field boolean <created> in class Object
- <created> has value true iff argument object has been created
- Object creation modeled as \{heap :=create(heap, ob) \} for not (yet) created ob (essentially sets <created> field of ob to true)

$$
\begin{aligned}
& \Gamma, \text { select(heap, ob, <created }\rangle)=\text { FALSE } \Longrightarrow \\
& \{\text { heap }:=\text { create }(\text { heap }, o b)\}\{\mathrm{o}:=\mathrm{ob}\}\langle\mathrm{o} .<\text { init }\rangle(\text { param }) ; \omega\rangle \phi, \Delta \\
& \Gamma \Longrightarrow\langle\mathrm{o}=\text { new } \mathrm{T}(\text { param }) ; \omega\rangle \phi, \Delta
\end{aligned}
$$

ob is a fresh program variable

## Object Creation (background; no need to remember this)

## Realizing Constant Domain Assumption

- Implicitly declared field boolean <created> in class Object
- <created> has value true iff argument object has been created
- Object creation modeled as \{heap :=create (heap, ob) \} for not (yet) created ob (essentially sets <created> field of ob to true)

$$
\begin{aligned}
& \Gamma, \text { select(heap, ob, <created }>)=\text { FALSE } \Longrightarrow \\
& \quad\{\text { heap }:=\text { create }(\text { heap }, \text { ob })\}\{0:=\mathrm{ob}\}\langle 0 .<\text { init }>(\text { param }) ; \omega\rangle \phi, \Delta \\
& \Gamma \Longrightarrow\langle 0=\text { new } \mathrm{T}(\text { param }) ; \omega\rangle \phi, \Delta
\end{aligned}
$$

ob is a fresh program variable
Alternatives exisit in the literature. E.g.:
[Ahrendt, de Boer, Grabe, Abstract Object Creation in Dynamic Logic To Be or Not To Be Created, Springer, LNCS 5850]

## Symbolic Execution

## Updates

## Parallel Undates

## Modeling OO Programs

Object Creation
Round Tour
Java Programs
Arrays
Side Effects
Abrupt Termination
Aliasing
Null Pointers

## Summary

## Literature

## Dynamic Logic to (almost) full Java

KeY supports full sequential Java, with some limitations:

- Limited concurrency
- No generics
- No I/O
- Only preliminary support for floats
- No dynamic class loading or reflexion
- API method calls: need either JML contract or implementation


## Java Features in Dynamic Logic: Arrays

Arrays


- Java type hierarchy includes array types
- Types ordered according to JaVA subtyping rules
- Function arr : int $\rightarrow$ Field turns integer index into type Field (required in store).
- Store array elements on heap
- Value of a[i] on the heap store(heap, a, $\operatorname{arr}(i), 17)$ is 17
- Arrays a and b can refer to same object (aliasing)


## Java Features in Dynamic Logic: Complex Expressions

Complex expressions with side effects

- Java expressions may have side effects, due to method calls, increment/decrement operators, nested assignments
- FOL terms have no side effect on the state

> Example (Complex expression with side effects in Java) int $i=0$; if ( $(i=2)>=2) i++$; value of $i$ ?

## Complex Expressions Cont'd

Decomposition of complex terms by symbolic execution
Follow the rules laid down in Java Language Specification
Local code transformations

$$
\text { evalOrderlteratedAssgnmt } \frac{\Gamma \Longrightarrow\langle\mathrm{y}=\mathrm{t} ; \mathrm{x}=\mathrm{y} ; \omega\rangle \phi, \Delta}{\Gamma \Longrightarrow\langle\mathrm{x}=\mathrm{y}=\mathrm{t} ; \omega\rangle \phi, \Delta} \quad \mathrm{t} \text { simple }
$$

Temporary variables store result of evaluating subexpression

$$
\text { ifEval } \frac{\Gamma \Longrightarrow\langle\text { boolean v0; v0 }=\mathrm{b} ; \text { if (v0) } \mathrm{p} ; \omega\rangle \phi, \Delta}{\Gamma \Longrightarrow\langle\text { if (b) } \mathrm{p} ; \omega\rangle \phi, \Delta} \quad \text { b complex }
$$

## Java Features in Dynamic Logic: Abrupt Termination

Abrupt Termination: Exceptions and Jumps
Redirection of control flow via return, break, continue, exceptions

$$
\langle\operatorname{try}\{p\} \operatorname{catch}(T \mathrm{e})\{q\} \text { finally }\{r\} \omega\rangle \phi
$$

## Java Features in Dynamic Logic: Abrupt Termination

Abrupt Termination: Exceptions and Jumps
Redirection of control flow via return, break, continue, exceptions

$$
\langle\operatorname{try}\{p\} \operatorname{catch}(T \mathrm{e})\{q\} \text { finally }\{r\} \omega\rangle \phi
$$

Rule tryThrow matches try-catch in pre-/postfix and active throw
$\Longrightarrow\langle\mathbf{i f}$ (e instanceof $T$ ) $\{\operatorname{try}\{x=e ; q\}$ finally $\{r\}\}$ else $\{r ;$ throw $e ;\} \omega\rangle \phi$ $\Longrightarrow\langle$ try $\{$ throw $e ; p\}$ catch ( $\mathrm{T} x$ ) $\{q\}$ finally $\{r\} \omega\rangle \phi$

## Java Features in Dynamic Logic: Abrupt Termination

Abrupt Termination: Exceptions and Jumps
Redirection of control flow via return, break, continue, exceptions

$$
\langle\operatorname{try}\{p\} \operatorname{catch}(T \mathrm{e})\{q\} \text { finally }\{r\} \omega\rangle \phi
$$

Rule tryThrow matches try-catch in pre-/postfix and active throw
$\Longrightarrow\langle\mathbf{i f}$ (e instanceof $T$ ) $\{\operatorname{try}\{x=e ; q\}$ finally $\{r\}\}$ else $\{r ;$ throw $e ;\} \omega\rangle \phi$ $\Rightarrow\langle$ try $\{$ throw $e ; p\} \operatorname{catch}(T x)\{q\}$ finally $\{r\} \omega\rangle \phi$

## Demo

exceptions/try-catch.key

## Java Features in Dynamic Logic: Aliasing

Demo<br>aliasing/attributeAlias1.key

## Java Features in Dynamic Logic: Aliasing

Demo<br>aliasing/attributeAlias1.key

Reference Aliasing
Alias resolution causes proof split

## A Round Tour of Java Features in DL Cont'd

Null pointer exceptions
There are no "exceptions" in FOL: $\mathcal{I}$ total on FSym
Need to model possibility that $0=$ null in o.a

- KeY branches over o!= null upon each field access


## Summary

- Most Java features covered in KeY
- Several of remaining features available in experimental version
- Simplified multi-threaded JMM
- Floats
- Degree of automation for loop-free programs is very high
- Proving loops requires user to provide invariant
- Automatic invariant generation sometimes possible
- Symbolic execution paradigm lets you use KeY w/o understanding details of logic


## Literature for this Lecture

KeYbook W. Ahrendt, B. Beckert, R. Bubel, R. Hähnle, P. Schmitt, M. Ulbrich, editors.

Deductive Software Verification - The KeY Book
Vol 10001 of LNCS, Springer, 2016
(E-book at link.springer.com)

- B. Beckert, V. Klebanov, B. Weiß, Dynamic Logic for Java Chapter 3 in [KeYbook] on the surface only: Sections 3.1, 3.2, 3.4, 3.5.5, 3.5.6, 3.5.7, 3.6
- W. Ahrendt, S. Grebing, Using the KeY Prover Chapter 15 in [KeYbook]

