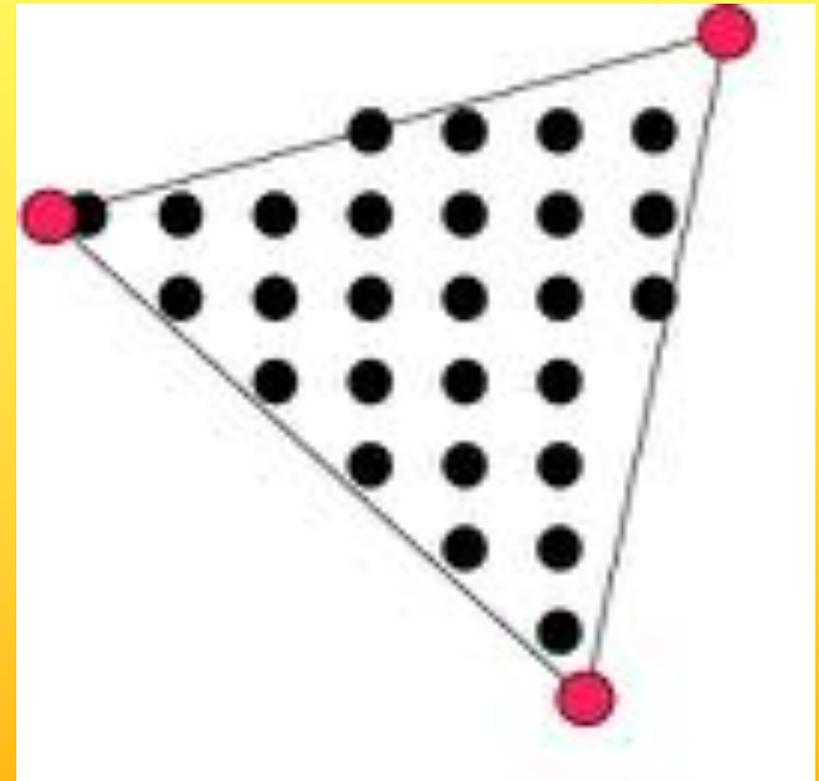
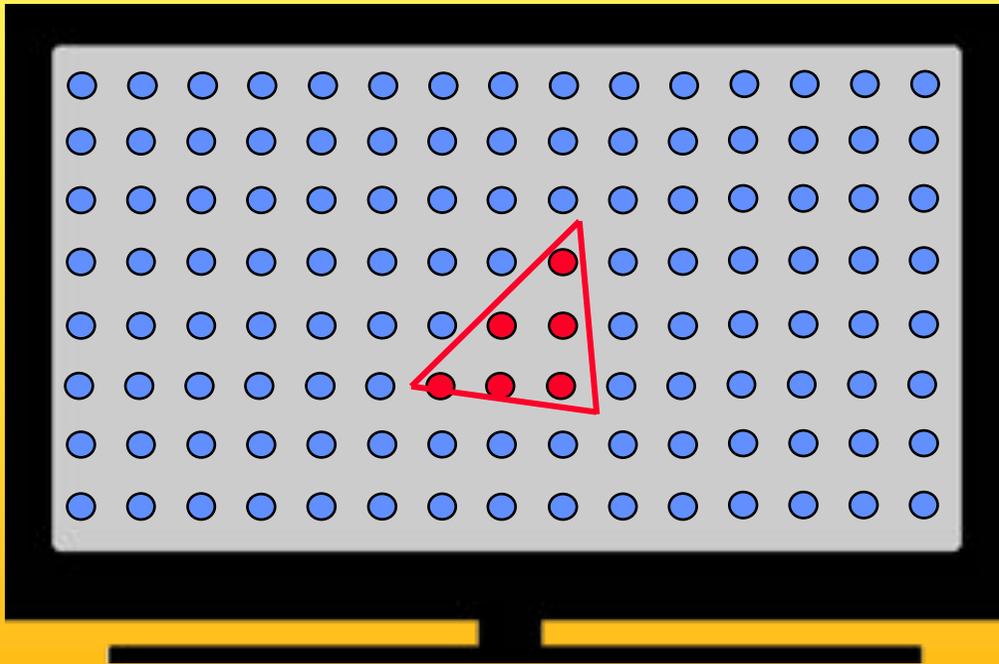


# Realistic Real-time Rendering Today and in the Future

Ulf Assarsson

Chalmers University of Technology

# The screen consists of pixels

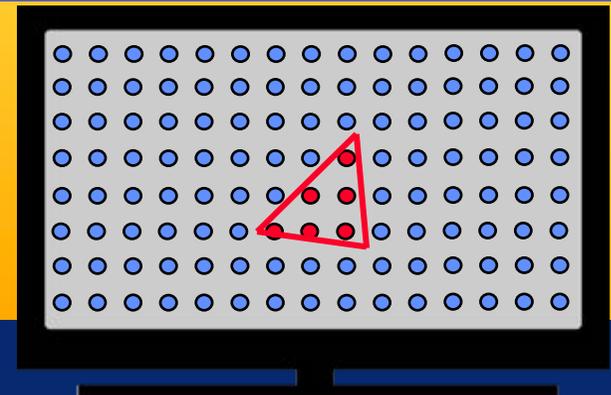
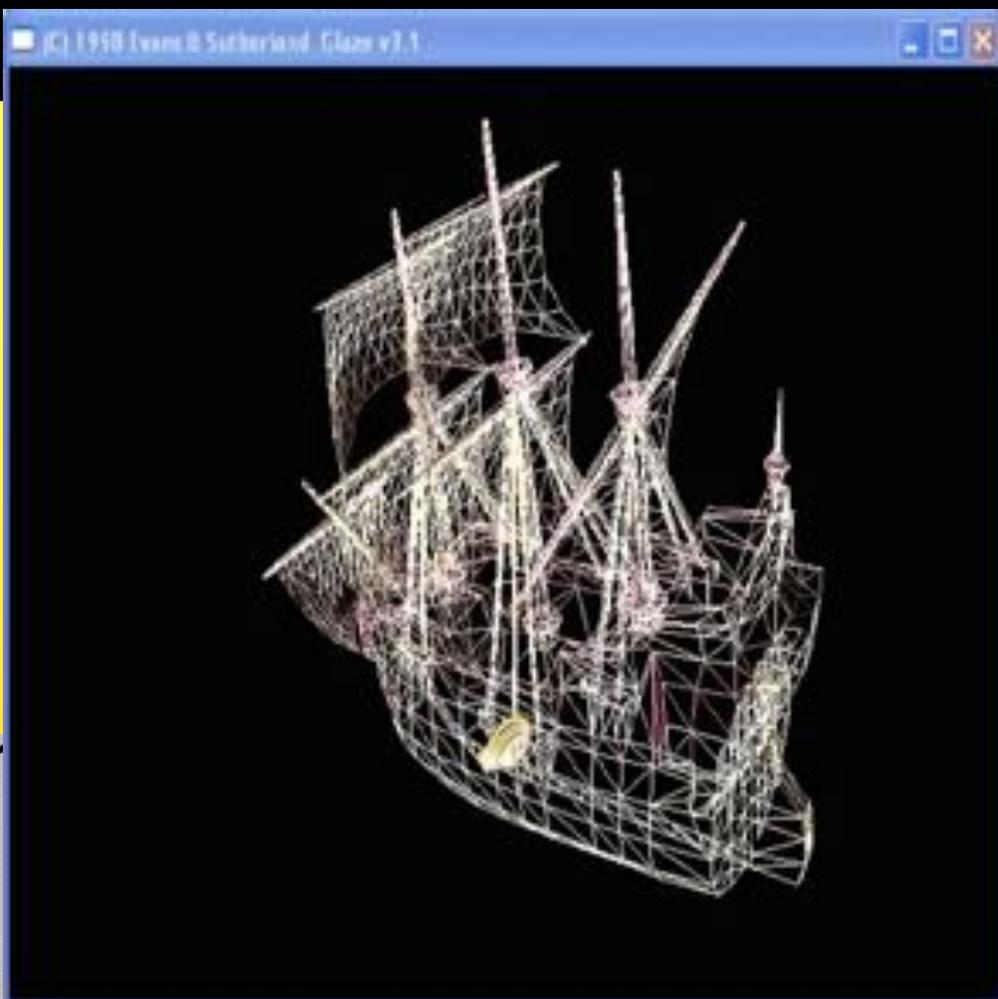
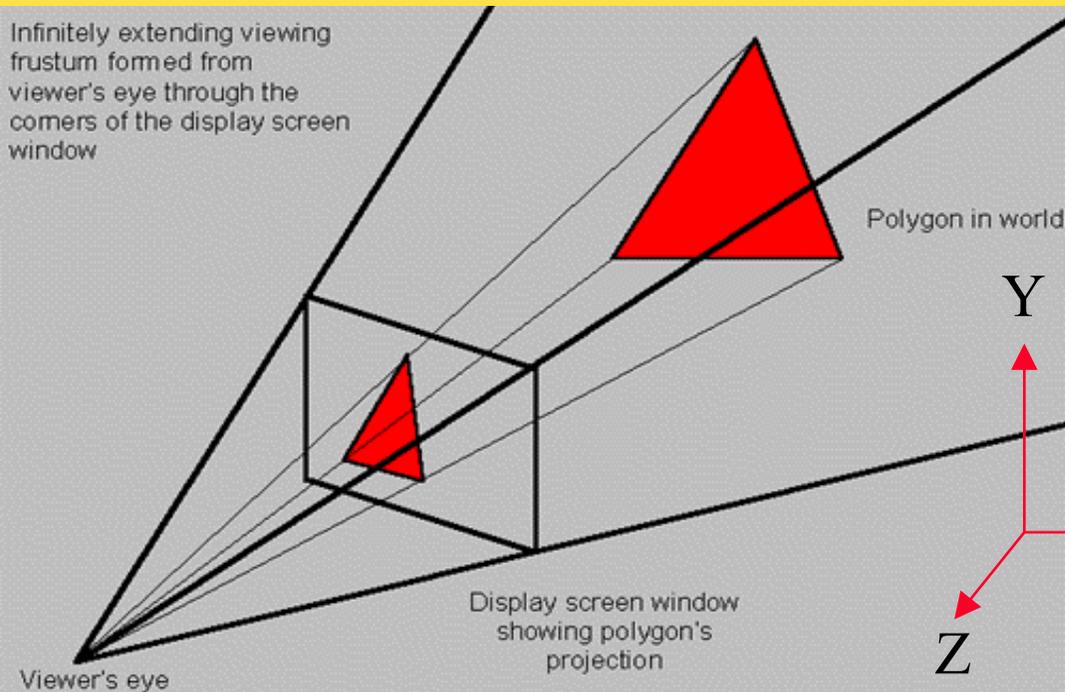


# Grafikkort



# 3D-Rendering

- Objects are often made of triangles
- $x, y, z$ - coordinate for each vertex



# 4D Matrix Multiplication

$$\begin{bmatrix} s_x & \bullet & \bullet & t_x \\ \bullet & s_y & \bullet & t_y \\ \bullet & \bullet & s_z & t_z \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix}$$

# Real-Time Rendering

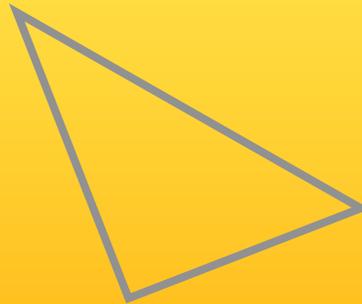


# Textures

- One application of texturing is to "glue" images onto geometrical object



+



=



# Texturing: Glue images onto geometrical objects

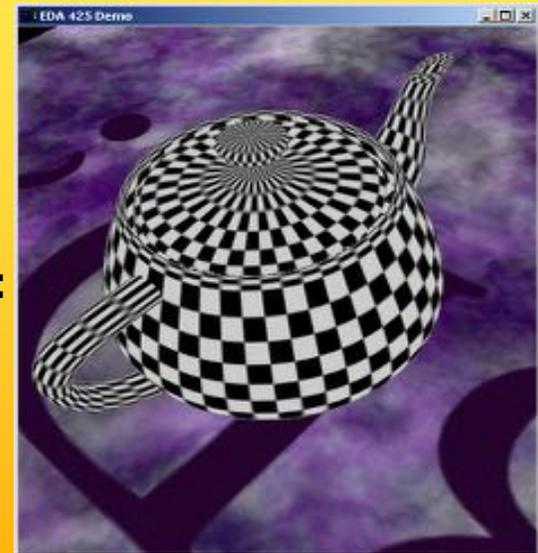
- Purpose: more realism, and this is a cheap way to do it



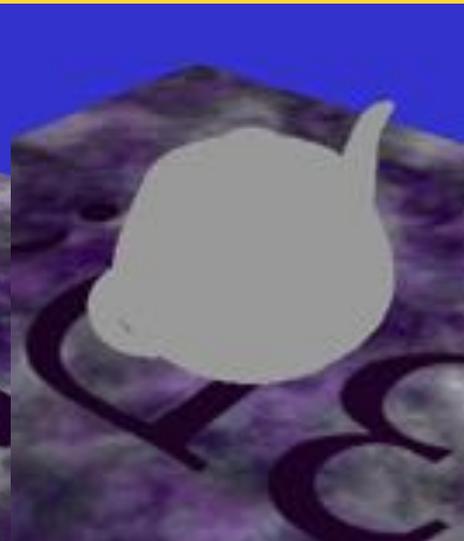
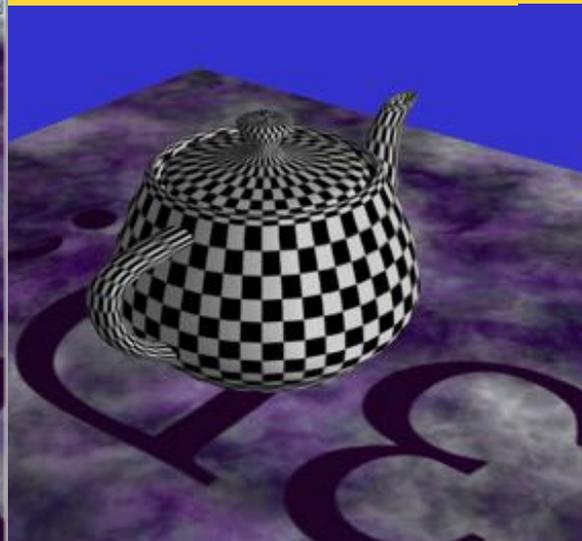
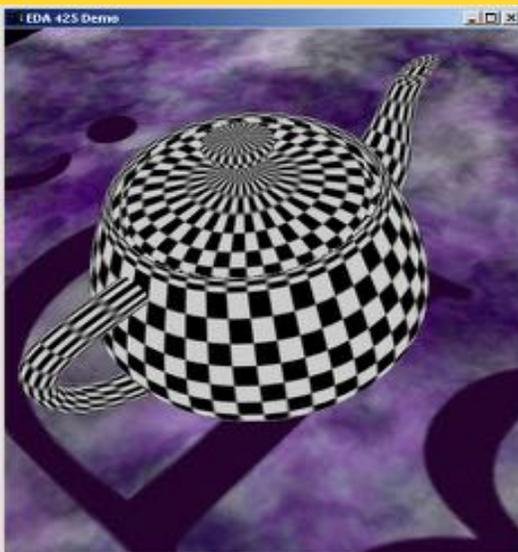
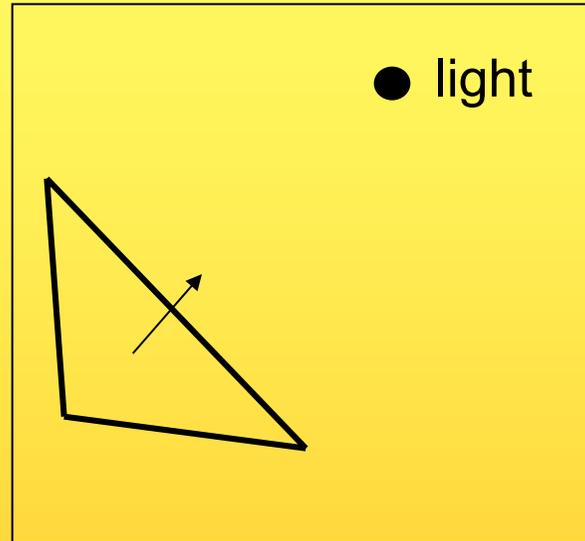
+



=



# Light computation per triangle



# More



Reflections



Shadows



Materials

However, this does not look very realistic! Why?



Water



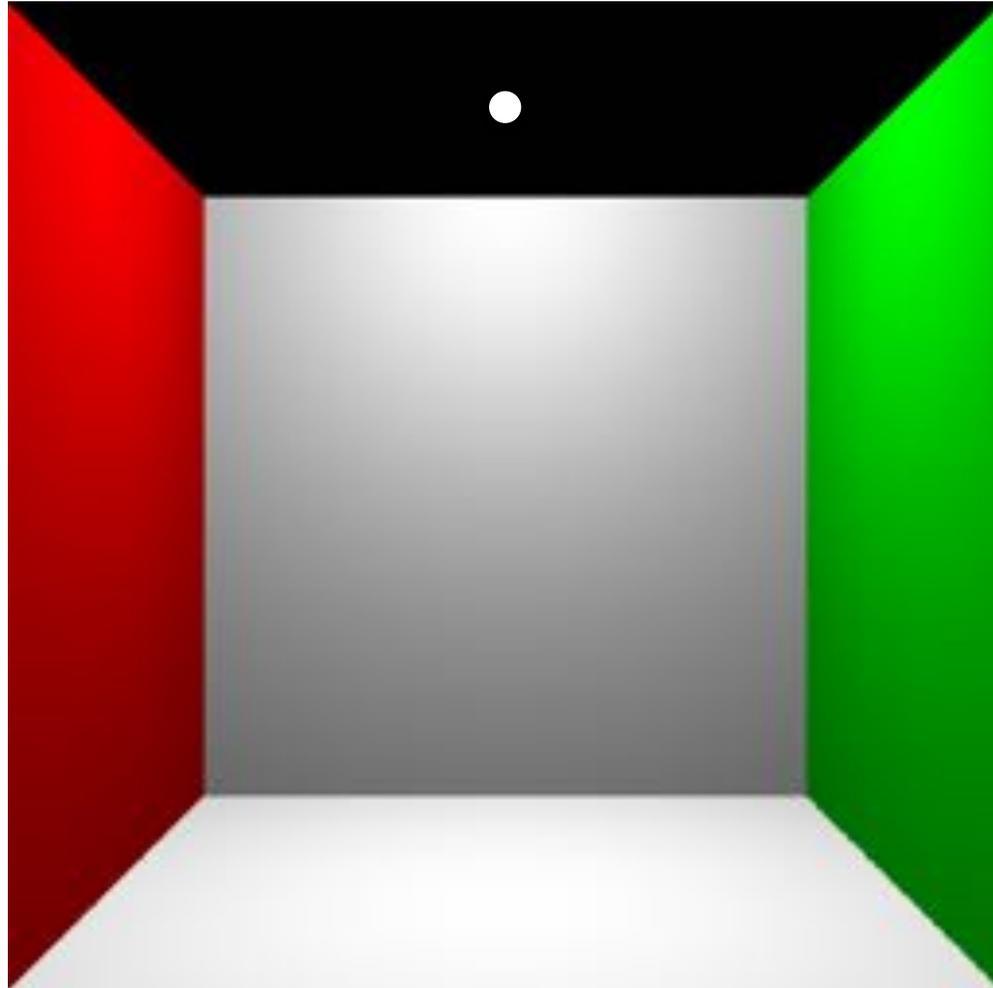
Airlight



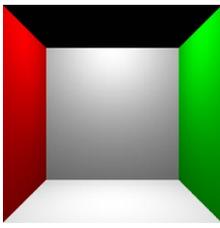
Fire

# Light Bounces

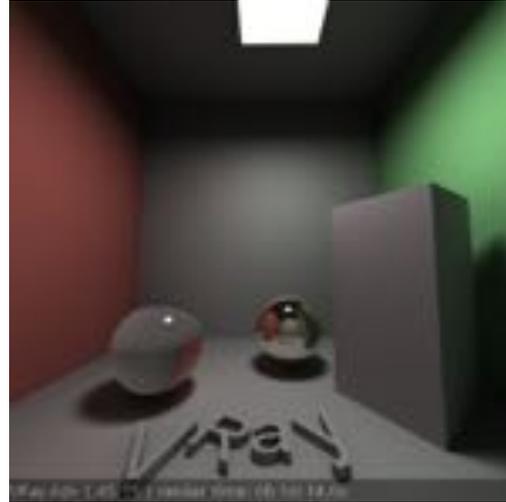
Typical test box (Cornell box), often compared to actual photograph:



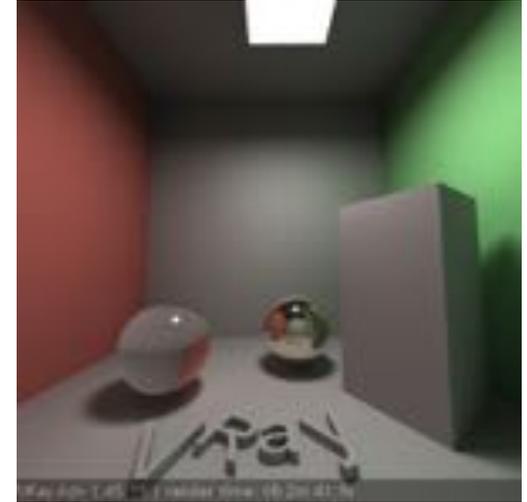
# Light Bounces



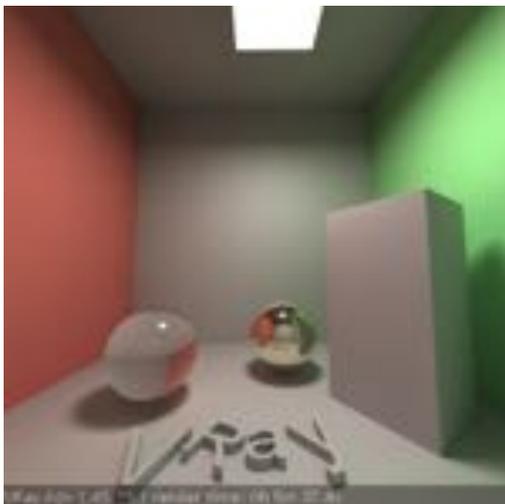
0 bounces



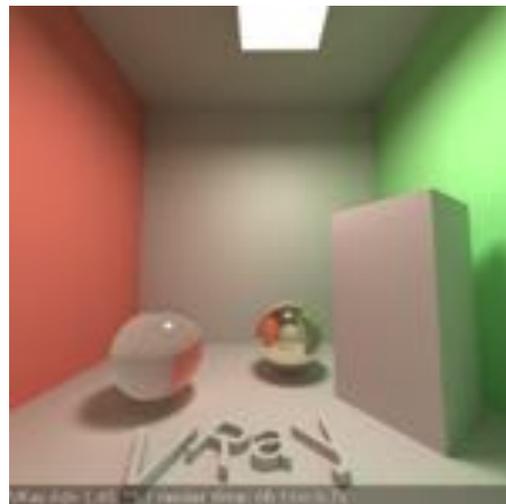
1 bounce



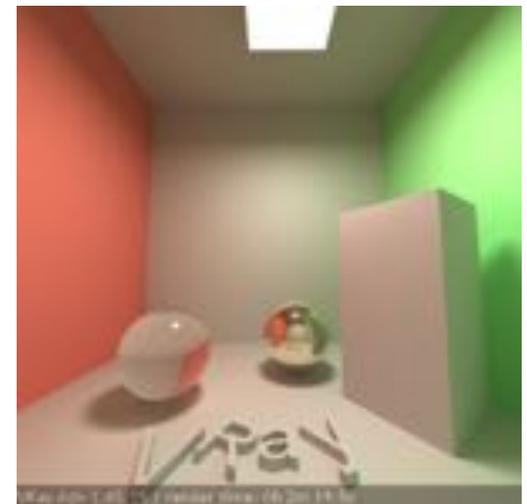
2 bounces



4 bounces



8 bounces



infinite bounces

# The Problem of Computer Graphics

- Is not CG soon a solved problem?
- Will not computers soon be fast enough?

Probably not...

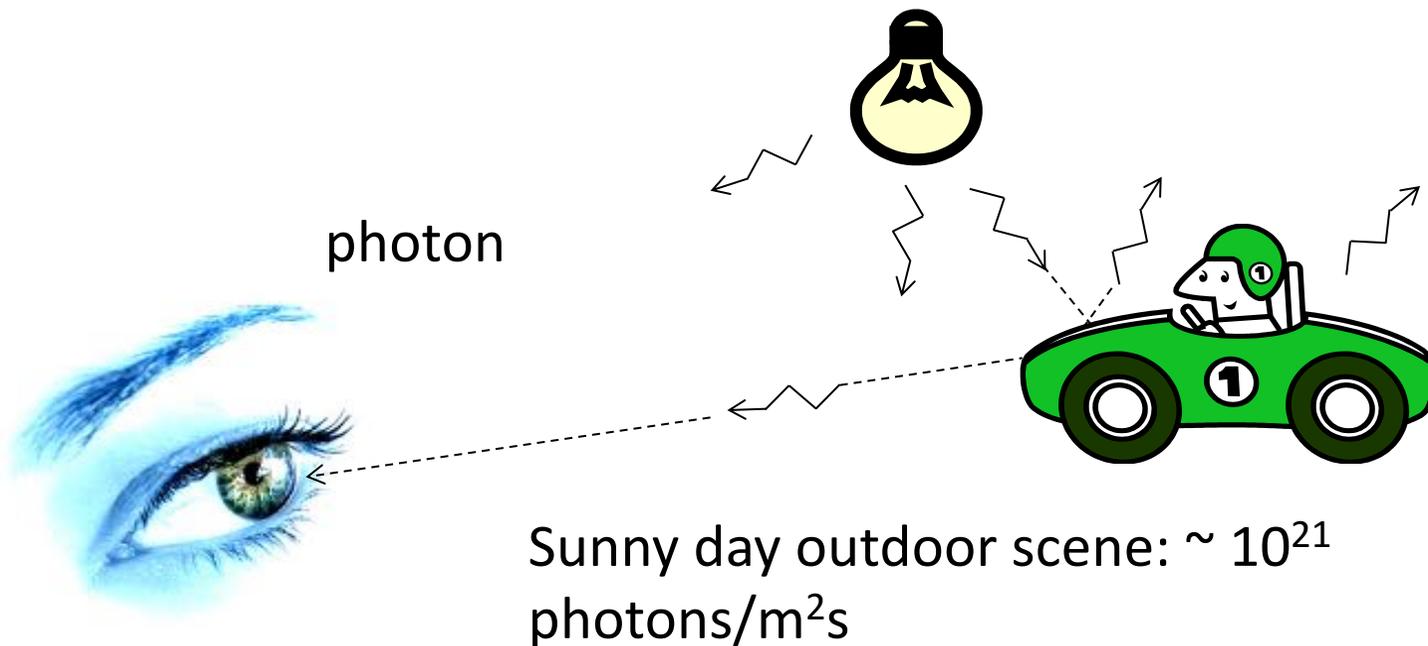


~20 to ~10<sup>15</sup> photons/s

The eye has a resolution of 130M receptors:  
120M gray scale (rods / stavar)  
7M color (cones / tappar)

# The problem of Computer Graphics

- Eye sensitivity:  $\sim 20$  photons/s to  $\sim 10^{15}$  photons/s
- So, if we could trace only the photons that hit the eye, the problem would be limited.
- But, the only really guaranteed 100% correct way (still) is tracing photons from light to eye.



## Facts:

- Eye sensitivity:  $\sim 20$  to  $\sim 10^{15}$  photons/s
- Sensitivity is logarithmic
  - i.e., difference between 100 or 200 photons is as noticeable as for  $10^{10}$  or  $2 \cdot 10^{10}$  photons
- $\sim 10^{21}$  photons/m<sup>2</sup>s
- 1 photon costs  $\sim 10,000$  cycles

10 billion years per square meter for 1 computer



# Solutions

For games: Smart specialized algorithms. And cheat, cheat, cheat.... as long as it is not too noticable

For movies: we typically trace  $\sim 100M - 10B$  photon bounces (and also cheat).



Typically: 100M – 1B photon bounces













So, what is the state-of-the-art for  
real-time graphics today?



LIVE AT THE MEADE BUILDING

# Beäst + Unreal Engine





# Illuminate Labs

Illuminate Labs produkt "Beäst" för realistisk belystning i spel

Beast used in e.g.:

*WET (A2M)*

*Mirror's Edge (EA Digital Illusions Creative Entertainment)*

*Mortal Kombat (Midway)*

*EVE Online (CCP Games)*

*CrimeCraft (Vogster Entertainment LLC)*

*Alpha Protocol (Obsidian Entertainment Inc)*

*Dragon Age: Origins (BioWare)*

*God of War III [8] (Sony Computer Entertainment)*

*Gran Turismo (Polyphony Digital)*

and also the Unreal Engine



Fallout 4,  
NVIDIA



Hair and Fur  
(games)



Shadows  
(games)



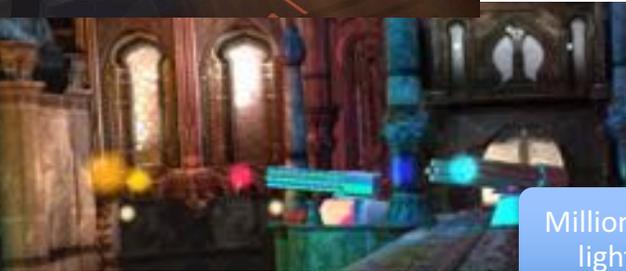
Splinter Cell  
Sim City  
Infamous 2



Scene  
compression



Airlight  
(games)



Millions of  
lights  
(games)

Our  
Research  
Projects



Free  
Viewpoint  
Video

GPGPU



Avalanche Studios  
Bosch  
Intel



e.g. sorting:  
19 5 100 1 63 79  
↓  
1 5 19 63 79 100

# Beast + Unreal Engine

*It is possible to do better...*



# Mix of graphics and photographing

Textures from photographs



# Mix of graphics and photographing

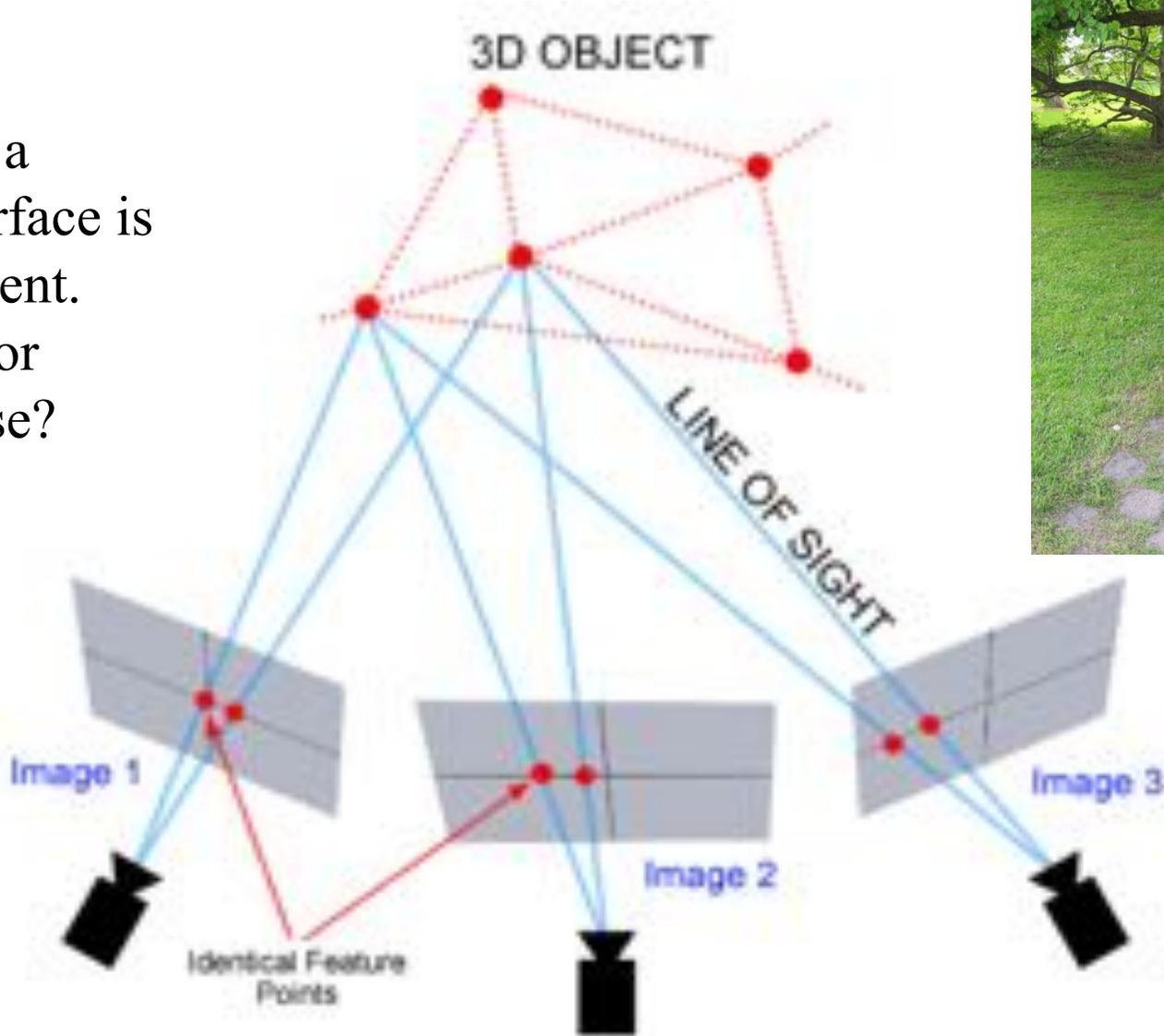
- Istället för att modellera 3D-grafik och beräkna realistiskt utseende:
  - Fotografera/filma verkligheten och konvertera den till 3D-grafik.
- Ofta vill man mixa modellerade och verkliga konverterade objekt.



<http://www.cse.chalmers.se/~uffe/mindary/demo/v2.html>

# Reflective surfaces (=view-dependent colors) are a problem

The color of a reflective surface is view dependent. So, what color should we use?



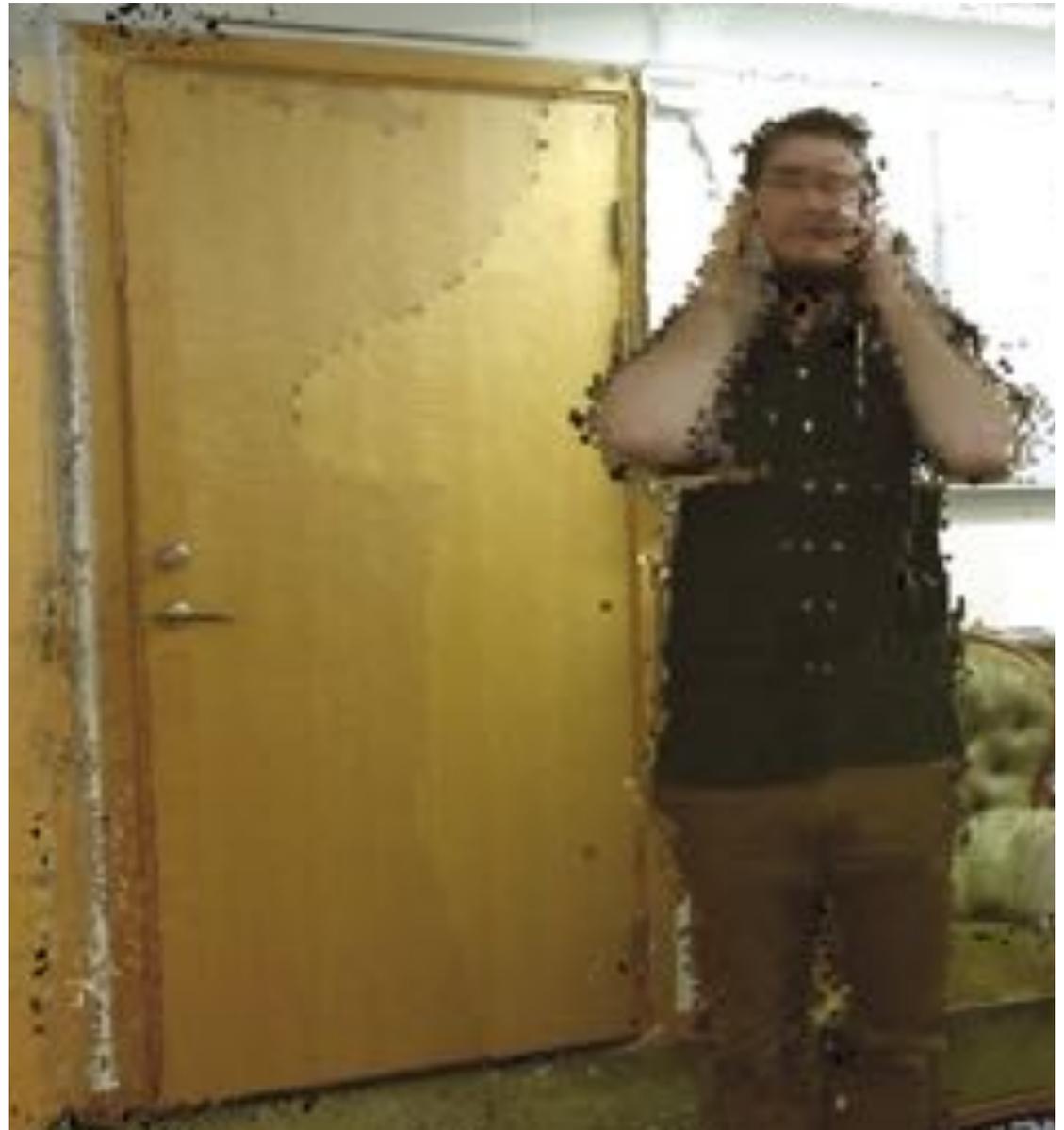
1. View-dependent colors.  
(here also different exposure times for the two cameras).

The more reflective surface,  
the larger the problem.

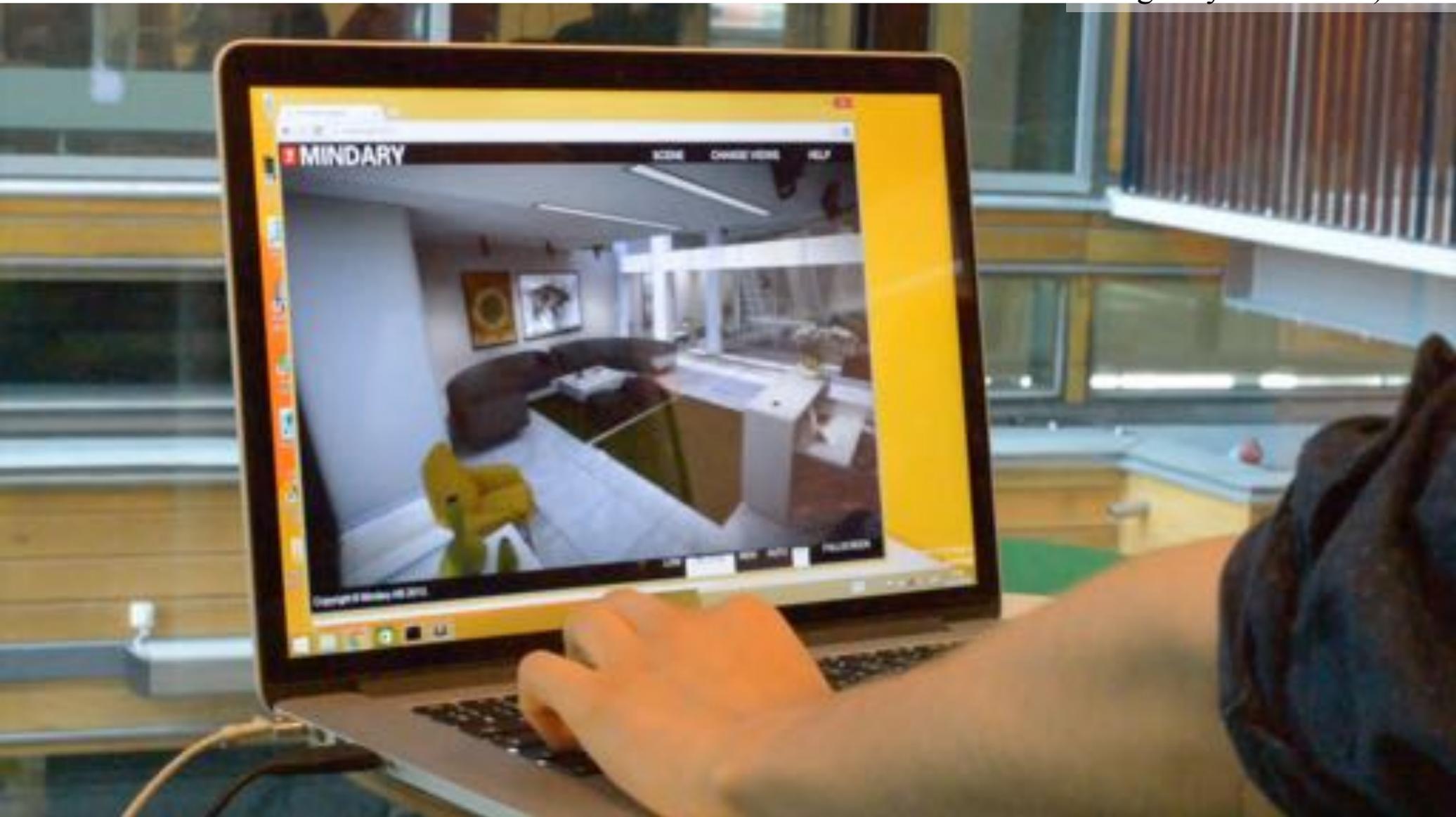
“Solution”:

- Suppress reflections when photographing.
- Computer-generate the reflections when visualizing the 3D scene.

Very reflective surfaces (e.g. mirror) does not work.



The most important 1<sup>st</sup>  
light bounces (i.e., sharp  
and glossy reflections)



Combinig photo textures and  
computer-generated view-  
dependent reflections

# Unreal Engine 4

The most important 1<sup>st</sup>  
light bounces (i.e., sharp  
and glossy reflections)

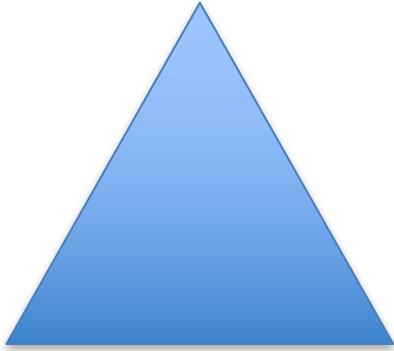


Increasing the amount of geometric  
details

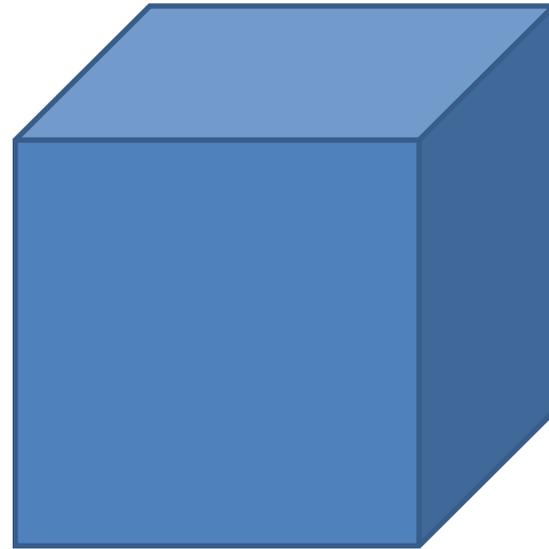
# Triangles



# Voxels



Triangle  
36 bytes



Voxel  
Volume – element  
1 bit

# Voxels

- Desirable to be able to use very high resolutions



# Voxels

Why use voxels?



Autodesk fluid simulation

# Voxels

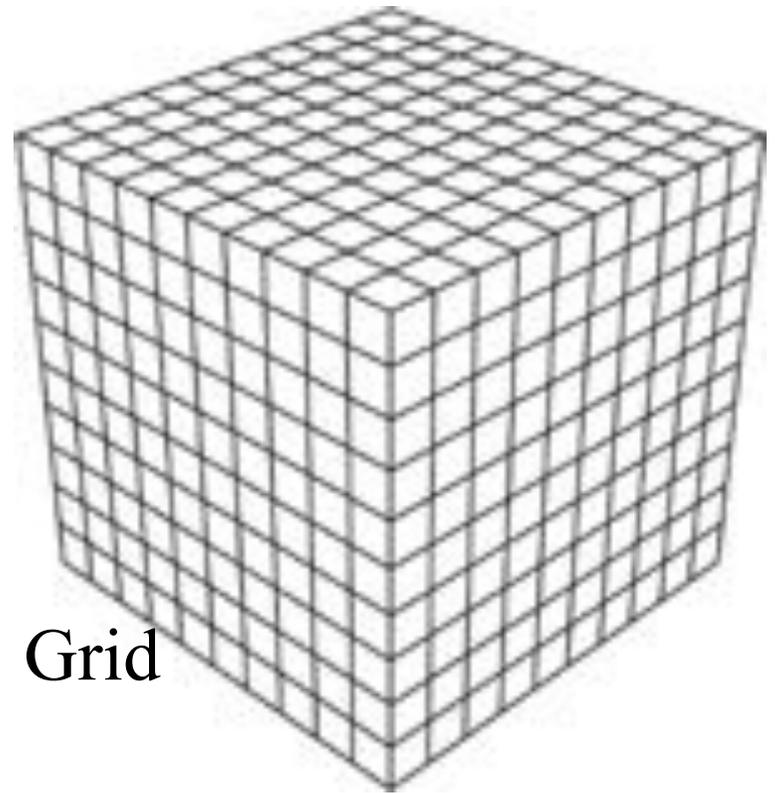
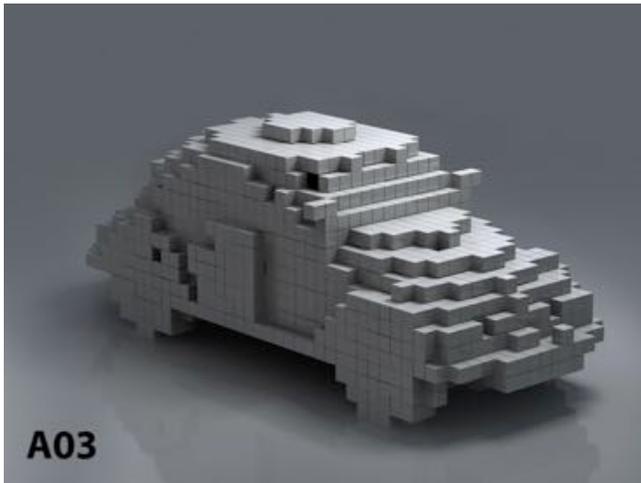


RealFlow by nextLimit

# Voxels

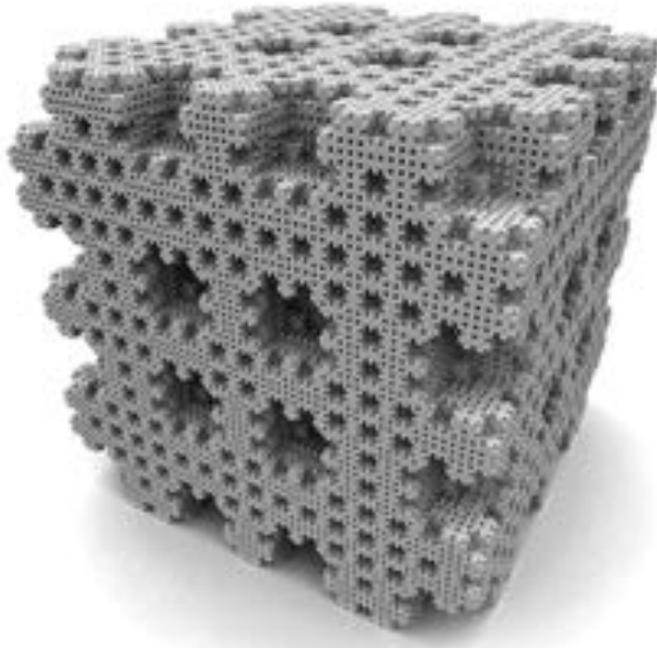
One possible data structure:

- Grids – 3D array of 0:s and 1:s

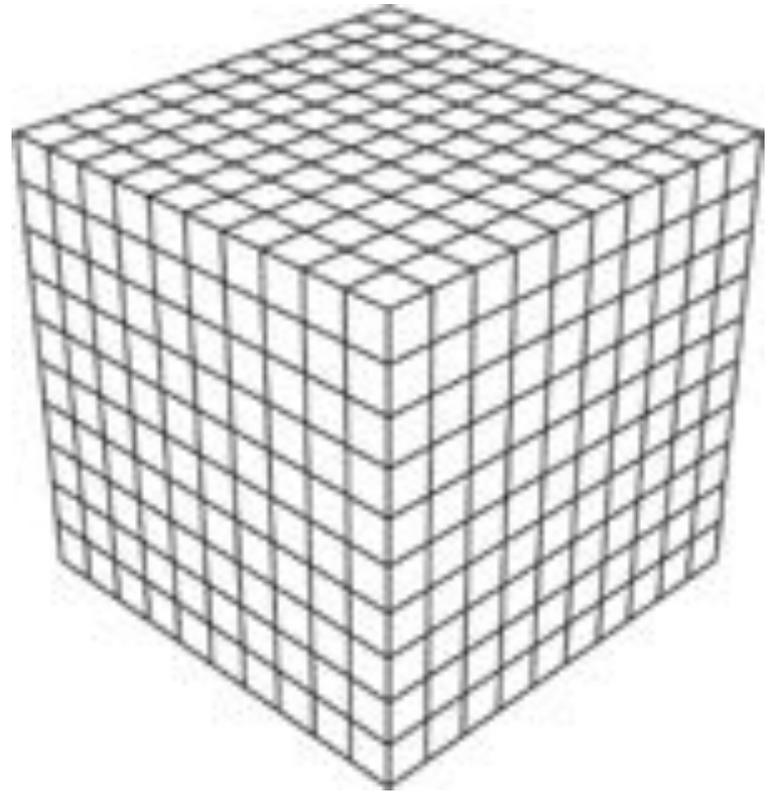


# Voxels

One possible data structure:

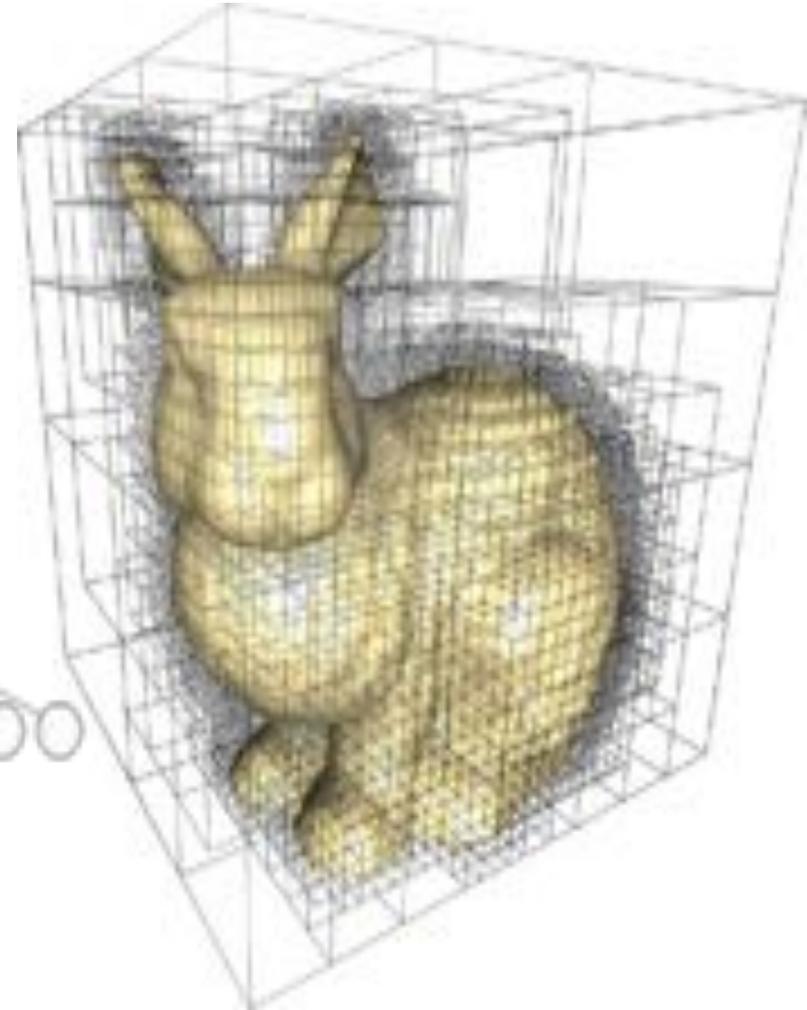
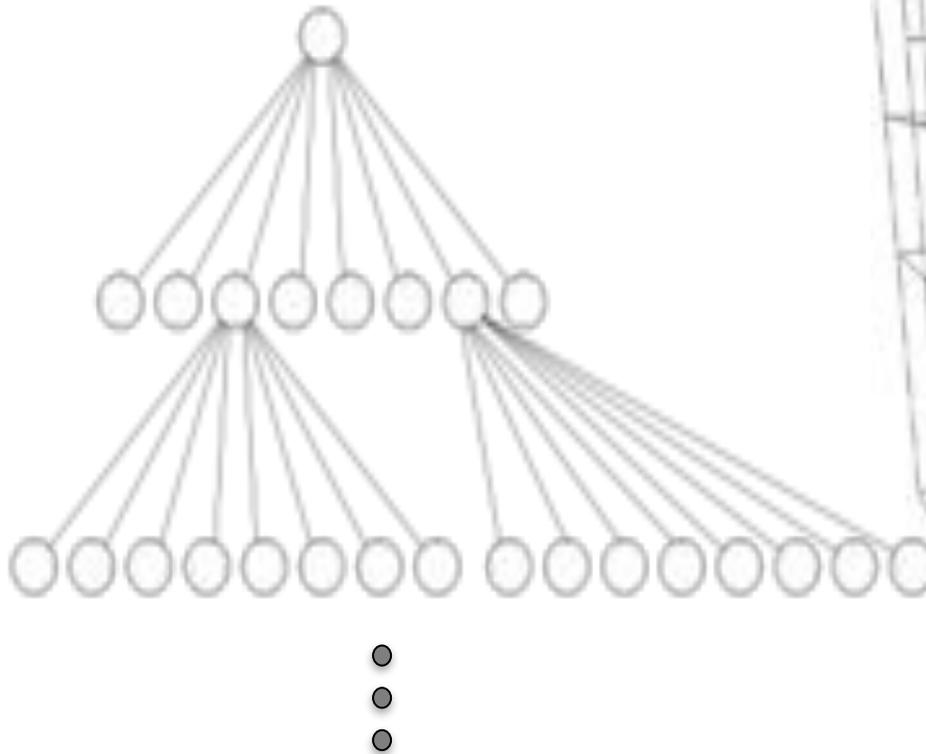
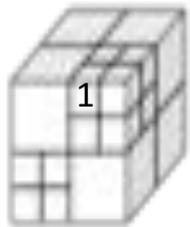
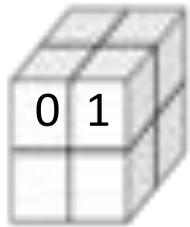


3ACHS



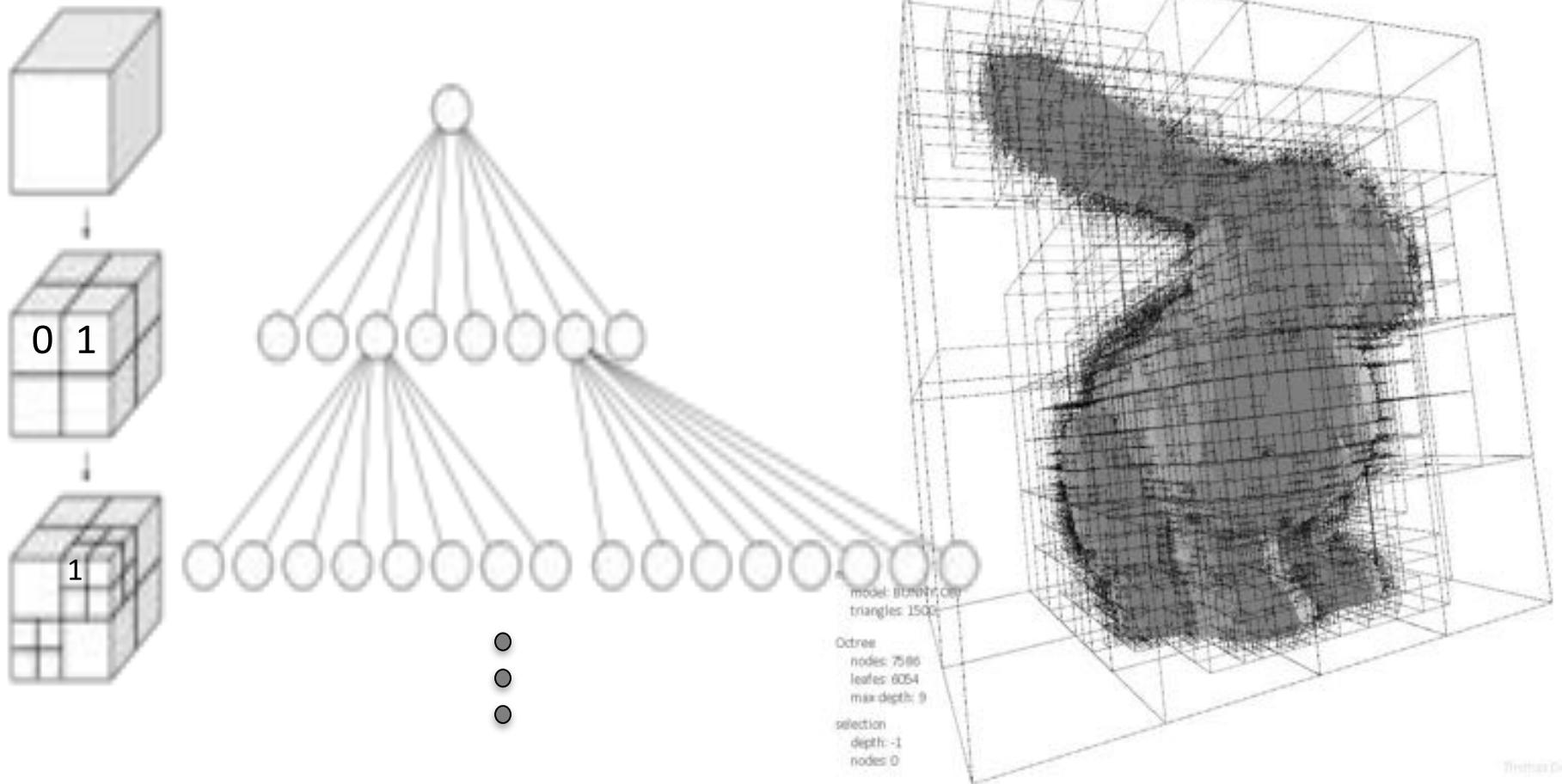
# Sparse Voxel Octree

Each node has eight children, representing an octant of the parent node's volume.



# Sparse Voxel Octree

Each node has eight children, representing an octant of the parent node's volume.



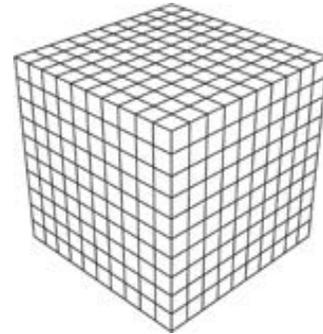
# Sparse Voxel Octree

- SVO: Id Software, rage 6
- 1.15 bits/ non-empty voxel
- We: 0.08 bit/non-empty voxel



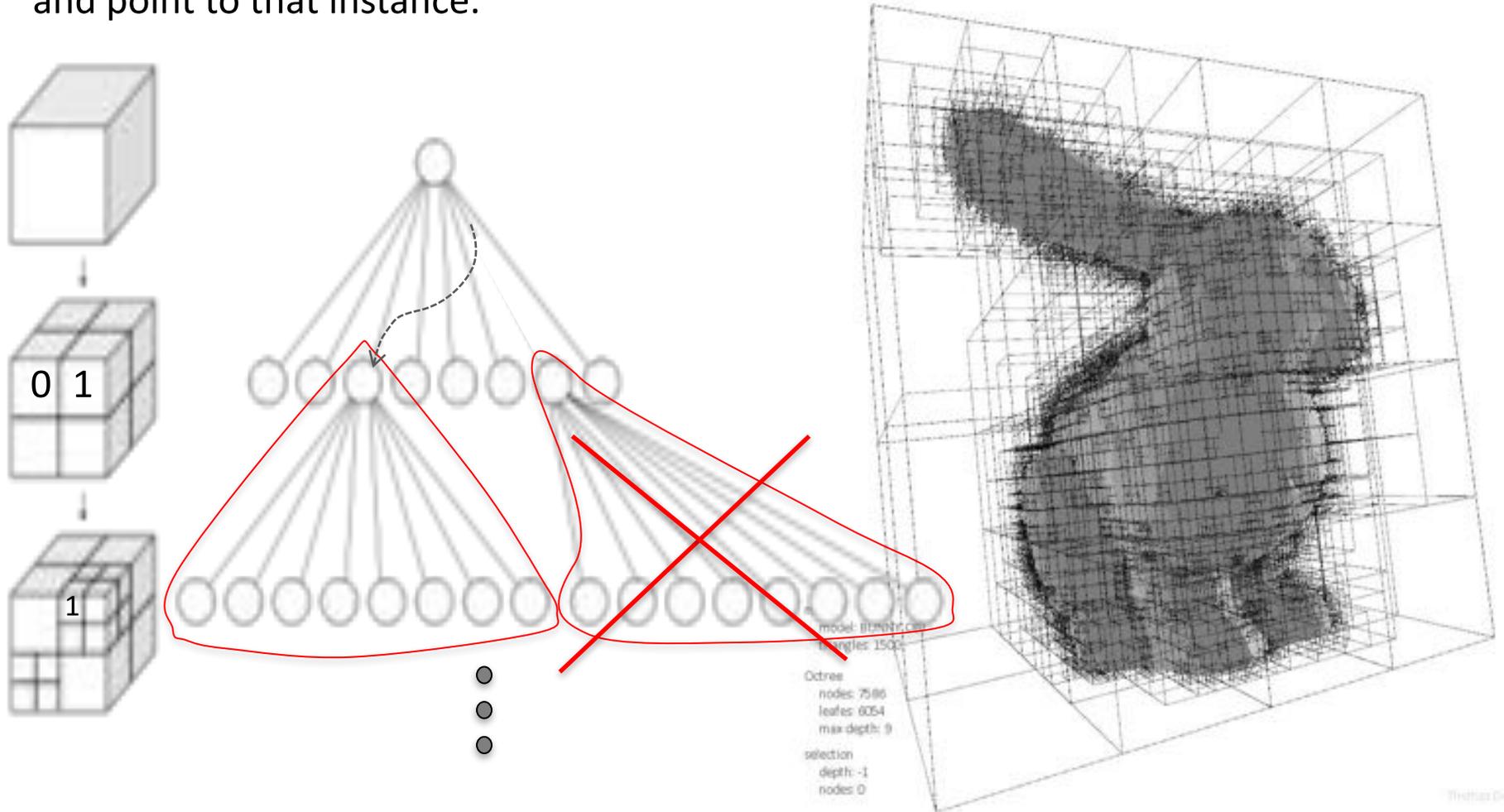
# Voxels

- Voxel = 1 bit.
- We currently handle scene of res =  $128.000^3$ 
  - Naively: 262 TB
  - We => < 1GB

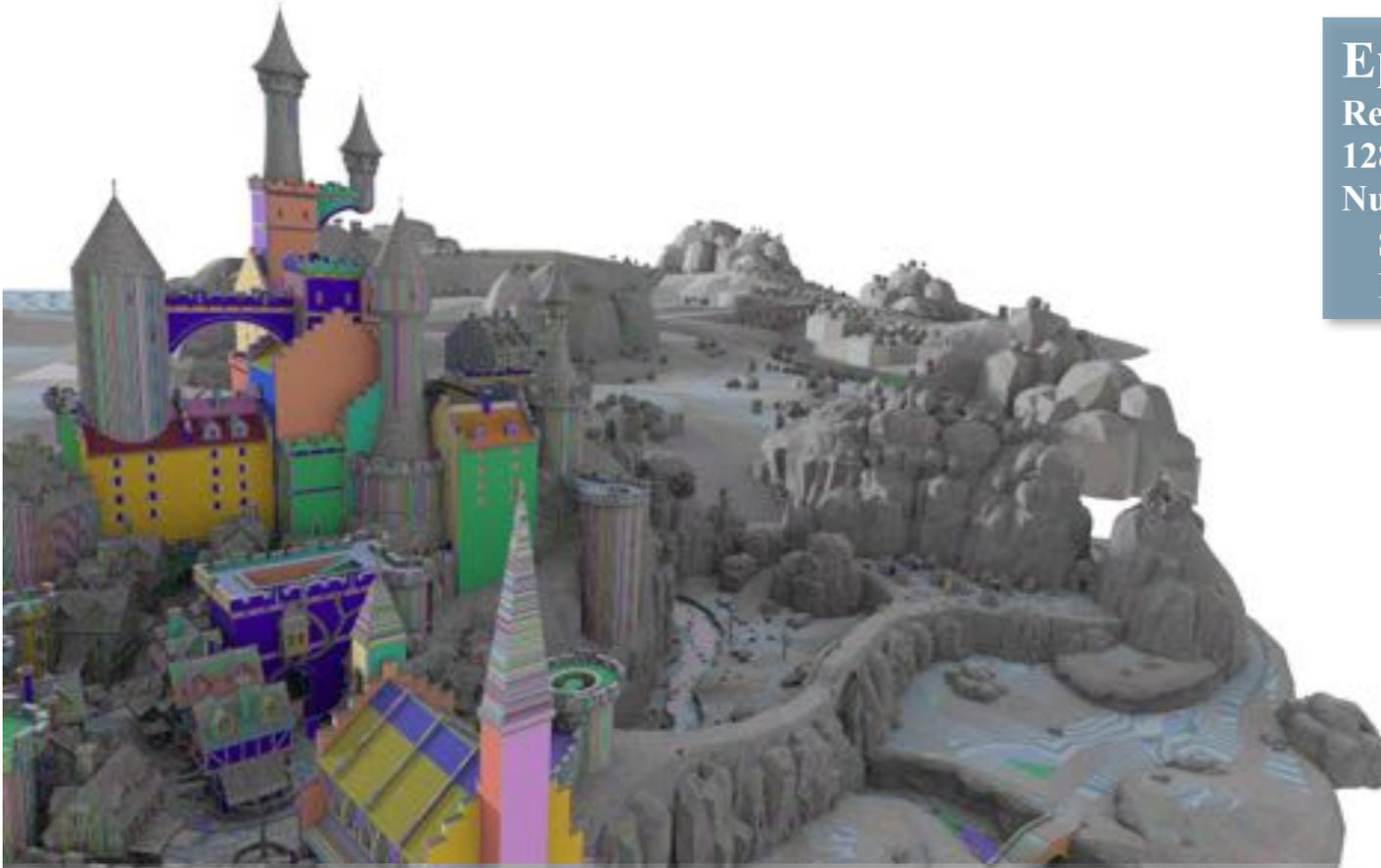


# Our Voxel DAGs

For identical subgraphs, only store one instance, and point to that instance.



# Visualizing Identical Subtrees



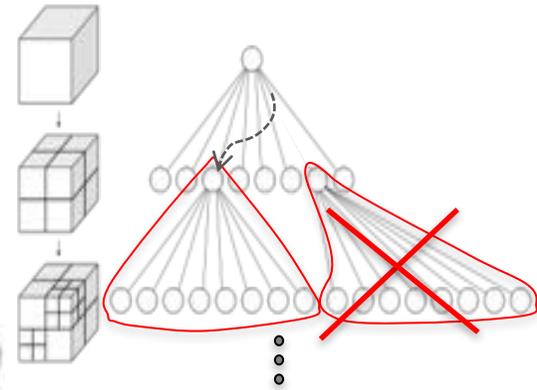
## Epic Citadel

Resolution: 128K × 128K × 128K

Number of nodes

SVO: 5.5 billion

DAG: 45 million (0.8%)



# Visualizing Identical Subtrees

## Hairball

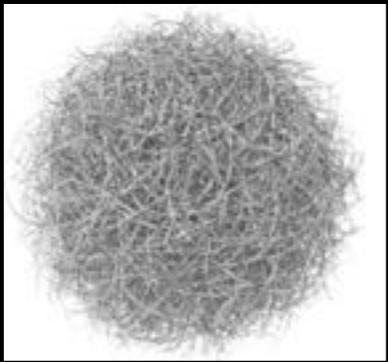
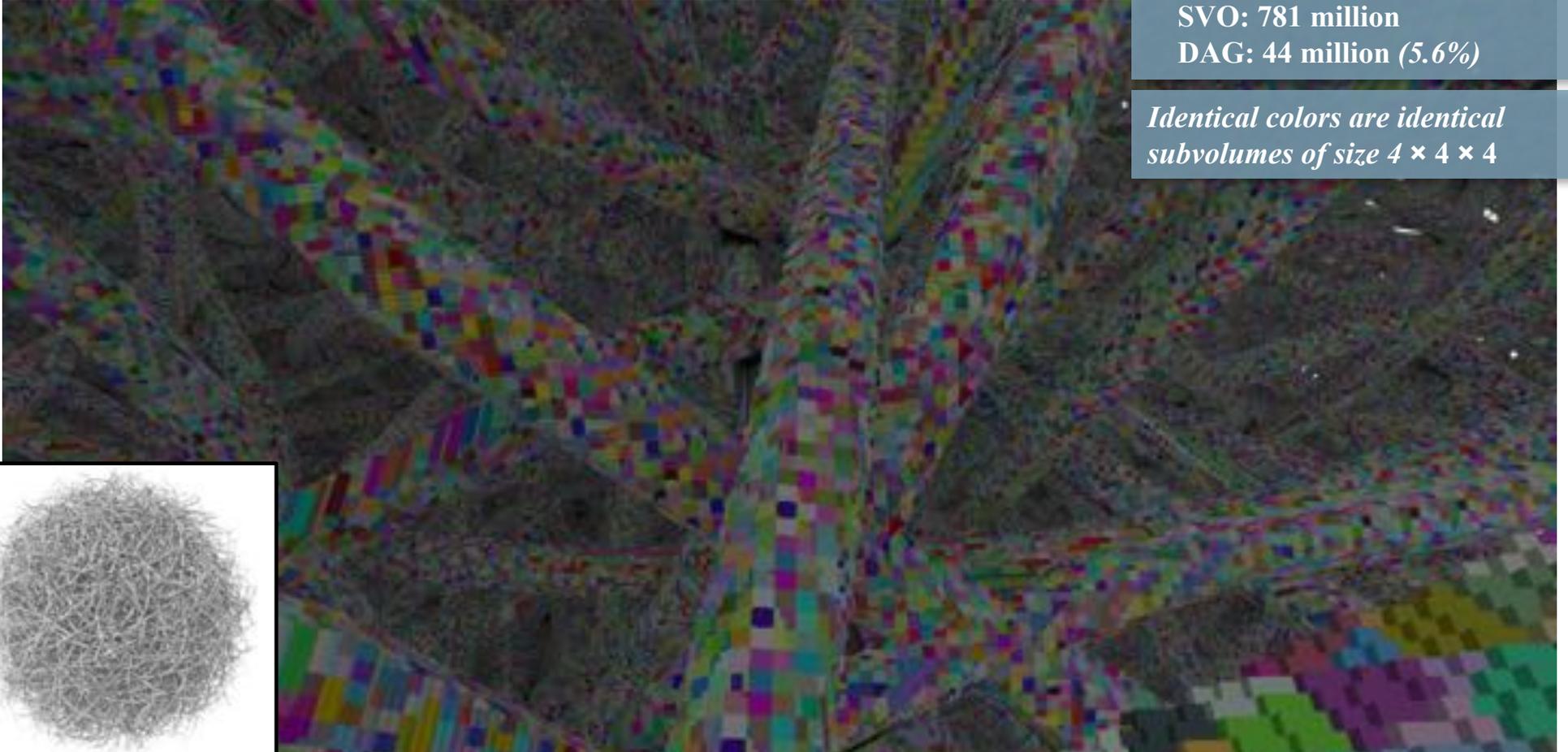
Resolution: 8K × 8K × 8K

Number of nodes

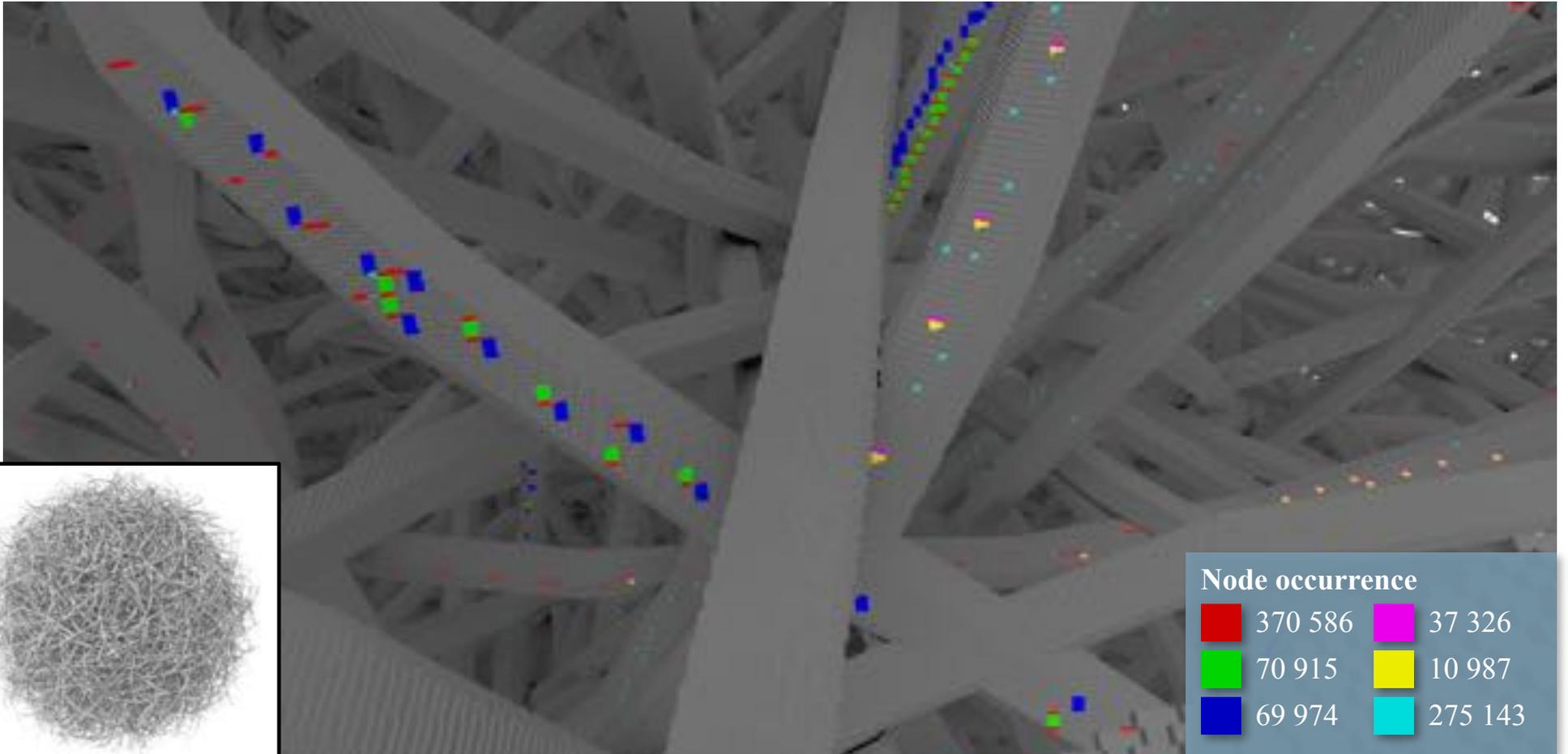
SVO: 781 million

DAG: 44 million (5.6%)

*Identical colors are identical  
subvolumes of size 4 × 4 × 4*



# Visualizing Identical Subtrees





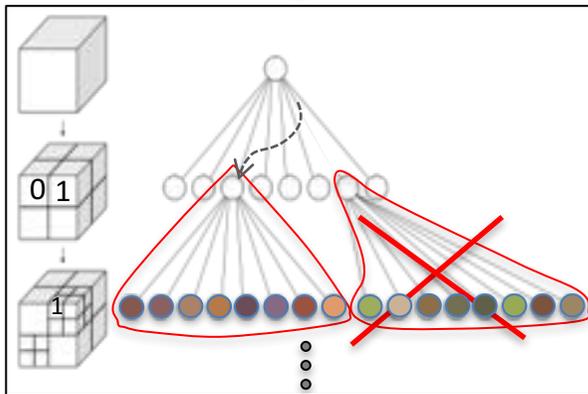
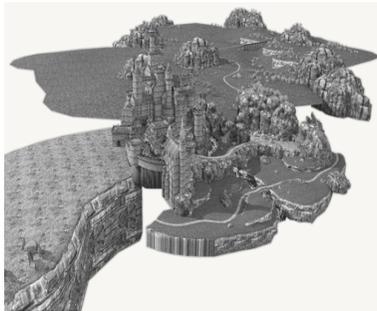
What about colors?



What about colors?

# Compress geometry and colors separately with different specialized methods.

Geometry:



Voxel colors:



Three problems:

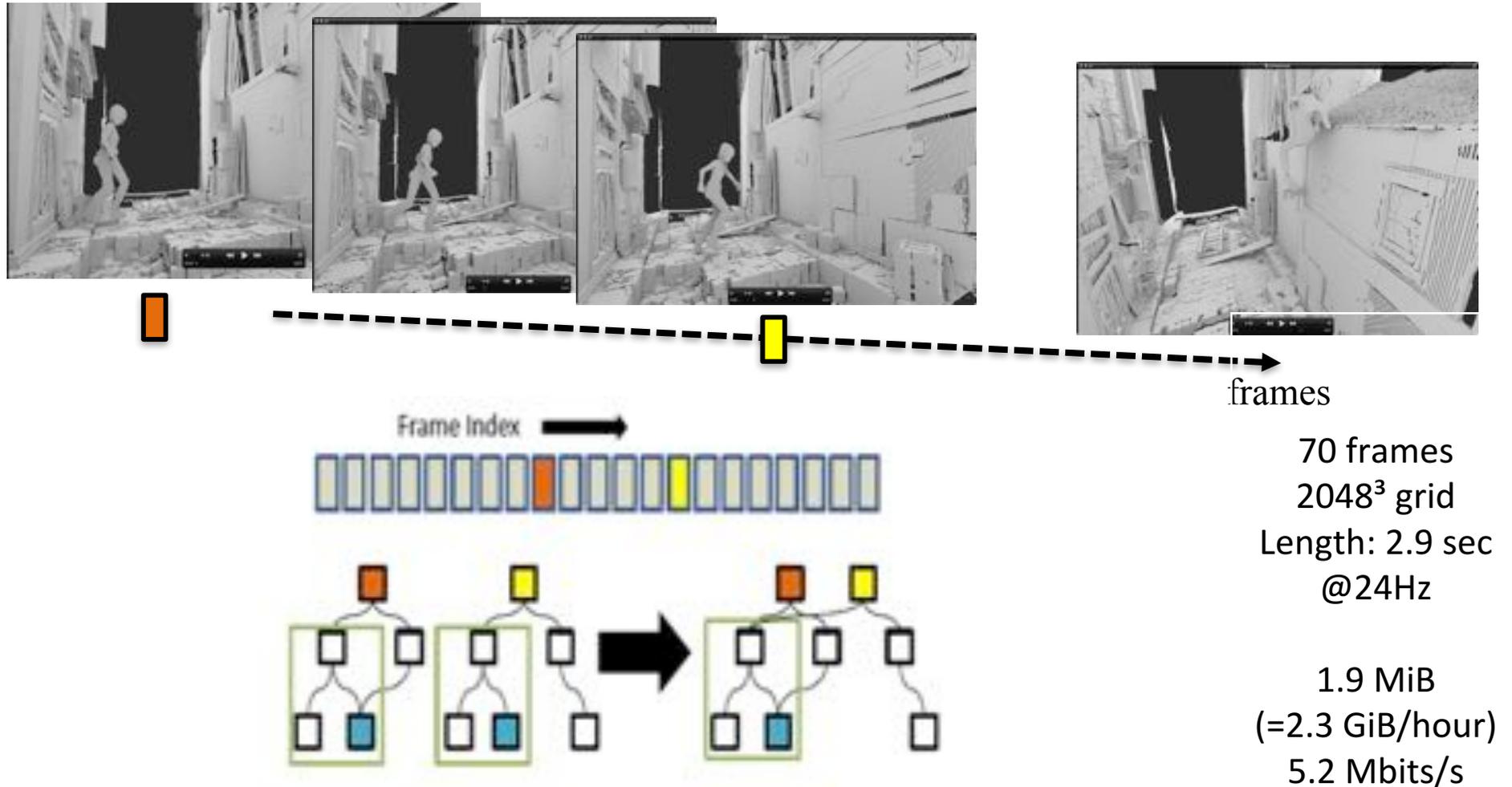
1. How can we compress the colors efficiently?
2. Connection between voxels and their colors
3. Fast color lookups

**From static scenes  
to dynamic (moving) scenes  
to Free Viewpoint Video**

# Voxel DAGs – dynamic scenes

## 3D geometry + time dimension

For every time step (=frame) in a dynamic scene, convert the whole voxelized 3D scene to a DAG:



# Voxel DAGs – dynamic scenes

## 3D geometry + time dimension



70 frames  
2048<sup>3</sup> grid  
Length: 2.9 sec  
@24Hz

1.9 MiB  
(=2.3 GiB/hour)  
5.2 Mbits/s

# Free Viewpoint Video

Want:

1. convert a real scene to 3D graphics, 24 times/second.
2. Render scene from any viewpoint.



Med 2 eller fler kameror kan man beräkna djup – precis som våra ögon.



Med 2 eller fler kameror kan man beräkna djup – precis som våra ögon.



Med 2 eller fler kameror kan man beräkna djup – precis som våra ögon.



Med 2 eller fler kameror kan man beräkna djup – precis som våra ögon.

Varje kub  $\sim 1\text{cm}^3$ . Önskar  $\sim 1\text{mm}^3$



# Free Viewpoint Video

## KINECT

Input: Three depth streams from Kinect cameras  
Voxel grid resolution: 512x512x512  
Frames: 480



## Cameras:



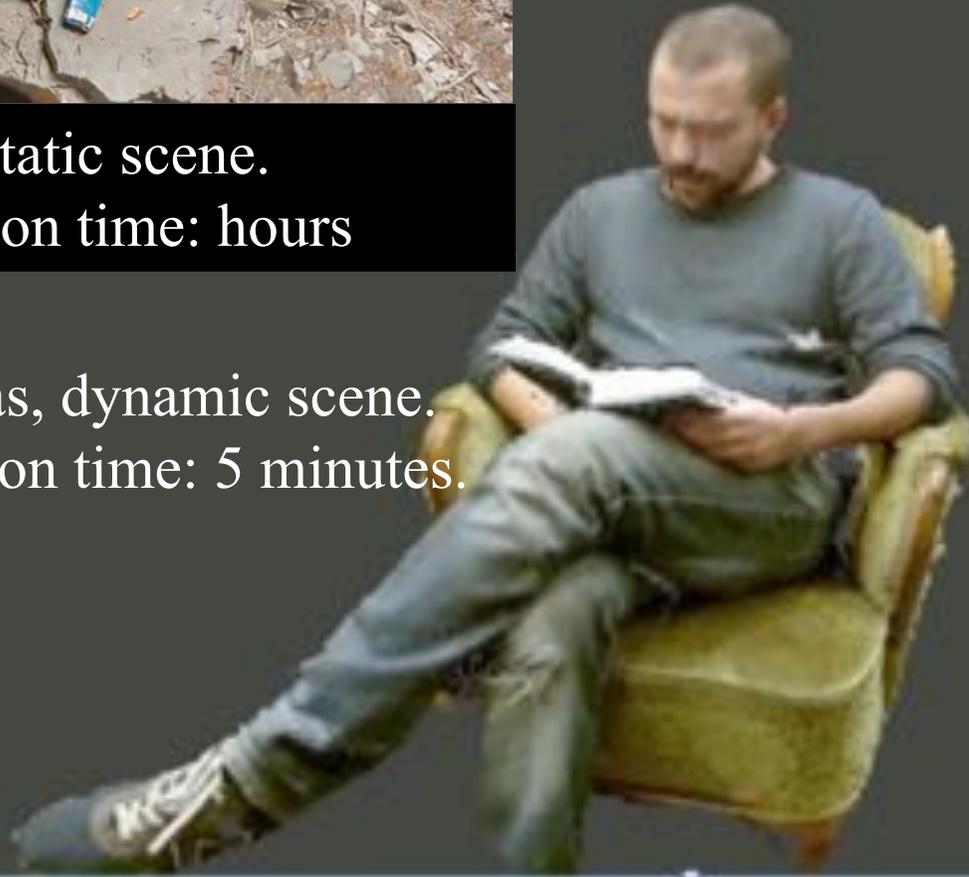
480 frames  
512<sup>3</sup> grid  
20 sec  
@24Hz

5.2 MiB  
0.9  
GiB/hour  
2.1 Mbits/s



500 photos, static scene.  
Precomputation time: hours

We: 3 cameras, dynamic scene.  
Precomputation time: 5 minutes.



Cameras:





LG/LT: 16 cams geometry + 8 cams texture

Microsoft: ~100 cameras, triangles  
Precomputation time: ~100 hours.

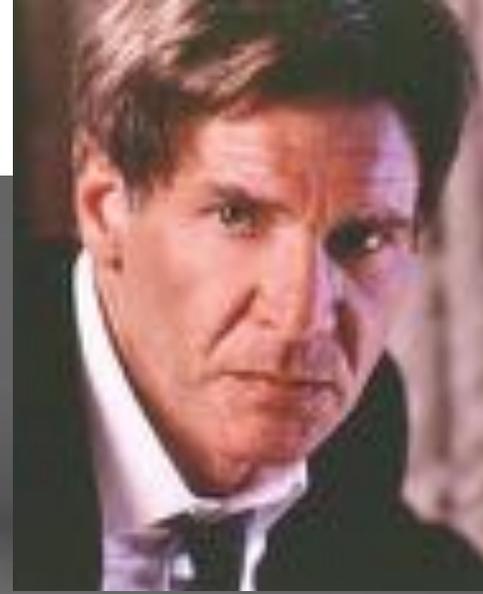




### Our method:

- Does not change or throw away input data.
- Higher geometrical detail.
- Same data sizes.
- Faster computation times
- Much simpler and also robust

But we still have no view-dependent colors.  
I.e., no reflections that change with the view position



# Deadpool (to demonstrate view-dependent reflections)



# Deadpool

(to demonstrate desired quality of FVV with view-dependent reflections)



# Framtidens mediatekniker

- Filma (4-10 kameror)
- 3D-rekonstruera varje frame
  - För varje tidssteg i filmen:
    - 3D rekonstruera scenen från kamerornas foton.
- Komprimera från TB till GB.
  - streambar över internet
- Spela upp filmen från valfri synvinkel
  - Dvs vi kan gå omkring i filmen medan den spelar.



# Framtidens mediatekniker

- Science Fiction visar vägen
  - Visar vad vi vill ha
  - Människan skaffar det hon vill ha (bland annat...)

Star Trek



60:ies



2000

# Star Trek - Tablets

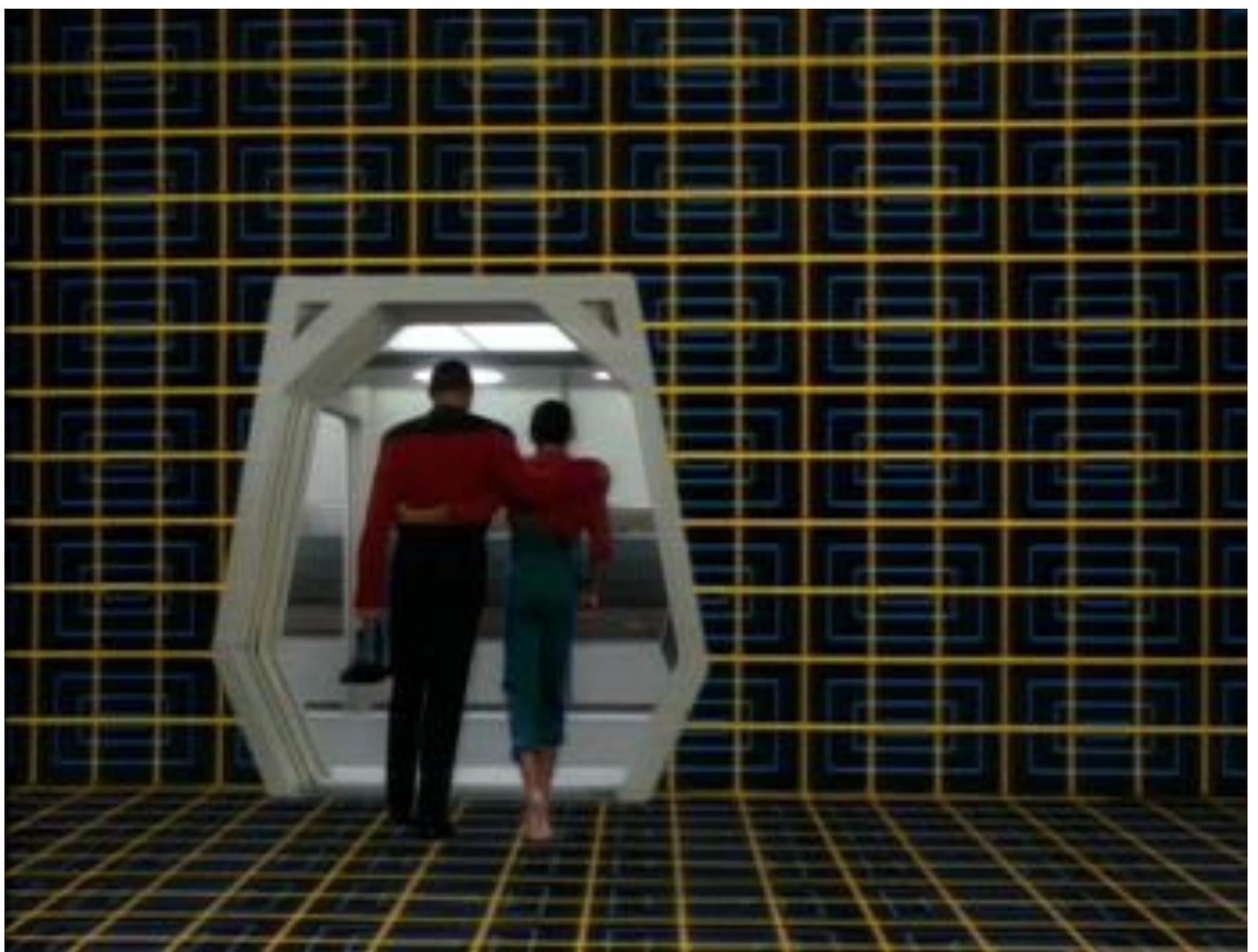
80:ies

2010

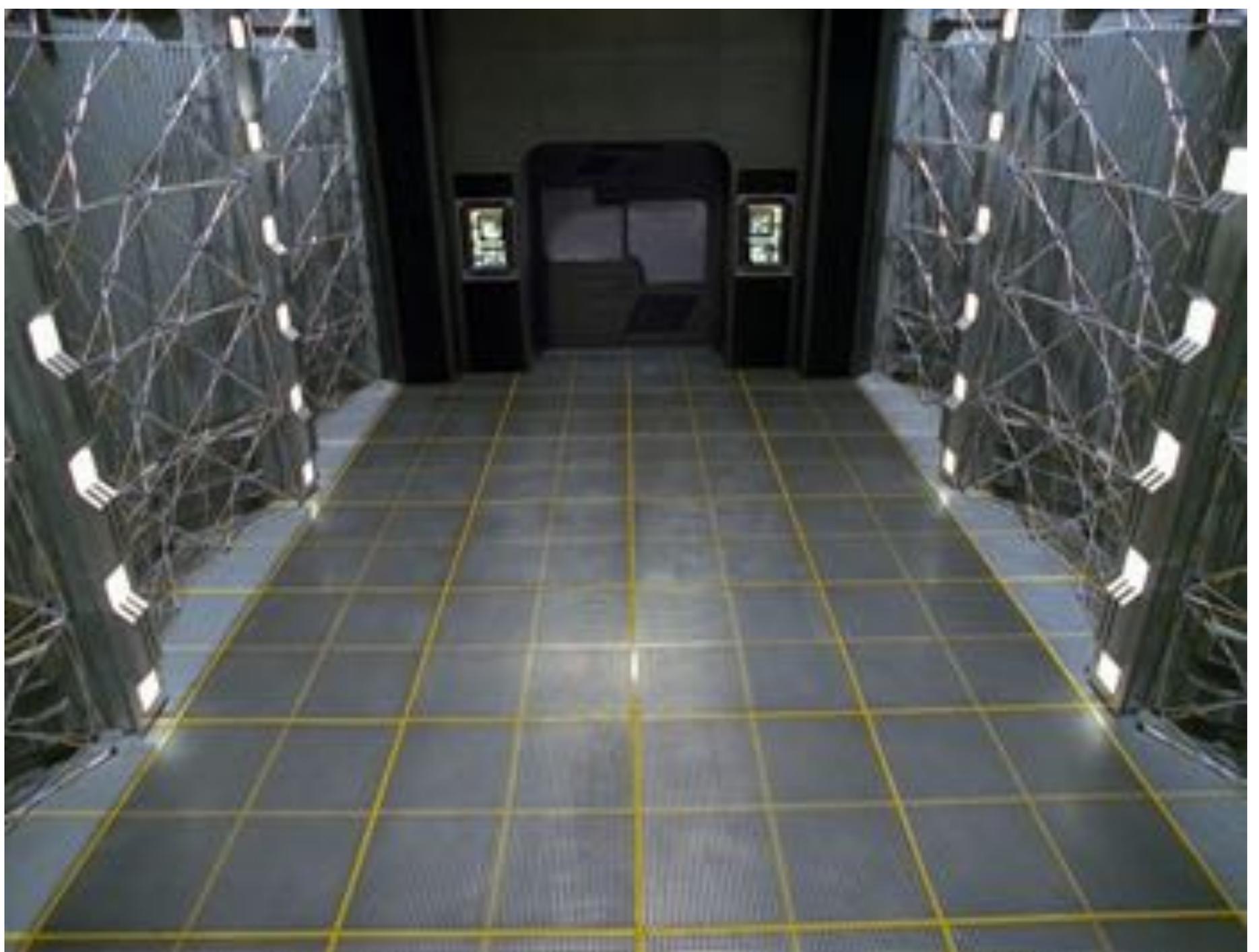


# Star Trek - Holodeck









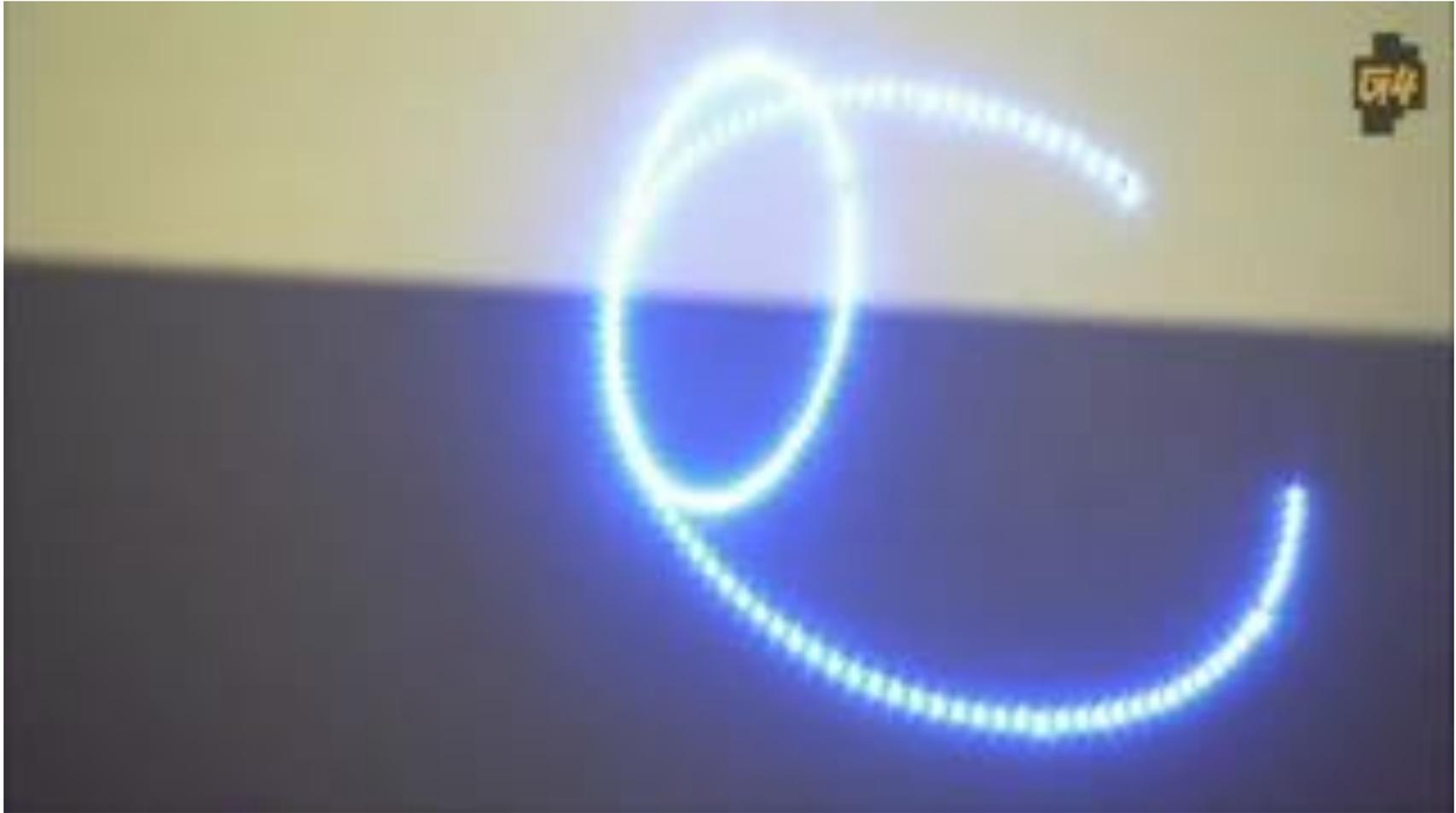
Oculus Rift



HTC Vive



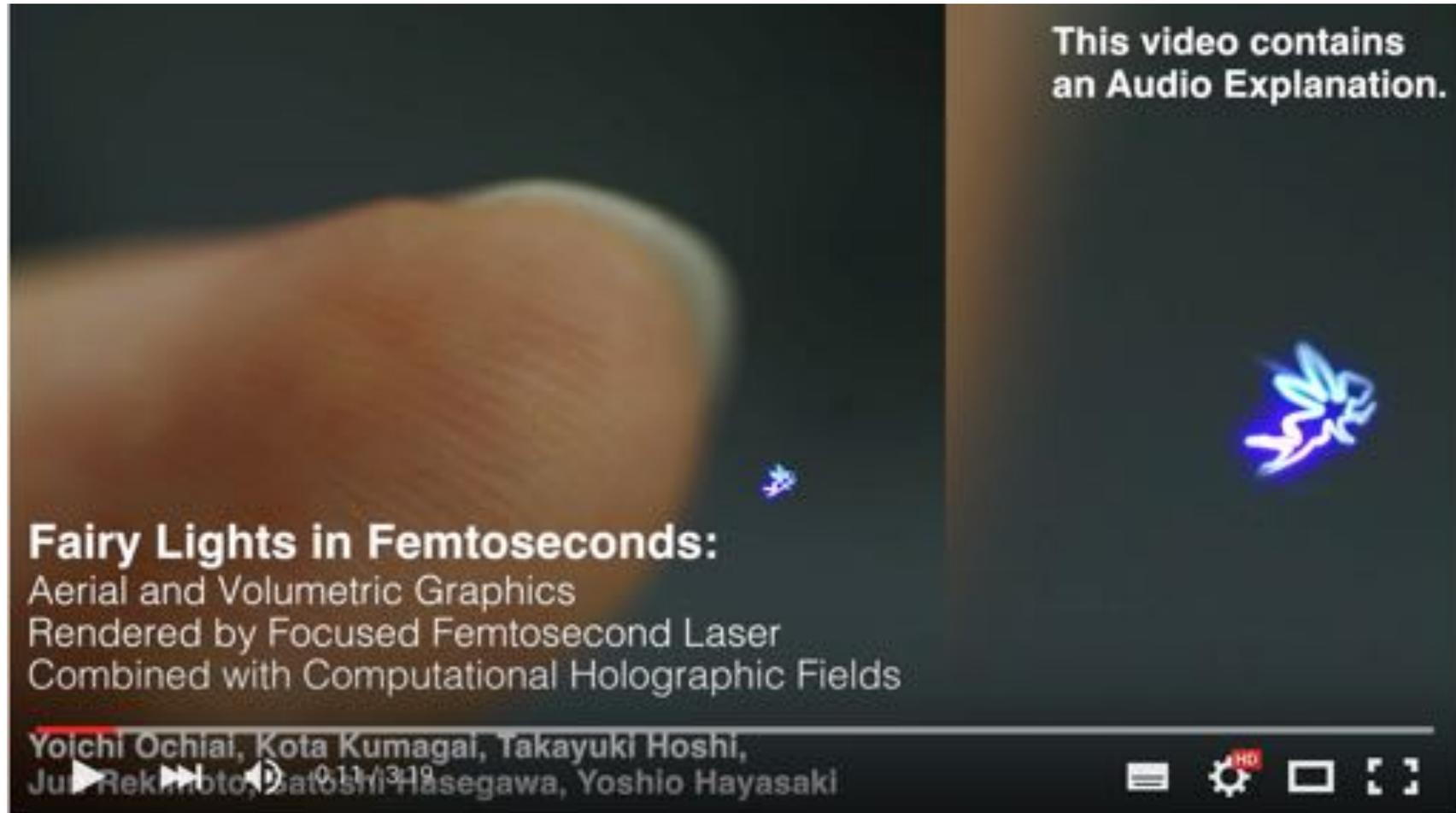
# Mid air display



# Mid air display



# Mid air displays 2015



This video contains an Audio Explanation.

**Fairy Lights in Femtoseconds:**  
Aerial and Volumetric Graphics  
Rendered by Focused Femtosecond Laser  
Combined with Computational Holographic Fields

Yoichi Ochiai, Kota Kumagai, Takayuki Hoshi,  
Julian Rekimoto, Satoshi Hasegawa, Yoshio Hayasaki

0:11 / 3:19

⏪ ⏩ ⏴ ⏵ 🔊 ⚙️ 📺 🗑️

The video player shows a dark scene with a large, blurry, brownish object on the left and a small, glowing blue and purple fairy-like figure on the right. The video player interface includes a progress bar, a play button, and various control icons.

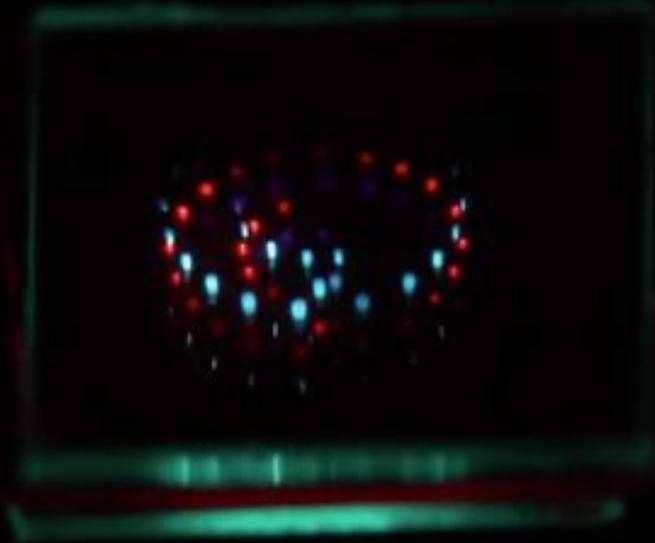
# Mid air displays 2015

This video contains an Audio Explanation.

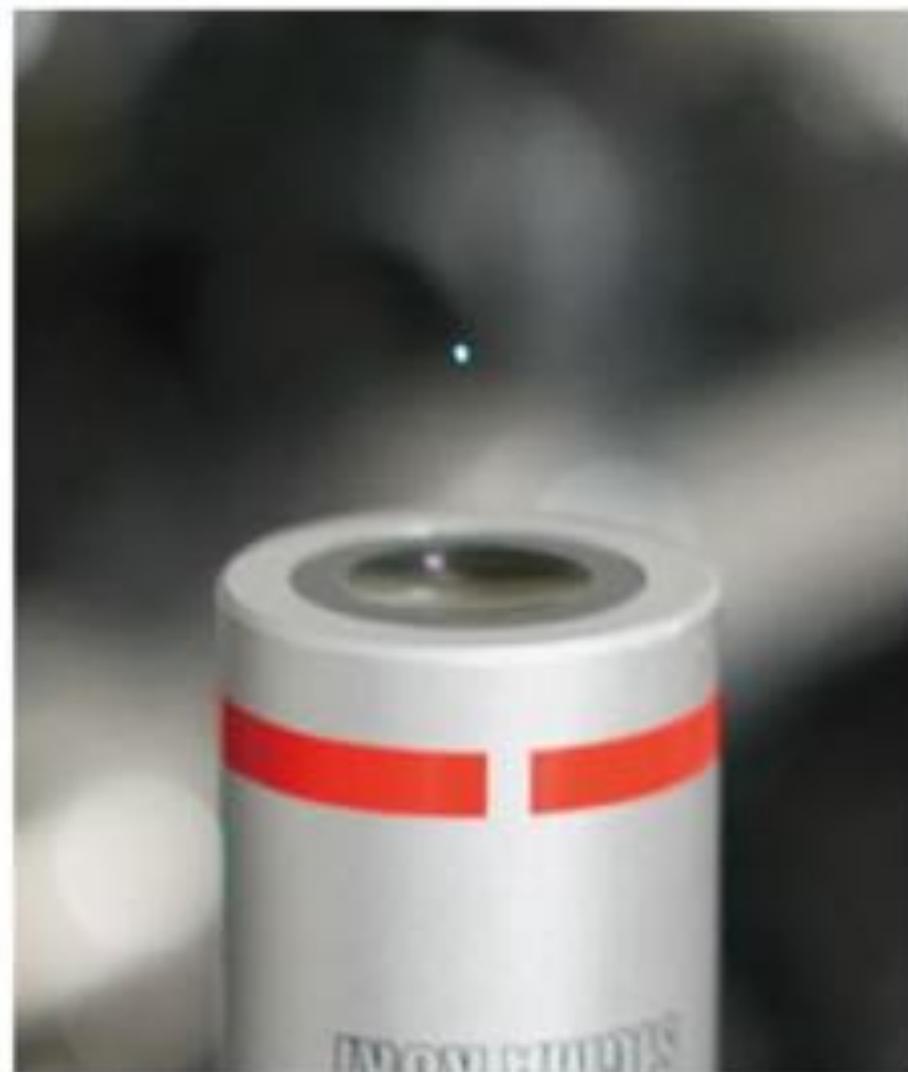
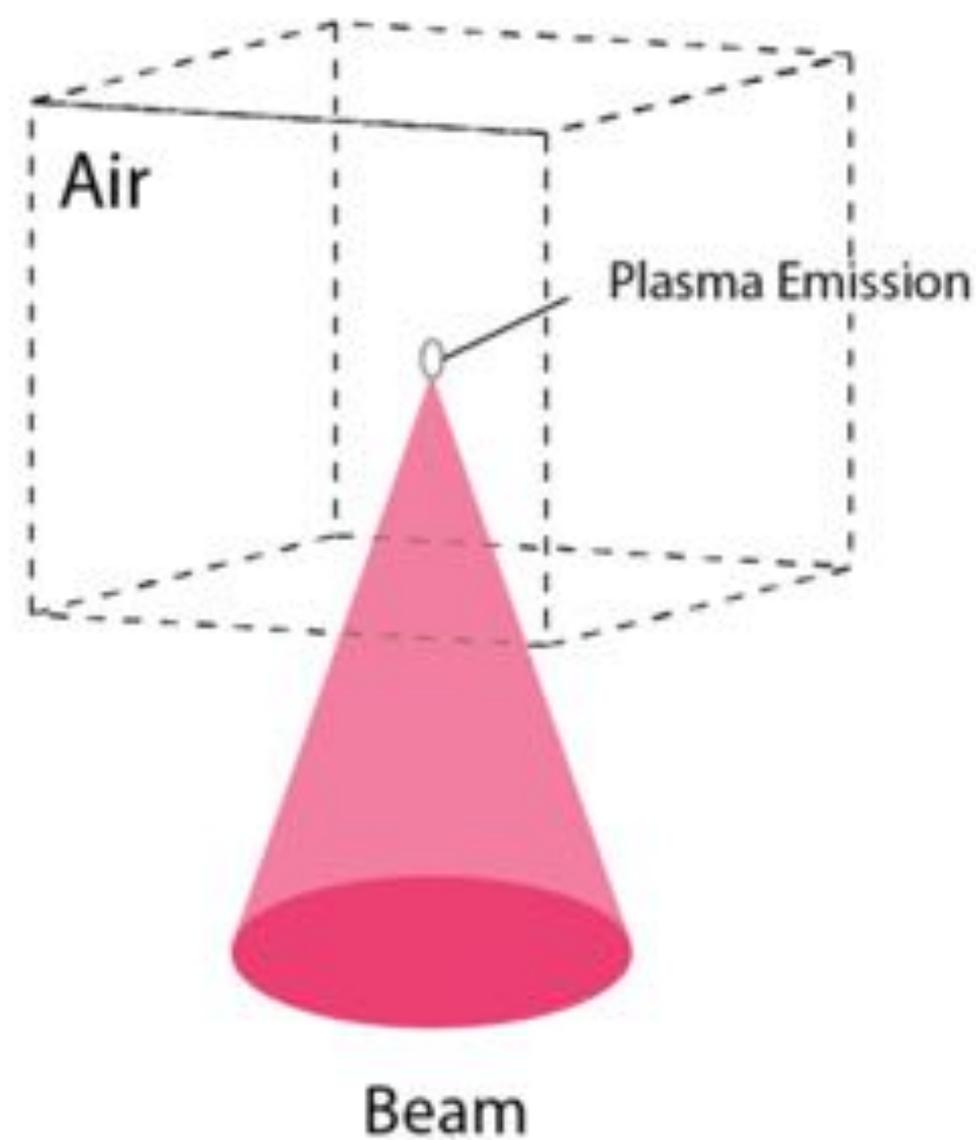


**Fairy Lights in Femtoseconds:**  
Aerial and Volumetric Graphics  
Rendered by Focused Femtosecond Laser  
Combined with Computational Holography

Yolchi Ochiai, Kota Kumagai, Takayuki Hoshi,  
Jun Rekimoto, Satoshi Hasegawa, Yoshio Hayashi



0:14 / 3:18



**Figure 4:** *Laser plasma induced by focused femtosecond laser.*



Rendering Volumetric Haptic Shapes in Mid-Air using Ultrasound

# Inget nytt under solen

- Titta på Automan från 1983-1984.

# Inget nytt under solen

- Titta på Automan från 1983-1984.



# Inget nytt under solen

- T





# The Future?

- Much science fiction will become possible
- We want to enter computer-generated virtual worlds
  - Holodeck (maybe in a few decades)
  - Or plug into brain like in Matrix...
- We want computer-generated objects to enter our real world
  - 3D printers
  - Mid-air displays
  - Virtual matter (particles)

