

CHALMERS

Graphics Hardware



Ulf Assarsson

Graphics hardware – why?

- About 100x faster!
- Another reason: about 100x faster!
- Simple to pipeline and parallelize

- Current hardware based on triangle rasterization with programmable shading (e.g., OpenGL acceleration)
- Ray tracing: there are research architectures, and few commercial products
 - Renderdrive, RPU, (Gelato), NVIDIA OptiX
 - Or write your own GPU ray-tracer

POSSESSION

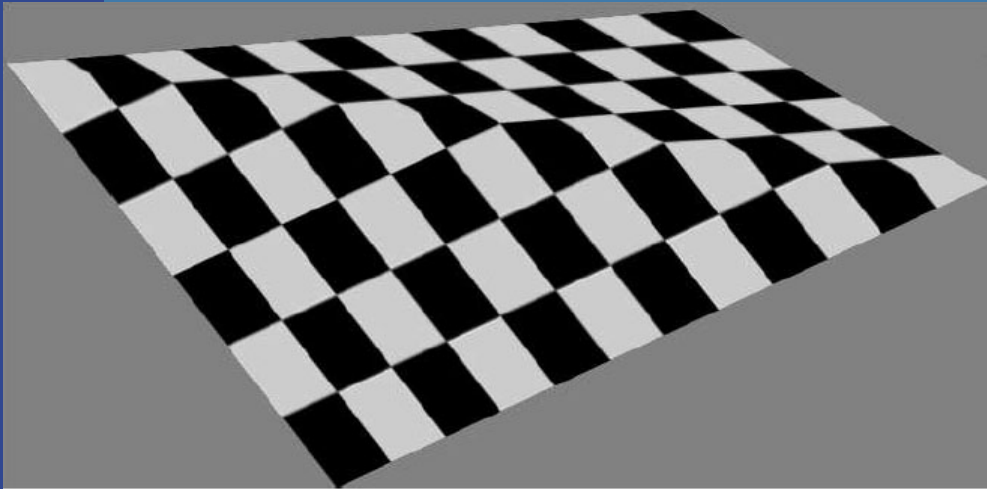


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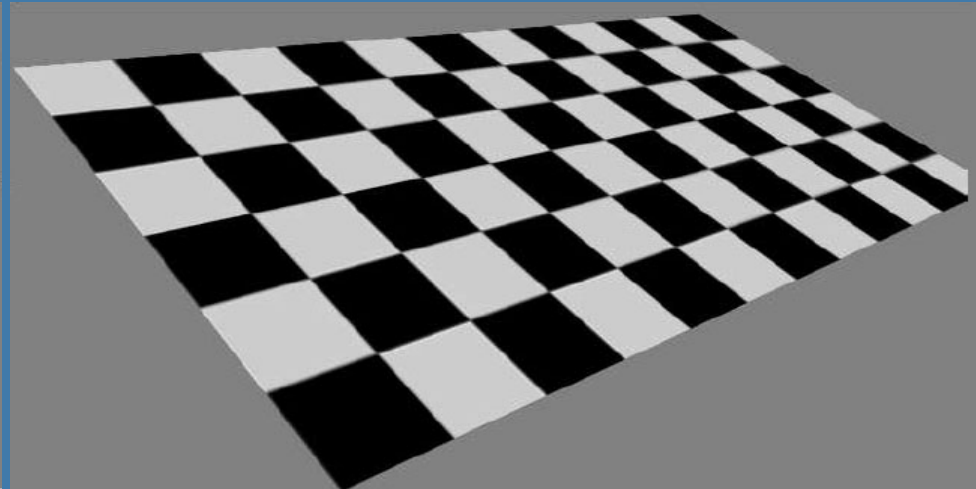
PSS PORTAL

Perspective-correct texturing

- How is texture coordinates interpolated over a triangle?
- Linearly?

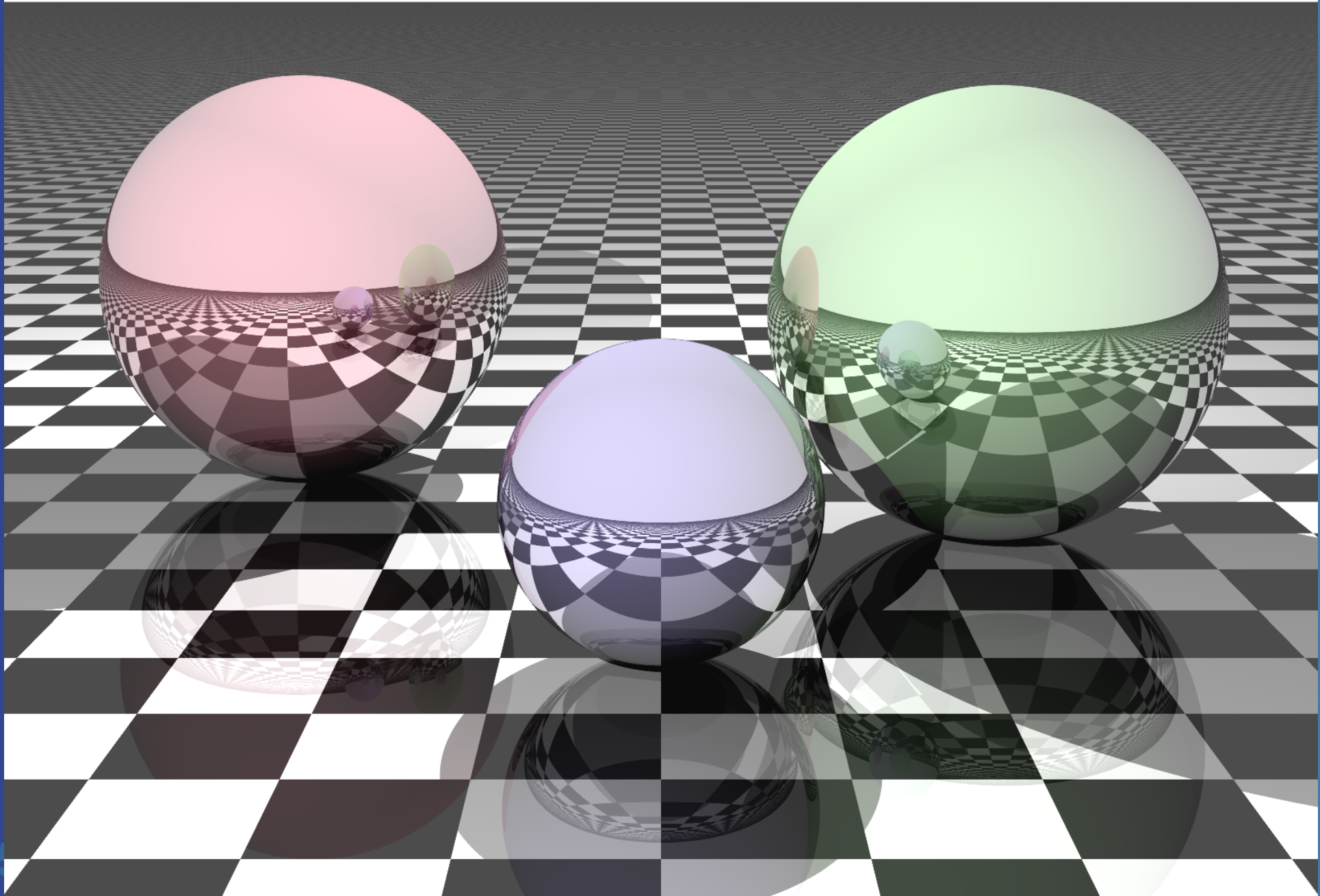


Linear interpolation



Perspective-correct interpolation

- Perspective-correct interpolation gives foreshortening effect!
- Hardware does this for you, but you need to understand this anyway!



Recall the following

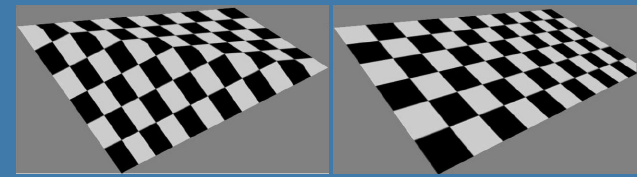
- Before projection, \mathbf{v} , and after \mathbf{p} ($\mathbf{p}=\mathbf{M}\mathbf{v}$)
- After projection p_w is not 1!
- Homogenization: $(p_x/p_w, p_y/p_w, p_z/p_w, 1)$
- Gives $(p_x', p_y', p_z', 1)$

$$\mathbf{p} = \mathbf{M}\mathbf{v} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1/d & 0 \end{pmatrix} \begin{pmatrix} v_x \\ v_y \\ v_z \\ 1 \end{pmatrix} = \begin{pmatrix} v_x \\ v_y \\ v_z \\ -v_z/d \end{pmatrix}$$

Texture coordinate interpolation

- Linear interpolation does not work
- Rational linear interpolation does:
 - $u(x) = (ax+b) / (cx+d)$ (along a scanline where $y = \text{constant}$)
 - a, b, c, d are computed from triangle's vertices (x, y, z, w, u, v)
- Not really efficient to compute a, b, c, d per scan line
- Smarter:
 - Compute $(u/w, v/w, 1/w)$ per vertex
 - These quantities can be linearly interpolated!
 - Then at each pixel, compute $1/(1/w) = w$
 - And obtain: $(w * u/w, w * v/w) = (u, v)$
 - The (u, v) are perspective-correctly interpolated
- Need to interpolate shading this way too
 - Though, not as annoying as textures
- Since linear interpolation now is OK, compute, e.g., $\Delta(u/w) / \Delta x$, and use this to update u/w when stepping in the x -direction (similarly for other parameters)

Put differently:



- Linear interpolation in screen space does not work for u, v
- Solution:
 - We have applied a non-linear transform to each vertex $(x/w, y/w, z/w)$.
 - Non-linear due to $1/w$ – factor from the homogenisation
 - We must apply the same non-linear transform to u, v
 - E.g. $(u/w, v/w)$. This can now be correctly screenspace interpolated since it follows the same non-linear $(1/w)$ transform and then interpolation as $(x/w, y/w, z/w)$
 - When doing the texture lookups, we still need (u, v) and not $(u/w, v/w)$.
 - So, multiply by w . But we don't have w at the pixel.
 - So, linearly interpolate $(u/w, v/w, 1/w)$, which is computed in screenspace at each vertex.
 - Then at each pixel:
 - $u = (u/w) / (1/w)$
 - $v = (v/w) / (1/w)$

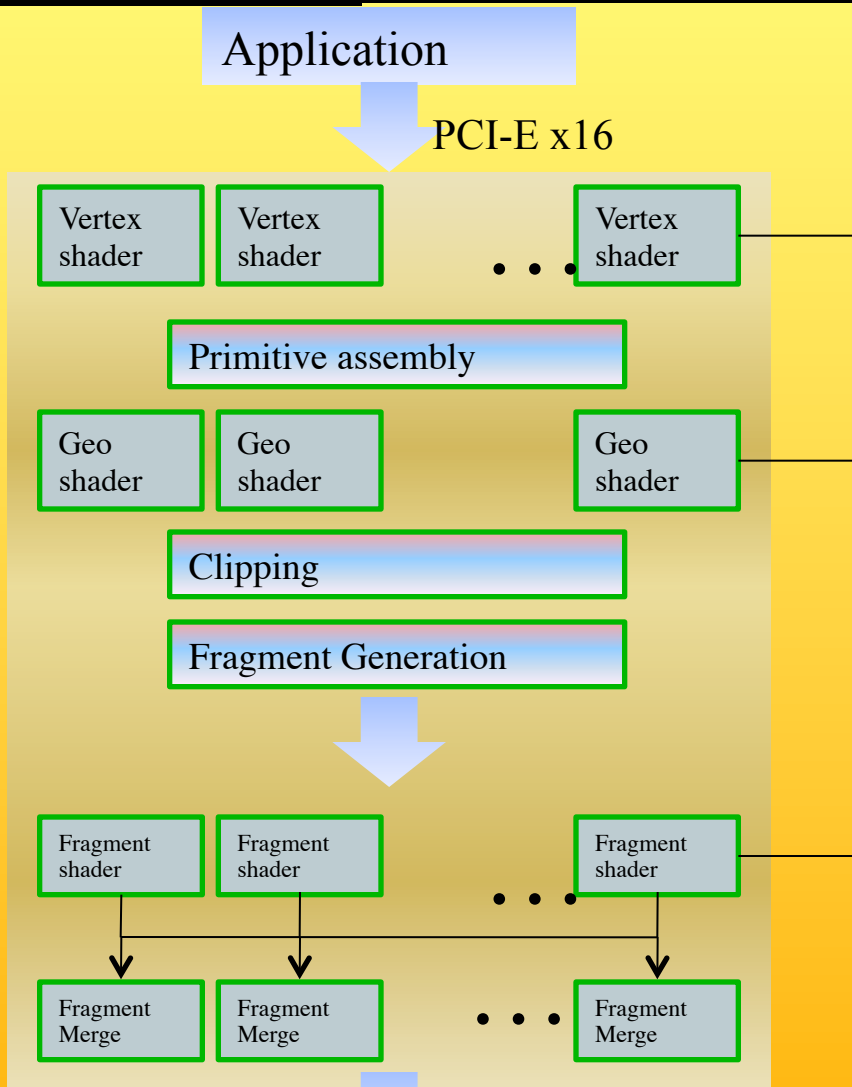
For a formal proof, see Jim Blinn, "W Pleasure, W Fun", IEEE Computer Graphics and Applications, p78-82, May/June 1998

Need to interpolate shading this way too, though, not as annoying as textures

Background:

Graphics hardware architectures

- Evolution of graphics hardware has started from the end of the pipeline
 - Rasterizer was put into hardware first (most performance to gain from this)
 - Then the geometry stage
 - Application will not be put into hardware (?)
- Two major ways of getting better performance:
 - Pipelining
 - Parallelization
 - Combinations of these are often used

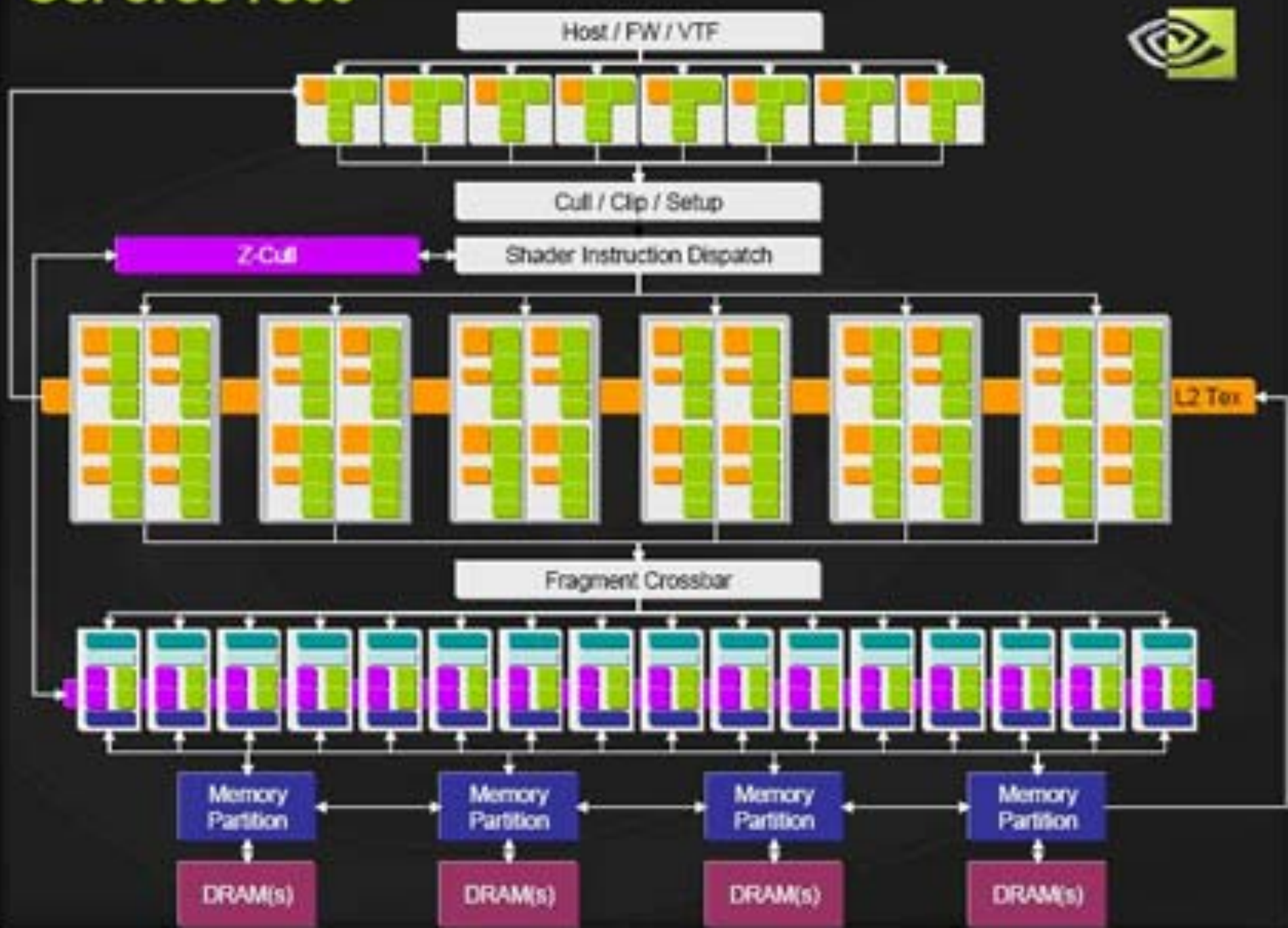


On NVIDIA
8000/9000/200/400/500/
600-series:
Vertex-, Geometry- and
Fragment shaders allocated
from a pool of
128/240/480/512/1536/2880
ALUs

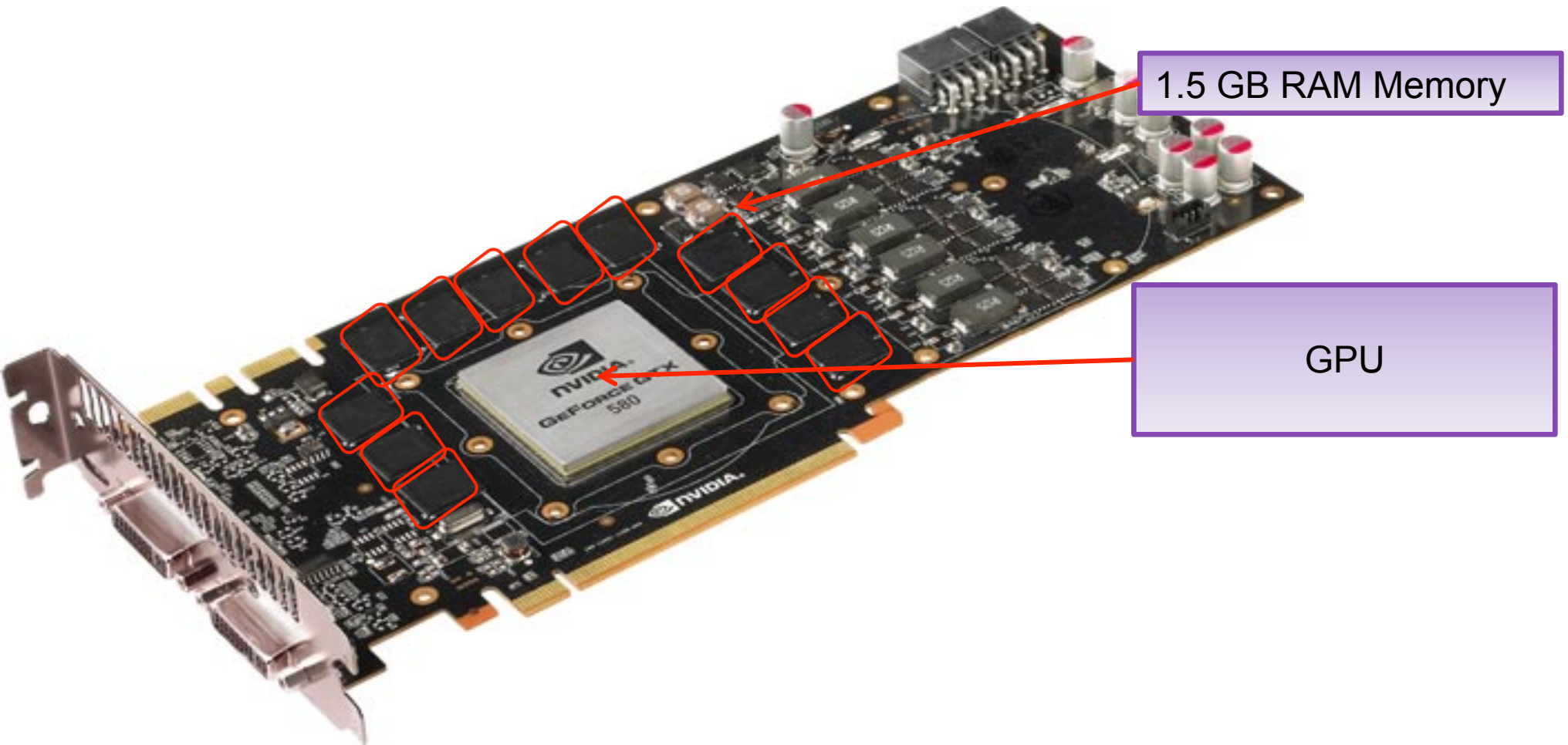


Display

GeForce 7800

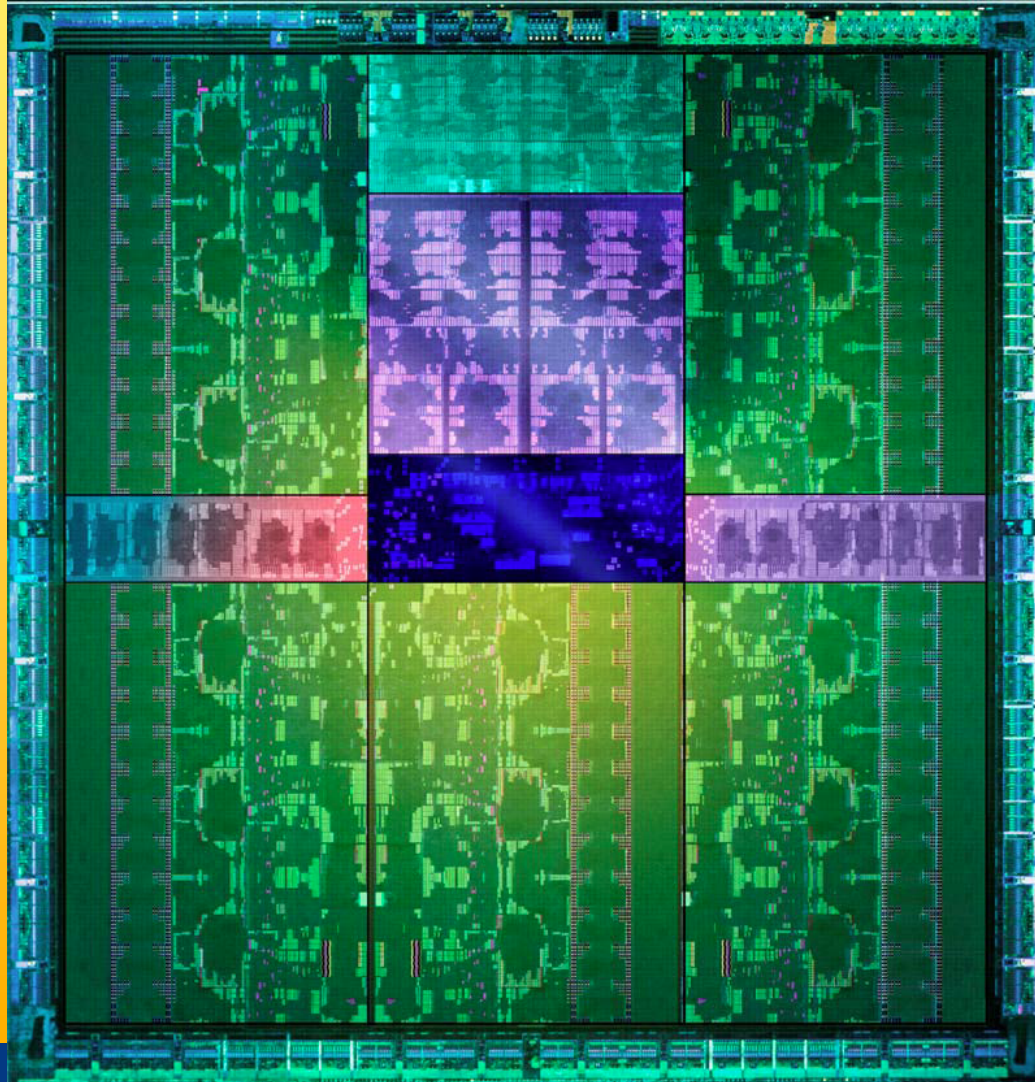


Graphics Processing Unit - GPU

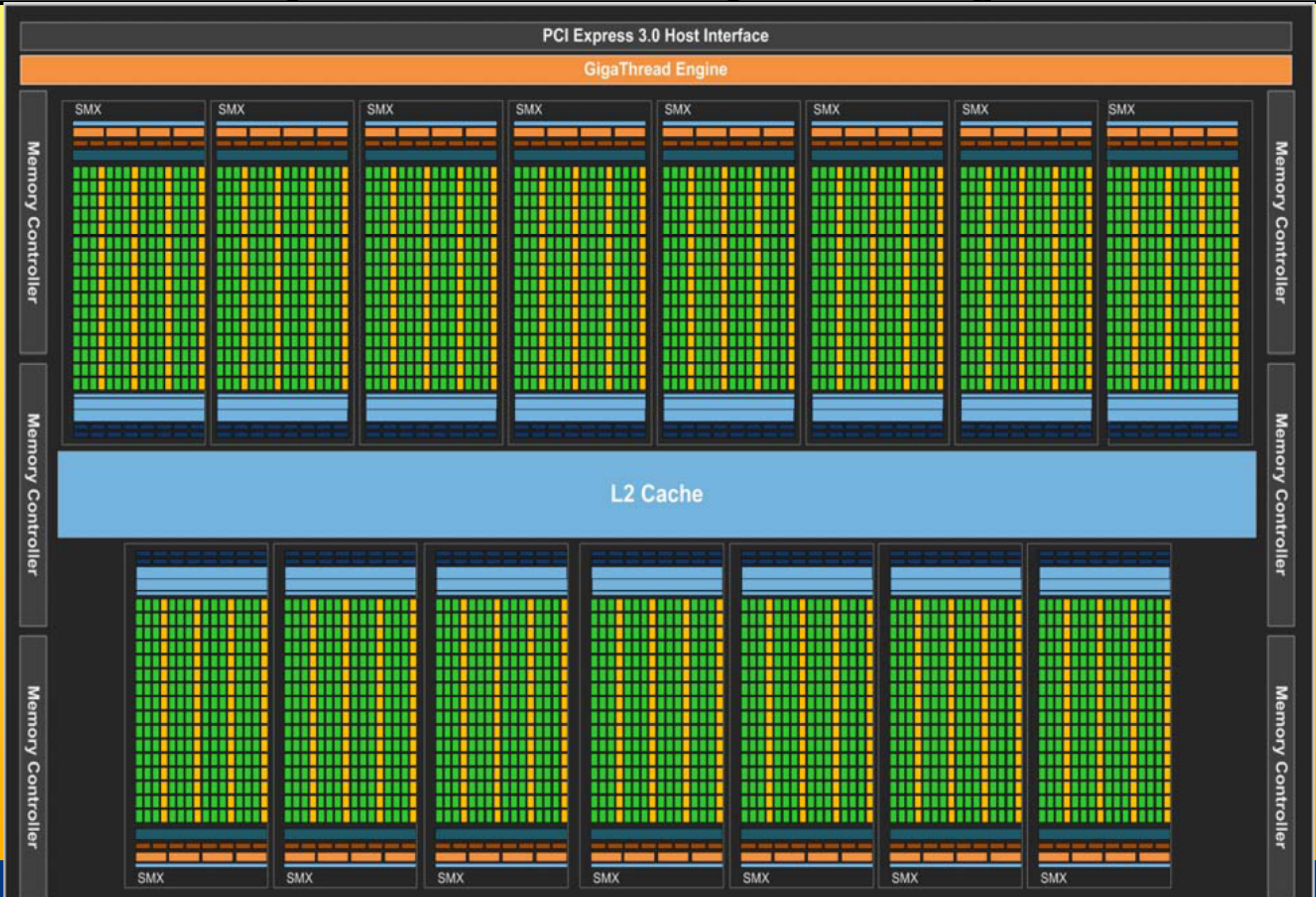


- NVIDIA Geforce GTX 580

Kepler GK110 Die Photo



Kepler GK110 Full chip block diagram



SMX:

- **12x16=192 single-precision CUDA cores,**
- **64 double-precision units,**
- **32 special function units (SFU), and**
- **32 load/store units (LD/ST).**



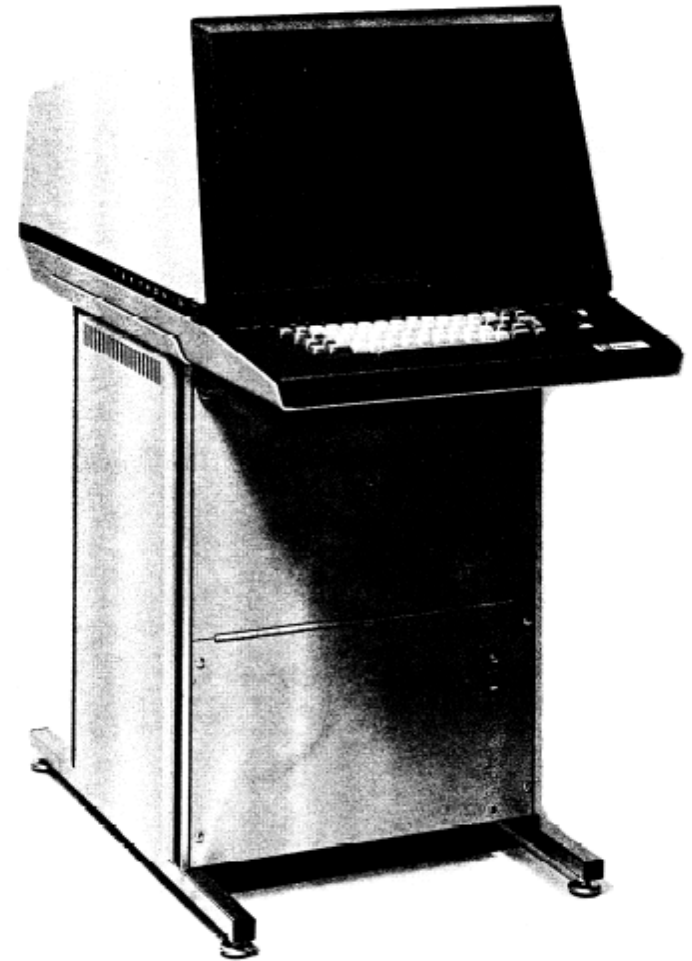
Graphics Hardware History

- 80's:
 - linear interpolation of color over a scanline
 - Vector graphics
- 91' Super Nintendo, Neo Geo,
 - Rasterization of 1 single 3D rectangle per frame (FZero)
- 95-96': Playstation 1, 3dfx Voodoo 1
 - Rasterization of whole triangles (Voodoo 2, 1998)
- 99' Geforce (256)
 - Transforms and Lighting (geometry stage)
- 02' 3DLabs WildCat Viper, P10
 - Pixel shaders, integers,
- 02' ATI Radion 9700, GeforceFX
 - Vertex shaders and **Pixel shaders** with floats
- 06' Geforce 8800
 - Geometry shaders, integers and floats, logical operations
- Then:
 - More general multiprocessor systems, higher SIMD-width, more cores



Direct View Storage Tube

- Created by Tektronix
 - Did not require constant refresh
 - Standard interface to computers
 - Allowed for standard software
 - Plot3D in Fortran
 - Relatively inexpensive
 - Opened door to use of computer graphics for CAD community



Tektronix 4014

Fig. 1-1. 4014 Computer Display Terminal.

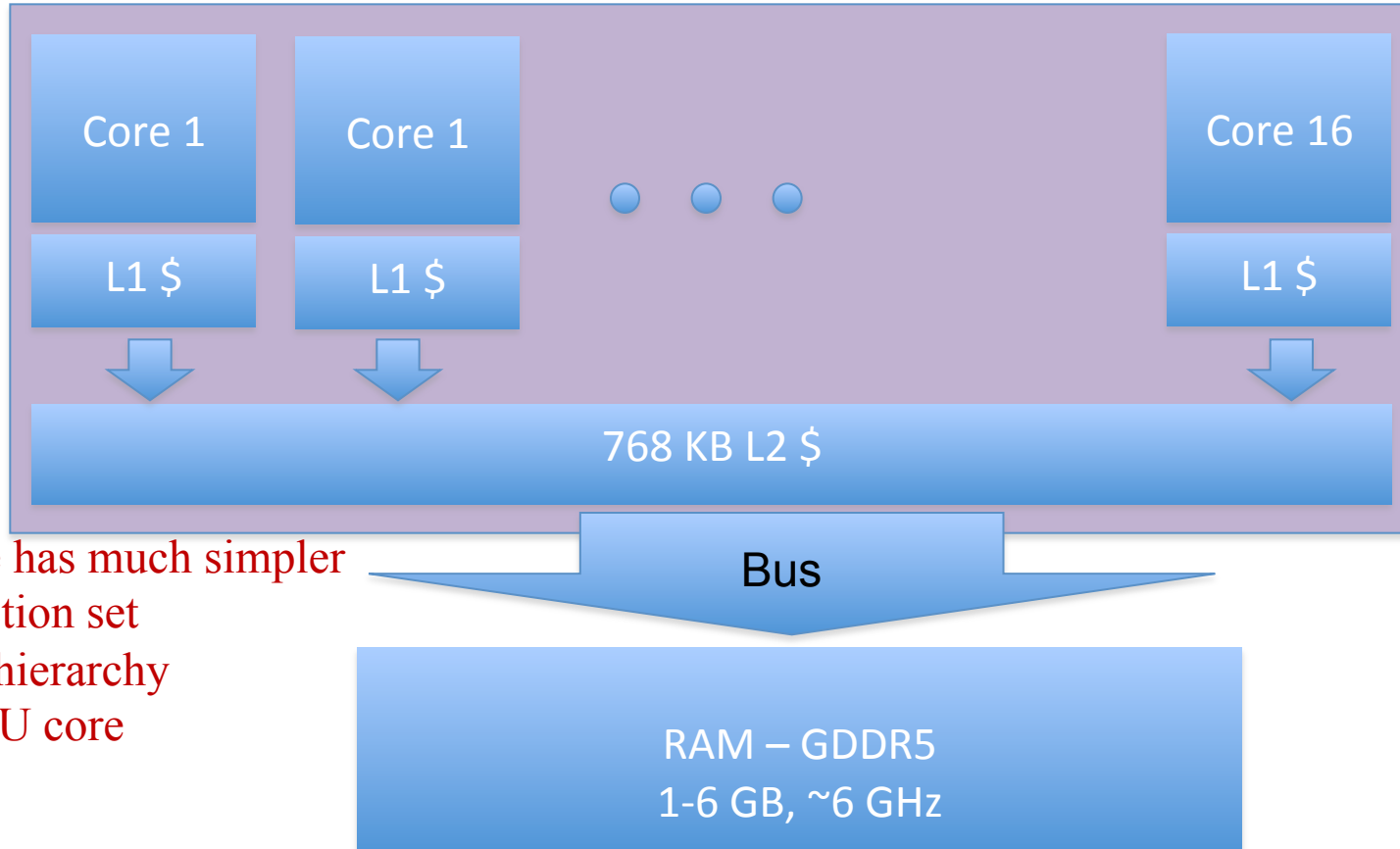
Briefly about Graphics HW pipelining

- 2001 ● In GeForce3: 600-800 pipeline stages!
 - 57 million transistors
 - First Pentium IV: 20 stages, 42 million transistors,
 - Core2 Duo, 271 Mtrans, Intel Core 2 Extreme QX9770 – 820Mtrans.
 - Intel Pentium D 900, 376M trans, Intel i7 (quad): 731Mtrans, 10-core Xeon Westmere: 2.6Gtrans
- Evolution of cards:
 - 2004 – X800 – 165M transistors
 - 2005 – X1800 – 320M trans, 625 MHz, 750 Mhz mem, 10Gpixels/s, 1.25G verts/s
 - 2004 – GeForce 6800: 222 M transistors, 400 MHz, 400 MHz core/550 MHz mem
 - 2005 – GeForce 7800: 302M trans, 13Gpix/s, 1.1Gverts/s, bw 54GB/s, 430 MHz core, mem 650MHz(1.3GHz)
 - 2006 – GeForce 8800: 681M trans, 39.2Gpix/s, 10.6Gverts/s, bw:103.7 GB/s, 612 MHz core (1500 for shaders), 1080 MHz mem (effective 2160 GHz)
 - 2008 – Geforce 280 GTX: 1.4G trans, 65nm, 602/1296 MHz core, 1107(*2)MHz mem, 142GB/s, 48Gtex/s
 - 2007 – ATI Radeon HD 5870: 2.15G trans, 153GB/s, 40nm, 850 MHz, GDDR5, 256bit mem bus,
 - 2010 – Geforce GTX480: 3Gtrans, 700/1401 MHz core, Mem (1.848G(*2)GHz), 177.4GB/s, 384bit mem bus, 40Gtexels/s
 - 2011 – GXT580: 3Gtrans, 772/1544, Mem: 2004/4008 MHz, 192.4GB/s, GDDR5, 384bit mem bus, 49.4 Gtex/s
 - 2012 – GTX680: 3.5Gtrans (7.1 for Tesla), 1006/1058, 192.2GB/s, 6GHz GDDR5, 256-bit mem bus.
 - 2013 – GTX780: 7.1B, core clock: 837MHz, 336 GB/s, Mem clock: 6GHz GDDR5, 384-bit mem bus
- Lesson learned: #trans doubles ~per 2 years. Core clock increases slowly. Mem clock –increases with new technology DDR2, DDR3, GDDR5, and with more memory busses (à 64-bit)
- We want as fast memory as possible! Why?
 - Parallelization can cover for slow clock. Parallelization more energy efficient than high clock frequency. Powerconsumption prop. to freq².
 - Memory transfers often the bottleneck

GPU- Nvidia's Kepler 2012



Overview:



16 cores à
192-SIMD width
(2*6*16)

16/48 KB per
each 48 SIMD

Bandwidth
~330 GB/s

Bus: 256/384
bits

Compare to
ATI 2900:

- 2x512bits

Larrabee:

- 2x512bits

GPU core has much simpler

- instruction set
 - cache hierarchy
- than a CPU core

Wish:

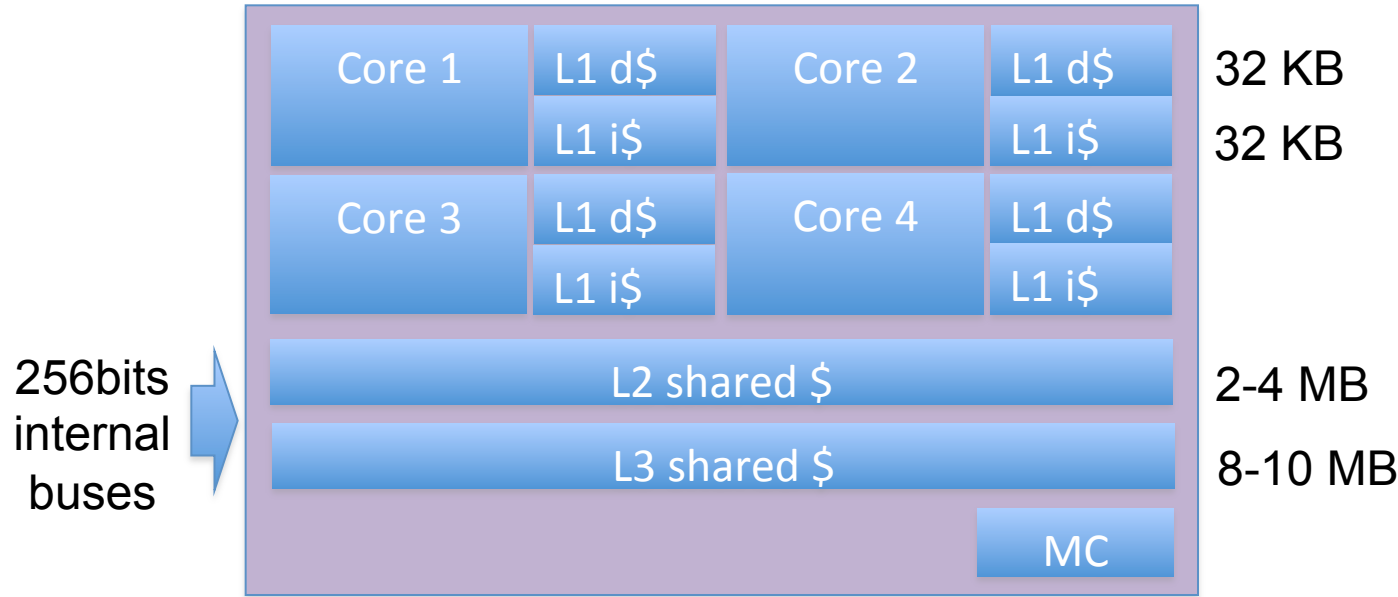
3072 ALUs à 1 float/clock => 12KB/clock

~1GHz core clock => 12000 GB/s request

We have ~330GB/s. In reality we can do 20-40 instr. between each RAM-read/write. Solved by L1\$ + L2\$ + latency hiding (warp switching)

CPU - 2011

AVX:
Intel's Sandybridge
AMD's Bulldozer



1 – 8 cores à
4 SIMD floats
(16 SIMD for
bytes)



- 8 cores à 4 floats
- ⇒ We want 128 bytes/clock (e.g. from RAM)
- ⇒ 128GByte/s, 1GHz CPU

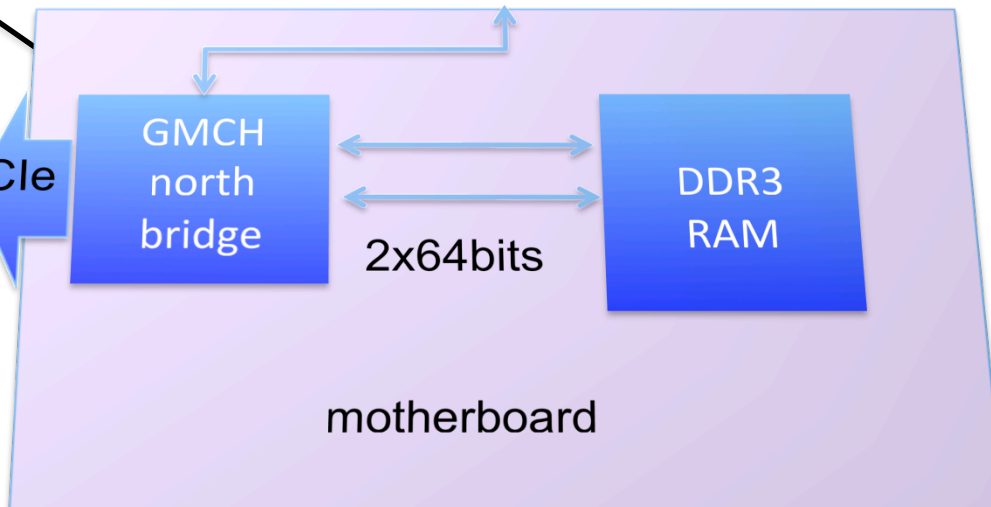
- In addition, x3, since:
 $r1 = r2 + r3;$

In reality: 6-12GB/s

Solved by \$-hierarchy + registers

Graphics
Memory
Controller
HUB

Gfx card PCIe



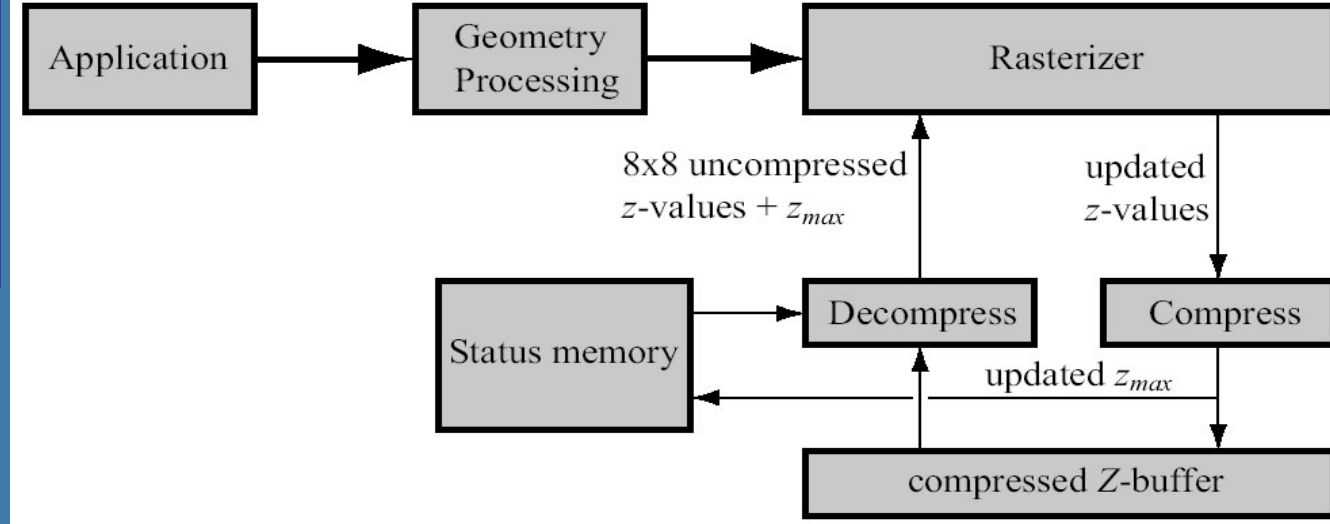
Memory bandwidth usage is huge!!

- On top of that bandwidth usage is never 100%.
- However, there are many techniques to reduce bandwidth usage:
 - Texture caching with prefetching
 - Texture compression
 - Z-compression
 - Z-occlusion testing (HyperZ)

Z-occlusion testing and Z-compression

- One way of reducing bandwidth
 - ATI Inc., pioneered with their HyperZ technology
- Very simple, and very effective
- Divide screen into tiles of 8x8 pixels
- Keep a status memory on-chip
 - Very fast access
 - Stores additional information that this algorithm uses
- Enables occlusion culling on triangle basis, z-compression, and fast Z-clears

Architecture of Z-cull and Z-compress



- Store z_{max} per tile, and a flag (whether cleared, compressed/uncompressed)
- Rasterize one tile at a time
- Test if z_{min} on triangle is farther away than tile's z_{max}
 - If so, don't do any work for that tile!!!
 - Saves texturing and z-read for entire tile – huge savings!
- Otherwise read compressed Z-buffer, & unpack
- Write to unpacked Z-buffer, and when finished compress and send back to memory, and also: update z_{max}
- For fast Z-clears: just set a flag to "clear" for each tile
 - Then we don't need to read from Z-buffer, just send cleared Z for that tile

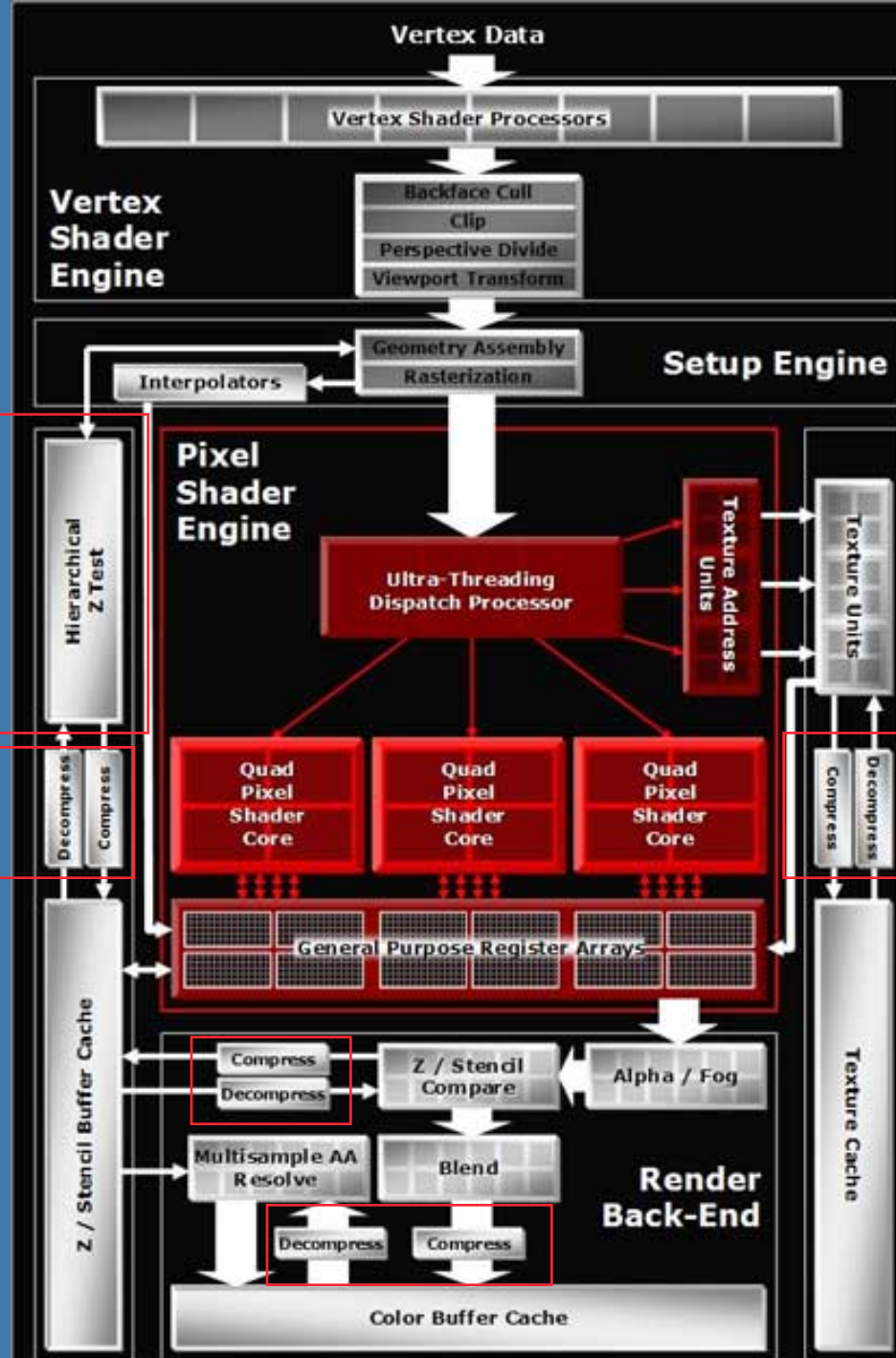
X1800 GTO

- Real example

Z-cull

Z-compress

Also note texture compress and color compress



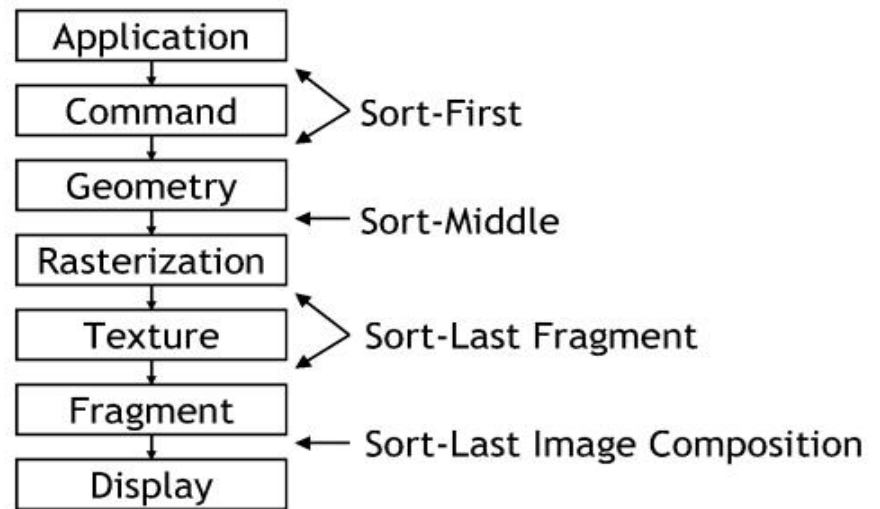
Taxonomy of Hardware

- We can do many computations in parallel:
 - Pixel shading, vertex shading, geometry shading
 - x, y, z, w r, g, b, a
- But results need to be sorted somewhere before reaching the screen.
 - Operations can be parallelized but result on screen must be as if each triangle were rendered one by one in their incoming order (according to OpenGL spec)
 - E.g., for blending (transparency), (z-culling, stencil test)

Taxonomy of hardware

- Need to sort from model space to screen space
- Gives four major architectures:
 - Sort-first
 - Sort-middle
 - Sort-Last Fragment
 - Sort-Last Image

Sorting Taxonomy



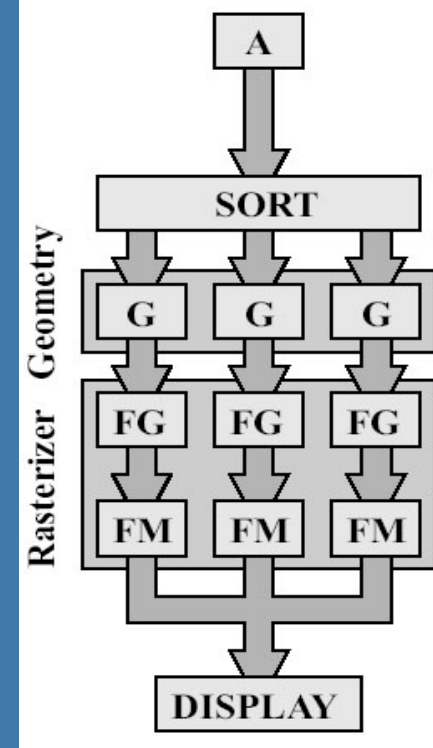
CS448 Lecture 9

Kurt Akeley, Pat Hanrahan, Fall 2001

- Will describe these briefly. Sort-last fragment (and sort middle) are most common in commercial hardware

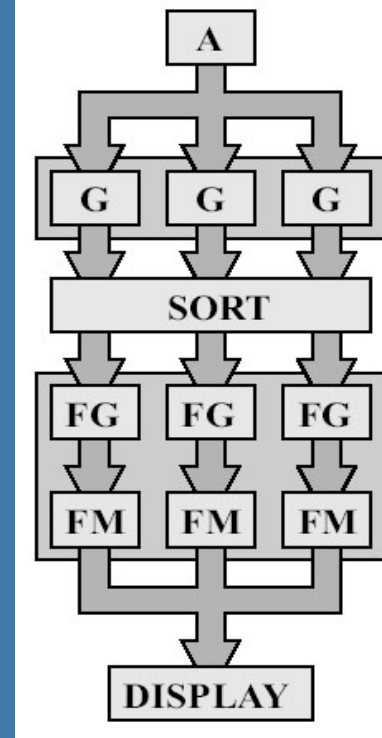
Sort-First

- Sorts primitives before geometry stage
 - Screen is divided into large regions
 - A separate pipeline is responsible for each region (or many)
- G is geometry, FG & FM is part of rasterizer
 - A fragment is all the generated information for a pixel on a triangle
 - FG is Fragment Generation (finds which pixels are inside triangle)
 - FM is Fragment Merge (merges the created fragments with various buffers (Z, color))
- Not explored much at all



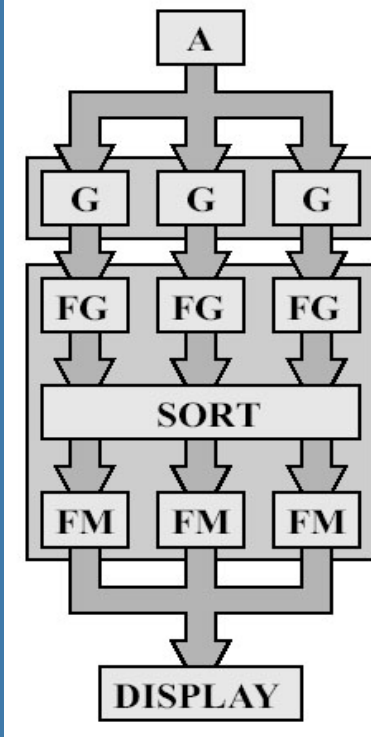
Sort-Middle

- Sorts between G and R
- Pretty natural, since after G, we know the screen-space positions of the triangles
- Older/cheaper hardware uses this
 - Examples include InfiniteReality (from SGI) and the KYRO architecture (from Imagination)
- Spread work arbitrarily among G's
- Then depending on screen-space position, sort to different R's
 - Screen can be split into "tiles". For example:
 - Rectangular blocks (8x8 pixels)
 - Every n scanlines
- The R is responsible for rendering inside tile
- A triangle can be sent to many FG's depending on overlap (over tiles)



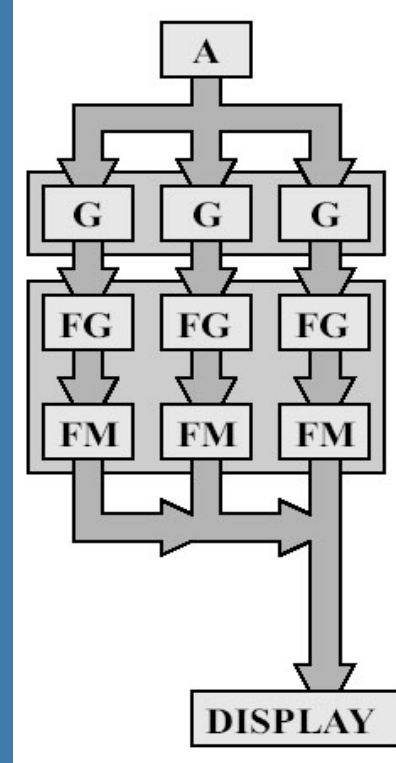
Sort-Last Fragment

- Sorts between FG and FM
- XBOX, PS3, nVidia use this
- Again spread work among G's
- The generated work is sent to FG's
- Then sort fragments to FM's
 - An FM is responsible for a tile of pixels
- A triangle is only sent to one FG, so this avoids doing the same work twice
 - Sort-Middle: If a triangle overlaps several tiles, then the triangle is sent to all FG's responsible for these tiles
 - Results in extra work

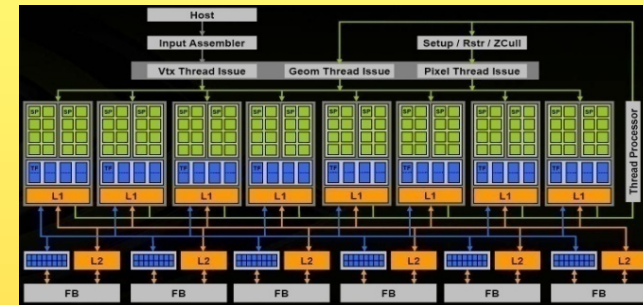
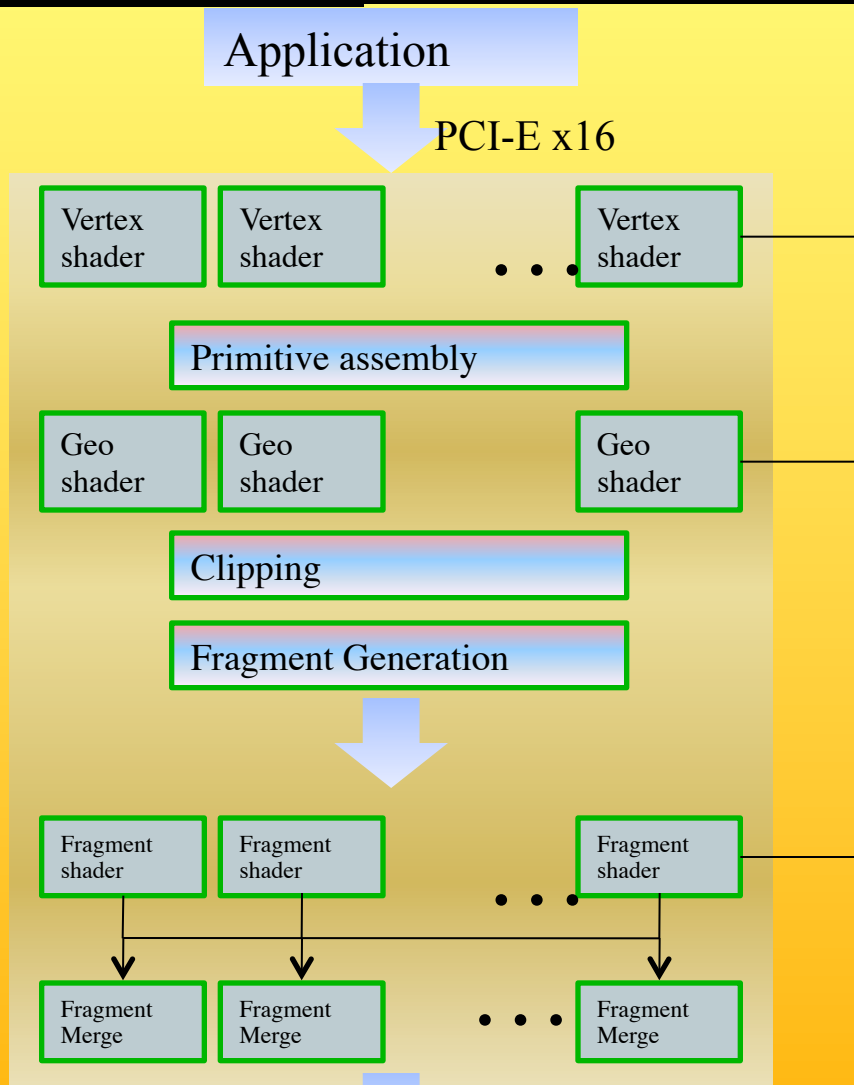


Sort-Last Image

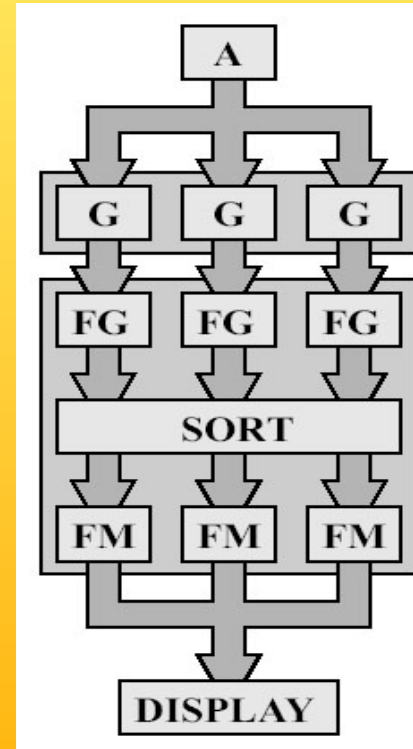
- Sorts after entire pipeline
- So each FG & FM has a separate frame buffer for entire screen (Z and color)
- After all primitives have been sent to the pipeline, the z-buffers and color buffers are merged into one color buffer
- Can be seen as a set of independent pipelines
- Huge memory requirements!
- Used in research, but probably not commercially



Logical layout of a graphics card:



On NVIDIA
8000/9000/200/400
/600-series:
→ Vertex-, Geometry- and
Fragment shaders
allocated from a pool of
128/240/480/1536/3072
processors (=ALUs)

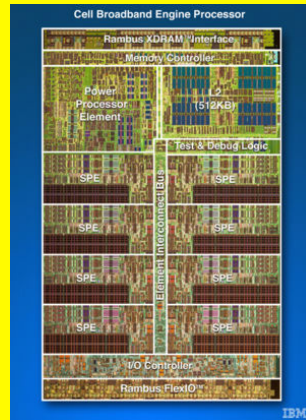


Current and Future Multicores in Graphics

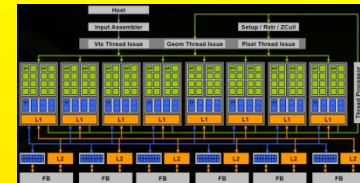
- Cell – 2005
 - 8 cores à 4-float SIMD
 - 256KB L2 cache/core
 - 128 entry register file
 - 3.2 GHz

PowerXCell 8i Processor – 2008

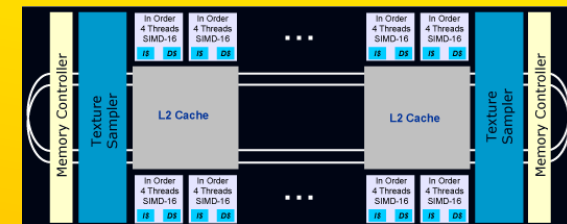
- 8 cores à 4-float SIMD
- 256KB L2 cache
- 128 entry register file
- but has better double precision support



- NVIDIA 8800 GTX – Nov 2006
 - 16 cores à 8-float SIMD (GTX 280 - 30 cores à 8, june '08)
 - 16 KB L1 cache, 64KB L2 cache (rumour)
 - 1.2-1.625 GHz



- Larrabee – "2010"
 - 16-24 cores à 16-float SIMD (Xeon Phi: 61 cores, 2012)
 - Core = 16-float SIMD (=512bit FPU) + x86 proc with loops, branches + scalar ops, 4 threads/core
 - 32KB L1cache, 256KB L2-cache (512KB/core)
 - 1.7-2.4 GHz (1.1 GHz)



- NVIDIA Fermi GF100 – 2010, (GF110 2011)
 - 16 cores à 2x16-float SIMD (1x16 double SIMD)
 - 16/48 KB L1 cache, 768 KB L2 cache

- NVIDIA Kepler 2012 - 16 cores à 2x3x16=96 float SIMD
- NVIDIA Kepler 2013 - 16 cores à 2x6x16=192 float SIMD

NVIDIA year 2020

- Exaflop machine:
- Google on:
"The Challenge of Future High-Performance Computing" Uppsala
- [http://media.medfarm.uu.se/play/video/3261#_utma=1.4337140.1361541635.1361541635.1361541635.1&_utmb=1.4.10.1361541635&_utmc=1&_utmz=1.1361541635.1.1.utmcsr=\(direct\)%7Cutmccn=\(direct\)%7Cutmcmd=\(none\)&_utmh=-&_utmk=104508928](http://media.medfarm.uu.se/play/video/3261#_utma=1.4337140.1361541635.1361541635.1361541635.1&_utmb=1.4.10.1361541635&_utmc=1&_utmz=1.1361541635.1.1.utmcsr=(direct)%7Cutmccn=(direct)%7Cutmcmd=(none)&_utmh=-&_utmk=104508928)
- Bill Dally, Chief Scientist & sr VP of Research, NVIDIA, prof. of Engineering, Stanford Univ.
- “Energy efficiency is key to performance”
– Flops/W.

Intel Xeon Phi

- Knights Corner

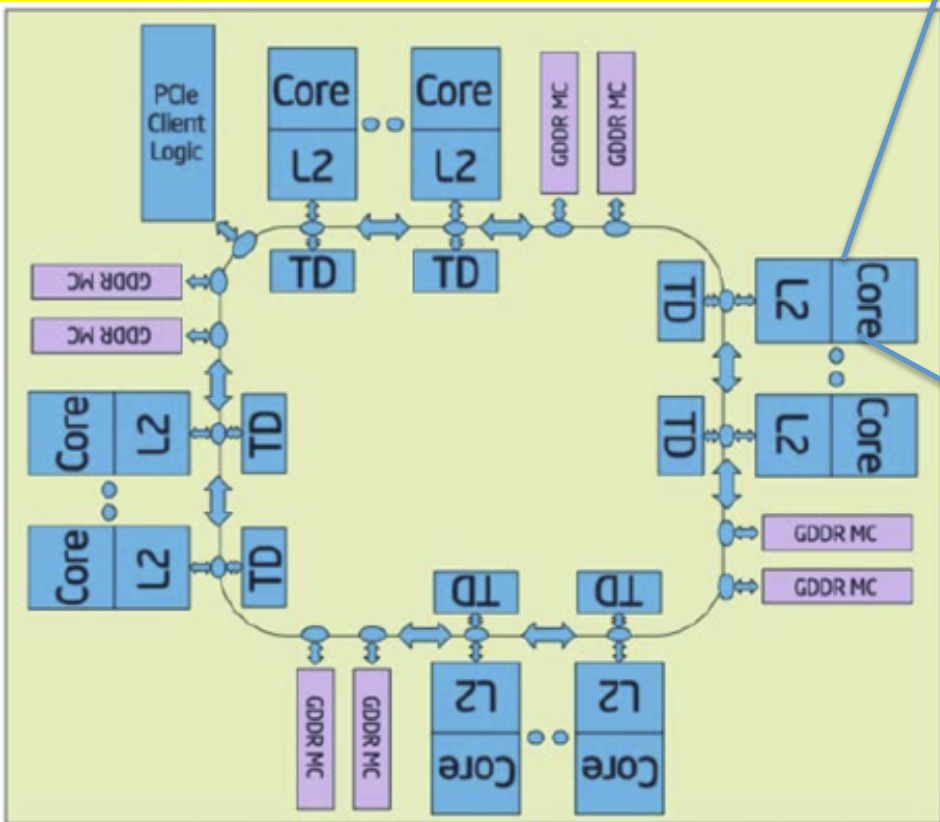


Figure 5: Knights Corner Microarchitecture

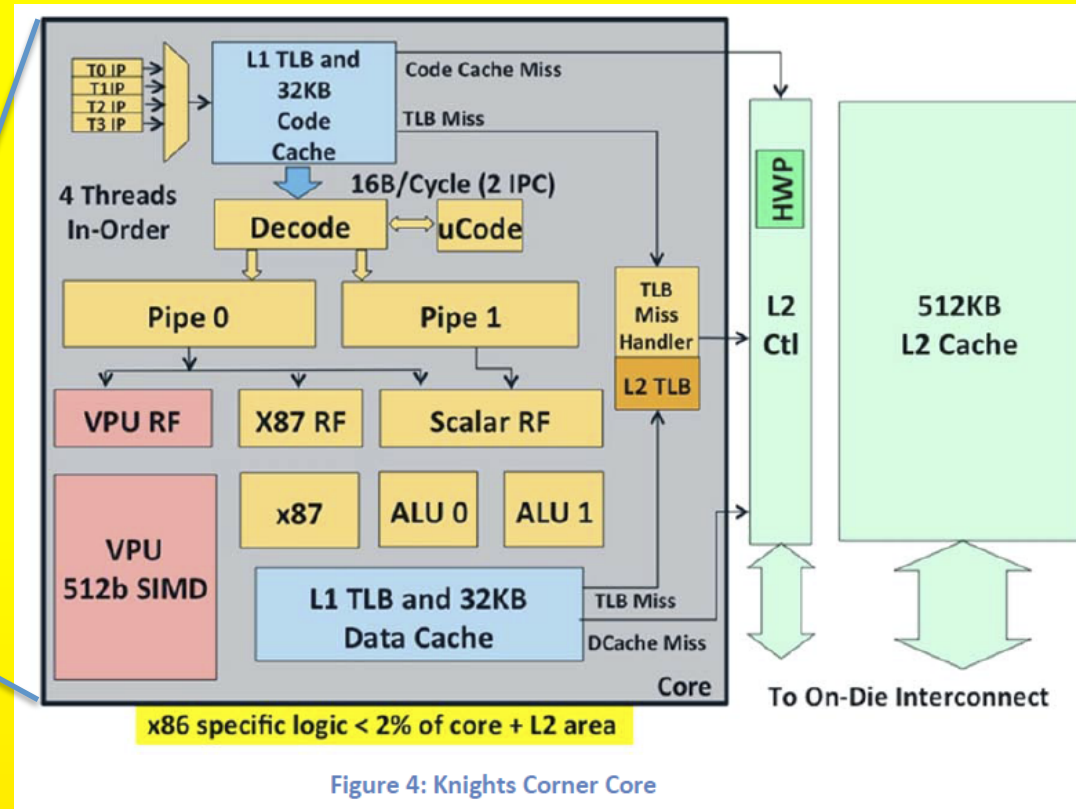


Figure 4: Knights Corner Core

<http://www.tomshardware.com/reviews/xeon-phi-larrabee-stampede-hpc,3342-3.html>

Need to know:

- Perspective correct texturing

- Taxonomy:

- Sort first
- sort middle
- sort last fragment
- sort last image

- Bandwidth

- Why it is a problem
- How to "solve" it

- Be able to sketch the architecture of a moder graphics card

- As visualized on the next slide

Linearly interpolate $(u_i/w_i, v_i/w_i, 1/w_i)$ in screenspace from each triangle vertex i .

Then at each pixel:

$$u_{ip} = (u_{ip}/w_{ip}) / (1/w_{ip})$$
$$v_{ip} = (v_{ip}/w_{ip}) / (1/w_{ip})$$

where ip = screen-space interpolated value from the triangle vertices.

